Computing the Rank and Nullspace of Rectangular Sparse Matrices

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To model biochemical networks, systems biologists are generating increasingly large stoichiometric matrices S, whose rows and columns correspond to chemical species and chemical reactions. An important step toward evaluating drug targets and analyzing transient behavior of the network is called conservation analysis, which reduces to finding the rank of S and the nullspace of S^T . SVD is not practical, but with care, sparse QR or sparse LU factors can serve both purposes.

On some large authentic examples, the sparse QR package of Davis [1,2] has proved remarkably efficient (with Q stored in sparse product form). However, the QR factors are sometimes significantly less sparse than S.

As an alternative, we consider the threshold rook pivoting option in LUSOL [3, 4]. With suitable permutations, this finds factors S = LDU in which L and U have unit diagonals and bounded off-diagonals and are likely to be well-conditioned, so that D should reliably indicate $\mathrm{rank}(S)$.

We find that LUSOL's LDU factors of S can be significantly more sparse than QR, but also significantly more expensive to compute. We therefore study two alternatives. Starting with conventional threshold partial pivoting factors S = LU (with L well-conditioned),

- apply threshold rook pivoting to *U*,
- or apply threshold partial pivoting to U^T .

We evaluate the options using a new Matlab interface to LUSOL [5].

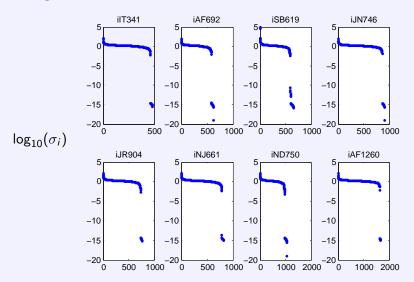
- T. A. Davis. SuiteSparseQR: multithreaded multifrontal sparse QR factorization, http://www.cise.ufl.edu/research/sparse/SPQR/
- [2] T. A. Davis. SuiteSparseQR: Algorithm 9xx: SuiteSparseQR, a multifrontal multithreaded sparse QR factorization package, submitted to ACM TOMS
- [3] P. E. Gill, W. Murray, M. A. Saunders. SNOPT: An SQP algorithm for large-scale constrained optimization, SIAM Rev 47(1), 99–131 (2005)
- [4] P. E. Gill, W. Murray, M. A. Saunders, M. H. Wright. Maintaining LU factors of a general sparse matrix, *Linear Alg Appl* 88/89, 239–270 (1987)
- [5] N. W. Henderson. Matlab interface to LUSOL, https://github.com/nwh/lusol

rank(S) by SVD

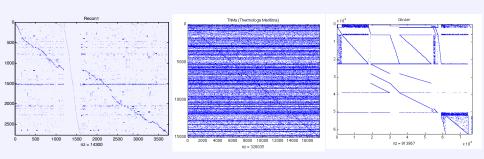
Singular value decomposition
$$S = UDV^T$$

- $U^TU = I$ $V^TV = I$ D diagonal rank(S) = rank(D)
- Ideal for rank-estimation but U, V are dense
- model 9 (Recon1) 2800×3700 17 secs model 10 (ThMa) 15000×18000 11 hours model 11 (GlcAer) 62000×77000 ∞

Singular values of models 1–8 Dense SVD of S^T



S for models 9, 10, 11



 2800×3700

15000 × 18000

 62000×77000

rank(S) by QR

Householder QR factorization
$$SP = QR$$

- $P = \text{col perm} \quad Q^T Q = I \quad R \text{ triangular}$ rank(S) = rank(R)
- Nearly as reliable as SVD
- Dense QR used by Vallabhajosyula, Chickarmane, Sauro (2005)
- Sparse QR (SPQR) now available: Davis (2013)
- model 9 (Recon1) 2800 × 3700 0.1 secs
 model 10 (ThMa) 15000 × 18000 2.5 secs
 model 11 (GlcAer) 62000 × 77000 0.2 secs(!)

