Graph theory and the Graph ADT

Outline

A graph is an abstract data type for storing adjacency relations

- We start with definitions:
 - Vertices, edges, degree and sub-graphs
- We will describe paths in graphs
 - Simple paths and cycles
- Definition of connectedness
- Weighted graphs
- We will then reinterpret these in terms of directed graphs
- Directed acyclic graphs

Outline

We will define an Undirected Graph ADT as a collection of *vertices*

$$V = \{v_1, v_2, ..., v_n\}$$

The number of vertices is denoted by

$$|V| = n$$

- Associated with this is a collection E of <u>unordered</u> pairs $\{v_i, v_j\}$ termed edges which connect the vertices

There are a number of data structures that can be used to implement abstract undirected graphs

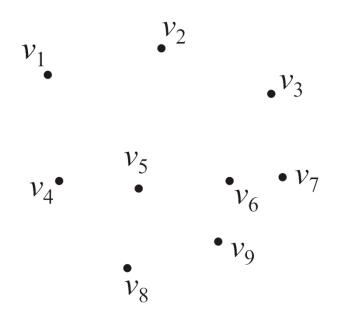
- Adjacency matrices
- Adjacency lists

Graphs

Consider this collection of vertices

$$V = \{v_1, v_2, ..., v_9\}$$

where |V| = n

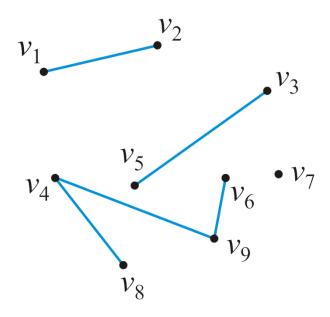


Undirected graphs

Associated with these vertices are |E| = 5 edges

$$E = \{\{v_1, v_2\}, \{v_3, v_5\}, \{v_4, v_8\}, \{v_4, v_9\}, \{v_6, v_9\}\}$$

- The pair $\{v_j, v_k\}$ indicates that both vertex v_j is adjacent to vertex v_k and vertex v_k is adjacent to vertex v_j



Undirected graphs

We will assume in this course that a vertex is never adjacent to itself

- For example, $\{v_1, v_1\}$ will not define an edge

The maximum number of edges in an undirected graph is

$$|E| \le {|V| \choose 2} = \frac{|V|(|V|-1)}{2} = O(|V|^2)$$

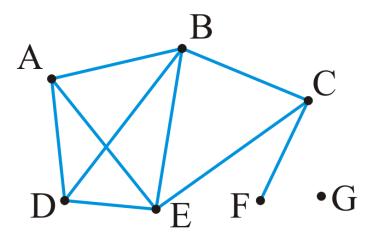
An undirected graph

Example: given the |V| = 7 vertices

$$V = \{A, B, C, D, E, F, G\}$$

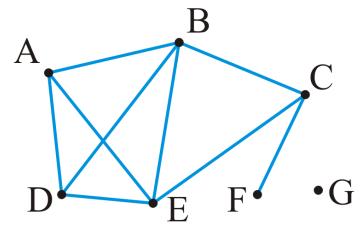
and the |E| = 9 edges

$$E = \{\{A, B\}, \{A, D\}, \{A, E\}, \{B, C\}, \{B, D\}, \{B, E\}, \{C, E\}, \{C, F\}, \{D, E\}\}\}$$



Degree

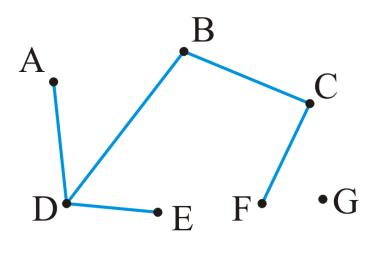
The degree of a vertex is defined as the number of adjacent vertices

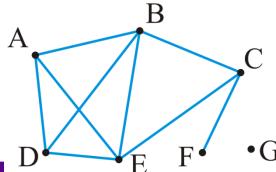


Those vertices adjacent to a given vertex are its *neighbors*

Sub-graphs

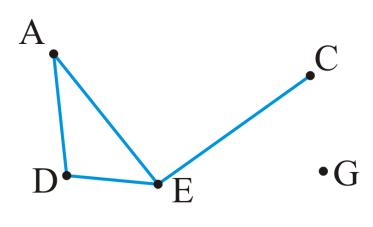
A *sub-graph* of a graph a subset of the vertices and a subset of the edges that connected the subset of vertices in the original graph

