

인공지능 기반 설계 이론 및 사례 연구  
9차/10차) Variational AutoEncoder (VAE)

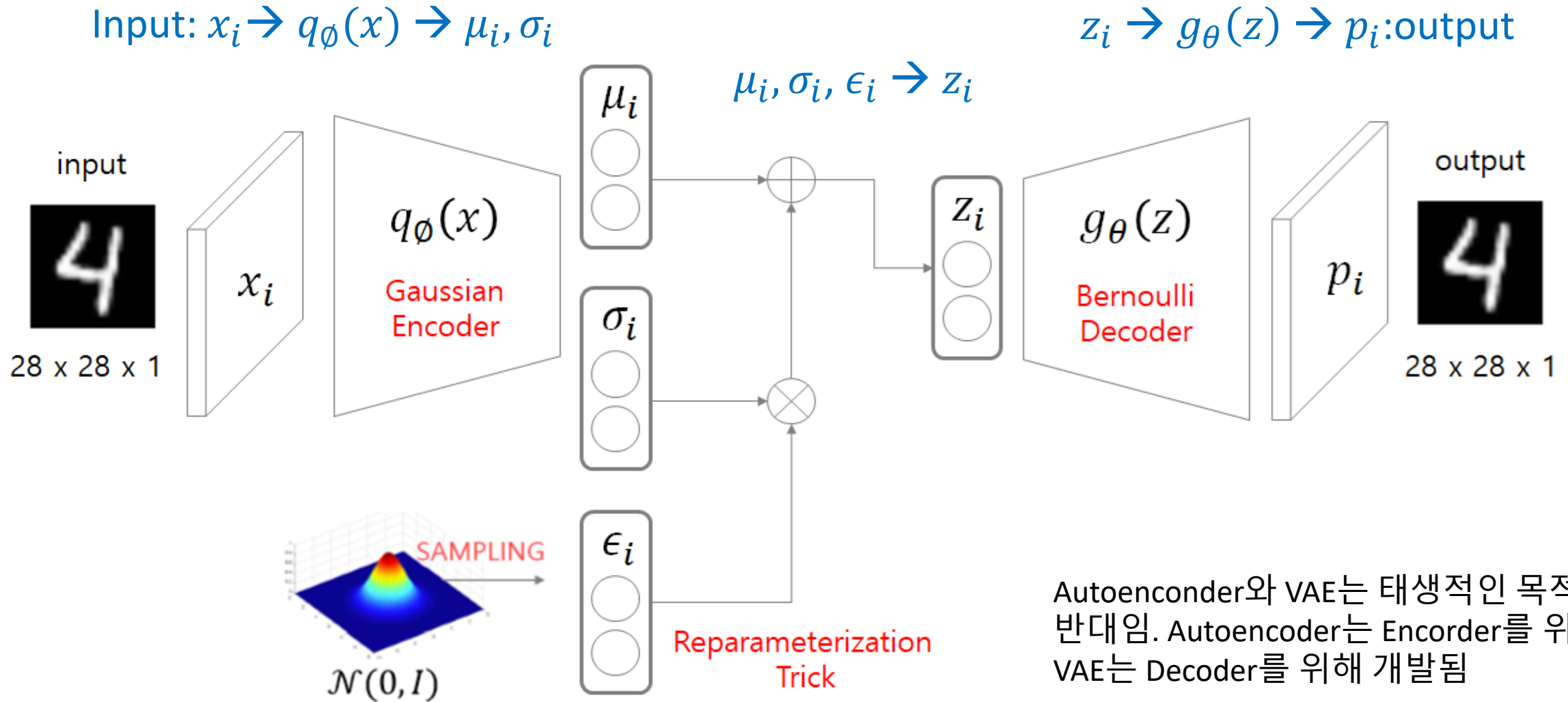
2020년 10월

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# Variational Autoencoders (VAE) – How to work

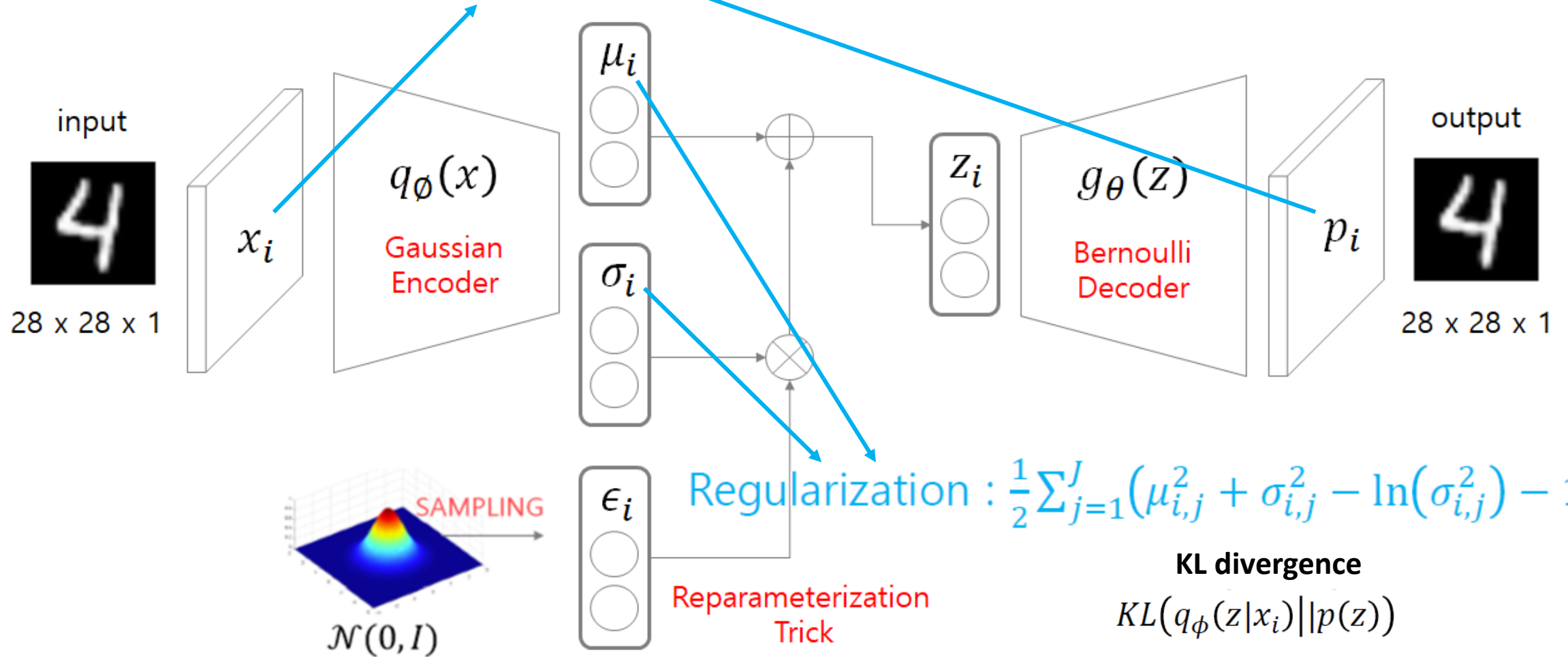


# VAE – How to work

$$-\mathbb{E}_{q_{\phi}(z|x_i)}[\log(p(x_i|g_{\theta}(z)))]$$

Cross entropy

$$\text{Reconstruction Error: } -\sum_{j=1}^D x_{i,j} \log p_{i,j} + (1 - x_{i,j}) \log(1 - p_{i,j})$$



# VAE - Loss Function

Probabilistic spin on autoencoders - will let us sample from the model to generate data!

