Machine Learning, Spring 2019

Interpretable classification (and regression) using Decision Trees

Reading Assignment: Chapter 6 & 7

Python tutorial: http://learnpython.org/

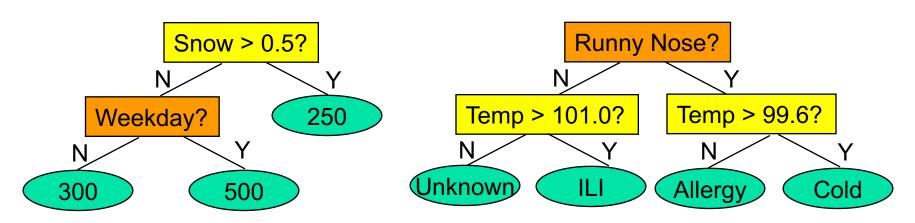
TensorFlow tutorial: https://www.tensorflow.org/tutorials/

PyTorch tutorial: https://pytorch.org/tutorials/

Acknowledge: The slides are partially referred to coursera online machine learning course by Prof. Andrew Ng, and NYU machine learning course. All copyrights owned by original authors. (i.e. http://u.cs.biu.ac.il/~89-570/)

Rule-based learning with decision trees

- A <u>decision tree</u> is a set of rules that can be learned from data and used to predict an unknown value.
 - Unknown real value (regression): What is the expected incidence of car thefts in NYC on a given day?
 - Unknown category value (classification): What type of illness does patient X have, given their symptoms and demographic data?



How many thefts on Tuesday, January 3 (0.2 inches of snow)?

What do we predict for a patient with Temp = 100 and a runny nose?

Example dataset:

Predicting whether a car is fuel-efficient, given its number of cylinders (4, 6, or 8), weight (light, medium, or heavy), and horsepower (real-valued).

MPG, cylinders, HP, weight

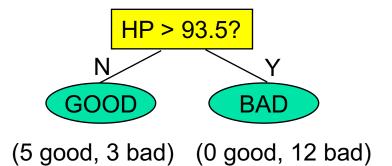
 Step 1: Start with all data points in a single node.
 Predict the most common value (classification) or mean value (regression).



MPG, cylinders, HP, weight

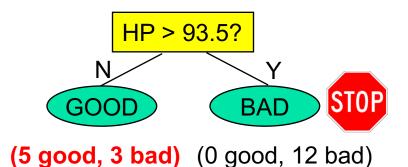
good, 4, 75, light

- Step 1: Start with all data points in a single node.
 Predict the most common value (classification) or mean value (regression).
- Step 2: Choose the "best" binary decision rule, and use it to split the data into two groups.



MPG, cylinders, HP, weight

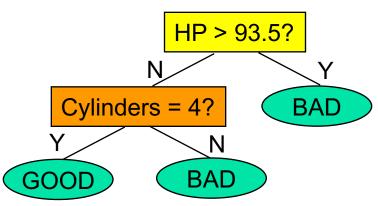
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MPG, cylinders, HP, weight

good, 4, 75, light

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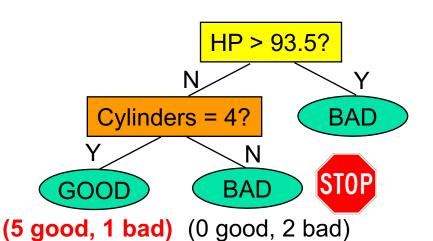
(5 good, 1 bad) (0 good, 2 bad)

good, 4, 75, light bad, 6, 90, medium bad, 4, 110, medium bad, 8, 175, weighty bad, 6, 95, medium bad, 4, 94, light bad, 4, 95, light bad, 8, 139, weighty bad, 8, 190, weighty bad, 8, 145, weighty bad, 6, 100, medium good, 4, 92, medium bad, 6, 100, weighty bad, 8, 170, weighty good, 4, 89, medium good, 4, 65, light bad, 6, 85, medium bad, 4, 81, light bad, 6, 95, medium

