Bayesian Methods & Multiclass

Mengye Ren

NYU

Oct 31, 2023

Announcement

- Schedule your project consultation soon.
- Use the provided template! (if your final report fails to use template then there will be marks off)
- Homework 3 is released and due Nov 14 11:59AM.

- Bayesian modeling adds a prior on the parameters.
- Models the distribution of parameters

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• Conjugate prior: Having the same form of distribution as the posterior.

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- Common options:
 - posterior mean $\hat{\theta} = \mathbb{E}[\theta \mid \mathcal{D}]$
 - maximum a posteriori (MAP) estimate $\hat{\theta} = \arg \max_{\theta} p(\theta \mid D)$
 - Note: this is the mode of the posterior distribution

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- Extract a **credible set** for θ (a Bayesian confidence interval).
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- Select a point estimate using Bayesian decision theory:
 - Choose a loss function.
 - Find action minimizing expected risk w.r.t. posterior

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 - Parameter space Θ .
 - **Prior**: Distribution $p(\theta)$ on Θ .
 - Action space A.
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- A Bayes action a^* is an action that minimizes posterior risk:

$$r(a^*) = \min_{a \in \mathcal{A}} r(a)$$

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- Squared Loss : $\ell(\hat{\theta}, \theta) = (\theta \hat{\theta})^2$ \Rightarrow posterior mean
- Zero-one Loss: $\ell(\theta,\hat{\theta}) = \mathbb{1}[\theta \neq \hat{\theta}] \quad \Rightarrow \text{ posterior mode}$
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- Example: I have a card drawing from a deck of 2,3,3,4,4,5,5,5, and you guess the value of my card.

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- Example: I have a card drawing from a deck of 2,3,3,4,4,5,5,5, and you guess the value of my card.
- mean: 3.875; mode: 5; median: 4

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• The Bayes action for square loss is the posterior mean.

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Interim summary

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 - For decision making, we need a loss function.

Recap: Conditional Probability Models

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- Outcome space \mathcal{Y}
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- A parametric family of conditional densities is a set

$$\{p(y \mid x, \theta) : \theta \in \Theta\},\$$

- where $p(y \mid x, \theta)$ is a density on **outcome space** \mathcal{Y} for each x in **input space** \mathcal{X} , and
- θ is a **parameter** in a [finite dimensional] **parameter space** Θ .

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- θ is a parameter in a [finite dimensional] parameter space Θ .
- This is the common starting point for either classical or Bayesian regression.

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Classical treatment: Likelihood Function

- **Data**: $\mathcal{D} = (y_1, ..., y_n)$
- ullet The probability density for our data ${\mathcal D}$ is

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• For fixed \mathcal{D} , the function $\theta \mapsto p(\mathcal{D} \mid x, \theta)$ is the **likelihood function**:

$$L_{\mathcal{D}}(\theta) = p(\mathcal{D} \mid x, \theta),$$

where $x = (x_1, ..., x_n)$.

Maximum Likelihood Estimator

• The maximum likelihood estimator (MLE) for θ in the family $\{p(y \mid x, \theta) \mid \theta \in \Theta\}$ is

$$\hat{\theta}_{\mathsf{MLE}} = \underset{\theta \in \Theta}{\mathsf{arg\,max}} L_{\mathcal{D}}(\theta).$$

• MLE corresponds to ERM, if we set the loss to be the negative log-likelihood.

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- MLE corresponds to ERM, if we set the loss to be the negative log-likelihood.
- The corresponding prediction function is

$$\hat{f}(x) = p(y \mid x, \hat{\theta}_{MLE}).$$

Bayesian Conditional Probability Models

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• A prior distribution $p(\theta)$ on $\theta \in \Theta$.

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- Posterior represents the rationally updated beliefs after seeing \mathfrak{D} .
- \bullet Each θ corresponds to a prediction function,
 - i.e. the conditional distribution function $p(y \mid x, \theta)$.

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- We can use Bayesian decision theory to derive point estimates.
- We may want to use
 - $\hat{\theta} = \mathbb{E}[\theta \mid \mathcal{D}, x]$ (the posterior mean estimate)
 - $\hat{\theta} = \text{median}[\theta \mid \mathcal{D}, x]$
 - $\hat{\theta} = \operatorname{arg\,max}_{\theta \in \Theta} p(\theta \mid \mathcal{D}, x)$ (the MAP estimate)
- depending on our loss function.