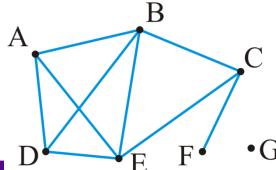




Vertex-induced sub-graphs

A *vertex-induced sub-graph* is a subset of a the vertices where the edges are all edges in the original graph that originally





A path in an undirected graph is an ordered sequence of vertices

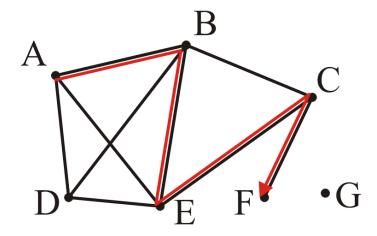
$$(v_0, v_1, v_2, ..., v_k)$$

where $\{v_{j-1}, v_j\}$ is an edge for j = 1, ..., k

- Termed a path from v_0 to v_k
- The length of this path is k

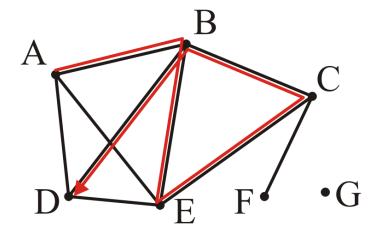
A path of length 4:

(A, B, E, C, F)



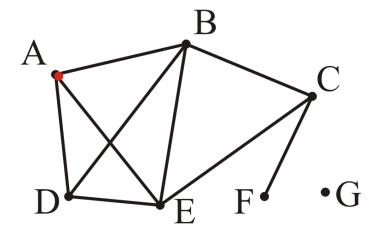
A path of length 5:

(A, B, E, C, B, D)



A trivial path of length 0:

(A)

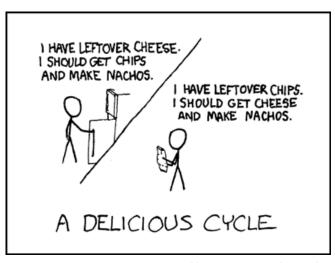


Simple paths

A *simple path* has no repetitions other than perhaps the first and last vertices

A simple cycle is a simple path of at least two vertices with the first and last vertices equal

Note: these definitions are not universal

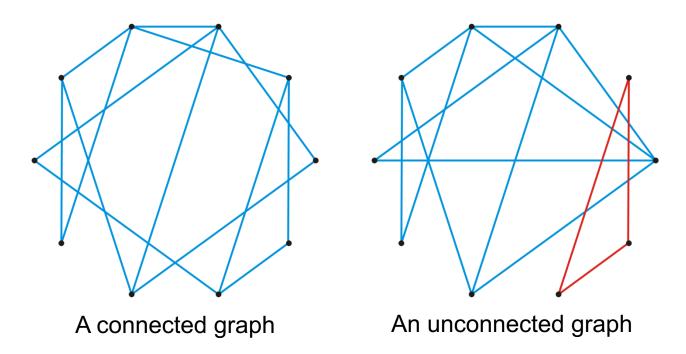


http://xkcd.com/140/

Connectedness

Two vertices v_i , v_j are said to be *connected* if there exists a path from v_i to v_j

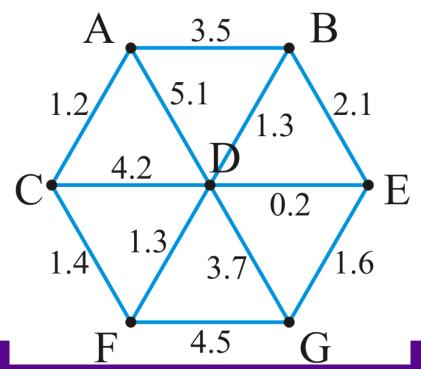
A graph is connected if there exists a path between any two vertices



