# Roman Niukhalov

+61 403999482 r.nyukhalov@gmail.com

# **Employment**

## **Software Engineer**

## Canva (Australia)

Nov 2021 – Present

• Developing core libraries and tools to enable secure and efficient communication between microservices.

#### **Senior Software Engineer**

# nuTonomy/Aptiv/Motional (Singapore)

Aug 2019 – Aug 2021

- Developed services, data pipelines and mapping software for creating High-Definition maps.
- Increased the speed of creating maps by automating the most time-consuming manual operations.

### **Software Engineer**

## Agoda (Thailand)

Jun 2017 - Aug 2019

- Reduced the end-to-end time of updating hotels' prices from several minutes to tens of seconds by re-designing and optimizing internal services.
- Reduced the load on the internal monitoring system by more than 1000% by aggregating measurements on clients before sending them to the system.

# **Software Engineer**

## **DG-Soft (Russia)**

Dec 2015 - Jun 2017

- Created an automated pipeline for importing geodata from OpenSteetMap to internal storage.
- Created a geosearch API for querying geodata features by a feature class and a bounding box.

## **Software Engineer**

# **Center of Financial Technologies (Russia)**

**Apr 2013 – Dec 2015** 

- Developed a library for performing contactless payments using Android Host-base Card Emulation.
- Developed firmware for Point-of-Sale (POS) terminals.
- Reduced release cycle time by developing an automated testing framework.

#### **Education**

### Udacity

**Summer 2018 – Winter 2019** 

- Self-Driving Car Engineer Nanodegree Program.
- Coursework: Computer Vision; Sensor Fusion; Localization; Motion Control; Path Planner.

#### Novosibirsk, Russia

### **Novosibirsk State Technical University**

**Fall 2007 – Summer 2011** 

- B.S.E. in Applied Mathematics and Computer Science, June 2011.
- Undergraduate Coursework: Operating Systems; Databases; Algorithms; Programming Languages; Comp. Architecture; Linear Algebra; Calculus.

# **Technical Experience**

## **Course Projects**

- Advanced Lane Finding (2018). A software pipeline to identify the lane boundaries in a video. The pipeline consists of several computer vision techniques such as color and gradient thresholding.
- **Traffic Sign Recognition** (2018). A convolutional neural network for classifying traffic sign images using the German Traffic Sign Dataset.
- **Behavioral Cloning** (2018). A convolutional neural network for predicting the steering angle of the simulated vehicle by images from its camera.
- Extended Kalman Filter (2018). Kalman Filter implementation to estimate the state of a moving object of interest with noisy lidar and radar measurements.
- **Highway Driving** (2019). A behaviour planning program to safely navigate the simulated car around a virtual highway with other traffic.

# **Languages and Technologies**

• Java; Scala; Python3; C++; C; C#; PostgreSQL; Cassandra; Couchbase; Kafka; Docker; Docker Compose; Kubernetes; AWS; Terraform; Jenkins, Gitlab CI, Teamcity, Bamboo, GitHub, Bitbucket