

대한기계학회 인공지능머신연구회  
2021년 인공지능 여름학교

# 강의 소개 - 딥러닝 중급

2021.8.17

**Namwoo Kang**

Smart Design Lab

CCS Graduate School of Green Transportation

KAIST



# 강사소개: Namwoo Kang (강남우)

## ■ Education

- 2014 Ph.D. Design Science (Mechanical Engineering & Marketing), University of Michigan
- 2007 M.S. Technology and Management, Seoul National University
- 2005 B.S. Mechanical and Aerospace Engineering, Seoul National University

## ■ Academic Work & Industrial Experiences

- 2021 ~ Present, Assistant Professor, CCS Graduate School of Green Transportation, KAIST
- 2018 ~ 2021, Assistant Professor, Mechanical Systems Engineering, Sookmyung Women's University
- 2016 ~ 2018, Assistant Professor, K-School, KAIST
- 2014 ~ 2016, Research Fellow & Adjunct Lecturer, Mechanical Engineering, University of Michigan
- 2007 ~ 2010, Research Engineer, Hyundai Motor Company

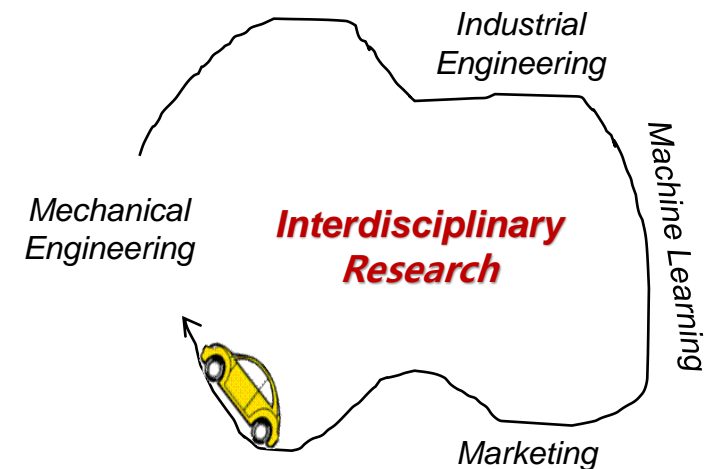


## ■ Professional Service

- Associate Editor - Journal of Mechanical Science and Technology (JMST)
- CAE 및 응용역학부문 총무이사 - Korean Society of Mechanical Engineers (KSME)
- 인공지능머신연구회 이사 - Korean Society of Mechanical Engineers (KSME)
- 인공지능소사이어티 이사 - Korean Institute of Information Scientists and Engineers (KIISE)
- 재무이사 - Korean Society for Prognostics and Health Management (KSPHM)
- IT융합부문 사업이사 - Korean Society of Mechanical Engineers (KSME)

## ■ Awards

- Young Scientist Award, ACSMO (Asian Congress of Structural and Multidisciplinary Optimization), 2020
- 미래기술상, 한국전산구조공학회, 2019
- Dow Distinguished Award, Dow Sustainability Fellows, University of Michigan, 2014



# 강사소개: AI-based Mobility Design



*Product*

*Service*

## AI-based Mobility Design (Physics + Data)

### Mobility Product Design (Virtual Product Development)

### Mobility Service Design (Digital Twin for Shared Mobility)



Real World (Data)



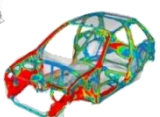
Decisions  
Prediction



Data  
Feedback



Style



Body



Chassis



Powertrain

System Simulation, Prediction, and Optimization

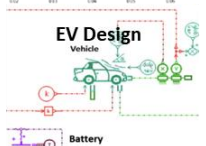
Max {Sustainability, Profit}

Autonomous Fleet Assignment  
(Deep Learning)

Charging Station  
(Network Model)

