

# Multiclass Classification

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# Overview

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  - Sentiment analysis (positive vs. negative)
  - Spam filter (spam vs. non-spam)

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  - Document classification (over 10 classes)
  - Object recognition (over 20k classes)
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- Many real-world problems have more than two classes.
  - Document classification (over 10 classes)
  - Object recognition (over 20k classes)
  - Face recognition (millions of classes)
- What are some potential issues when we have a large number of classes?
  - Computation cost
  - Class imbalance
  - Different cost of errors

# Today's lecture

- How to *reduce* multiclass classification to binary classification?
  - We can think of binary classifier or linear regression as a black box. Naive ways:
  - E.g. multiple binary classifiers produce a binary code for each class (000, 001, 010)
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- How do we *generalize* binary classification algorithm to the multiclass setting?
  - We also need to think about the loss function.
- Example of very large output space: structured prediction.
  - Multi-class: Mutually exclusive class structure.
  - Text: Temporal relational structure.



## Reduction to Binary Classification

# One-vs-All / One-vs-Rest

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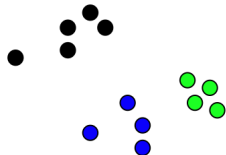
- Majority vote:

$$h(x) = \arg \max_{i \in \{1, \dots, k\}} h_i(x)$$

- Ties can be broken arbitrarily.

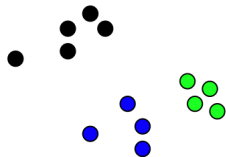
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Consider a dataset with three classes:

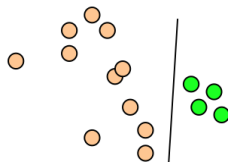
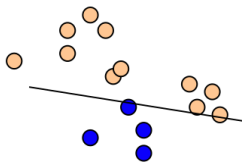
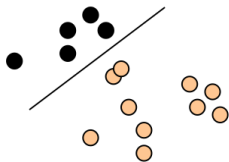


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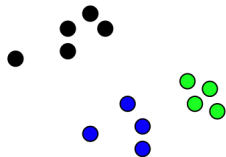


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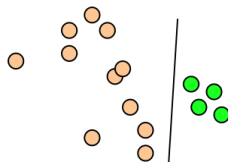
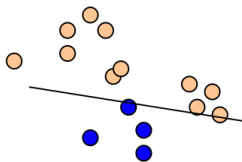
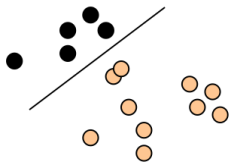
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**Assumption:** each class is linearly separable from the rest.

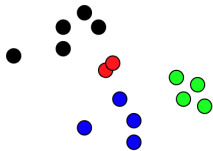
Ideal case: only target class has positive score.

Train OvA classifiers:

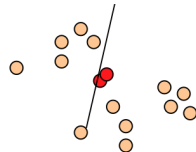
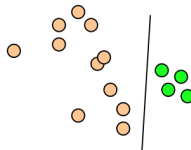
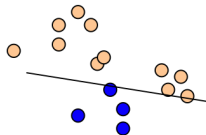
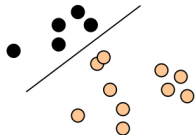


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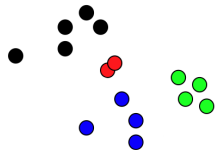
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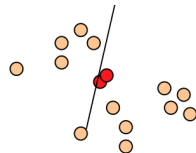
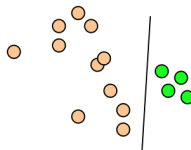
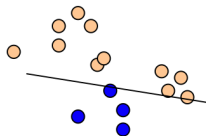
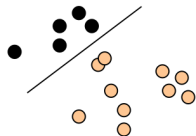
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Consider a dataset with four classes:



Cannot separate **red** points from the rest.  
Which classes might have low accuracy?