good, 4, 93, light

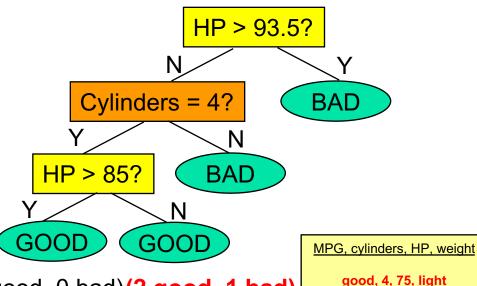
MPG, cylinders, HP, weight

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MPG, cylinders, HP, weight

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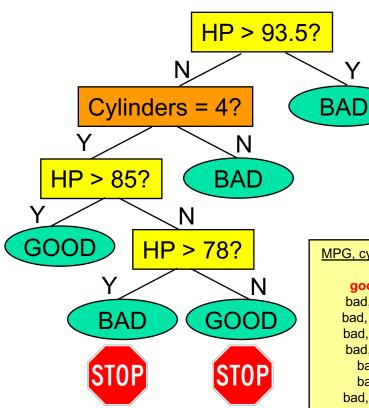
(3 good, 0 bad)(2 good, 1 bad)

STOP .

bad, 6, 90, medium bad, 4, 110, medium bad, 8, 175, weighty bad, 6, 95, medium bad, 4, 94, light bad, 4, 95, light bad, 8, 139, weighty bad, 8, 190, weighty bad, 8, 145, weighty bad, 6, 100, medium good, 4, 92, medium bad, 6, 100, weighty bad, 8, 170, weighty good, 4, 89, medium good, 4, 65, light bad, 6, 85, medium bad, 4, 81, light

bad, 6, 95, medium good, 4, 93, light

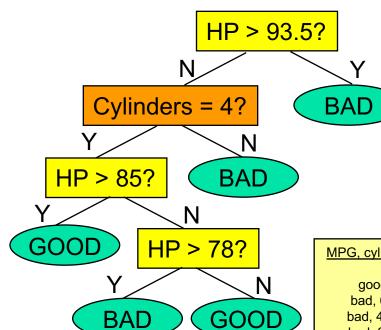
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MPG, cylinders, HP, weight

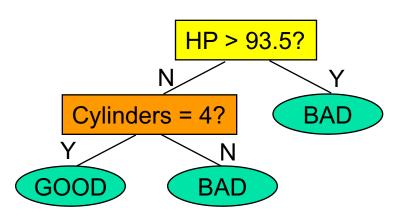
- Step 1: Start with all data points in a single node. Predict the most common value (classification) or mean value (regression).
- Step 2: Choose the "best" binary decision rule, and use it to split the data into two groups.
- Step 3: Repeat step 2 on each group, until some stopping criterion is reached.
 - All outputs same?
 - All inputs same?

bad, 4, 81, light good, 4, 81, light



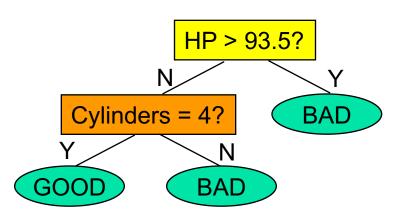
MPG, cylinders, HP, weight

- Step 1: Start with all data points in a single node. Predict the most common value (classification) or mean value (regression).
- Step 2: Choose the "best" binary decision rule, and use it to split the data into two groups.
- Step 3: Repeat step 2 on each group, until some stopping criterion is reached.
- Step 4: Prune the tree to remove irrelevant rules.



MPG, cylinders, HP, weight

- Step 1: Start with all data points in a single node. Predict the most common value (classification) or mean value (regression).
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- Step 3: Repeat step 2 on each group, until some stopping criterion is reached.
- Step 4: Prune the tree to remove irrelevant rules.



Question 1: How to choose the best decision rule for a given node?

Question 2: How to prune the tree (and why bother?)

MPG, cylinders, HP, weight

- We can use any input attribute to split.
 - <u>If discrete</u>: choose a class, split into = and ≠.
 - If real: choose a threshold, split into > and ≤.
- To choose a threshold for a real attribute: sort the values, and use midpoints.

<u>Split</u>	Group Y	Group N
Cylinders = 4?	5+ / 4-	0+ / 11-
Cylinders = 6?	0+ / 6-	5+ / 9-
Cylinders = 8?	0+ / 5-	5+ / 10-
HP > 78?	2+ / 0-	3+ / 15-
HP > 87?	2+ / 2-	3+ / 13-
HP > 89.5?	3+ / 2-	2+ / 13-
HP > 91?	3+/3-	2+ / 12-
HP > 93.5?	5+/3-	0+ / 12-
Weight = light?	3+/3-	2+ / 12-
Weight = medium?	2+ / 6-	3+ / 9-
Weight = heavy?	0+ / 6-	5+ / 9-