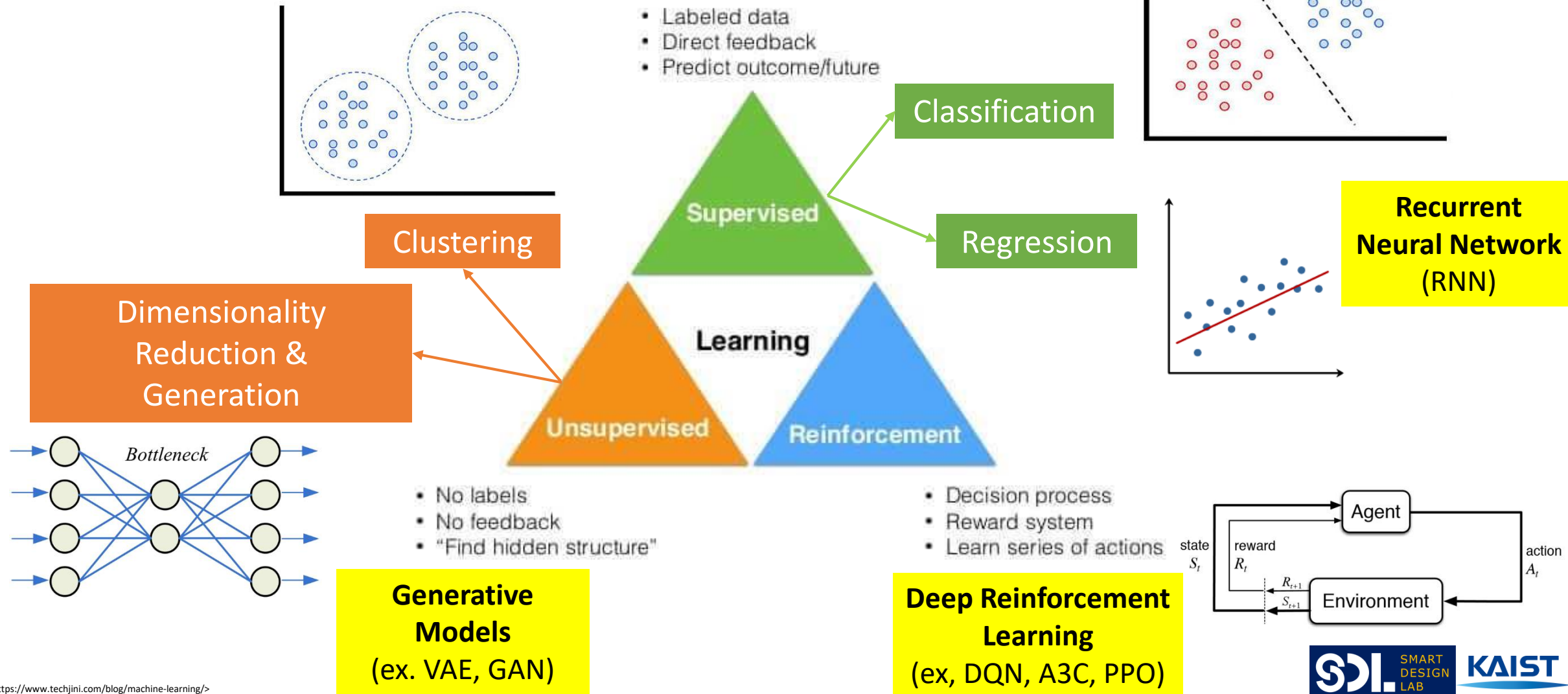
Demand Forecasting  
(Deep Learning)


EV Design  
(Engineering Simulation)



# Contents

## ❖ Types of Learning



- **Ch1: Introduction to Unsupervised Learning Part I** → Probability & Maximum Likelihood
  - **Ch2: Introduction to Unsupervised Learning Part II** → Generative Model & Dimensionality Reduction
  - **Ch3: Principal Component Analysis (PCA)** → Machine Learning Model
  - **Ch4: Autoencoder & Anomaly Detection**  
+ 실습
  - **Ch5: Variational AutoEncoder (VAE)**  
+ 실습
  - **Ch6: Generative Adversarial Network (GAN)**  
+ 실습
  - **Ch7: Application: Mechanical Design + AI** → CAD/CAM/CAE/Design Optimization + AI
- 

## □ 강의 슬라이드 및 실습코드는 아래의 링크에서 받으실 수 있습니다

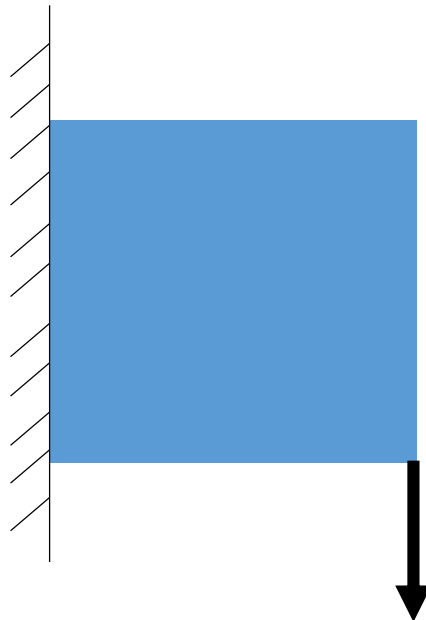
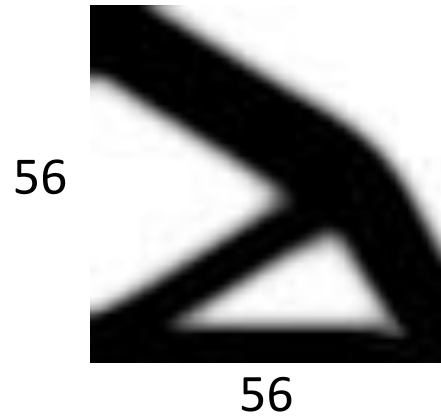
- [http://www.smartdesignlab.org/dl\\_aischool\\_2021.html](http://www.smartdesignlab.org/dl_aischool_2021.html)
- Contributors: 김성신, 유소영, 이성희, 김은지

