Nicholas Westbury

Key Skills _

Languages C#, Java, JavaScript/Typescript, Python, Go, C, C++, SQL, PHP, HTML/CSS, Bash

Technologies .NET Core, Docker, NodeJS, ReactJS, React Native, PostgreSQL, MongoDB, Apache, Nginx, Django, Git

Biligual Fluent in verbal and written French

Education

University of Waterloo

Waterloo, Ontario

September 2015 - June 2019

Work Experience _____

BACHELOR OF COMPUTER SCIENCE

Google Inc Seattle, WA

FULL-STACK SOFTWARE ENGINEER

January 2020 - Present

- Integrated Google's AppSheet with Google's Artifical Intelligence offerings (Gemini) on frontend and backend
- · Worked on Google Workspace / AppSheet intergations: Google Drive / Sheets / Forms / Chat / Cloud / Apps Script
- · Co-inventor on 4 distinct patents related to novel no-code functionality

AppSheet (Solvebot Inc)

Seattle, WA

FULL-STACK SOFTWARE ENGINEER

May 2019 - January 2020

- Design & developed features for the no/low code developement platform AppSheet: adding undo/redo, adding template support for web hooks, working on the app & web editor
- · Customer support rotation, fixed 100s of bugs / issues as reported

Ultimate Software San Francisco, CA

SOFTWARE ENGINEER INTERN

April 2018 - December 2018

· Supported website survey timeseries and question bank features

Toronto-Dominion Bank Asset Management

Toronto, ON

PORTFOLIO ANALYTICS FULL-STACK WEB DEVELOPER INTERN

August 2017 - December 2017

• Supported internal portfolio management tools implemented bulk portfolio loading, import tool, administrator session editor

ARB Labs Niagara Falls, ON

PYTHON DATA SCIENCE & WEB DEVELOPER INTERN

January 2017 - April 2017

Improved accuracy of image-recognition system called ChipVue to recognize casino chips. Wrote low-level hardware Python
extension in C to interface with a camera array

Computer Science Computing Facility (CSCF)

Waterloo, ON

PYTHON WEB DEVELOPER INTERN

May 2016 - September 2016

Reinforcement Learning and Artificial Intelligence (RLAI) Lab

Edmonton, AB

NSERC Undergraduate Research Award Intern

Summer 2013-2015

• Implemented machine learning for continuous-space search and reinforcement learning algorithms for Roomba shape detection

Hackathons & Projects.

Hack the North, Winning team 2016/2018 with a weed-detecting and picking robot & VR haptic

2016-2018 feedback vest

2009-2014 **FLL/FTC Robotics Team**, Programmed for four-time national champion robotics team