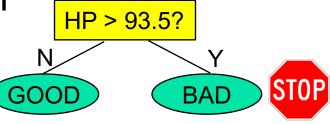
good, 4, 75, light bad, 6, 90, medium bad, 4, 110, medium bad, 8, 175, weighty bad, 6, 95, medium bad, 4, 94, light bad, 4, 95, light bad, 8, 139, weighty bad, 8, 190, weighty bad, 8, 145, weighty bad, 6, 100, medium good, 4, 92, medium bad, 6, 100, weighty bad, 8, 170, weighty good, 4, 89, medium good, 4, 65, light bad, 6, 85, medium bad, 4, 81, light bad, 6, 95, medium good, 4, 93, light

MPG, cylinders, HP, weight

- We can use any input attribute to split.
 - If discrete: choose a class, split into = and ≠.
 - If real: choose a threshold, split into > and ≤.
- To choose a threshold for a real attribute: sort the values, and use midpoints.
- Choose the split with highest information gain.

<u>Split</u>	Group Y	Group N	<u>Gain</u>
Cylinders = 4?	5+ / 4-	0+ / 11-	0.365
Cylinders = 6?	0+ / 6-	5+ / 9-	0.153
Cylinders = 8?	0+ / 5-	5+ / 10-	0.123
HP > 78?	2+ / 0-	3+ / 15-	0.226
HP > 87?	2+ / 2-	3+ / 13-	0.054
HP > 89.5?	3+ / 2-	2+ / 13-	0.144
HP > 91?	3+/3-	2+ / 12-	0.097
HP > 93.5?	5+ / 3-	0+ / 12-	0.430
Weight = light?	3+/3-	2+ / 12-	0.097
Weight = medium?	2+ / 6-	3+ / 9-	0.000
Weight = heavy?	0+ / 6-	5+ / 9-	0.153

 We repeat this process for each non-terminal node of the tree.



(5 good, 3 bad) (0 good, 12 bad)

<u>Split</u>	Group Y	Group N	<u>Gain</u>
Cylinders = 4?	5+ / 1-	0+ / 2-	0.467
HP > 78?	2+ / 0-	3+/3-	0.204
HP > 87?	2+ / 2-	3+ / 1-	0.049
HP > 89.5?	3+ / 2-	2+ / 1-	0.003
HP > 91?	3+ / 3-	2+ / 0-	0.204
Weight = light?	3+ / 1-	2+ / 2-	0.049

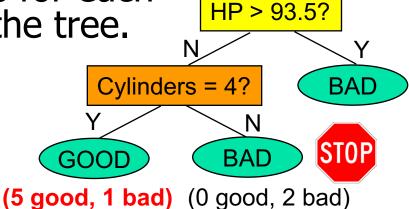
bad, 6, 90, medium bad, 4, 110, medium bad, 8, 175, weighty bad, 6, 95, medium bad, 4, 94, light bad, 4, 95, light bad, 8, 139, weighty bad, 8, 190, weighty bad, 8, 145, weighty bad, 6, 100, medium good, 4, 92, medium bad, 6, 100, weighty

bad, 8, 170, weighty good, 4, 89, medium good, 4, 65, light bad, 6, 85, medium bad, 4, 81, light bad, 6, 95, medium good, 4, 93, light

MPG, cylinders, HP, weight

good, 4, 75, light

 We repeat this process for each non-terminal node of the tree.



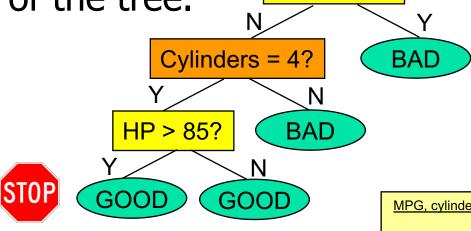
<u>Split</u>	Group Y	Group N	<u>Gain</u>
HP > 78?	3+ / 1-	2+ / 0-	0.109
HP > 85?	3+ / 0-	2+ / 1-	0.191
Weight = light?	3+ / 1-	2+ / 0-	0.109

good, 4, 75, light bad, 6, 90, medium bad, 4, 110, medium bad, 8, 175, weighty bad, 6, 95, medium bad, 4, 94, light bad, 4, 95, light bad, 8, 139, weighty bad, 8, 190, weighty bad, 8, 145, weighty bad, 6, 100, medium good, 4, 92, medium bad, 6, 100, weighty bad, 8, 170, weighty good, 4, 89, medium good, 4, 65, light bad, 6, 85, medium bad, 4, 81, light bad, 6, 95, medium

good, 4, 93, light

MPG, cylinders, HP, weight

 We repeat this process for each non-terminal node of the tree.