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• and a prior distribution $p(\theta)$ on this set.

Back to the basic question - Bayesian Prediction Function

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- and a prior distribution $p(\theta)$ on this set.
- Having set our Bayesian model, how do we predict a distribution on y for input x?
- We don't need to make a discrete selection from the hypothesis space: we maintain uncertainty.

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• In the Bayesian approach, we integrate out over Θ w.r.t. $p(\theta \mid D)$ and predict with

$$p(y \mid x, \mathcal{D}) = \int p(y \mid x; \theta) p(\theta \mid \mathcal{D}) d\theta$$

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- Each of these can be derived from p(y | x, D).

Gaussian Regression Example

- Input space $\mathfrak{X} = [-1, 1]$ Output space $\mathfrak{Y} = \mathsf{R}$
- Given x, the world generates y as

$$y = w_0 + w_1 x + \varepsilon$$
,

where $\varepsilon \sim \mathcal{N}(0, 0.2^2)$.

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• Written another way, the conditional probability model is

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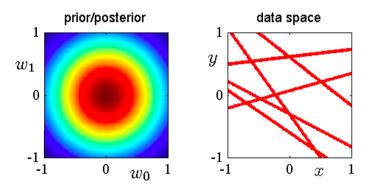
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- Prior distribution: $w = (w_0, w_1) \sim \mathcal{N}(0, \frac{1}{2}I)$

Example in 1-Dimension: Prior Situation

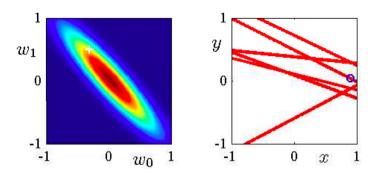
• Prior distribution: $w = (w_0, w_1) \sim \mathcal{N}\left(0, \frac{1}{2}I\right)$ (Illustrated on left)



• On right, $y(x) = \mathbb{E}[y \mid x, w] = w_0 + w_1 x$, for randomly chosen $w \sim p(w) = \mathcal{N}(0, \frac{1}{2}I)$.

Bishop's PRML Fig 3.7

Example in 1-Dimension: 1 Observation

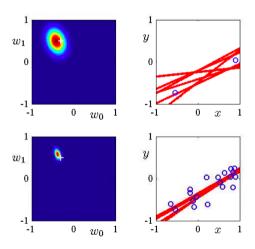


- On left: posterior distribution; white cross indicates true parameters
- On right:
 - blue circle indicates the training observation
 - red lines, $y(x) = \mathbb{E}[y \mid x, w] = w_0 + w_1 x$, for randomly chosen $w \sim p(w \mid \mathcal{D})$ (posterior)

Bishop's PRML Fig 3.7

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Example in 1-Dimension: 2 and 20 Observations



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Gaussian Regression: Closed form

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$$w \sim \mathcal{N}(0, \Sigma_0)$$

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$$\mu_P = (X^T X + \sigma^2 \Sigma_0^{-1})^{-1} X^T y$$

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• Posterior Variance Σ_P gives us a natural uncertainty measure.

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$$\hat{\mathbf{w}} = \mathbf{\mu}_P = \left(X^T X + \lambda I \right)^{-1} X^T \mathbf{y},$$

which is of course the ridge regression solution.

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• The Posterior density on w for $\Sigma_0 = \frac{\sigma^2}{\lambda}I$:

$$p(w \mid \mathcal{D}) \propto \underbrace{\exp\left(-\frac{\lambda}{2\sigma^2} \|w\|^2\right)}_{\text{prior}} \underbrace{\prod_{i=1}^{n} \exp\left(-\frac{(y_i - w^T x_i)^2}{2\sigma^2}\right)}_{\text{likelihood}}$$

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$$\hat{w}_{\mathsf{MAP}} = \underset{w \in \mathsf{R}^d}{\mathsf{arg\,min}} \left[-\log p(w \mid \mathfrak{D}) \right]$$

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Which is the ridge regression objective.

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• For Gaussian regression, predictive distribution has closed form.

