


Fall



Cost: reduce force on hand.

Free gravity

C₁: Left knee and right knee position

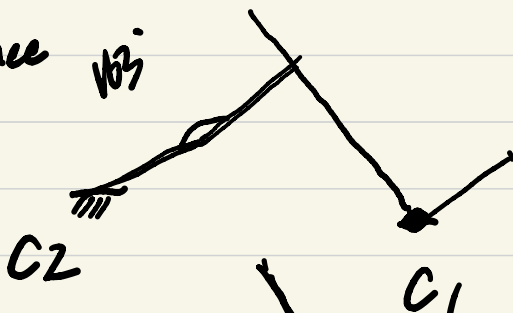
fix knee joint

C₂: Left hand position

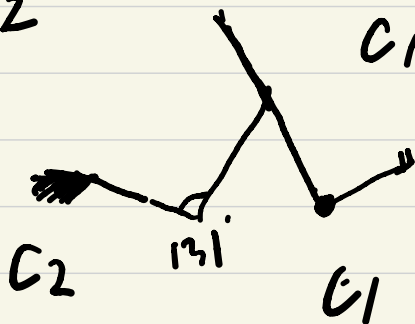
Right knee pos

4 constraints
friction.
knee joint
lock
constraint

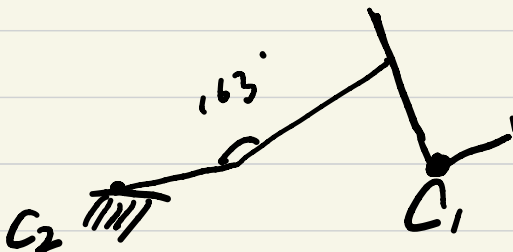
1.



2.



3.



Cost: ① reduce force on hand

② rotate the torso along longitudinal axis

③ leg trajectory (left)

④ hand trajectory (left)

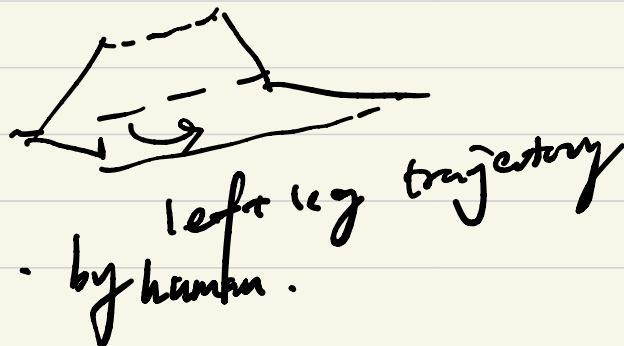
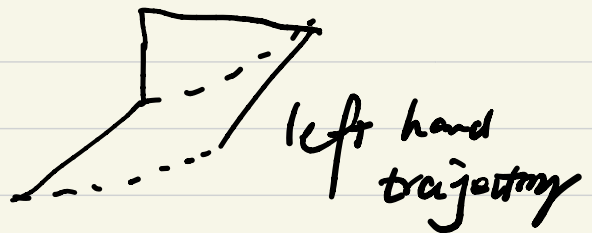
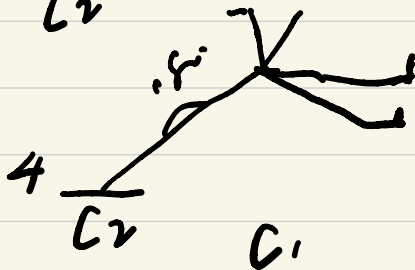
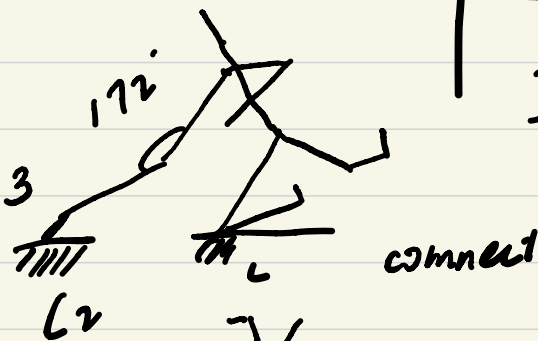
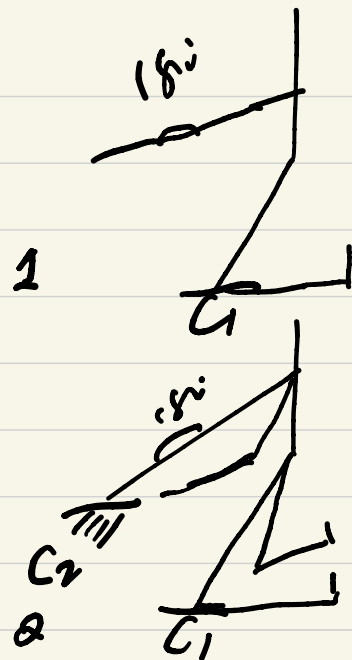
C_1 : right knee

C_2 : right hand

fracture point SE(3)

C_1 , C_2 position constraint

friction constraints



Generate ... by hand.

Plan

1. Attach 4 points on ODF

2. Check API

force cost

position constraint

rotation cost

position cost

3. Write code } Optimization

4. Test

5. Simulation

6. Test bed

7. Experiment

8. Paper