Train OvA classifiers:



# All vs All / One vs One / All pairs

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- Train  $\binom{k}{2}$  binary classifiers, one for each pair:  $h_{ij} : \mathcal{X} \rightarrow \mathbb{R}$  for  $i \in [1, k]$  and  $j \in [i+1, k]$ .
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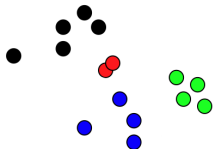
- Majority vote (each class gets  $k-1$  votes)

$$h(x) = \arg \max_{i \in \{1, \dots, k\}} \sum_{j \neq i} \underbrace{h_{ij}(x) \mathbb{I}\{i < j\}}_{\text{class } i \text{ is } +1} - \underbrace{h_{ji}(x) \mathbb{I}\{j < i\}}_{\text{class } i \text{ is } -1}$$

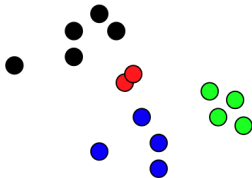
- Tournament
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## AvA: four-class example

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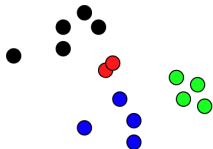


What's the decision region for the red class?



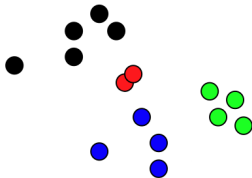
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**Assumption:** each pair of classes are linearly separable.  
More expressive than OvA.

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# OvA vs AvA

		OvA	AvA
computation	train	$O(k^2)$	$O(k^2)$
	test	$O(k)$	$O(k^2)$

# OvA vs AvA

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computation	train	$O(kB_{\text{train}}(n))$	$O(k^2B_{\text{train}}(n/k))$
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challenges



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challenges	train	class imbalance	small training set
	test	calibration / scale tie breaking	

Lack theoretical justification but simple to implement and works well in practice (when # classes is small).

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OvA uses  $k$  bits to encode each label, what's the minimal number of bits you can use?

# Error correcting output codes (ECOC)

Example: 8 classes, 6-bit code

class	$h_1$	$h_2$	$h_3$	$h_4$	$h_5$	$h_6$
1	0	0	0	1	0	0
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3	0	1	1	0	1	0
4	1	1	0	0	0	0
5	1	1	0	0	1	0
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**Prediction** Closest label in terms of Hamming distance.

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**Code design** Want good binary classifiers.



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  - In plain words, if rows are far from each other, ECOC is robust to errors.
- Trade-off between code distance and binary classification performance.
- Nice theoretical results [Allwein et al., 2000] (also incorporates AvA).

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- Key is to design “natural” binary classification problems without large computation cost.

But,

- Unclear how to generalize to extremely large # of classes.
- ImageNet: >20k labels; Wikipedia: >1M categories.

Next, generalize previous algorithms to multiclass settings.

## Multiclass Loss

# Binary Logistic Regression

- Given an input  $x$ , we would like to output a classification between  $(0,1)$ .

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- Another way to view: one class has  $(+w, +b)$  and the other class has  $(-w, -b)$ .

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- Gradient:  $\frac{\partial L}{\partial z} = f - y$ . Recall: MSE loss.

## Comparison to OvA

- **Base Hypothesis Space:**  $\mathcal{H} = \{h : \mathcal{X} \rightarrow \mathbb{R}\}$  (score functions).
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- At test time, to predict  $(x, i)$  correctly we only need

$$h_i(x) > h_j(x) \quad \forall j \neq i. \quad (4)$$



# Multiclass Perceptron

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- Multiclass perceptron:

Given a multiclass dataset  $\mathcal{D} = \{(x, y)\}$ ;

Initialize  $w \leftarrow 0$ ;

**for**  $iter = 1, 2, \dots, T$  **do**

**for**  $(x, y) \in \mathcal{D}$  **do**

$\hat{y} = \arg \max_{y' \in \mathcal{Y}} w_{y'}^T x$ ;

**if**  $\hat{y} \neq y$  **then** // We've made a mistake

$w_y \leftarrow w_y + x$  ; // Move the target-class scorer towards  $x$

$w_{\hat{y}} \leftarrow w_{\hat{y}} - x$  ; // Move the wrong-class scorer away from  $x$

**end**

**end**

**end**

## Rewrite the scoring function

- Remember that we want to scale to very large # of classes and reuse algorithms and analysis for binary classification
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$$w_i^T x = w^T \psi(x, i) \quad (5)$$

$$h_i(x) = h(x, i) \quad (6)$$

- Encode labels in the feature space.
- Score for each label  $\rightarrow$  score for the “*compatibility*” of a label and an input.