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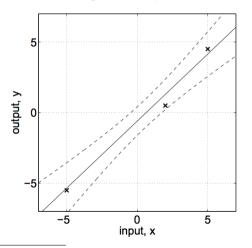
$$y_{\text{new}} \mid x_{\text{new}}, \mathcal{D} \sim \mathcal{N}\left(\eta_{\text{new}}, \sigma_{\text{new}}^2\right)$$

$$\eta_{\text{new}} = \mu_{\text{P}}^T x_{\text{new}}$$

$$\sigma_{\text{new}}^2 = \underbrace{x_{\text{new}}^T \Sigma_{\text{P}} x_{\text{new}}}_{\text{from variance in } w} + \underbrace{\sigma^2}_{\text{inherent variance in } y}$$

Bayesian Regression Provides Uncertainty Estimates

• With predictive distributions, we can give mean prediction with error bands:



Rasmussen and Williams' Gaussian Processes for Machine Learning, Fig.2.1(b)

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Multi-class Overview

Motivation

- So far, most algorithms we've learned are designed for binary classification.
 - Sentiment analysis (positive vs. negative)
 - Spam filter (spam vs. non-spam)

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 - Object recognition (over 20k classes)
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- Many real-world problems have more than two classes.
 - Document classification (over 10 classes)
 - Object recognition (over 20k classes)
 - Face recognition (millions of classes)
- What are some potential issues when we have a large number of classes?
 - Computation cost
 - Class imbalance
 - Different cost of errors

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Today's lecture

- How to reduce multiclass classification to binary classification?
 - We can think of binary classifier or linear regression as a black box. Naive ways:
 - E.g. multiple binary classifiers produce a binary code for each class (000, 001, 010)
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- How do we generalize binary classification algorithm to the multiclass setting?
 - We also need to think about the loss function.
- Example of very large output space: structured prediction.
 - Multi-class: Mutually exclusive class structure.
 - Text: Temporal relational structure.

Reduction to Binary Classification

One-vs-All / One-vs-Rest

Setting • Input space: X

• Output space: $\mathcal{Y} = \{1, \dots, k\}$

One-vs-All / One-vs-Rest

Setting

- Input space: χ
- Output space: $\mathcal{Y} = \{1, \dots, k\}$

Training

- Train k binary classifiers, one for each class: $h_1, \ldots, h_k : \mathcal{X} \to \mathbb{R}$.
- Classifier h_i distinguishes class i (+1) from the rest (-1).

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Prediction

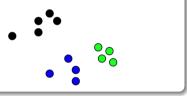
Majority vote:

$$h(x) = \underset{i \in \{1, \dots, k\}}{\operatorname{arg\,max}} h_i(x)$$

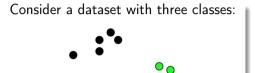
• Ties can be broken arbitrarily.

OvA: 3-class example (linear classifier)

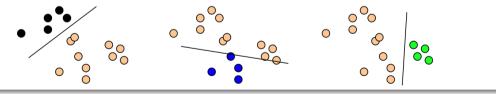
Consider a dataset with three classes:



OvA: 3-class example (linear classifier)



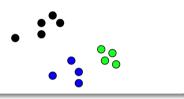
Train OvA classifiers:



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OvA: 3-class example (linear classifier)

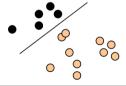
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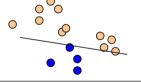


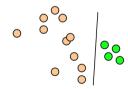
Assumption: each class is linearly separable from the rest.

Ideal case: only target class has positive score.

Train OvA classifiers:







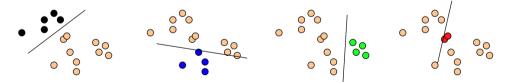
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OvA: 4-class non linearly separable example

Consider a dataset with four classes:



Train OvA classifiers:



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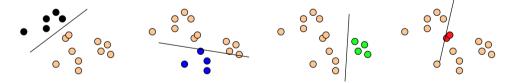
OvA: 4-class non linearly separable example

Consider a dataset with four classes:



Cannot separate red points from the rest. Which classes might have low accuracy?

Train OvA classifiers:



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All vs All / One vs One / All pairs

Setting

- Input space: χ
 - Output space: $\mathcal{Y} = \{1, \dots, k\}$

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- Input space: X
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Training

- Train $\binom{k}{2}$ binary classifiers, one for each pair: $h_{ii}: \mathcal{X} \to \mathsf{R}$ for $i \in [1, k]$ and $i \in [i + 1, k]$.
- Classifier h_{ii} distinguishes class i (+1) from class j (-1).