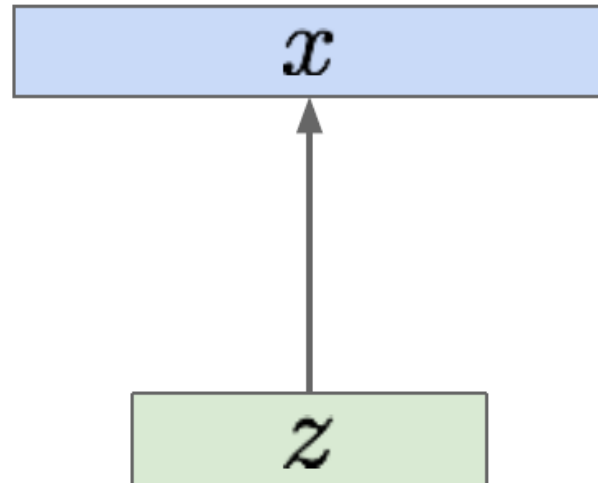
Assume training data  $\{x^{(i)}\}_{i=1}^N$  is generated from underlying unobserved (latent) representation  $\mathbf{z}$

Sample from  
true conditional

$$p_{\theta^*}(x \mid z^{(i)})$$

Sample from  
true prior

$$p_{\theta^*}(z)$$



**Intuition** (remember from autoencoders!):  
 $\mathbf{x}$  is an image,  $\mathbf{z}$  is latent factors used to  
generate  $\mathbf{x}$ : attributes, orientation, etc.

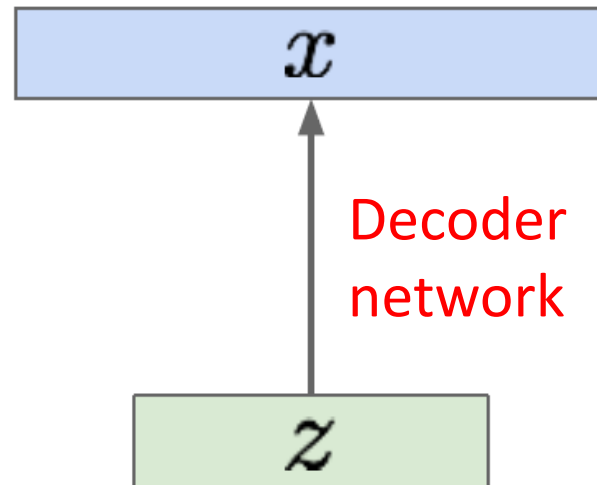
# VAE - Loss Function

We want to estimate the true parameters  $\theta^*$  of this generative model.

How should we represent this model?

Sample from  
true conditional  
 $p_{\theta^*}(x | z^{(i)})$

Sample from  
true prior  
 $p_{\theta^*}(z)$



Choose prior  $p(z)$  to be simple, e.g. Gaussian. Reasonable for latent attributes, e.g. pose, how much smile.

Conditional  $p(x|z)$  is complex (generates image) => represent with neural network

# VAE - Loss Function

We want to estimate the true parameters  $\theta^*$  of this generative model.

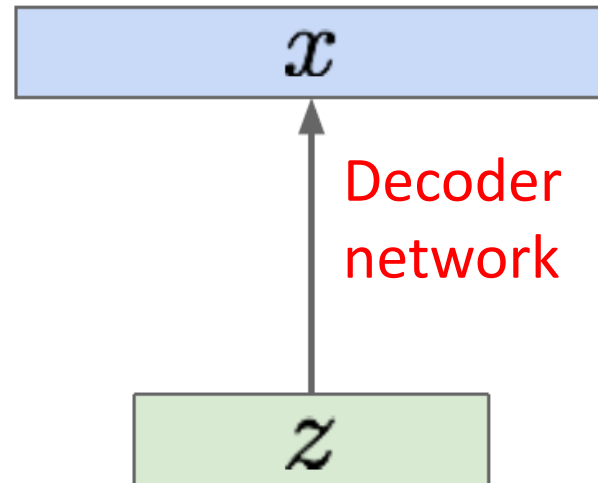
How to train the model?

Sample from  
true conditional

$$p_{\theta^*}(x | z^{(i)})$$

Sample from  
true prior

$$p_{\theta^*}(z)$$



Learn model parameters to maximize  
likelihood of training data

$$p_{\theta}(x) = \int p_{\theta}(z)p_{\theta}(x|z)dz$$

Q: What is the problem  
with this?

Intractable!

Now with latent  $z$

# VAE - Loss Function

Intractable to compute  
 $p(x|z)$  for every  $z$ !

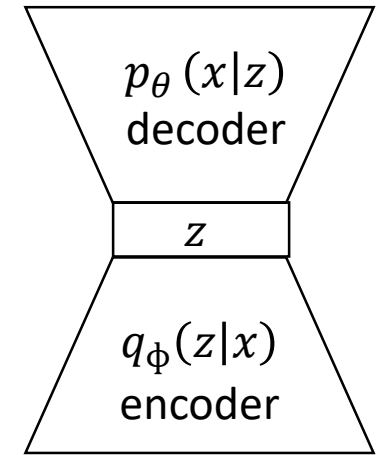
Data likelihood:  $p_{\theta}(x) = \int p_{\theta}(z)p_{\theta}(x|z)dz$

Simple Gaussian prior

Decoder neural network

Posterior density also intractable:  $p_{\theta}(z|x) = p_{\theta}(x|z)p_{\theta}(z)/p_{\theta}(x)$

Intractable data likelihood



Solution: In addition to decoder network modeling  $p_{\theta}(x|z)$ , define additional encoder network  $q_{\phi}(z|x)$  that approximates  $p_{\theta}(z|x)$

Will see that this allows us to derive a lower bound on the data likelihood that is tractable, which we can optimize

# VAE - Loss Function

Now equipped with our encoder and decoder networks, let's work out the (log) data likelihood:

$$\log p_{\theta}(x^{(i)}) = \mathbf{E}_{z \sim q_{\phi}(z|x^{(i)})} [\log p_{\theta}(x^{(i)})] \quad (p_{\theta}(x^{(i)}) \text{ Does not depend on } z)$$

(Bayes' Rule)  $p(z|x) = \frac{p(x|z)p(z)}{p(x)}$

$$= \mathbf{E}_z \left[ \log \frac{p_{\theta}(x^{(i)}|z)p_{\theta}(z)}{p_{\theta}(z|x^{(i)})} \right]$$

Taking expectation wrt.  $z$  (using encoder network) will come in handy later

$$= \mathbf{E}_z \left[ \log \frac{p_{\theta}(x^{(i)}|z)p_{\theta}(z)}{p_{\theta}(z|x^{(i)})} \frac{q_{\phi}(z|x^{(i)})}{q_{\phi}(z|x^{(i)})} \right] \quad (\text{Multiply by constant})$$