## □ 강의 소스

- Andrew Ng의 ML Class ([www.holehouse.org/mlclass/](http://www.holehouse.org/mlclass/))
- Fei-Fei Li & Justin Johnson & Serena Yeung, CS231n: Convolutional Neural Networks for Visual Recognition, Stanford (<http://cs231n.stanford.edu/>)
- Stefano Ermon & Aditya Grover, CS 236: Deep Generative Models , Stanford (<https://deepgenerativemodels.github.io/>)
- 모두를 위한 딥러닝 (<https://hunkim.github.io/ml/>)
- 모두를 위한 딥러닝 시즌 2 ([https://deeplearningzerotoall.github.io/season2/lec\\_tensorflow.html](https://deeplearningzerotoall.github.io/season2/lec_tensorflow.html))
- 이활석, Autoencoders (<https://www.slideshare.net/NaverEngineering/ss-96581209>)
- 최윤제, 1시간만에 GAN(Generative Adversarial Network) 완전 정복하기 ([https://www.slideshare.net/NaverEngineering/1-gangenerative-adversarial-network?qid=c53ce33f-6643-4437-8e93-88776c9cebb1&v=&b=&from\\_search=5](https://www.slideshare.net/NaverEngineering/1-gangenerative-adversarial-network?qid=c53ce33f-6643-4437-8e93-88776c9cebb1&v=&b=&from_search=5))
- 김성범, [핵심 머신러닝] Principal Component Analysis (PCA, 주성분 분석) (<https://youtu.be/FhQm2Tc8Kic>)

# 실습 - Structural Design Data

Input: design

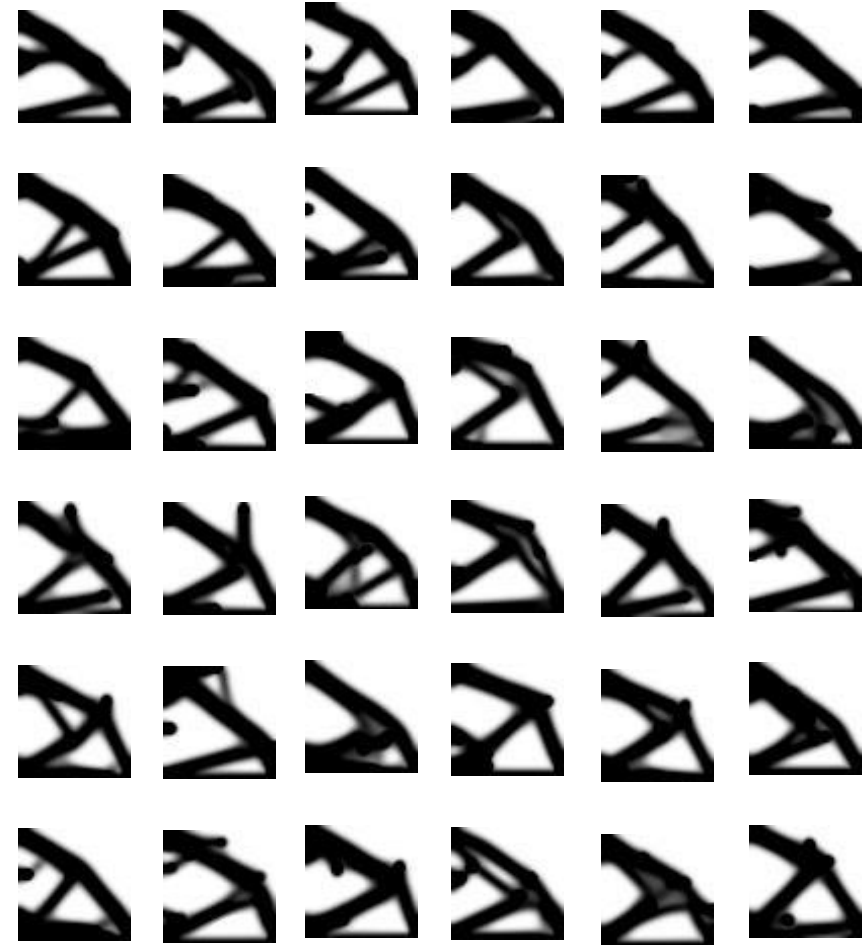


Output: compliance

$$c(\mathbf{x}) = \mathbf{U}^T \mathbf{K} \mathbf{U}$$

where  $\mathbf{K} \mathbf{U} = \mathbf{F}$

data\_3000 / data\_5000



# What Questions Do You Have?

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[www.smartdesignlab.org](http://www.smartdesignlab.org)