

## Solution — Knights

### 1 The problem in a nutshell

Finding the maximum number of edge disjoint paths with specified starting vertices and ending edges in an undirected graph where vertex capacities are bounded.

### 2 Modelling

We are given an undirected graph with grid structure, whose vertices and edges represent hallway segments and intersections correspondingly. There can be either 0 or 1 knight at each vertex. The knights can move in a way such that each edge is traversed by at most 1 knight and each vertex is traversed by at most  $C$  knights. The goal is to maximize the number of knights reaching to the outside, which can be modelled as a vertex incident to all ending segments of the hallways.

Since we are looking for edge disjoint paths, flow is a natural candidate approach. However, we can only apply the maximum flow algorithm on a directed graph with a source and without vertex capacities. So we need to model the following:

**The Source** Create a special vertex that connects to each knight's starting vertex via a directed edge of capacity 1.

**Undirected Edges** For an undirected edge  $\{u, v\}$ , the standard approach is to model it by 2 directed edges  $\{u, v\}$  and  $\{v, u\}$ . However, this seems to be problematic as now two knights can traverse the same edge in different directions. So we need to make the following observation: if two knights traverse edge  $\{u, v\}$  in opposite directions and they both make it to the outside, they can also succeed by not traversing  $\{u, v\}$  without passing through any additional edges or vertices. To see this, assume the escaping paths for the knights are  $s_0, \dots, u_0, u, v, v_0, \dots, t$  and  $s_1, \dots, v_1, v, u, u_1, \dots, t$ , where  $t$  is the vertex modelling the outside, while  $s_0$  and  $s_1$  are the starting vertices for the knights. Clearly,  $s_0, \dots, u_0, u, u_1, \dots, t$  and  $s_1, \dots, v_1, v, v_0, \dots, t$  are also valid escaping paths.

**Vertex Capacity** For a vertex  $v$  with capacity  $c$ , we split it into two vertices  $v_{in}$  (receiving all incoming edges to  $v$ ) and  $v_{out}$  (sending all outgoing edges from  $v$ ), and add a directed edge  $\{v_{in}, v_{out}\}$  with capacity  $c$ .

### 3 Algorithm Design

Before we start to implement our solution, let us estimate whether it is fast enough. From the problem description and modelling we learn that our graph has  $V = 2 * nm + 2 = 5002$  vertices. Each  $v_{in}$  is incident to at most 6 edges, i.e. an incoming one from the source, 4 incoming ones from the neighbours, and an outgoing one to  $v_{out}$ . Each  $v_{out}$  is incident to at most 4 outgoing edges to the neighbours or the outside. Altogether the number of edges  $E$  is bounded by  $10nm = 25000$ . For the two algorithms introduced in the tutorial, `push_relabel_max_flow` have

a complexity of  $O(V^3)$ , while `edmonds_karp_max_flow` runs in  $O(VE^2)$  or  $O(VEU)$  when the edge capacities are integers bounded by some constant  $U$ . In our case, we have  $U = 1$  and  $VEU \approx 10^8$ , which is just below the time limit. However, note that although `push_relabel_max_flow` has a worse worst-case time complexity here, it outperforms `edmonds_karp_max_flow` for all testsets we have. Try it out!

Now we can focus on the subtask specifications.

**First subtask:  $C = 2$**  It might seem weird that the first subtask asks for  $C = 2$  instead of  $C = 1$ . However, since each edge can be traversed by at most 1 knight and each vertex is incident to 4 edges, there can not be more than 2 knights passing through the same vertex. So if the capacity of edges is set to 1, the vertices obtain a capacity limit of 2 automatically. As a result, one does not need to do the splitting trick to set the vertex capacity for this subtask.

**Second subtask:  $C = 1$**  In addition to the solution for the first subtask, we now need to put a limit of 1 on the capacity of vertices, otherwise there might be more knights managing to escape successfully.