A weight may be associated with each edge in a graph

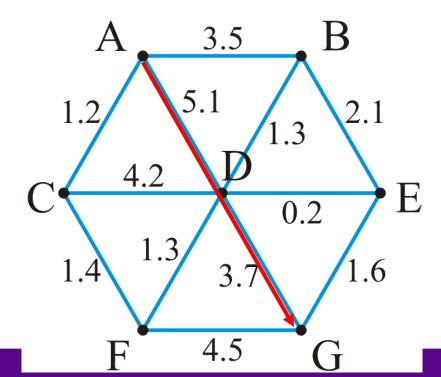
- This could represent distance, energy consumption, cost, etc.
- Such a graph is called a weighted graph

Pictorially, we will represent weights by numbers next to the edges



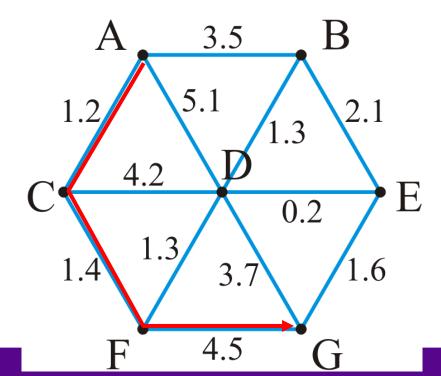
The *length* of a path within a weighted graph is the sum of all of the edges which make up the path

- The length of the path (A, D, G) in the following graph is 5.1 + 3.7 = 8.8



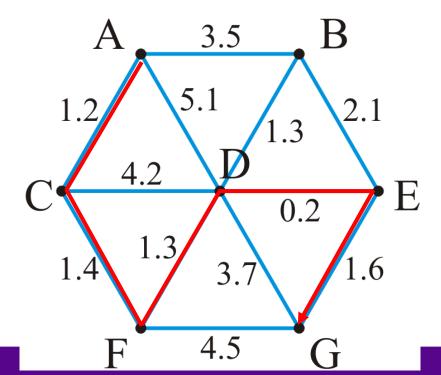
Different paths may have different weights

- Another path is (A, C, F, G) with length 1.2 + 1.4 + 4.5 = 7.1



Problem: find the shortest path between two vertices

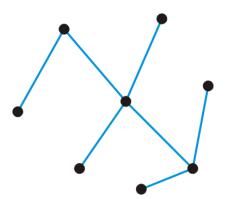
- Here, the shortest path from A to H is (A, C, F, D, E, G) with length 5.7

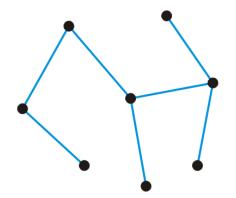


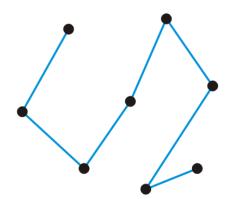
Trees

A graph is a tree if it is connected and there is a unique path between any two vertices

Three trees on the same eight vertices







Consequences:

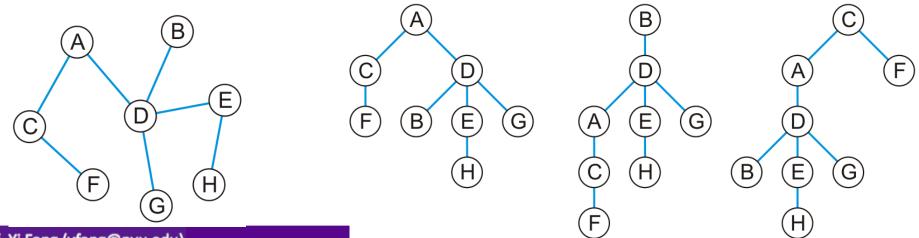
- The number of edges is |E| = |V| 1
- The graph is *acyclic*, that is, it does not contain any cycles
- Adding one more edge must create a cycle
- Removing any one edge creates two disjoint non-empty sub-graphs

Trees

Any tree can be converted into a rooted tree by:

- Choosing any vertex to be the root
- Defining its neighboring vertices as its children and then recursively defining:
- All neighboring vertices other than that one designated its parent are now defined to be that vertices children