All vs All / One vs One / All pairs

Setting

- Input space: $\mathfrak X$
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Prediction

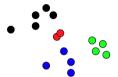
• Majority vote (each class gets k-1 votes)

$$h(x) = \operatorname*{arg\,max}_{i \in \{1, \dots, k\}} \sum_{j \neq i} \underbrace{h_{ij}(x) \mathbb{I}\{i < j\}}_{\text{class } i \text{ is } +1} - \underbrace{h_{ji}(x) \mathbb{I}\{j < i\}}_{\text{class } i \text{ is } -1}$$

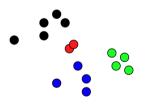
- Tournament
- Ties can be broken arbitrarily.

AvA: four-class example

Consider a dataset with four classes:



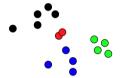
What's the decision region for the red class?



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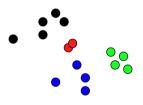
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Consider a dataset with four classes:



Assumption: each pair of classes are linearly separable. More expressive than OvA.

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OvA vs AvA

		OvA	\	AvA		
computation	train test	O(k O(k)	$O(k^2 \\ O(k^2$))

OvA vs AvA

		OvA	AvA
computation	train test	$O(kB_{train}(n)) \ O(kB_{test})$	$O(k^2 B_{train}(n/k))$ $O(k^2 B_{test})$

challenges

		OvA	AvA
computation	train test	$O(kB_{train}(n)) \ O(kB_{test})$	$O(k^2 B_{train}(n/k))$ $O(k^2 B_{test})$
challenges	train test	class imbalance small training s calibration / scale tie breaking	

Lack theoretical justification but simple to implement and works well in practice (when # classes is small).

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2	0	1	0	0
3	0	0	1	0
4	0	0	0	1

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OvA uses k bits to encode each label, what's the minimal number of bits you can use?

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Error correcting output codes (ECOC)

Example: 8 classes, 6-bit code

class	h_1	h ₂	h ₃	h ₄	h_5	h ₆
1	0	0	0	1	0	0
2	1	0	0	0	0	0
3	0	1	1	0	1	0
4	1	1	0	0	0	0
5	1	1	0	0	1	0
6	0	0	1	1	0	1
7	0	0	1	0	0	0
8	0	1	0	1	0	0

Training Binary classifier h_i :

- +1: classes whose *i*-th bit is 1
- -1: classes whose *i*-th bit is 0

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Prediction Closest label in terms of Hamming distance.

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0	1	1	0	1	0
1	1	0	0	0	0
1	1	0	0	1	0
0	0	1	1	0	1
0	0	1	0	0	0
0	1	0	1	0	0
	0 1 0 1 1 0 0	0 0 1 0 0 1 1 1 1 1 0 0	0 0 0 1 0 0 0 1 1 1 1 0 0 0 1 0 0 1	0 0 0 1 1 0 0 0 0 1 1 0 1 1 0 0 1 1 0 0 0 0 1 1 0 0 1 0	0 0 0 1 0 1 0 0 0 0 0 1 1 0 1 1 1 0 0 0 1 1 0 0 1 0 0 1 1 0 0 0 1 0 0

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Code design Want good binary classifiers.

Error correcting output codes: summary

- Computationally more efficient than OvA (a special case of ECOC). Better for large k.
- Why not use the minimal number of bits $(\log_2 k)$?

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 - In plain words, if rows are far from each other, ECOC is robust to errors.

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- Why not use the minimal number of bits $(\log_2 k)$?
 - If the minimum Hamming distance between any pair of code word is d, then it can correct $\lfloor \frac{d-1}{2} \rfloor$ errors.
 - In plain words, if rows are far from each other, ECOC is robust to errors.
- Trade-off between code distance and binary classification performance.
- Nice theoretical results [Allwein et al., 2000] (also incoporates AvA).

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Review

Reduction-based approaches:

- Reducing multiclass classification to binary classification: OvA, AvA
- Key is to design "natural" binary classification problems without large computation cost.

Reduction-based approaches:

- Reducing multiclass classification to binary classification: OvA, AvA
- Key is to design "natural" binary classification problems without large computation cost.

But,

- Unclear how to generalize to extremely large # of classes.
- ImageNet: >20k labels; Wikipedia: >1M categories.

Next, generalize previous algorithms to multiclass settings.

Multiclass Loss

Binary Logistic Regression

• Given an input x, we would like to output a classification between (0,1).

$$f(x) = sigmoid(z) = \frac{1}{1 + \exp(-z)} = \frac{1}{1 + \exp(-w^{\top}x - b)}.$$
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• The other class is represented in 1 - f(x):

$$1 - f(x) = \frac{\exp(-w^{\top}x - b)}{1 + \exp(-w^{\top}x - b)} = \frac{1}{1 + \exp(w^{\top}x + b)} = sigmoid(-z).$$
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• Another way to view: one class has (+w,+b) and the other class has (-w,-b).