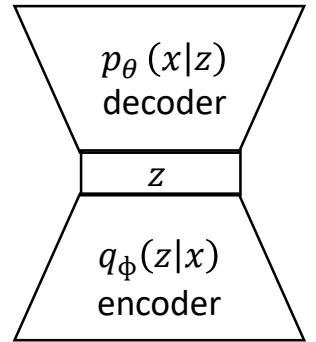
$$= \mathbf{E}_z [\log p_{\theta}(x^{(i)}|z)] - \mathbf{E}_z \left[ \log \frac{q_{\phi}(z|x^{(i)})}{p_{\theta}(z)} \right] + \mathbf{E}_z \left[ \log \frac{q_{\phi}(z|x^{(i)})}{p_{\theta}(z|x^{(i)})} \right] \quad (\text{Logarithms})$$

$$= \mathbf{E}_z [\log p_{\theta}(x^{(i)}|z)] - D_{KL} (q_{\phi}(z|x^{(i)}) || p_{\theta}(z)) + D_{KL} (q_{\phi}(z|x^{(i)}) || p_{\theta}(z|x^{(i)}))$$

참고:  $E_{z \sim q_{\phi}(z|x^{(i)})} \left[ \log \frac{q_{\phi}(z|x^{(i)})}{p_{\theta}(z)} \right] = \int_z \log \frac{q_{\phi}(z|x^{(i)})}{p_{\theta}(z)} q_{\phi}(z|x^{(i)}) dz$

$$KL(P||Q) = \sum_x P(x) \log \frac{P(x)}{Q(x)}$$

The expectation wrt.  $z$  (using encoder network) let us write nice KL terms





# VAE - Loss Function

Now equipped with our encoder and decoder networks, let's work out the (log) data likelihood:

$$\log p_{\theta}(x^{(i)}) = \mathbf{E}_{z \sim q_{\phi}(z|x^{(i)})} [\log p_{\theta}(x^{(i)})] \quad (p_{\theta}(x^{(i)}) \text{ Does not depend on } z)$$

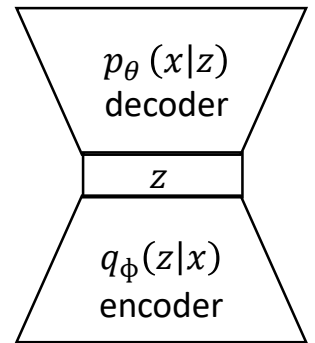
We want to maximize the data likelihood

$$= \mathbf{E}_z \left[ \log \frac{p_{\theta}(x^{(i)}|z)p_{\theta}(z)}{p_{\theta}(z|x^{(i)})} \right] \quad (\text{Bayes' Rule})$$

$$= \mathbf{E}_z \left[ \log \frac{p_{\theta}(x^{(i)}|z)p_{\theta}(z)}{p_{\theta}(z|x^{(i)})} \frac{q_{\phi}(z|x^{(i)})}{q_{\phi}(z|x^{(i)})} \right] \quad (\text{Multiply by constant})$$

$$= \mathbf{E}_z [\log p_{\theta}(x^{(i)}|z)] - \mathbf{E}_z \left[ \log \frac{q_{\phi}(z|x^{(i)})}{p_{\theta}(z)} \right] + \mathbf{E}_z \left[ \log \frac{q_{\phi}(z|x^{(i)})}{p_{\theta}(z|x^{(i)})} \right] \quad (\text{Logarithms})$$

$$= \mathbf{E}_z [\log p_{\theta}(x^{(i)}|z)] - D_{KL} (q_{\phi}(z|x^{(i)}) || p_{\theta}(z)) + D_{KL} (q_{\phi}(z|x^{(i)}) || p_{\theta}(z|x^{(i)}))$$



Decoder network gives  $p_{\theta}(x|z)$ , can compute estimate of this term through sampling. (Sampling differentiable through reparam. trick, see paper.)

This KL term (between Gaussians for encoder and  $z$  prior) has nice closed-form solution!

$p_{\theta}(z|x)$  intractable (saw earlier), can't compute this KL term :( But we know KL divergence always  $\geq 0$ .

# VAE - Loss Function

Now equipped with our encoder and decoder networks, let's work out the (log) data likelihood:

$$\log p_{\theta}(x^{(i)}) = \mathbf{E}_{z \sim q_{\phi}(z|x^{(i)})} [\log p_{\theta}(x^{(i)})] \quad (p_{\theta}(x^{(i)}) \text{ Does not depend on } z)$$

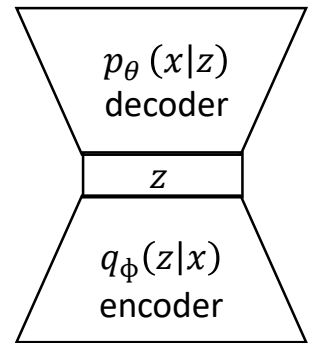
We want to maximize the data likelihood

$$= \mathbf{E}_z \left[ \log \frac{p_{\theta}(x^{(i)}|z)p_{\theta}(z)}{p_{\theta}(z|x^{(i)})} \right] \quad (\text{Bayes' Rule})$$

$$= \mathbf{E}_z \left[ \log \frac{p_{\theta}(x^{(i)}|z)p_{\theta}(z)}{p_{\theta}(z|x^{(i)})} \frac{q_{\phi}(z|x^{(i)})}{q_{\phi}(z|x^{(i)})} \right] \quad (\text{Multiply by constant})$$

$$= \mathbf{E}_z [\log p_{\theta}(x^{(i)}|z)] - \mathbf{E}_z \left[ \log \frac{q_{\phi}(z|x^{(i)})}{p_{\theta}(z)} \right] + \mathbf{E}_z \left[ \log \frac{q_{\phi}(z|x^{(i)})}{p_{\theta}(z|x^{(i)})} \right] \quad (\text{Logarithms})$$

$$= \underbrace{\mathbf{E}_z [\log p_{\theta}(x^{(i)}|z)] - D_{KL}(q_{\phi}(z|x^{(i)}) || p_{\theta}(z))}_{\mathcal{L}(x^{(i)}, \theta, \phi)} + \underbrace{D_{KL}(q_{\phi}(z|x^{(i)}) || p_{\theta}(z|x^{(i)}))}_{\geq 0}$$



**Tractable lower bound** which we can take gradient of and optimize! ( $p_{\theta}(x|z)$  differentiable, KL term differentiable)

# VAE - Loss Function

Now equipped with our encoder and decoder networks, let's work out the (log) data likelihood:

$$\log p_{\theta}(x^{(i)}) = \mathbf{E}_{z \sim q_{\phi}(z|x^{(i)})} [\log p_{\theta}(x^{(i)})] \quad (p_{\theta}(x^{(i)}) \text{ Does not depend on } z)$$