Given this tree, here are three rooted trees associated with it



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Forests

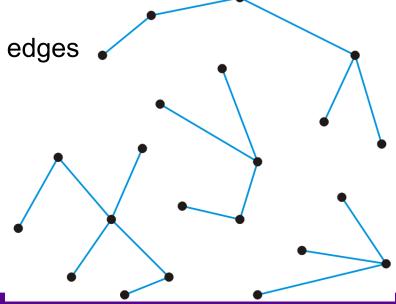
A forest is any graph that has no cycles

Consequences:

- The number of edges is |E| < |V|
- The number of trees is |V| |E|
- Removing any one edge adds one more tree to the forest

Here is a forest with 22 vertices and 18 edges

There are four trees



Directed graphs

In a *directed graph*, the edges on a graph are be associated with a direction

- Edges are ordered pairs (v_j, v_k) denoting a connection from v_j to v_k
- The edge (v_i, v_k) is different from the edge (v_k, v_j)

Streets are directed graphs:

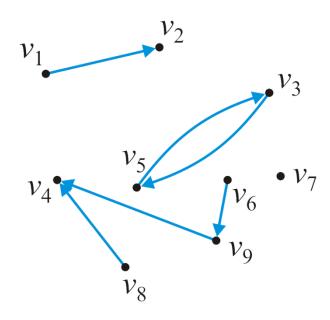
In most cases, you can go two ways unless it is a one-way street

Directed graphs

Given our graph of nine vertices $V = \{v_1, v_2, ... v_9\}$

- These six pairs (v_i, v_k) are directed edges

$$E = \{(v_1, v_2), (v_3, v_5), (v_5, v_3), (v_6, v_9), (v_8, v_4), (v_9, v_4)\}$$



Directed graphs

The maximum number of directed edges in a directed graph is

$$|E| \le 2 {|V| \choose 2} = 2 \frac{|V|(|V|-1)}{2} = |V|(|V|-1) = O(|V|^2)$$

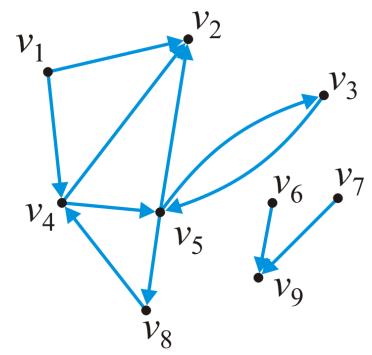
In and out degrees

The degree of a vertex must be modified to consider both cases:

- The out-degree of a vertex is the number of vertices which are adjacent to the given vertex
- The *in-degree* of a vertex is the number of vertices which this vertex is adjacent to

In this graph:

in_degree
$$(v_1) = 0$$
 out_degree $(v_1) = 2$
in_degree $(v_5) = 2$ out_degree $(v_5) = 3$



Sources and sinks

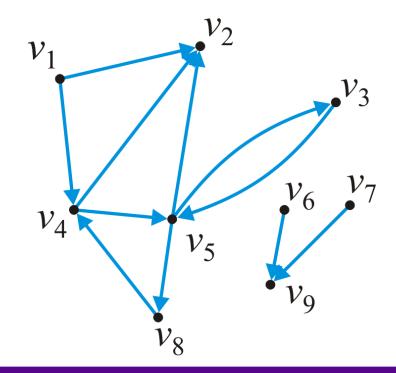
Some definitions:

- Vertices with an in-degree of zero are described as sources
- Vertices with an out-degree of zero are described as sinks

In this graph:

- Sources: v_1 , v_6 , v_7

- Sinks: v_2 , v_9



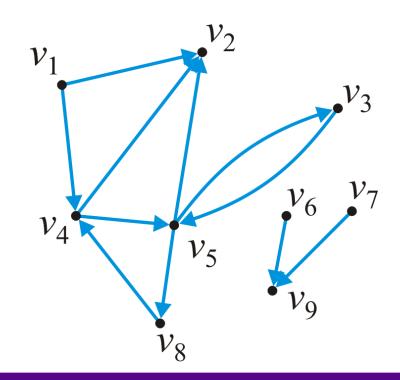
A path in a directed graph is an ordered sequence of vertices

$$(v_0, v_1, v_2, ..., v_k)$$

where (v_{j-1}, v_j) is an edge for j = 1, ..., k

A path of length 5 in this graph is $(v_1, v_4, v_5, v_3, v_5, v_2)$

A simple cycle of length 3 is (v_8, v_4, v_5, v_8)