HP > 93.5?

(3 good, 0 bad)(2 good, 1 bad)

<u>Split</u>	<u>Group Y</u>	<u>Group N</u>	<u>Gain</u>
HP > 78?	0+ / 1-	2+ / 0-	0.918

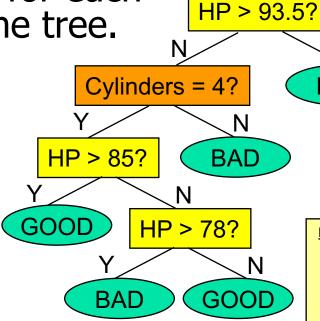
MPG, cylinders, HP, weight

 We repeat this process for each non-terminal node of the tree.

Information gain is an informationtheoretic measure of how well the split separates the data.

It can be computed as a function of the numbers of + and – examples in each group.

Group Y Group N
A+ / B- C+ / D-



MPG, cylinders, HP, weight

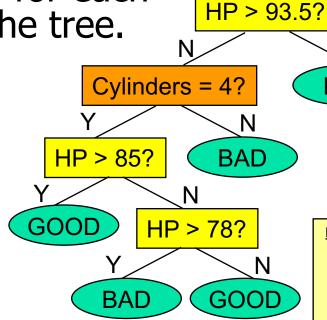
BAD

 We repeat this process for each non-terminal node of the tree.

Information gain is an informationtheoretic measure of how well the split separates the data.

It can be computed as a function of the numbers of + and – examples in each group.

$$Gain = \frac{F((A+C),(B+D)) - F(A,B) - F(C,D)}{A+B+C+D}$$
 where:
$$F(X,Y) = Xlog_2 \frac{X+Y}{X} + Ylog_2 \frac{X+Y}{Y}$$



MPG, cylinders, HP, weight

BAD

good, 4, 75, light bad, 6, 90, medium bad, 4, 110, medium bad, 8, 175, weighty bad, 6, 95, medium bad, 4, 94, light bad, 4, 95, light bad, 8, 139, weighty bad, 8, 190, weighty bad, 8, 145, weighty bad, 6, 100, medium good, 4, 92, medium bad, 6, 100, weighty bad, 8, 170, weighty good, 4, 89, medium good, 4, 65, light bad, 6, 85, medium bad, 4, 81, light bad, 6, 95, medium good, 4, 93, light

(You don't have to memorize this formula.)

 We repeat this process for each non-terminal node of the tree.

Information gain is an informationtheoretic measure of how well the split separates the data.

It can be computed as a function of the numbers of + and – examples in each group.

Group Y	Group N	<u>Gain</u>
3+ / 1-	6+ / 2-	0.000
8+ / 1-	1+ / 2-	0.204
9+ / 0-	0+/3-	0.811

Cylinders = 4?

Y

HP > 85?

BAD

GOOD

HP > 78?

N

BAD

GOOD

HP > 93.5?

Intuitively, the information gain is large when the proportions of positive examples in the two groups are very different, and zero when they are the same.

MPG, cylinders, HP, weight

BAD

Mathematical formulation

From http://scikit-learn.org/stable/modules/tree.html

Given training vectors x_i and a label vector y. Let data at tree node m be represented by Q.

$$x_i \in R^n \qquad y \in R^l$$

Consider a set of candidate binary splits, each consisting of a feature j and threshold t_m, and partitioning Q into subsets Q_{left} and Q_{right}.

$$\theta = (j, t_m)$$

$$Q_{left}(\theta) = (x, y)|x_j <= t_m$$

$$Q_{right}(\theta) = Q \setminus Q_{left}(\theta)$$

Select the split that minimizes the average impurity of Q_{left} and Q_{right}, and recurse.

$$\begin{split} \theta^* &= \operatorname{argmin}_{\theta} G\big(Q, \theta\big) \\ G(Q, \theta) &= \frac{n_{left}}{N_m} H(Q_{left}(\theta)) + \frac{n_{right}}{N_m} H(Q_{right}(\theta)) \end{split}$$

For classification, use *cross-entropy.* (p_{mk} are class proportions at node m).

$$p_{mk} = 1/N_m \sum_{x_i \in R_m} I(y_i = k)$$

$$H(X_m) = -\sum_{k} p_{mk} \log(p_{mk})$$

For regression, use *mean squared error* (c_m is the mean at node m).

$$c_m = \frac{1}{N_m} \sum_{i \in N_m} y_i$$

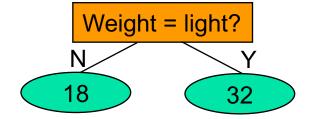
$$H(X_m) = \frac{1}{N_m} \sum_{i \in N_m} (y_i - c_m)^2$$

• If we are trying to predict a real-valued attribute (i.e. doing regression), minimize the sum of squared errors instead of maximizing information gain.