We want to maximize the data likelihood

$$= \mathbf{E}_z \left[ \log \frac{p_{\theta}(x^{(i)}|z)p_{\theta}(z)}{p_{\theta}(z|x^{(i)})} \right] \quad (\text{Bayes' Rule})$$

$$= \mathbf{E}_z \left[ \log \frac{p_{\theta}(x^{(i)}|z)p_{\theta}(z)}{p_{\theta}(z|x^{(i)})} \frac{q_{\phi}(z|x^{(i)})}{q_{\phi}(z|x^{(i)})} \right] \quad (\text{Multiply by constant})$$

$$= \mathbf{E}_z [\log p_{\theta}(x^{(i)}|z)] - \mathbf{E}_z \left[ \log \frac{q_{\phi}(z|x^{(i)})}{p_{\theta}(z)} \right] + \mathbf{E}_z \left[ \log \frac{q_{\phi}(z|x^{(i)})}{p_{\theta}(z|x^{(i)})} \right] \quad (\text{Logarithms})$$

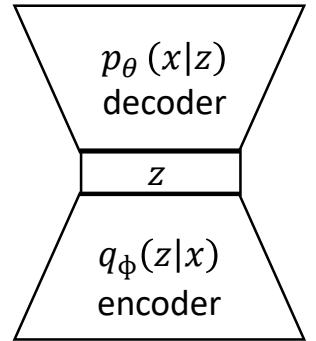
$$= \underbrace{\mathbf{E}_z [\log p_{\theta}(x^{(i)}|z)] - D_{KL}(q_{\phi}(z|x^{(i)}) || p_{\theta}(z))}_{\mathcal{L}(x^{(i)}, \theta, \phi)} + \underbrace{D_{KL}(q_{\phi}(z|x^{(i)}) || p_{\theta}(z|x^{(i)}))}_{\geq 0}$$

$$\log p_{\theta}(x^{(i)}) \geq \mathcal{L}(x^{(i)}, \theta, \phi)$$

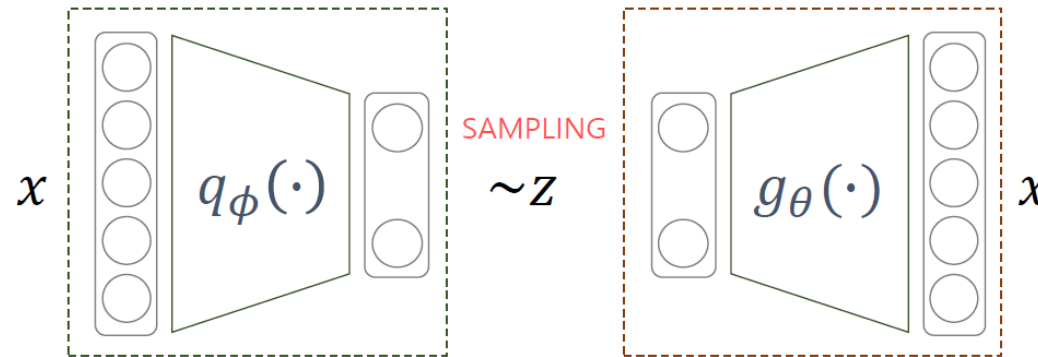
Variational lower bound ("ELBO")

$$\theta^*, \phi^* = \arg \max_{\theta, \phi} \sum_{i=1}^N \mathcal{L}(x^{(i)}, \theta, \phi)$$

Training: Maximize lower bound



# VAE - Loss Function



$$\arg \min_{\theta, \phi} \sum_i -\mathbb{E}_{q_{\phi}(z|x_i)} [\log(p(x_i|g_{\theta}(z)))] + KL(q_{\phi}(z|x_i)||p(z))$$

## Reconstruction Error

- 현재 샘플링용 함수에 대한 negative log likelihood
- $x_i$ 에 대한 복원 오차 (Autoencoder 관점)

## Regularization

- 현재 샘플링용 함수에 대한 추가 조건
- 샘플링의 용의성/생성 데이터에 대한 통제성을 위한 조건을 prior에 부여하고 이와 유사해야 한다는 조건을 부여

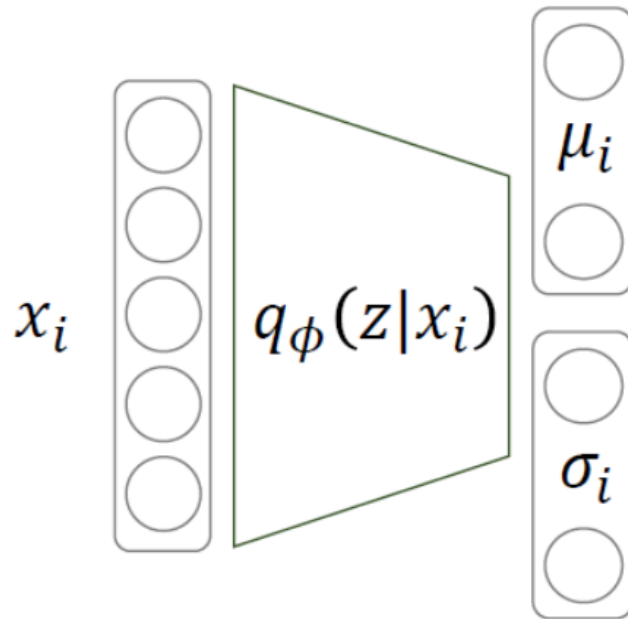
참고:  $p(x|g_{\theta}(z)) = p_{\theta}(x|z)$

# VAE - Optimization

## Assumptions

$$\arg \min_{\theta, \phi} \sum_i -\mathbb{E}_{q_{\phi}(z|x_i)} [\log(p(x_i|g_{\theta}(z)))] + \text{KL}(q_{\phi}(z|x_i)||p(z))$$

Regularization



## Assumption 1

[Encoder : approximation class]

multivariate gaussian distribution with a diagonal covariance

$$q_{\phi}(z|x_i) \sim N(\mu_i, \sigma_i^2 I)$$

## Assumption 2

[prior] multivariate normal distribution

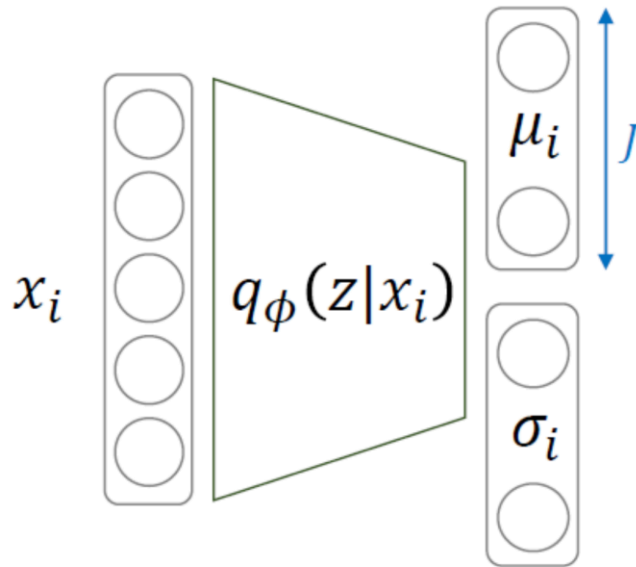
$$p(z) \sim N(0, I)$$

# VAE - Optimization

**KLD**

$$\arg \min_{\theta, \phi} \sum_i -\mathbb{E}_{q_{\phi}(z|x_i)} [\log(p(x_i|g_{\theta}(z)))] + \textcolor{red}{KL(q_{\phi}(z|x_i)||p(z))}$$