rank(S) by LUSOL with Threshold Rook Pivoting

Sparse LU with TRP
$$P_1SP_2 = LDU$$

- $P_1, P_2 = \text{perms}$ D diagonal $\text{rank}(S) \approx \text{rank}(D)$ L, U well-conditioned
- $L_{ii} = U_{ii} = 1$ $|L_{ij}|$ and $|U_{ij}| \le \texttt{factol} = 4$ (or 2 or 1.2, 1.1, ...)
- LUSOL: Main engine in sparse linear/nonlinear optimizers MINOS, SQOPT, SNOPT
- model 9 (Recon1) 2800 × 3700 0.1 secs model 10 (ThMa) 15000 × 18000 4.0 secs model 11 (GlcAer) 62000 × 77000 158 secs

rank(S) by LUSOL with Threshold Partial Pivoting

Sparse LU with TPP
$$P_1SP_2 = LU$$

- $P_1, P_2 = \text{perms}$ U trapezoidal $\text{rank}(S) \approx \text{rank}(U)$ L well-conditioned
- $ullet L_{ii}=1 \ |L_{ij}| \leq extstyle extstyle extstyle extstyle |L_{ij}| = 1.2, 1.1, \ldots$
- LUSOL: Main engine in sparse linear/nonlinear optimizers MINOS, SQOPT, SNOPT
- model 9 (Recon1) 2800 × 3700 0.1 secs model 10 (ThMa) 15000 × 18000 0.2 secs model 11 (GlcAer) 62000 × 77000 0.3 secs

SPQR vs LUSOL with Threshold Rook Pivoting

SPQR: $S = QR$							
	n rank(S) nnz(S)	•		ime (secs) PQR			
Recon1 2766 ThMa 15024	3742 2674 14300 17582 14983 326035 76664 62182 913967	2750 21093 844096 10595016	11hrs	2.5			
	LUSOL: $S = LDU$	$ L_{ij} , U_{ij} \leq 2.0$					
		nnz(L) nnz(U)	•	ime			
Recon1 ThMa		4280 16463 30962 346122	1				
GlcAer		635571 1810491	18	6.2			
	LUSOL: $S = LDU$	$ L_{ij} , U_{ij} \leq 4.0$					
		nnz(L) nnz(U)	l t	ime			
Recon1		2701 12896	•				
ThMa GlcAer		36350 330485 427456 1584188	•				

SPQR vs LUSOL with Threshold Rook Pivoting

SPQR: $S^T = QR$							
	n rank(S') nnz(S)	-			(secs)		
Recon1 3742 ThMa 17582	2766 2674 14300 15024 14983 326035 62212 62182 913967	107935 624640	36929 605888	11hrs 0.7			
	LUSOL: $S^T = LDU$	$ L_{ij} ,$	$ U_{ij} \leq 2.0$				
		nnz(L)		time			
Recon1		12832	7421	0.3			
ThMa GlcAer				37.8 586.0			
	LUSOL: $S^T = LDU$	$ L_{ij} ,$	$ U_{ij} \leq 4.0$				
		nnz(L)	nnz(U)	time			
Recon1		9811	6093	0.2			
ThMa GlcAer				14.8 791.2			
GICKET		1023007	111900	191.2			

SPQR vs LUSOL with Threshold Partial Pivoting

SPQR:	S = QR		
	•		time (secs
3742 2674 14300 17582 14983 326035	2750 21093 844096 10595016	11hrs	2.5
LUSOL: $S = LU$	$ L_{ij} , U_{ij} \leq 2.0$		
	721 13585	1	0.1
LUSOL: $S = LU$	$ L_{ij} , U_{ij} \leq 4.0$		
	nnz(L) nnz(U)	1	time
	764 13577	 	0.1
	7782 323929	1	0.2
	533 913781	1	0.4
	n rank(S) nnz(S) 3742	$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	n rank(S) nnz(S) nnz(Q) nnz(R) SVD $ \begin{array}{c ccccccccccccccccccccccccccccccccccc$