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$$w = \left( \underbrace{-\frac{\sqrt{2}}{2}, \frac{\sqrt{2}}{2}}_{w_1}, \underbrace{0, 1}_{w_2}, \underbrace{\frac{\sqrt{2}}{2}, \frac{\sqrt{2}}{2}}_{w_3} \right)$$

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- And then do the following:  $\Psi : \mathbb{R}^2 \times \{1, 2, 3\} \rightarrow \mathbb{R}^6$  defined by

$$\Psi(x, 1) := (x_1, x_2, 0, 0, 0, 0)$$

$$\Psi(x, 2) := (0, 0, x_1, x_2, 0, 0)$$

$$\Psi(x, 3) := (0, 0, 0, 0, x_1, x_2)$$

# The Multivector Construction

How to construct the feature map  $\psi$ ?

- What if we stack  $w_i$ 's together (e.g.,  $x \in \mathbb{R}^2, y = \{1, 2, 3\}$ )

$$w = \left( \underbrace{-\frac{\sqrt{2}}{2}, \frac{\sqrt{2}}{2}}_{w_1}, \underbrace{0, 1}_{w_2}, \underbrace{\frac{\sqrt{2}}{2}, \frac{\sqrt{2}}{2}}_{w_3} \right)$$

- And then do the following:  $\Psi : \mathbb{R}^2 \times \{1, 2, 3\} \rightarrow \mathbb{R}^6$  defined by

$$\Psi(x, 1) := (x_1, x_2, 0, 0, 0, 0)$$

$$\Psi(x, 2) := (0, 0, x_1, x_2, 0, 0)$$

$$\Psi(x, 3) := (0, 0, 0, 0, x_1, x_2)$$

- Then  $\langle w, \Psi(x, y) \rangle = \langle w_y, x \rangle$ , which is what we want.



## Rewrite multiclass perceptron

Multiclass perceptron using the multivector construction.

Given a multiclass dataset  $\mathcal{D} = \{(x, y)\}$ ;

Initialize  $w \leftarrow 0$ ;

**for**  $iter = 1, 2, \dots, T$  **do**

**for**  $(x, y) \in \mathcal{D}$  **do**

$\hat{y} = \arg \max_{y' \in \mathcal{Y}} w^T \psi(x, y')$  ; // Equivalent to  $\arg \max_{y' \in \mathcal{Y}} w_{y'}^T x$

**if**  $\hat{y} \neq y$  **then** // We've made a mistake

$w \leftarrow w + \psi(x, y)$  ; // Move the scorer towards  $\psi(x, y)$

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**Exercise:** What is the base binary classification problem in multiclass perceptron?

# Features

Toy multiclass example: Part-of-speech classification

- $\mathcal{X} = \{\text{All possible words}\}$
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How to construct the feature vector?

- Multivector construction:  $w \in \mathbb{R}^{d \times k}$ —doesn't scale.
- Directly design features for each class.

$$\Psi(x, y) = (\psi_1(x, y), \psi_2(x, y), \psi_3(x, y), \dots, \psi_d(x, y)) \quad (7)$$

- Size can be bounded by  $d$ .

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- E.g.,  $\Psi(x = \text{run}, y = \text{NOUN}) = (0, 1, 0, 0, \dots)$
- After training, what's  $w_1, w_2, w_3, w_4$ ?
- No need to include features unseen in training data.

## Feature templates: implementation

- Flexible, e.g., neighboring words, suffix/prefix.
- “Read off” features from the training data.
- Often sparse—efficient in practice, e.g., NLP problems.
- Can use a hash function:  $\text{template} \rightarrow \{1, 2, \dots, d\}$ .

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Next,

- How to generalize SVM to the multiclass setting.
- **Concept check:** Why might one prefer SVM / perceptron?

