# **Nolan Chang**

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### **SKILLS**

- Programming Languages: C++, C#, ADA, Linux/Unix, Verilog, Python, SQL
- Technologies/Tools: Jira, Github/Gitkraken, VMWare, Bitbucket, Visual Studio, FPGA, PSPICE, Vivado, PyCharm, Matlab, Jupyter, Photoshop, Solidworks, AutoCAD

#### **EXPERIENCE**

#### **Lockheed Martin Aeronautics**

Fort Worth, TX

Software Engineer

January 2020 - Present

- **F16 Platform Development**: Developed, maintained and updated software for the F16 using ADA and C++. Often collaborated and engaged with other teams throughout the development life cycle.
- Simulation Testing: Tested developed features and code in an F16 simulation environment to verify correct functionality
- Algorithms: Created and adjusted algorithms for testing purposes
- **Agile Development and Teamwork**: Worked closely with teammates in an agile environment to develop working, deliverable code on a bi-weekly basis, with daily team meetings and bi-weekly demos

CyberPowerPCCity of Industry, CAMarketing AssociateMar 2016 - Jun 2018

- Testing: Tested different computer products for performance and benchmark comparisons
- **Electronics and Computer Conventions**: Worked at booths during electronic and gaming conventions by demonstrating virtual reality systems such as the HTC Vive and Oculus Rift as well as demonstrated high-end computer systems
- Technical Writing: Contributed technical writing pieces for CyberPowerPC computer and electronic products on major retailers such as Amazon, Walmart, and Best Buy

## **EDUCATION**

# California State Polytechnic University, Pomona

Pomona, CA

Bachelor of Computer Engineering

Sep 2014 - May 2019

Relevant Coursework: Object-oriented programming, algorithms, operating systems, data structures, CPU design and scheduling, circuit analysis, logical and sequential circuit designs, microcontrollers, FPGAs, control systems, power, signal processing, lighting and illumination engineering

## **PROJECTS**

- JPL Balloon Launch with Satellite Bounce Detection: C++, Linux
  - Satellite attached to a helium-filled balloon with the goal of detecting a signal from the Sirius XM3 satellite and the bounce signal from the satellite onto a reflective surface such as a pool
  - o Researched aspects of satellite communications, telemetry, and control
- ZYNQ S-Curve Motion Controller with Configurable Kinematics: Python, Verilog, C++
  - Created an open-source, multi-feature motion controller with user-definable kinematics seeking to improve the flaws of industrial and open-source motion controllers
  - · Highly optimized S-Curve motion profiler, trajectory planner and PWM pulse generator using a combination of Verilog, Python, and C
  - o Implemented homing logic and a safety supervisor
  - o Functional prototype implemented on the PYNQ FPGA board
- Scantron Scanning and Grading Application using Image Detection: Python
  - o Reads in an answer key and scantron submissions and outputs questions marked incorrectly using Python 3 with OpenCV
  - Uses image detecting parameters to read an image preferably in grayscale
  - Adaptive thresholding applied on a pixel-to-pixel basis to accurately display outlines
  - First implementation uses AND to superimpose both scantrons onto a single image for comparison
  - Second implementation uses XNOR to detect differences in the image, additional adaptive thresholding for enhancement, and a Gaussian blur to remove noise for blob detection

# **CERTIFICATIONS & SKILLS**

- Certified SAFe Scrum Master/SAFe for Teams (ID: 78804471-5588)
- Certified Engineer-in-Training for Electrical and Computer Engineering (ID: 168007)
- Certified Solidworks Associate (ID: C-JGF9Y4MEA5)
- Spoken Languages: English, Mandarin Chinese