MPG, cylinders, HP, weight

32, 4, 75, light 20, 6, 95, medium 20, 4, 115, medium 14, 6, 95, medium

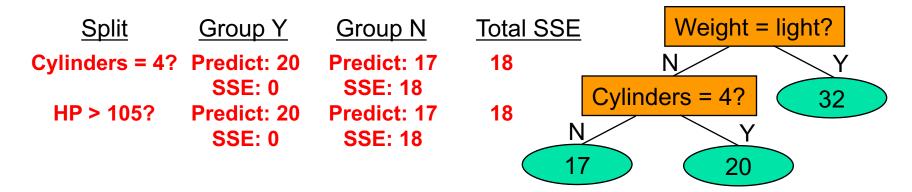
<u>Split</u>	Group Y	Group N	Total SSE
Cylinders = 4?	Predict: 26 SSE: 72	Predict: 17 SSE: 18	90
Weight = light?	Predict: 32 SSE: 0	Predict: 18 SSE: 24	24
HP > 85?	Predict: 18 SSE: 24	Predict: 32 SSE: 0	24
HP > 105?	Predict: 20 SSE: 0	Predict: 22 SSE: 168	168



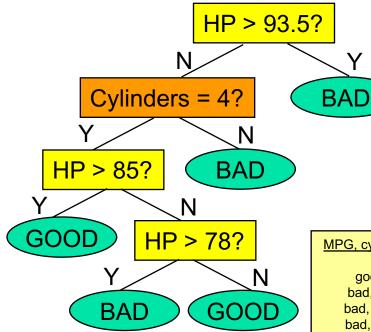
 If we are trying to predict a real-valued attribute (i.e. doing regression), minimize the sum of squared errors instead of maximizing information gain.

MPG, cylinders, HP, weight

32, 4, 75, light 20, 6, 95, medium 20, 4, 115, medium 14, 6, 95, medium



- Notice that the unpruned decision tree classifies every training example perfectly.
- This will always be the case (unless there are records with the same input values and different output values, as in the regression example).
- Does this mean we've found the best tree?



What we really want to know:
How well does this classifier predict values
for new data that we haven't already seen?

MPG, cylinders, HP, weight

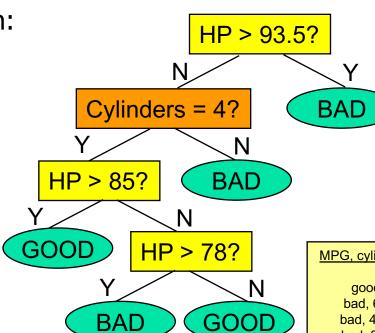
- One way to answer this question:
 - Hide part of your data (the "test set").
 - Learn a tree using the rest of the data (the "training set").
 - See what proportion of the test set is classified correctly.
- Consider <u>pruning</u> each node to see if it reduces test set error.

<u>Training set (20 examples):</u> 100% correct, 0% incorrect

<u>Test set (100 examples):</u>

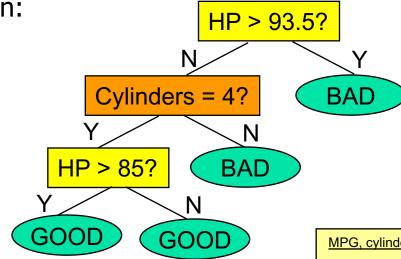
86% correct, 14% incorrect

What we really want to know: How well does this classifier predict values for new data that we haven't already seen?



MPG, cylinders, HP, weight

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Training set (20 examples):

95% correct, 5% incorrect

Test set (100 examples):

89% correct, 11% incorrect

What we really want to know:
How well does this classifier predict values
for new data that we haven't already seen?

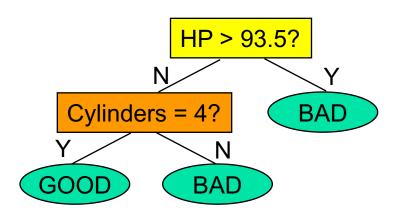
MPG, cylinders, HP, weight

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MPG, cylinders, HP, weight

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HP > 93.5?

N

Cylinders = 4?