# Margin for Multiclass

- Binary
- Margin for  $(x^{(n)}, y^{(n)})$ :

$$y^{(n)} w^T x^{(n)} \quad (8)$$

- Want margin to be large and positive ( $w^T x^{(n)}$  has same sign as  $y^{(n)}$ )

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- Multiclass
- Class-specific margin for  $(x^{(n)}, y^{(n)})$ :

$$h(x^{(n)}, y^{(n)}) - h(x^{(n)}, y). \quad (9)$$

- Difference between scores of the correct class and each other class
- Want margin to be large and positive for all  $y \neq y^{(n)}$ .



# Multiclass SVM: separable case

## Binary

$$\min_w \quad \frac{1}{2} \|w\|^2 \quad (10)$$

$$\text{s.t.} \quad \underbrace{y^{(n)} w^T x^{(n)}}_{\text{margin}} \geq 1 \quad \forall (x^{(n)}, y^{(n)}) \in \mathcal{D} \quad (11)$$

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**Multiclass** As in the binary case, take 1 as our target margin.

$$m_{n,y}(w) \stackrel{\text{def}}{=} \underbrace{\langle w, \Psi(x^{(n)}, y^{(n)}) \rangle}_{\text{score of correct class}} - \underbrace{\langle w, \Psi(x^{(n)}, y) \rangle}_{\text{score of other class}} \quad (12)$$

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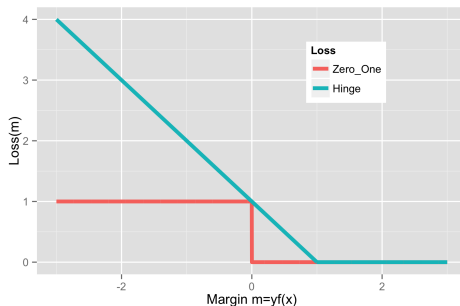
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**Exercise:** write the objective for the non-separable case

## Recap: hinge loss for binary classification

- Hinge loss: a convex upperbound on the 0-1 loss

$$\ell_{\text{hinge}}(y, \hat{y}) = \max(0, 1 - yh(x)) \quad (15)$$



## Generalized hinge loss

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- Upper bound on  $\Delta(y, y')$ .

$$\hat{y} \stackrel{\text{def}}{=} \arg \max_{y' \in \mathcal{Y}} \langle w, \Psi(x, y') \rangle \quad (17)$$

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$$\implies \langle w, \Psi(x, y) \rangle \leq \langle w, \Psi(x, \hat{y}) \rangle \quad (18)$$

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$$\implies \Delta(y, \hat{y}) \leq \Delta(y, \hat{y}) - \langle w, (\Psi(x, y) - \Psi(x, \hat{y})) \rangle \quad \text{When are they equal?} \quad (19)$$

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- Generalized hinge loss:

$$\ell_{\text{hinge}}(y, x, w) \stackrel{\text{def}}{=} \max_{y' \in \mathcal{Y}} (\Delta(y, y') - \langle w, (\Psi(x, y) - \Psi(x, y')) \rangle) \quad (20)$$

# Multiclass SVM with Hinge Loss

- Recall the hinge loss formulation for binary SVM (without the bias term):

$$\min_{w \in \mathbb{R}^d} \frac{1}{2} \|w\|^2 + C \sum_{n=1}^N \max \left( 0, 1 - \underbrace{y^{(n)} w^T x^{(n)}}_{\text{margin}} \right).$$

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- The multiclass objective:

$$\min_{w \in \mathbb{R}^d} \frac{1}{2} \|w\|^2 + C \sum_{n=1}^N \max_{y' \in \mathcal{Y}} \left( \Delta(y, y') - \underbrace{\langle w, (\Psi(x, y) - \Psi(x, y')) \rangle}_{\text{margin}} \right)$$

- $\Delta(y, y')$  as **target margin** for each class.
- If margin  $m_{n,y'}(w)$  meets or exceeds its target  $\Delta(y^{(n)}, y') \forall y \in \mathcal{Y}$ , then no loss on example  $n$ .

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  - Predict with  $\arg \max_{y \in \mathcal{Y}} h_y(x)$ .
  - Gave simple example where this fails for linear classifiers
- Solution 2: Multiclass loss
  - Train one model:  $h(x, y) : \mathcal{X} \times \mathcal{Y} \rightarrow \mathbb{R}$ .
  - Prediction involves solving  $\arg \max_{y \in \mathcal{Y}} h(x, y)$ .