**Regularization**



$$\begin{aligned} KL(q_{\phi}(z|x_i)||p(z)) &= \frac{1}{2} \left\{ \text{tr}(\sigma_i^2 I) + \mu_i^T \mu_i - J + \ln \frac{1}{\prod_{j=1}^J \sigma_{i,j}^2} \right\} \\ &= \frac{1}{2} \left\{ \sum_{j=1}^J \sigma_{i,j}^2 + \sum_{j=1}^J \mu_{i,j}^2 - J - \sum_{j=1}^J \ln(\sigma_{i,j}^2) \right\} \\ &= \frac{1}{2} \sum_{j=1}^J (\mu_{i,j}^2 + \sigma_{i,j}^2 - \ln(\sigma_{i,j}^2) - 1) \end{aligned}$$

**KLD for multivariate normal distributions**

$$D_{\text{KL}}(\mathcal{N}_0 \parallel \mathcal{N}_1) = \frac{1}{2} \left( \text{tr}(\Sigma_1^{-1} \Sigma_0) + (\mu_1 - \mu_0)^T \Sigma_1^{-1} (\mu_1 - \mu_0) - k + \ln \left( \frac{\det \Sigma_1}{\det \Sigma_0} \right) \right)$$

# VAE - Optimization

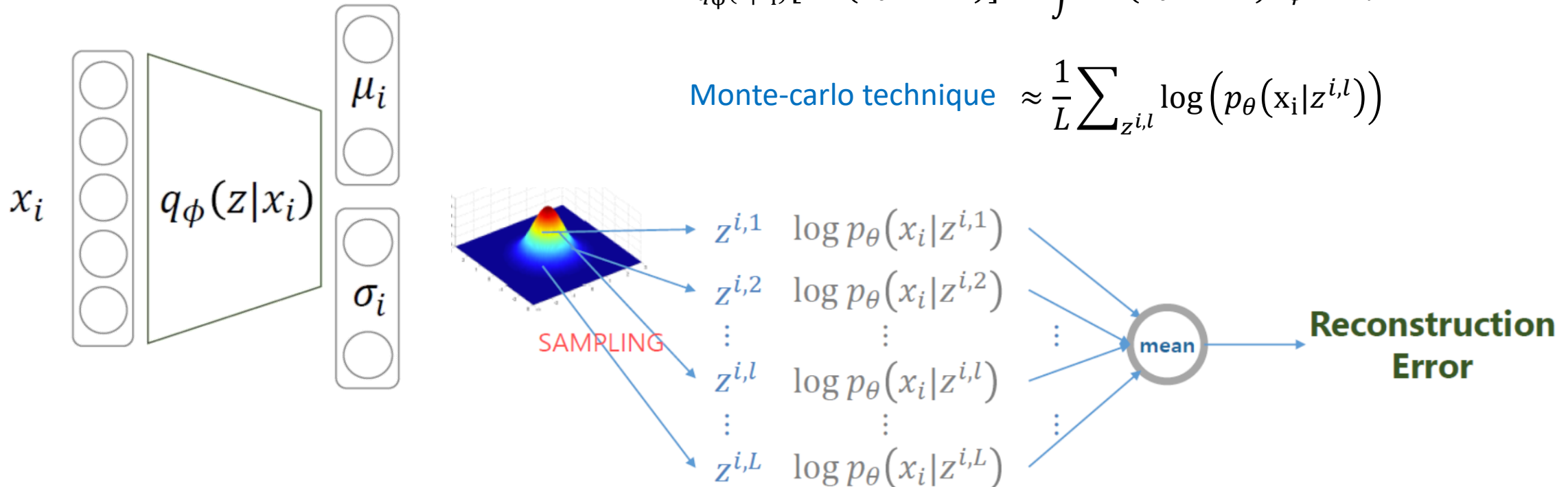
## Sampling

$$\arg \min_{\theta, \phi} \sum_i -\mathbb{E}_{q_{\phi}(z|x_i)} [\log(p(x_i|g_{\theta}(z)))] + KL(q_{\phi}(z|x_i)||p(z))$$

**Reconstruction Error**

$$\mathbb{E}_{q_{\phi}(z|x_i)} [\log(p_{\theta}(x_i|z))] = \int \log(p_{\theta}(x_i|z)) q_{\phi}(z|x_i) dz$$

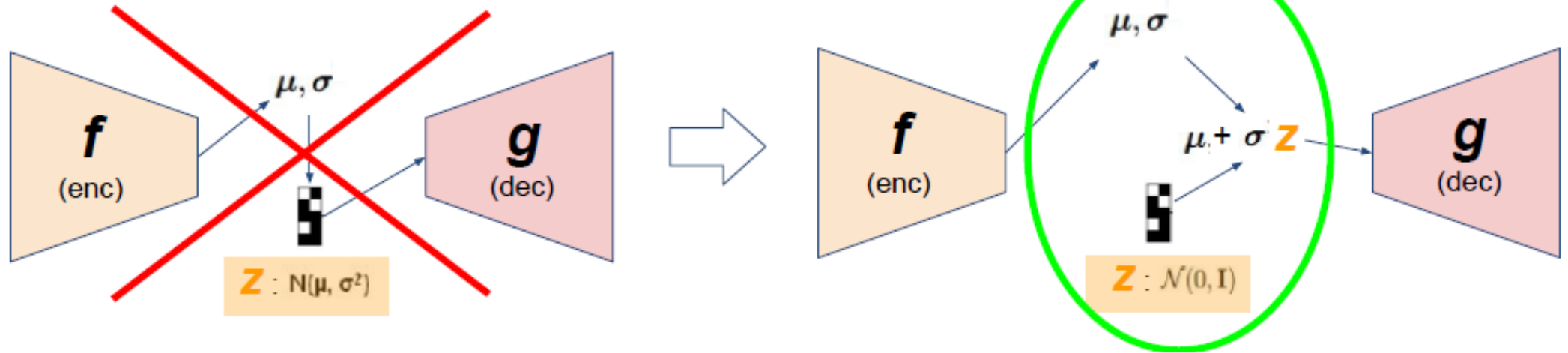
Monte-carlo technique  $\approx \frac{1}{L} \sum_{z^{i,l}} \log(p_{\theta}(x_i|z^{i,l}))$



- L is the number of samples for latent vector
- Usually L is set to 1 for convenience

# VAE - Optimization

## Reparameterization Trick



Sampling  
process

$$z^{i,l} \sim N(\mu_i, \sigma_i^2 I)$$



$$z^{i,l} = \mu_i + \sigma_i \odot \epsilon$$
$$\epsilon \sim N(0, I)$$

Same distribution!

But it makes backpropagation possible!