Connectedness

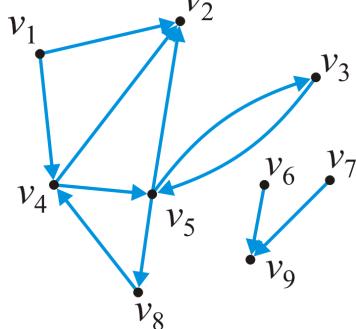
Two vertices v_j , v_k are said to be *connected* if there exists a path from v_j to v_k

 A graph is strongly connected if there exists a directed path between any two vertices

A graph is weakly connected there exists a path between any two vertices that ignores the direction

In this graph:

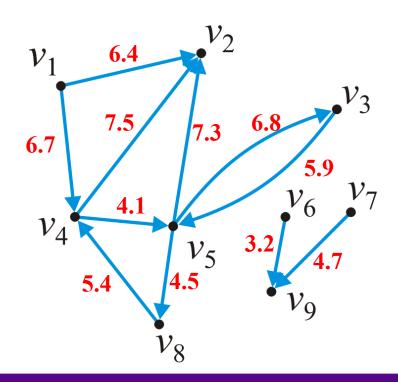
- The sub-graph {v₃, v₄, v₅, v₈} is strongly connected
- The sub-graph {v₁, v₂, v₃, v₄, v₅, v₈} is weakly connected



Weighted directed graphs

In a weighted directed graphs, each edge is associated with a value

Unlike weighted undirected graphs, if both (v_j, v_k) and (v_j, v_k) are edges, it is not required that they have the same weight

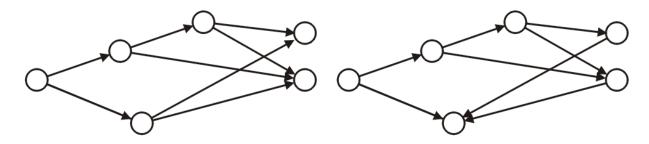


Directed acyclic graphs

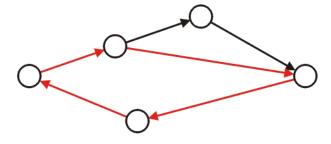
A directed acyclic graph is a directed graph which has no cycles

- These are commonly referred to as DAGs
- They are graphical representations of partial orders on a finite number of elements

These two are DAGs:



This directed graph is not acyclic:



Directed acyclic graphs

Applications of directed acyclic graphs include:

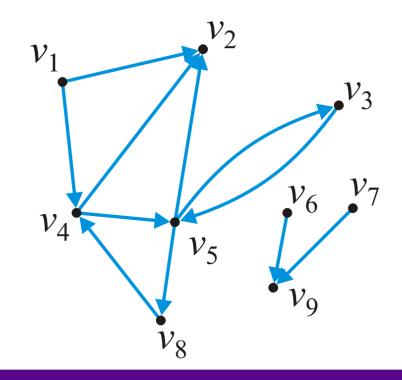
- The parse tree constructed by a compiler
- A reference graph that can be garbage collected using simple reference counting
- Dependency graphs such as those used in instruction scheduling and makefiles
- Dependency graphs between classes formed by inheritance relationships in object-oriented programming languages
- Information categorization systems, such as folders in a computer
- Directed acyclic word graph data structure to memory-efficiently store a set of strings (words)

Reference: http://en.wikipedia.org/wiki/Directed acyclic graph

Representations

How do we store the adjacency relations?