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- Gradient: $\frac{\partial L}{\partial z} = f y$. Recall: MSE loss.

Comparison to OvA

- Base Hypothesis Space: $\mathcal{H} = \{h : \mathcal{X} \to R\}$ (score functions).
- Multiclass Hypothesis Space (for *k* classes):

$$\mathcal{F} = \left\{ x \mapsto rg \max_{i} h_{i}(x) \mid h_{1}, \dots, h_{k} \in \mathcal{H} \right\}$$

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- OvA objective: $h_i(x) > 0$ for x with label i and $h_i(x) < 0$ for x with all other labels.

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- Intuitively, $h_i(x)$ scores how likely x is to be from class i.
- OvA objective: $h_i(x) > 0$ for x with label i and $h_i(x) < 0$ for x with all other labels.
- At test time, to predict (x, i) correctly we only need

$$h_i(x) > h_j(x) \qquad \forall j \neq i.$$
 (4)

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Multiclass Perceptron

• Base linear predictors: $h_i(x) = w_i^T x \ (w \in \mathbb{R}^d)$.

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- Multiclass perceptron:

```
Given a multiclass dataset \mathcal{D} = \{(x, y)\};
Initialize w \leftarrow 0:
for iter = 1, 2, ..., T do
    for (x, y) \in \mathcal{D} do
         \hat{y} = \operatorname{arg\,max}_{v' \in \mathcal{Y}} w_{v'}^T x;
         if \hat{v} \neq v then // We've made a mistake
              w_v \leftarrow w_v + x; // Move the target-class scorer towards x
              w_{\hat{v}} \leftarrow w_{\hat{v}} - x; // Move the wrong-class scorer away from x
         end
    end
end
```

Rewrite the scoring function

- Remember that we want to scale to very large # of classes and reuse algorithms and analysis for binary classification
 - \implies a single weight vector is desired
- How to rewrite the equation such that we have one w instead of k?

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$$w_i^T x = w^T \psi(x, i) \tag{5}$$

$$h_i(x) = h(x, i) \tag{6}$$

- Encode labels in the feature space.
- ullet Score for each label o score for the "compatibility" of a label and an input.

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The Multivector Construction

How to construct the feature map ψ ?

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• What if we stack w_i 's together (e.g., $x \in \mathbb{R}^2$, $y = \{1, 2, 3\}$)

$$w = \left(\underbrace{-\frac{\sqrt{2}}{2}, \frac{\sqrt{2}}{2}}_{w_1}, \underbrace{\frac{0, 1}{w_2}, \frac{\sqrt{2}}{2}, \frac{\sqrt{2}}{2}}_{w_3}\right)$$

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• And then do the following: $\Psi: \mathbb{R}^2 \times \{1,2,3\} \to \mathbb{R}^6$ defined by

$$\Psi(x,1) := (x_1, x_2, 0, 0, 0, 0)$$

$$\Psi(x,2) := (0,0,x_1,x_2,0,0)$$

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• Then $\langle w, \Psi(x,y) \rangle = \langle w_v, x \rangle$, which is what we want.

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end

```
Multiclass perceptron using the multivector construction.
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           w \leftarrow w + \psi(x, y); // Move the scorer towards \psi(x, y)
w \leftarrow w - \psi(x, \hat{y}); // Move the scorer away from \psi(x, \hat{y})
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     end
```

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end

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Exercise: What is the base binary classification problem in multiclass perceptron?

Features

Toy multiclass example: Part-of-speech classification

- $\mathfrak{X} = \{ All \text{ possible words} \}$
- $y = \{NOUN, VERB, ADJECTIVE, ...\}.$

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How to construct the feature vector?

• Multivector construction: $w \in \mathbb{R}^{d \times k}$ —doesn't scale.

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How to construct the feature vector?

- Multivector construction: $w \in \mathbb{R}^{d \times k}$ —doesn't scale.
- Directly design features for each class.

$$\Psi(x,y) = (\psi_1(x,y), \psi_2(x,y), \psi_3(x,y), \dots, \psi_d(x,y))$$
 (7)

• Size can be bounded by d.