SPQR vs LUSOL with Threshold Partial Pivoting

SPQR: $S^T = QR$							
model m	n rank(S') nnz(S)	nnz(Q)	nnz(R)	SVD	time (secs)		
ThMa 17582	2766 2674 14300 15024 14983 326035 62212 62182 913967	624640	605888	11hrs	0.7		
	LUSOL: $S^T = I$	LU L _{ij}	$ \leq 2.0$				
		nnz(L)	nnz(U)	1	time		
Recon1		9304	7813		0.2		
ThMa		81506	268938	1	2.7		
GlcAer		337433	703619	1	126.7		
	LUSOL: $S^T = I$	LU L _{ij}	$ \leq 4.0$				
		nnz(L)	nnz(U)	1	time		
Recon1		9030	6259		0.1		
ThMa		77274	268424	1	2.0		
GlcAer			701139				

Rank of Rectangular Sparse A

Matrix color code:	well-conditioned	ill-conditioned
SVD	$A = UDV^T$	too dense
QR with col perms QR + QR on R^T	A = QR $A = QR = QLP$	SuiteSparseQR insurance
partial pivoting? beware	$A = \begin{pmatrix} \delta & \times & \times & \times \\ & \delta & \times & \times \\ & & \delta & \times \\ & & & \delta \end{pmatrix} =$	LU
rook pivoting	$A = L^{\mathbf{D}}U$	LUSOL
partial pivoting pp + rp on U pp + pp on U T	$A = LU$ $A = LU = L\overline{L}\overline{D}\overline{U}$ $A = LU = L\overline{U}^{T}\overline{L}^{T}$	often ok safer safer + cheaper

LUSOL with TPP then TRP on U

•	766 3742 024 17582			21093 10595016	SVD SPQR 17.5 0.1 11hrs 2.5 infty 0.2
Scaled	S = LU	$ L_{ij} \leq 2.0$	then $U=ar{l}$	$\bar{L}\bar{D}\bar{U}$ $ \bar{L}$	$ \bar{U}_{ij} , \bar{U}_{ij} \leq 2.0$
Recon1 ThMa			nnz(L) 712 89 4043	nnz(U) 13598 13550 327461	time 0.0 0.0 1.2
 GlcAer			36298 534	355276 913883	6.8
			404044	1414563	152.5
		The same	for scaled S^7	Г	
Recon1			9797	4612	0.1
1			53	4562	0.0
ThMa			130976	218256	1.8
			218144	67419	1 2.2
GlcAer			820879	307625	39.8
			121717	342990	25.6

LUSOL with TPP then TPP on U^T

model Recon1 ThMa GlcAer	m 2766 15024 62212	3742 17582	ank(S) 2674 14983 62182	i I	nnz(S) 14300 326035 913967	2 [*] 8440	750	nnz(R) 21093 10595016 916600	 	SVD 17.5 11hrs infty	SPQR 0.1 2.5 0.2
	Scaled	S = LU	L _{ij}	<	≤ 2.0	then	U ^T	$= \bar{L}\bar{U}$	ΙĪ	$ z_{ij} \leq 2.$	0
						nnz	(L)	nnz(U)	Ī		time
Recon1						7:	12	13598	1		0.0
						978	39	3885	1		0.0
ThMa						404	43	327461	1		1.2
						1326	58	218914	1		1.8
GlcAer						5	34	913883	Ι		2.6
	Ì					8098	60	341586	ĺ		41.8
			The	e s	ame fo	scale	d <i>S</i> 7	г			
Recon1						979	97	4612	ı		0.1
						68	36	3908	1		0.0
ThMa						1309	76	218256	1		1.8
						157	46	213081	1		0.6
GlcAer						8208	79	307625	1		39.7
						163	30	306306	İ		1.0

Conclusions

Sparse rank-revealing factorizations:

- SuiteSparseQR on A or A^T often best
- LUSOL usually more sparse Important if used as null space operator
- Threshold rook pivoting reliable (LU version of SVD) but can be slow
- Threshold partial pivoting reliable for stoichiometric S or S^T
- General A might needs safeguards:
 - $A = LU = L\bar{L}\bar{D}\bar{U}$
 - $A = LU = L\overline{U}^T\overline{L}^T$