# VAE - Optimization

## Assumptions

$$\arg \min_{\theta, \phi} \sum_i -\mathbb{E}_{q_{\phi}(z|x_i)} [\log(p(x_i|g_{\theta}(z)))] + KL(q_{\phi}(z|x_i)||p(z))$$

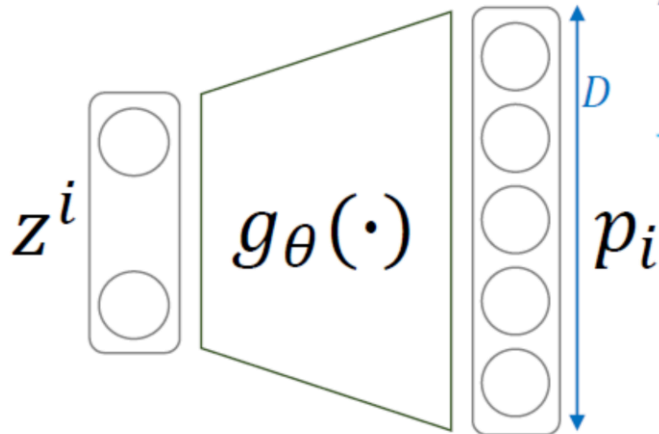
**Reconstruction Error**

$$\mathbb{E}_{q_{\phi}(z|x_i)} [\log(p_{\theta}(x_i|z))] = \int \log(p_{\theta}(x_i|z)) q_{\phi}(z|x_i) dz \approx \frac{1}{L} \sum_{z^{i,l}} \log(p_{\theta}(x_i|z^{i,l})) \approx \log(p_{\theta}(x_i|z^i))$$

Monte-carlo technique L=1

## Assumption 3-1

[Decoder, likelihood]  
multivariate bernoulli or gaussian distribution



$$p_{\theta}(x_i|z^i) \sim \text{Bernoulli}(p_i)$$

$$\begin{aligned} \log(p_{\theta}(x_i|z^i)) &= \log \prod_{j=1}^D p_{\theta}(x_{i,j}|z^i) = \sum_{j=1}^D \log p_{\theta}(x_{i,j}|z^i) \\ &= \sum_{j=1}^D \log p_{i,j}^{x_{i,j}} (1 - p_{i,j})^{1-x_{i,j}} \quad \leftarrow p_{i,j}: \text{network output} \\ &= \sum_{j=1}^D x_{i,j} \log p_{i,j} + (1 - x_{i,j}) \log(1 - p_{i,j}) \end{aligned}$$

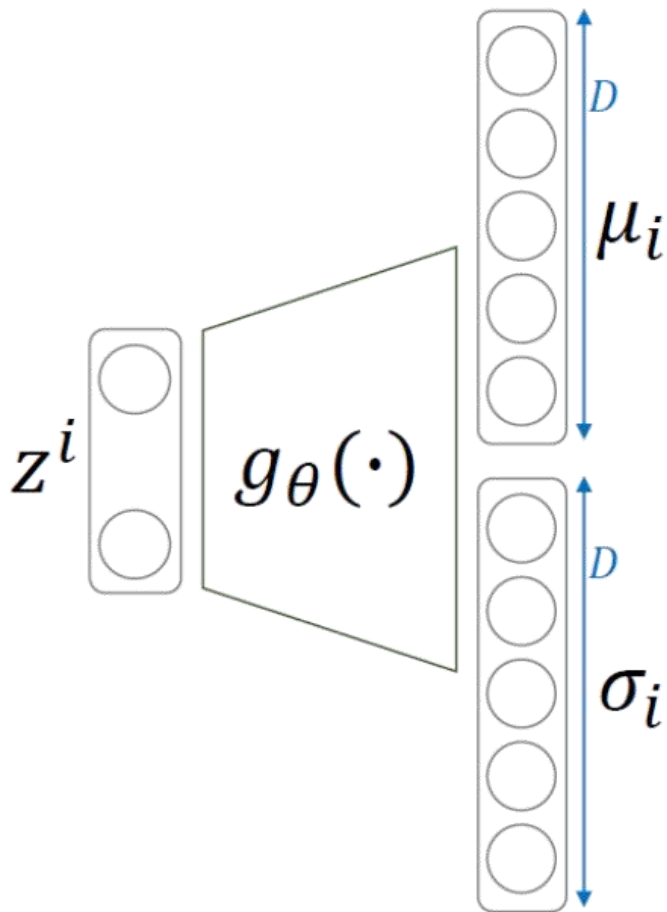
**Cross entropy**

# VAE - Optimization

## Assumptions

$$\arg \min_{\theta, \phi} \sum_i -\mathbb{E}_{q_{\phi}(z|x_i)} [\log(p(x_i|g_{\theta}(z)))] + KL(q_{\phi}(z|x_i)||p(z))$$

**Reconstruction Error**



$$\mathbb{E}_{q_{\phi}(z|x_i)} [\log(p_{\theta}(x_i|z))] \approx \log(p_{\theta}(x_i|z^i))$$

## Assumption 3-2

[Decoder, likelihood]

multivariate bernoulli or gaussian distribution

$$\log(p_{\theta}(x_i|z^i)) = \log(N(x_i; \mu_i, \sigma_i^2 I))$$

$$= -\sum_{j=1}^D \frac{1}{2} \log(\sigma_{i,j}^2) + \frac{(x_{i,j} - \mu_{i,j})^2}{2\sigma_{i,j}^2}$$

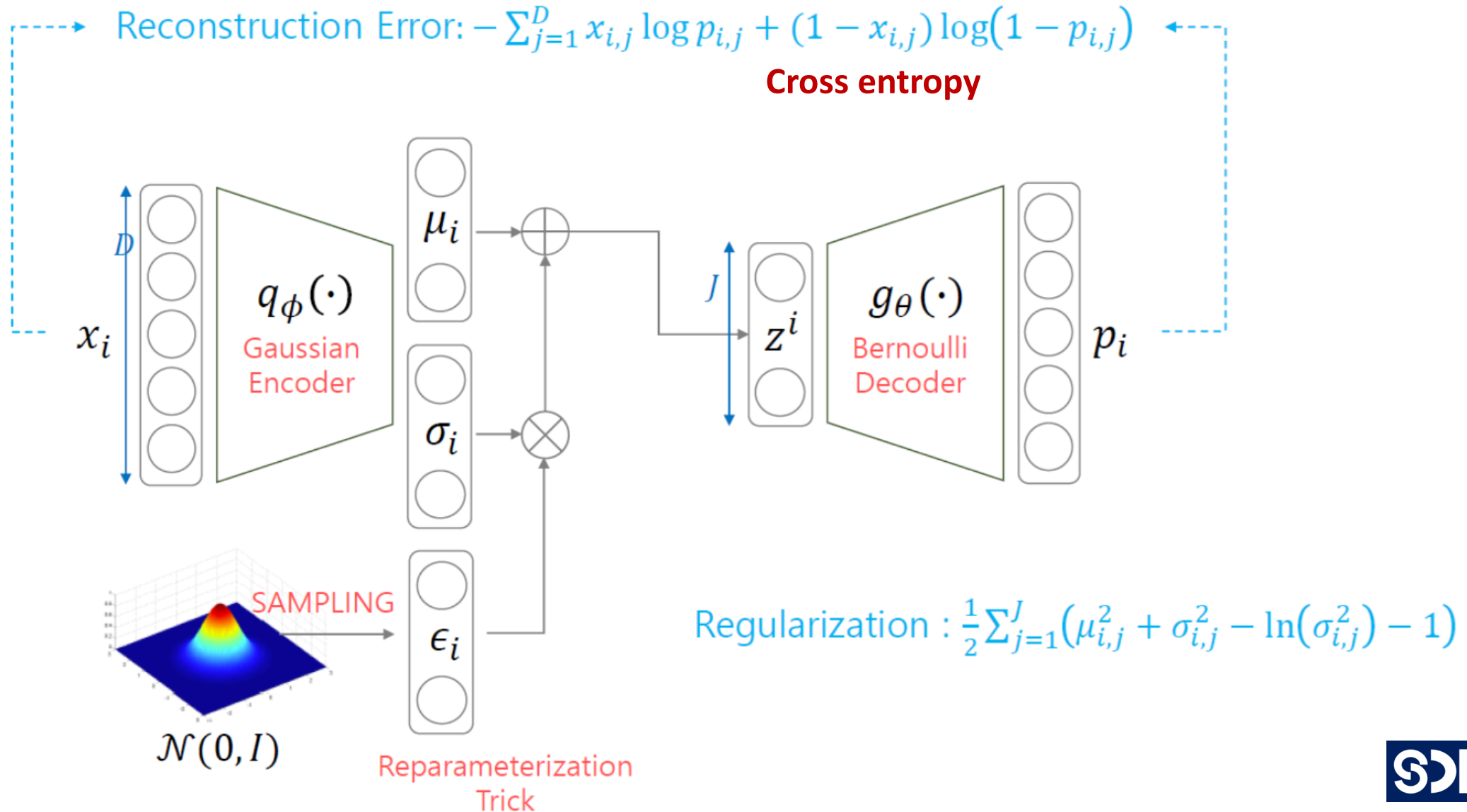
For gaussian distribution with identity covariance