**Third subtask:  $C \leq 4$**  Well, since the vertex capacity can be at most 2, we do not have any new test cases to deal with.

## 4 Full Solution

The implementation is basically constructing the graph and applying maximum flow. Since each vertex is described by 2 coordinates, it will be convenient to have a function that maps the coordinates to integers.

```
1 #include <iostream>
2 #include <boost/graph/adjacency_list.hpp>
3 #include <boost/graph/push_relabel_max_flow.hpp>
4 #include <boost/graph/edmonds_karp_max_flow.hpp>
5
6 // Graph Type with nested interior edge properties for flow algorithms
7 typedef boost::adjacency_list_traits<boost::vecS, boost::vecS, boost::directedS> traits;
8 typedef boost::adjacency_list<boost::vecS, boost::vecS, boost::directedS, boost::no_property,
9     boost::property<boost::edge_capacity_t, long,
10     boost::property<boost::edge_residual_capacity_t, long,
11     boost::property<boost::edge_reverse_t, traits::edge_descriptor>>>> graph;
12
13 typedef traits::vertex_descriptor vertex_desc;
14 typedef traits::edge_descriptor edge_desc;
15
16 // Custom edge adder class, highly recommended
17 class edge_adder {
18     graph &G;
19
20 public:
21     explicit edge_adder(graph &G) : G(G) {}
22 }
```

```

23 void add_edge(int from, int to, long capacity) {
24     auto c_map = boost::get(boost::edge_capacity, G);
25     auto r_map = boost::get(boost::edge_reverse, G);
26     const auto e = boost::add_edge(from, to, G).first;
27     const auto rev_e = boost::add_edge(to, from, G).first;
28     c_map[e] = capacity;
29     c_map[rev_e] = 0; // reverse edge has no capacity!
30     r_map[e] = rev_e;
31     r_map[rev_e] = e;
32 }
33 };
34
35 // mapping coordinates of a vertex to its index in G
36 int index(int x, int y, int m, int n, bool in) {
37     return y + n*x + in*m*n;
38 }
39
40 void solve() {
41     int m, n, k, c;
42     std::cin >> m >> n >> k >> c;
43
44     graph G(2*m*n);
45     edge_adder adder(G);
46     // Add special vertices source and sink
47     const vertex_desc source = boost::add_vertex(G);
48     const vertex_desc sink = boost::add_vertex(G);
49
50     // Configure outgoing edges from the source
51     for(int i=0; i<k; ++i){
52         int x, y;
53         std::cin >> x >> y;
54         adder.add_edge(source, index(x,y,m,n,true), 1);
55     }
56
57     int dx[4] = {0, 1, 0, -1};
58     int dy[4] = {1, 0, -1, 0};
59     for(int x=0; x<m; ++x){
60         for(int y=0; y<n; ++y){
61             // Configure the capacity for vertex (x, y)
62             adder.add_edge(index(x,y,m,n,true), index(x,y,m,n,false), c);
63             for(int i=0; i<4; ++i){
64                 int newx = x + dx[i];
65                 int newy = y + dy[i];
66                 if(newx>=0 && newx<m && newy>=0 && newy<n)
67                     // Configure the segments (excluding ending segments)
68                     adder.add_edge(index(x,y,m,n,false), index(newx,newy,m,n,true), 1);
69             }
70             // Configure the ending segments
71             if(x==0 || x==m-1)
72                 adder.add_edge(index(x,y,m,n,false), sink, 1);
73             if(y==0 || y==n-1)
74                 adder.add_edge(index(x,y,m,n,false), sink, 1);
75         }
76     }
77
78     //long flow = boost::push_relabel_max_flow(G, source, sink);
79     long flow = boost::edmonds_karp_max_flow(G, source, sink);
80     std::cout << flow << std::endl;
81 }

```

```
82
83 int main() {
84     int t;
85     std::cin >> t;
86     while(t --)
87         solve();
88     return 0;
89 }
```