# Does it work better in practice?

- Paper by Rifkin & Klautau: “In Defense of One-Vs-All Classification” (2004)
  - Extensive experiments, carefully done
    - albeit on relatively small UCI datasets
  - Suggests one-vs-all works just as well in practice
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  - Suggests one-vs-all works just as well in practice
    - (or at least, the advantages claimed by earlier papers for multiclass methods were not compelling)
- Compared
  - many multiclass frameworks (including the one we discuss)
  - one-vs-all for SVMs with RBF kernel
  - one-vs-all for square loss with RBF kernel (for classification!)
- All performed roughly the same

# Why Are We Bothering with Multiclass?

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  - compatibility features / scoring functions
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  - target margin / multiclass loss
- Generalizes to situations where  $k$  is very large and one-vs-all is intractable.
- Key idea is that we can generalize across outputs  $y$  by using features of  $y$ .

# Introduction to Structured Prediction

## Example: Part-of-speech (POS) Tagging

- Given a sentence, give a part of speech tag for each word:

$x$	$\underbrace{[\text{START}]}_{x_0}$	$\underbrace{\text{He}}_{x_1}$	$\underbrace{\text{eats}}_{x_2}$	$\underbrace{\text{apples}}_{x_3}$
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- $\mathcal{X} = \mathcal{V}^n, n = 1, 2, 3, \dots$  [Word sequences of any length]
- $\mathcal{P} = \{\text{START, Pronoun, Verb, Noun, Adjective}\}$
- $\mathcal{Y} = \mathcal{P}^n, n = 1, 2, 3, \dots$  [Part of speech sequence of any length]

# Multiclass Hypothesis Space

- **Discrete** output space:  $\mathcal{Y}(x)$ 
  - Very large but has structure, e.g., linear chain (sequence labeling), tree (parsing)
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  - $h(x, y)$  gives **compatibility score** between input  $x$  and output  $y$

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  - $h(x, y)$  gives **compatibility score** between input  $x$  and output  $y$
- Multiclass hypothesis space

$$\mathcal{F} = \left\{ x \mapsto \arg \max_{y \in \mathcal{Y}} h(x, y) \mid h \in \mathcal{H} \right\}$$

- Final prediction function is an  $f \in \mathcal{F}$ .
- For each  $f \in \mathcal{F}$  there is an underlying compatibility score function  $h \in \mathcal{H}$ .

# Structured Prediction

- Part-of-speech tagging

$x$ :	he	eats	apples
$y$ :	pronoun	verb	noun

- Multiclass hypothesis space:

$$h(x, y) = w^T \Psi(x, y) \quad (21)$$

$$\mathcal{F} = \left\{ x \mapsto \arg \max_{y \in \mathcal{Y}} h(x, y) \mid h \in \mathcal{H} \right\} \quad (22)$$

- A special case of multiclass classification
- How to design the feature map  $\Psi$ ? What are the considerations?

# Unary features

- A **unary feature** only depends on
  - the label at a **single position**,  $y_i$ , and  $x$
- Example:

$$\phi_1(x, y_i) = \mathbb{1}[x_i = \text{runs}] \mathbb{1}[y_i = \text{Verb}]$$

$$\phi_2(x, y_i) = \mathbb{1}[x_i = \text{runs}] \mathbb{1}[y_i = \text{Noun}]$$

$$\phi_3(x, y_i) = \mathbb{1}[x_{i-1} = \text{He}] \mathbb{1}[x_i = \text{runs}] \mathbb{1}[y_i = \text{Verb}]$$

# Markov features

- A **markov feature** only depends on
  - two **adjacent** labels,  $y_{i-1}$  and  $y_i$ , and  $x$
- Example:

$$\theta_1(x, y_{i-1}, y_i) = \mathbb{1}[y_{i-1} = \text{Pronoun}] \mathbb{1}[y_i = \text{Verb}]$$

$$\theta_2(x, y_{i-1}, y_i) = \mathbb{1}[y_{i-1} = \text{Pronoun}] \mathbb{1}[y_i = \text{Noun}]$$

- Reminiscent of Markov models in the output space
- Possible to have higher-order features