$$\log(p_{\theta}(x_i|z^i)) \propto -\sum_{j=1}^D (x_{i,j} - \mu_{i,j})^2$$

**Squared Error**

# VAE - Structure

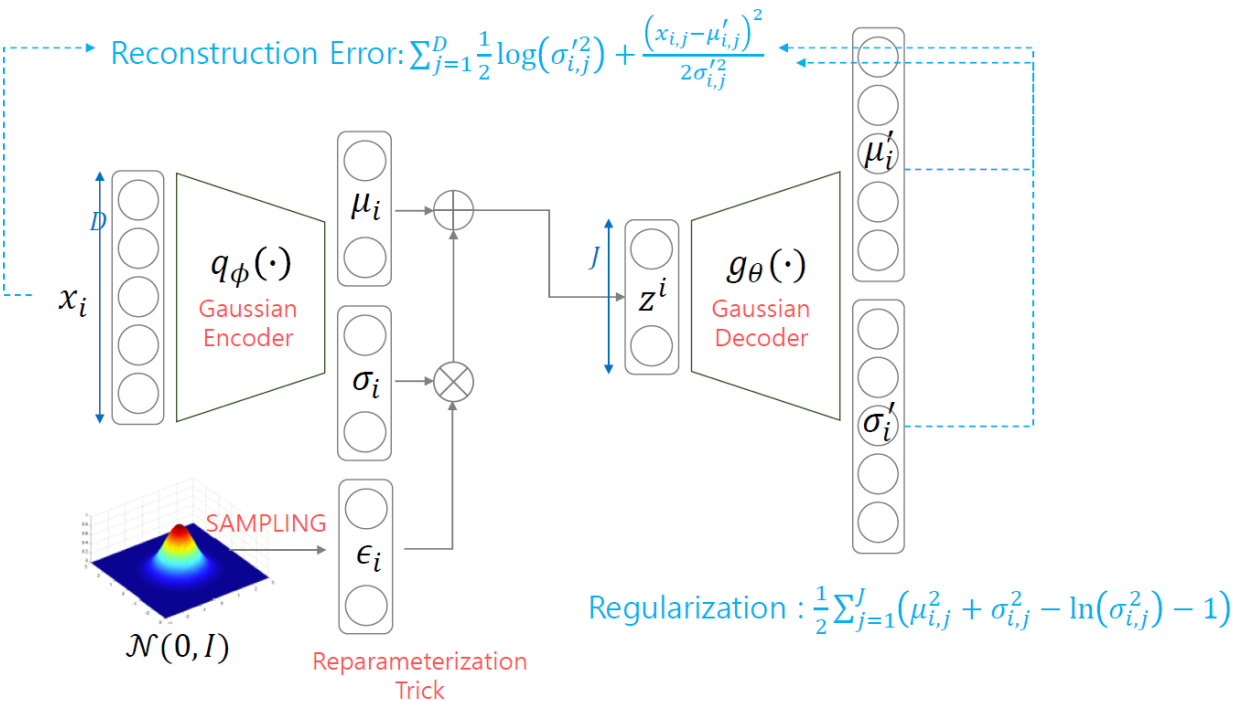
## Default : Gaussian Encoder + Bernoulli Decoder



# VAE - Structure

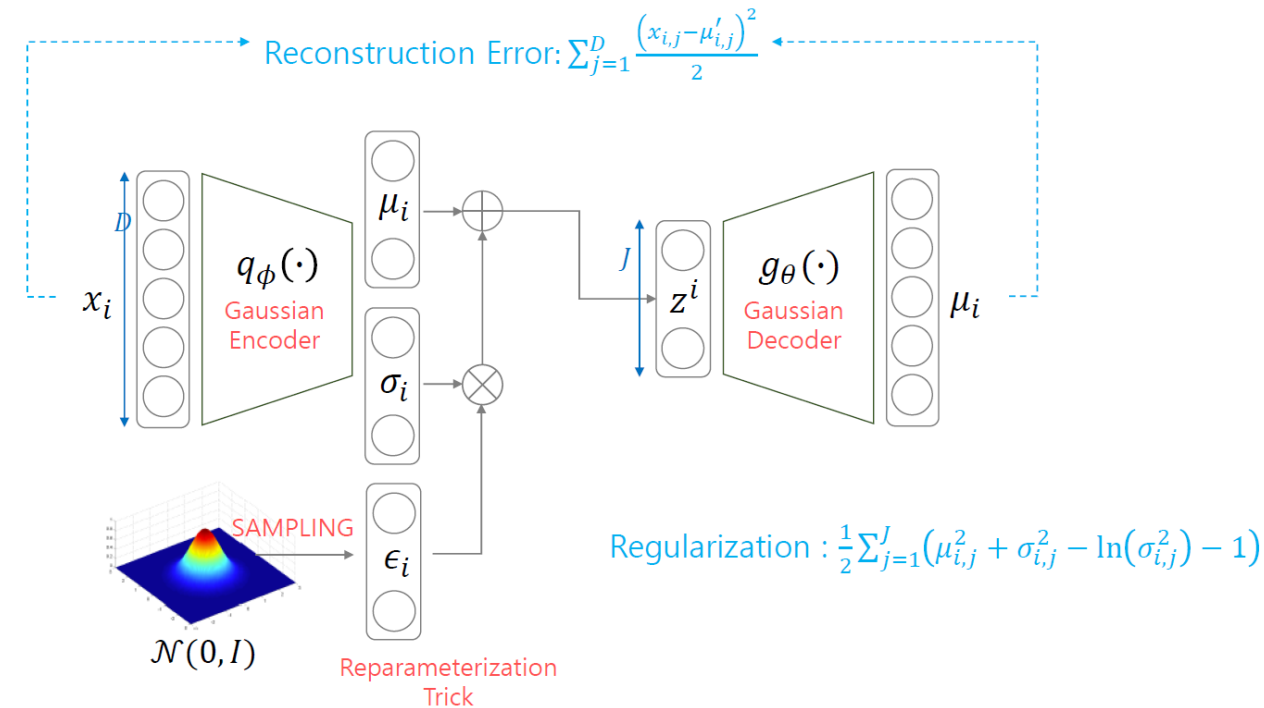
## Gaussian Encoder + Gaussian Decoder

$$\sum_{j=1}^D \frac{1}{2} \log(\sigma_{i,j}^2) + \frac{(x_{i,j} - \mu_{i,j})^2}{2\sigma_{i,j}^2}$$