- Binary-relation list
- Adjacency matrix
- Adjacency list

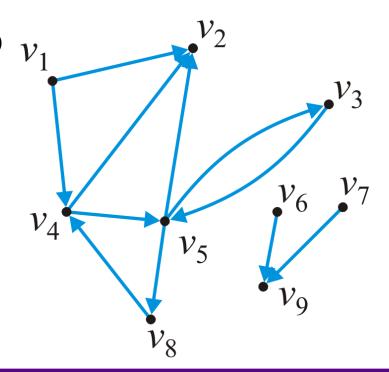


Binary-relation list

The most inefficient is a relation list:

A container storing the edges
 {(1, 2), (1, 4), (3, 5), (4, 2), (4, 5), (5, 2), (5, 3), (5, 8), (6, 9), (7, 9), (8, 4)}

- Requires $\Theta(|E|)$ memory
- Determining if v_j is adjacent to v_k is O(|E|)
- Finding all neighbors of v_i is $\Theta(|E|)$

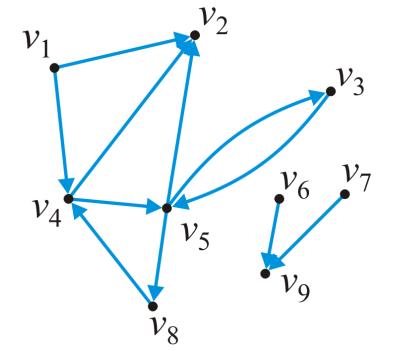


Adjacency matrix

Requiring more memory but also faster, an adjacency matrix

- The matrix entry (j, k) is set to true if there is an edge (v_j, v_k)

	1	2	3	4	5	6	7	8	9	
1		T		T						
2										
3					T					
4		T			T					
5		T	T					T		
6									T	
7									T	
8 9	Requires $\Theta(V ^2)$ memory									
9	Determining if v_j is adjacent to v_k is $O(1)$									
	- Finding all neighbors of v_j is $\Theta(V)$									



Adjacency list

Most efficient for algorithms is an adjacency list

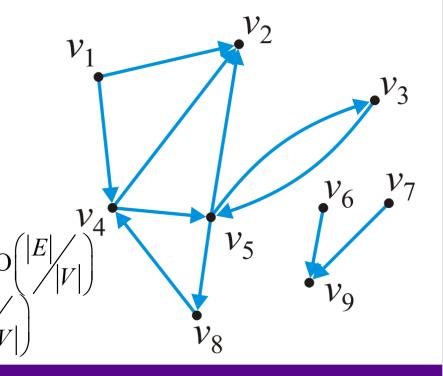
Each vertex is associated with a list of its neighbors

$$\begin{array}{ccc}
1 & \bullet \rightarrow 2 \rightarrow 4 \\
2 & \bullet \\
3 & \bullet \rightarrow 5 \\
4 & \bullet \rightarrow 2 \rightarrow 5 \\
5 & \bullet \rightarrow 2 \rightarrow 3 \rightarrow 8 \\
6 & \bullet \rightarrow 9 \\
7 & \bullet \rightarrow 9
\end{array}$$

- 8 \rightarrow 4 Requires $\Theta(|V| + |E|)$ memory
- On average:

• Determining if v_j is adjacent to v_k is

• Finding all neighbors of v_j is



The Graph ADT

The Graph ADT describes a container storing an adjacency relation

- Queries include:
 - The number of vertices
 - The number of edges
 - List the vertices adjacent to a given vertex
 - Are two vertices adjacent?
 - Are two vertices connected?
- Modifications include:
 - Inserting or removing an edge
 - Inserting or removing a vertex (and all edges containing that vertex)

The run-time of these operations will depend on the representation

Summary

In this topic, we have covered:

- Basic graph definitions
 - Vertex, edge, degree, adjacency
- Paths, simple paths, and cycles
- Connectedness
- Weighted graphs
- Directed graphs
- Directed acyclic graphs

We will continue by looking at a number of problems related to graphs

References

Wikipedia, http://en.wikipedia.org/wiki/Adjacency_matrix http://en.wikipedia.org/wiki/Adjacency_list

- [1] Donald E. Knuth, *The Art of Computer Programming, Volume 1: Fundamental Algorithms*, 3rd Ed., Addison Wesley, 1997, §2.2.1, p.238.
- [2] Cormen, Leiserson, and Rivest, *Introduction to Algorithms*, McGraw Hill, 1990, §11.1, p.200.
- [3] Weiss, Data Structures and Algorithm Analysis in C++, 3rd Ed., Addison Wesley, §3.6, p.94.
- [4] David H. Laidlaw, Course Notes, http://cs.brown.edu/courses/cs016/lectures/13%20Graphs.pdf

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