BAD

N

GOOD

BAD

Training set (20 examples): 95% correct, 5% incorrect

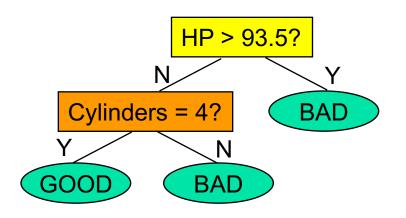
Test set (100 examples): 89% correct, 11% incorrect

If we pruned Cylinders = 4, test set error would increase to 16%, so stop here!

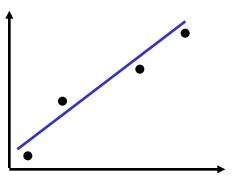
What we really want to know:
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MPG, cylinders, HP, weight

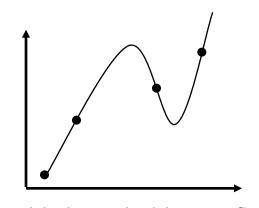
- Q: Why does pruning the tree reduce test set error?
- A: Because the unpruned tree was <u>overfitting</u> the training data (paying attention to parts of the data that are not relevant for prediction).



Here's another example of overfitting, this time for regression:



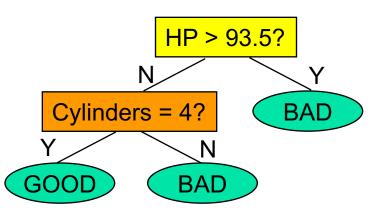
A line fits pretty well...



A cubic is probably overfitting.

MPG, cylinders, HP, weight

- Q: What if we don't have enough data points?
- A: Another way to prevent overfitting is to do a certain kind of significance test (chi-squared) for each node, and prune any nodes that are not significant.

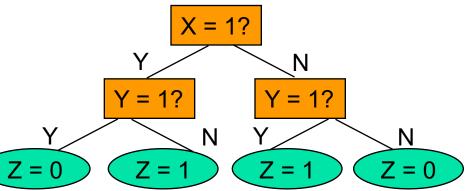


MPG, cylinders, HP, weight

- Q: Why bother building the whole tree, if we're just going to prune it?
- A: We could do significance testing while building the tree, but for many datasets, post-pruning gives better performance.

Consider the XOR function:

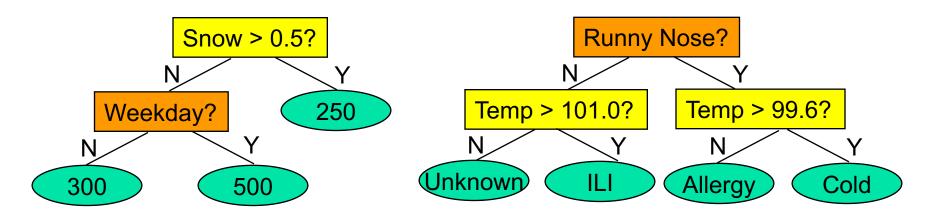
<u>X</u>	<u>Y</u>	<u>Z</u>
0	0	0
0	1	1
1	0	1
1	1	0



Each second level split has high information gain. The first level split has no information gain but is needed to make the second level splits possible.

Some advantages of decision trees

- Easy to learn the tree automatically from a dataset.
- Very easy to predict the target value given the tree.
- Generally good classification performance (though some fancier methods may do better, depending on the dataset).
- Can do both classification and regression, and can use both real and discrete inputs.
- Gives an idea of which variables are important in predicting the target value.
 - More important variables tend to be toward the top of the tree.
 - Unimportant variables are not included.



When to use decision trees?

- We have a dataset, with some attribute we want to <u>predict</u>.
 - We can do either classification or regression.
 - Datasets with lots of attributes, and/or lots of records, are okay. But if lots of attributes and not that many records, should probably use feature selection first to avoid overfitting.
 - Datasets with discrete or real values, or both, are okay.
- We want to be able to <u>explain</u> our prediction using a simple and interpretable set of rules.
 - We want to distinguish relevant from irrelevant attributes.
 - We want to provide a set of decision steps (e.g. "expert system" for medical diagnosis, don't want to perform irrelevant tests).
 - If all we care about is prediction accuracy and not interpretability, we might want to use some "black box" classifier instead (e.g. neural network, support vector machine).
- Can represent complex, non-linear functions.
- Performance is better when a tree structure makes sense.

References

- For next time: read Python documentation at <u>http://scikit-learn.org/stable/modules/tree.html</u>
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