1819-108-C1-W10-02

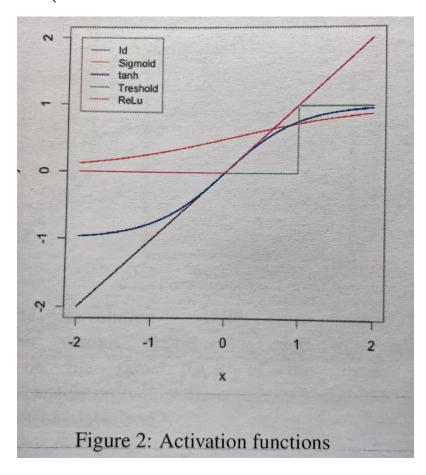
Nikola Juskoviča April 2019

HW WEEK 10

Functions:

Functions:
Id:
$$y = x$$
Sigmoid: $y = \frac{1}{e^{-x}+1}$
Tanh: $y = tanh(x)$
Treshold:
$$\begin{cases} y = 0 & x \le 1 \\ y = 1 & x > 1 \end{cases}$$
ReLu:
$$\begin{cases} y = 0 & x \le 0 \\ y = x & x > 1 \end{cases}$$

ReLu:
$$\begin{cases} y = 0 & x \le 0 \\ y = x & x > 1 \end{cases}$$



Matlab Code:

```
%% grafiks
%% ld
t_saw = (-2):0.01:0;
k = (-2-0)/(-2-0)
delay = 0;
y_saw = k*(t_saw-delay);
plot(t_saw,y_saw, 'k')
hold on
%% Sigmoid
t_{sin} = (-2):0.01:2;
A0 = 0.5;
A = 0.5;
T = (3-(-3))/(1/3);
f = 1/T;
delay = 0;
y_{sin} = A0+A*sin(2*pi*f*(t_sin-delay));
plot(t_sin,y_sin, 'r')
%% tahn
t_{sin} = (-2):0.01:2;
AO = 0;
A = 1;
T = (2-(-2))/(1/2);
```

```
f = 1/T;
delay = 0;
y_{sin} = A0+A*sin(2*pi*f*(t_sin-delay));
plot(t_sin,y_sin, 'b')
%% Treshold
t_{const1} = 0:0.01:1;
y_const1 = 0*ones(size(t_const1));
% plot(t_const1, y_const1)
t_{const2} = 1:0.01:2;
y_const2 = 1*ones(size(t_const2));
% plot(t_const2, y_const2)
t_const = [t_const1, t_const2];
y_const = [y_const1, y_const2];
plot(t_const, y_const, 'g')
%% ReLu
t_{constr} = (-2):0.01:0;
y_constr = 0*ones(size(t_constr));
t_sawr = 0:0.01:2;
k = (0-2)/(0-2)
delay = 0;
y_sawr = k*(t_sawr-delay);
t_relu = [t_constr, t_sawr];
y_relu = [y_constr, y_sawr];
```

```
plot(t_relu, y_relu, 'm')
z=plot(t_relu,y_relu)
za = get(z, 'Parent');
set(za, 'XTick', [-2 -1 0 1 2]);
set(za, 'YTick', [-2 -1 0 1 2]);
axis([-2 2 -2 2])
```