## Local Feature Vector and Compatibility Score

- At each position  $i$  in sequence, define the **local feature vector** (unary and markov):

$$\Psi_i(x, y_{i-1}, y_i) = (\phi_1(x, y_i), \phi_2(x, y_i), \dots, \\ \theta_1(x, y_{i-1}, y_i), \theta_2(x, y_{i-1}, y_i), \dots)$$



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- And **local compatibility score** at position  $i$ :  $\langle w, \Psi_i(x, y_{i-1}, y_i) \rangle$ .
- The compatibility score for  $(x, y)$  is the sum of local compatibility scores:

$$\sum_i \langle w, \Psi_i(x, y_{i-1}, y_i) \rangle = \left\langle w, \sum_i \Psi_i(x, y_{i-1}, y_i) \right\rangle = \langle w, \Psi(x, y) \rangle, \quad (23)$$

where we define the **sequence feature vector** by

$$\Psi(x, y) = \sum_i \Psi_i(x, y_{i-1}, y_i). \quad \text{decomposable}$$

# Structured perceptron

Given a dataset  $\mathcal{D} = \{(x, y)\}$ ;

Initialize  $w \leftarrow 0$ ;

**for**  $iter = 1, 2, \dots, T$  **do**

**for**  $(x, y) \in \mathcal{D}$  **do**

$\hat{y} = \arg \max_{y' \in \mathcal{Y}(x)} w^T \psi(x, y')$ ;

**if**  $\hat{y} \neq y$  **then** // We've made a mistake

$w \leftarrow w + \Psi(x, y)$  ; // Move the scorer towards  $\psi(x, y)$

$w \leftarrow w - \Psi(x, \hat{y})$  ; // Move the scorer away from  $\psi(x, \hat{y})$

**end**

**end**

**end**

# Structured perceptron

Given a dataset  $\mathcal{D} = \{(x, y)\}$ ;

Initialize  $w \leftarrow 0$ ;

**for**  $iter = 1, 2, \dots, T$  **do**

**for**  $(x, y) \in \mathcal{D}$  **do**

$\hat{y} = \arg \max_{y' \in \mathcal{Y}(x)} w^T \psi(x, y')$ ;

**if**  $\hat{y} \neq y$  **then** // We've made a mistake

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**end**

**end**

**end**

Identical to the multiclass perceptron algorithm except the  $\arg \max$  is now over the structured output space  $\mathcal{Y}(x)$ .

# Structured hinge loss

- Recall the generalized hinge loss

$$\ell_{\text{hinge}}(y, \hat{y}) \stackrel{\text{def}}{=} \max_{y' \in \mathcal{Y}(x)} (\Delta(y, y') + \langle w, (\Psi(x, y') - \Psi(x, y)) \rangle) \quad (24)$$

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- What is  $\Delta(y, y')$  for two sequences?
- Hamming loss** is common:

$$\Delta(y, y') = \frac{1}{L} \sum_{i=1}^L \mathbb{1}[y_i \neq y'_i]$$

where  $L$  is the sequence length.

## Exercise:

- Write down the objective of structured SVM using the structured hinge loss.
- Stochastic sub-gradient descent for structured SVM (similar to HW3 P3)
- Compare with the structured perceptron algorithm

# The argmax problem for sequences

**Problem** To compute predictions, we need to find  $\arg \max_{y \in \mathcal{Y}(x)} \langle w, \Psi(x, y) \rangle$ , and  $|\mathcal{Y}(x)|$  is exponentially large.



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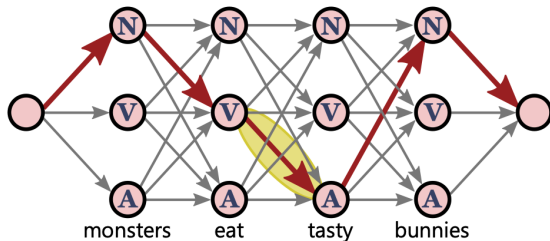
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**Observation**  $\Psi(x, y)$  decomposes to  $\sum_i \Psi_i(x, y)$ .

**Solution** Dynamic programming (similar to the Viterbi algorithm)



What's the running time?