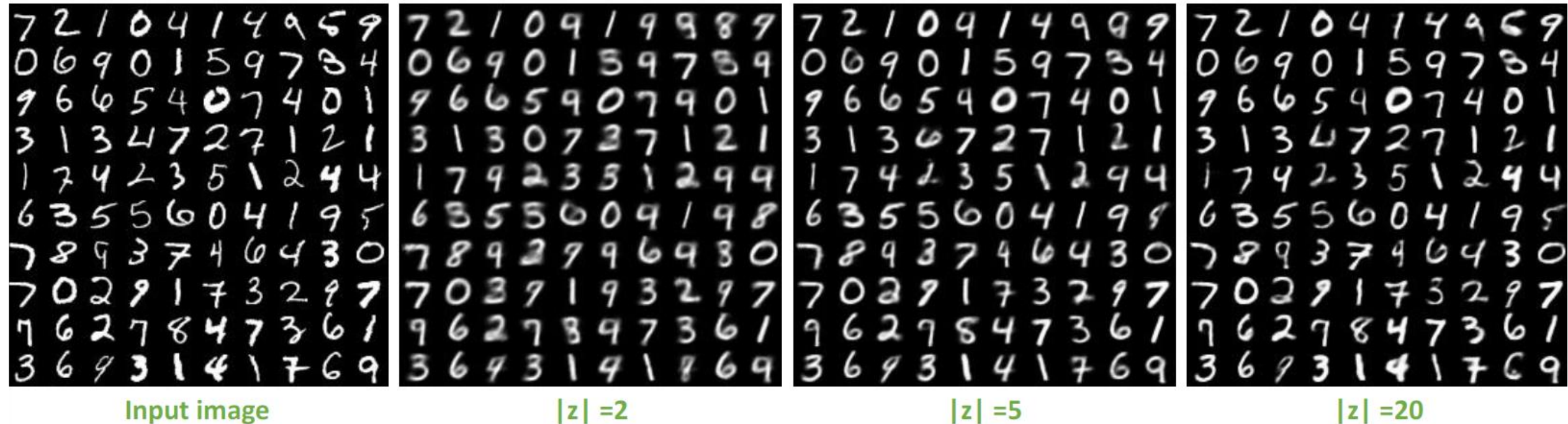
## Gaussian Encoder + Gaussian Decoder with Identity Covariance

$$\sum_{j=1}^D (x_{i,j} - \mu_{i,j})^2 \quad \text{Squared Error}$$



# VAE – Characteristics

## Latent variable dimensions

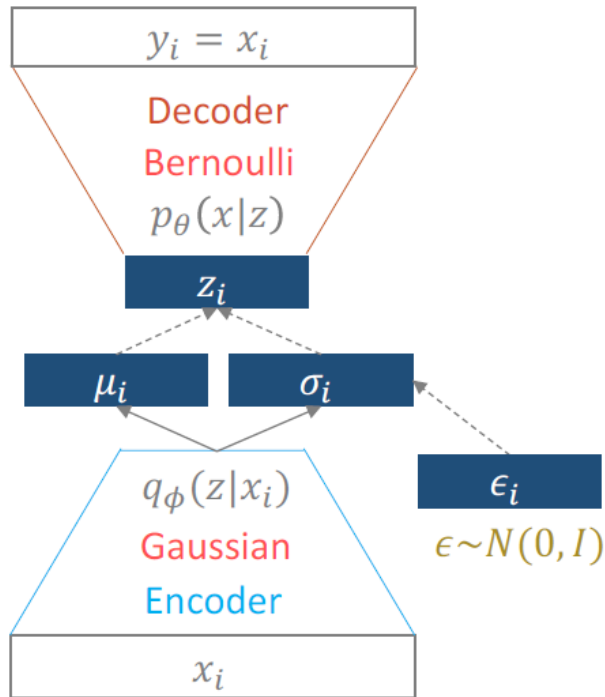


# VAE – Characteristics

$$\arg \min_{\theta, \phi} \sum_i \underbrace{-\mathbb{E}_{q_{\phi}(z|x_i)} [\log(p_{\theta}(x_i|z))]}_{\text{복원 오차}} + \underbrace{KL(q_{\phi}(z|x_i)||p(z))}_{\text{제약 조건}}$$

입력과 출력 간의 cross-entropy

Prior 분포와의 다른 정도



- Probabilistic spin to traditional autoencoders → allows generating data
- Defines an intractable density → derive and optimize a (variational) lower bound

## [ VAE의 특징들 ]

1. **Decoder**가 최소한 학습 데이터는 생성해 낼 수 있게 된다.  
→ 생성된 데이터가 학습 데이터 좀 닮아 있다.
2. **Encoder**가 최소한 학습 데이터는 잘 latent vector로 표현할 수 있게 된다.  
→ 데이터의 추상화를 위해 많이 사용된다.

# VAE coding

$$L_i(\phi, \theta, x_i) = \underbrace{-\mathbb{E}_{q_\phi(z|x_i)}[\log(p(x_i|g_\theta(z)))]}_{\text{Reconstruction Error}} + \underbrace{KL(q_\phi(z|x_i)||p(z))}_{\text{Regularization}} \rightarrow \text{argmax ELBO}(\phi)$$

*Reconstruction Error*  
원데이터에 대한 Log Likelihood

*Regularization*

다루기 쉬운 확률 분포 중 선택해서 변이추론을 위한 근사 class 중 선택하여 유사해야 한다는 조건을 부여함.

코딩에 적용된 수식

[Regularization : Kullback – leibler divergence]

$$KL(q_\phi(z|x_i)||p(z)) = \frac{1}{2} \sum_{j=1}^J (\mu_{i,j}^2 + \sigma_{i,j}^2 - \ln(\sigma_{i,j}^2) - 1)$$

[Reconstruction Error]

$$-\mathbb{E}_{q_\phi(z|x_i)}[\log(p(x_i|g_\theta(z)))] = \int \log(p(x_i|g_\theta(z))) \approx \frac{1}{L} \sum_{z^{i,l}} \log(p_\theta(x_i|z^{i,l})) \approx \log(p_\theta(x_i|z^{i,l})) = \sum_{j=1}^D x_{i,j} \log p_{i,j} + (1 - x_{i,j}) \log(1 - p_{i,j})$$

Monte-carlo technique

For Bernoulli = cross-entropy

For Gaussian distibition  
= mean square Error

# What Questions Do You Have?

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[www.smartdesignlab.org](http://www.smartdesignlab.org)