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- E.g., $\Psi(x = \text{run}, y = \text{NOUN}) = (0, 1, 0, 0, ...)$
- After training, what's w_1 , w_2 , w_3 , w_4 ?
- No need to include features unseen in training data.

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Feature templates: implementation

- Flexible, e.g., neighboring words, suffix/prefix.
- "Read off" features from the training data.
- Often sparse—efficient in practice, e.g., NLP problems.
- Can use a hash function: template $\rightarrow \{1, 2, ..., d\}$.

Review

Ingredients in multiclass classification:

- Scoring functions for each class (similar to ranking).
- Represent labels in the input space \implies single weight vector.

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We've seen

- How to generalize the perceptron algorithm to multiclass setting.
- Very simple idea. Was popular in NLP for structured prediction (e.g., tagging, parsing).

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Next,

- How to generalize SVM to the multiclass setting.
- Concept check: Why might one prefer SVM / perceptron?

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Margin for Multiclass

Binary • Margin for $(x^{(n)}, y^{(n)})$:

$$y^{(n)}w^Tx^{(n)} \tag{8}$$

• Want margin to be large and positive $(w^T x^{(n)})$ has same sign as $y^{(n)}$

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Margin for Multiclass

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$$y^{(n)}w^Tx^{(n)} \tag{8}$$

• Want margin to be large and positive ($w^T x^{(n)}$ has same sign as $y^{(n)}$)

Multiclass

• Class-specific margin for $(x^{(n)}, y^{(n)})$:

$$h(x^{(n)}, y^{(n)}) - h(x^{(n)}, y).$$
 (9)

- Difference between scores of the correct class and each other class
- Want margin to be large and positive for all $y \neq v^{(n)}$.

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Multiclass SVM: separable case

Binary

$$\min_{w} \quad \frac{1}{2} \|w\|^{2} \qquad (10)$$
s.t.
$$\underbrace{y^{(n)} w^{T} x^{(n)}}_{\text{margin}} \geqslant 1 \quad \forall (x^{(n)}, y^{(n)}) \in \mathcal{D} \qquad (11)$$

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Multiclass As in the binary case, take 1 as our target margin.

$$m_{n,y}(w) \stackrel{\text{def}}{=} \underbrace{\left\langle w, \Psi(x^{(n)}, y^{(n)}) \right\rangle}_{\text{score of correct class}} - \underbrace{\left\langle w, \Psi(x^{(n)}, y) \right\rangle}_{\text{score of other class}}$$
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s.t.
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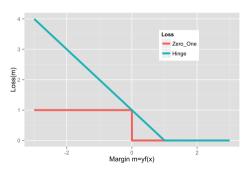
Exercise: write the objective for the non-separable case

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Recap: hingle loss for binary classification

• Hinge loss: a convex upperbound on the 0-1 loss

$$\ell_{\mathsf{hinge}}(y, \hat{y}) = \mathsf{max}(0, 1 - yh(x)) \tag{15}$$



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• What's the zero-one loss for multiclass classification?

(16)

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$$\Delta(y, y') = \mathbb{I}\left\{y \neq y'\right\} \tag{16}$$

• What's the zero-one loss for multiclass classification?

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• In general, can also have different cost for each class.

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Generalized hinge loss:

$$\ell_{\mathsf{hinge}}(y, x, w) \stackrel{\mathsf{def}}{=} \max_{y' \in \mathcal{Y}} \left(\Delta(y, y') - \left\langle w, \left(\Psi(x, y) - \Psi(x, y') \right) \right\rangle \right) \tag{20}$$

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Multiclass SVM with Hinge Loss

• Recall the hinge loss formulation for binary SVM (without the bias term):

$$\min_{w \in \mathbb{R}^d} \frac{1}{2} ||w||^2 + C \sum_{n=1}^N \max \left(0, 1 - \underbrace{y^{(n)} w^T x^{(n)}}_{\text{margin}} \right).$$

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• The multiclass objective:

$$\min_{w \in \mathbb{R}^d} \frac{1}{2} ||w||^2 + C \sum_{n=1}^N \max_{y' \in \mathcal{Y}} \left(\Delta(y, y') - \underbrace{\left\langle w, \left(\Psi(x, y) - \Psi(x, y') \right) \right\rangle}_{\text{margin}} \right)$$

- $\Delta(y, y')$ as target margin for each class.
- If margin $m_{n,y'}(w)$ meets or exceeds its target $\Delta(y^{(n)},y') \ \forall y \in \mathcal{Y}$, then no loss on example n.

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