# Conditional random field (CRF)

- Recall that we can write logistic regression in a general form:

$$p(y|x) = \frac{1}{Z(x)} \exp(w^\top \psi(x, y)).$$

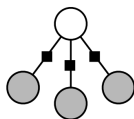
- $Z$  is normalization constant:  $Z(x) = \sum_{y \in Y} \exp(w^\top \psi(x, y))$ .

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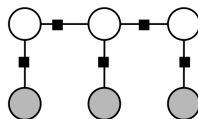
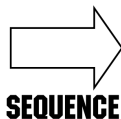
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- $Z$  is normalization constant:  $Z(x) = \sum_{y \in Y} \exp(w^\top \psi(x, y))$ .
- Example: linear chain  $\{y_t\}$
- We can incorporate unary and Markov features:  $p(y|x) = \frac{1}{Z(x)} \exp(\sum_t w^\top \psi(x, y_t, y_{t-1}))$



Logistic Regression



Linear-chain CRFs

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- We can draw samples in the output space.

# Conditional random field (CRF)

- Compared to Structured SVM, CRF has a probabilistic interpretation.
- We can draw samples in the output space.
- How do we learn  $w$ ? Maximum log likelihood, and regularization term:  $\lambda \|w\|^2$
- Loss function:

$$\begin{aligned} l(w) &= -\frac{1}{N} \sum_{i=1}^N \log p(y^{(i)} | x^{(i)}) + \frac{1}{2} \lambda \|w\|^2 \\ &= -\frac{1}{N} \sum_i \sum_t \sum_k w_k \psi_k(y_t^{(i)}, y_{t-1}^{(i)}) + \frac{1}{N} \sum_i \log Z(x^{(i)}) + \frac{1}{2} \sum_k \lambda w_k^2 \end{aligned}$$

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- Gradient:

$$\frac{\partial l(w)}{\partial w_k} = -\frac{1}{N} \sum_i \sum_t \sum_k \psi_k(x^{(i)}, y_t^{(i)}, y_{t-1}^{(i)}) \quad (25)$$

$$+ \frac{1}{N} \sum_i \frac{\partial}{\partial w_k} \log \sum_{y' \in Y} \exp\left(\sum_t \sum_{k'} w_{k'} \psi_{k'}(x^{(i)}, y'_t, y'_{t-1})\right) + \sum_k \lambda w_k \quad (26)$$

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- What is  $\frac{1}{N} \sum_i \sum_t \sum_k \psi_k(x^{(i)}, y_t^{(i)}, y_{t-1}^{(i)})$ ?



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- What is  $\frac{1}{N} \sum_i \sum_t \sum_k \psi_k(x^{(i)}, y_t^{(i)}, y_{t-1}^{(i)})$ ?
- It is the expectation  $\psi_k(x^{(i)}, y_t, y_{t-1})$  under the empirical distribution  $\tilde{p}(x, y) = \frac{1}{N} \sum_i \mathbb{1}[x = x^{(i)}] \mathbb{1}[y = y^{(i)}]$ .

## Conditional random field (CRF)

- What is  $\frac{1}{N} \sum_i \frac{\partial}{\partial w_k} \log \sum_{y' \in Y} \exp(\sum_t \sum_{k'} w_{k'} \psi_{k'}(x^{(i)}, y'_t, y'_{t-1}))$ ?

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- It is the expectation of  $\psi_k(x^{(i)}, y'_t, y'_{t-1})$  under the model distribution  $p(y'_t, y'_{t-1} | x)$ .

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- To compute the gradient, we need to infer expectation under the model distribution  $p(y|x)$ .
- Compare the learning algorithms: in structured SVM we need to compute the argmax, whereas in CRF we need to compute the model expectation.
- Both problems are NP-hard for general graphs.

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- In general graphs, we rely on approximate inference (e.g. loopy belief propagation).

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Relationship between pixels, e.g. a grass pixel is likely to be next to another grass pixel, and a sky pixel is likely to be above a grass pixel.
- Multi-label learning  
An image may contain multiple class labels, e.g. a bus is likely to co-occur with a car.

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- Structured prediction: Structured SVM, CRF. Data containing structure. Extremely large output space. Text and image applications.