

Back propagation through time (BPTT)

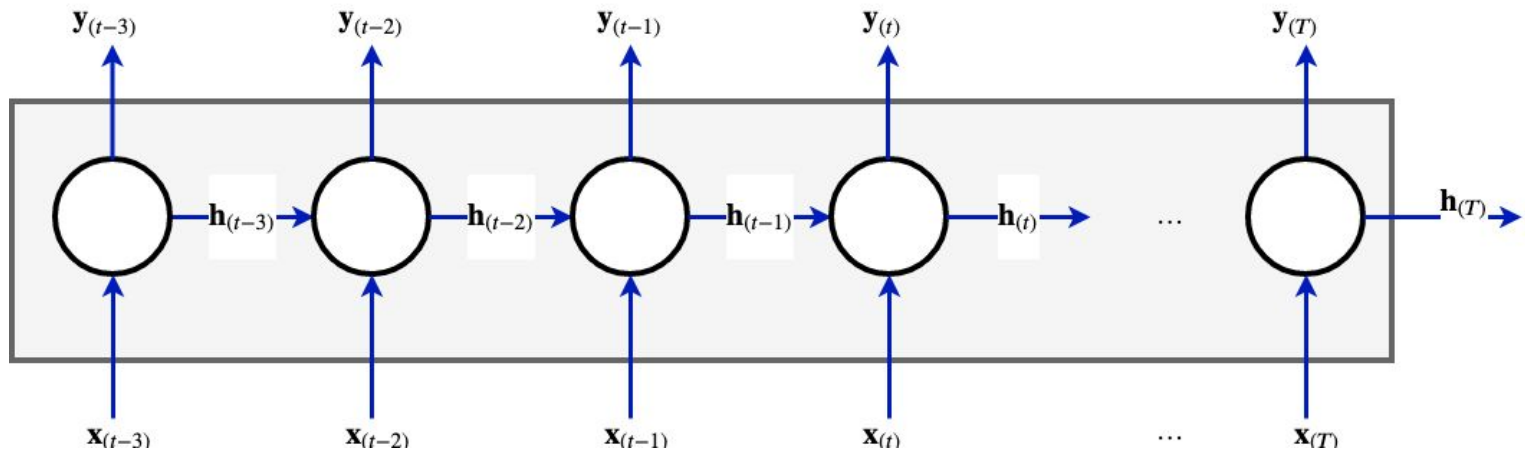
A Recurrent Neural Network (RNN)

- Can be viewed as a loop
- That can be unrolled
- Resulting in a multi-layer network
- One layer per time step

Here are the final layers of an unrolled RNN with input sequence

$$\mathbf{x}_{(1)}, \dots, \mathbf{x}_{(T)}$$

RNN many to many API



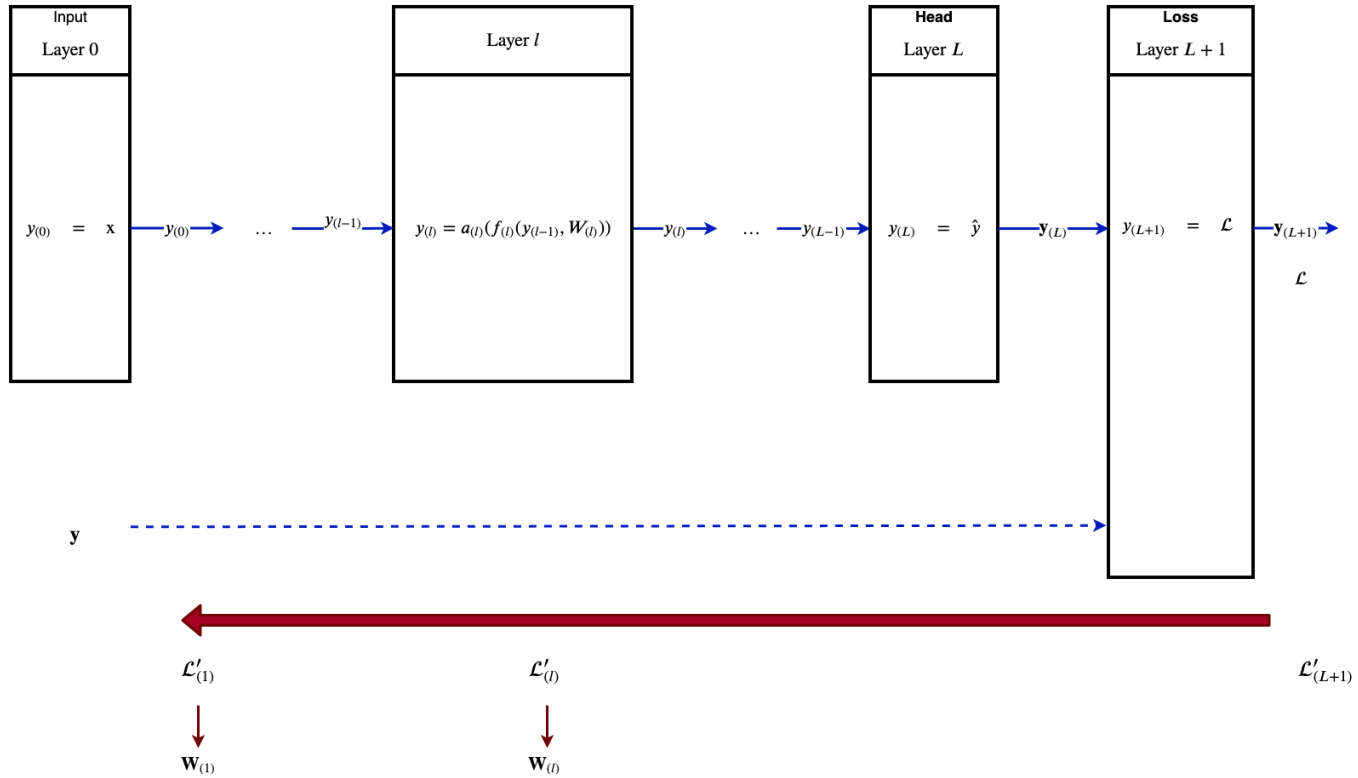
Given enough space: we would continue unrolling on the left to the Input layer

- Resulting in a network with T unrolled layers
- Plus a Loss layer

To compute the derivatives of the Loss with respect to weights

- We could, in theory, use Back Propagation
- Which is the weight update step of Gradient Descent

Backward pass: Loss to Weights



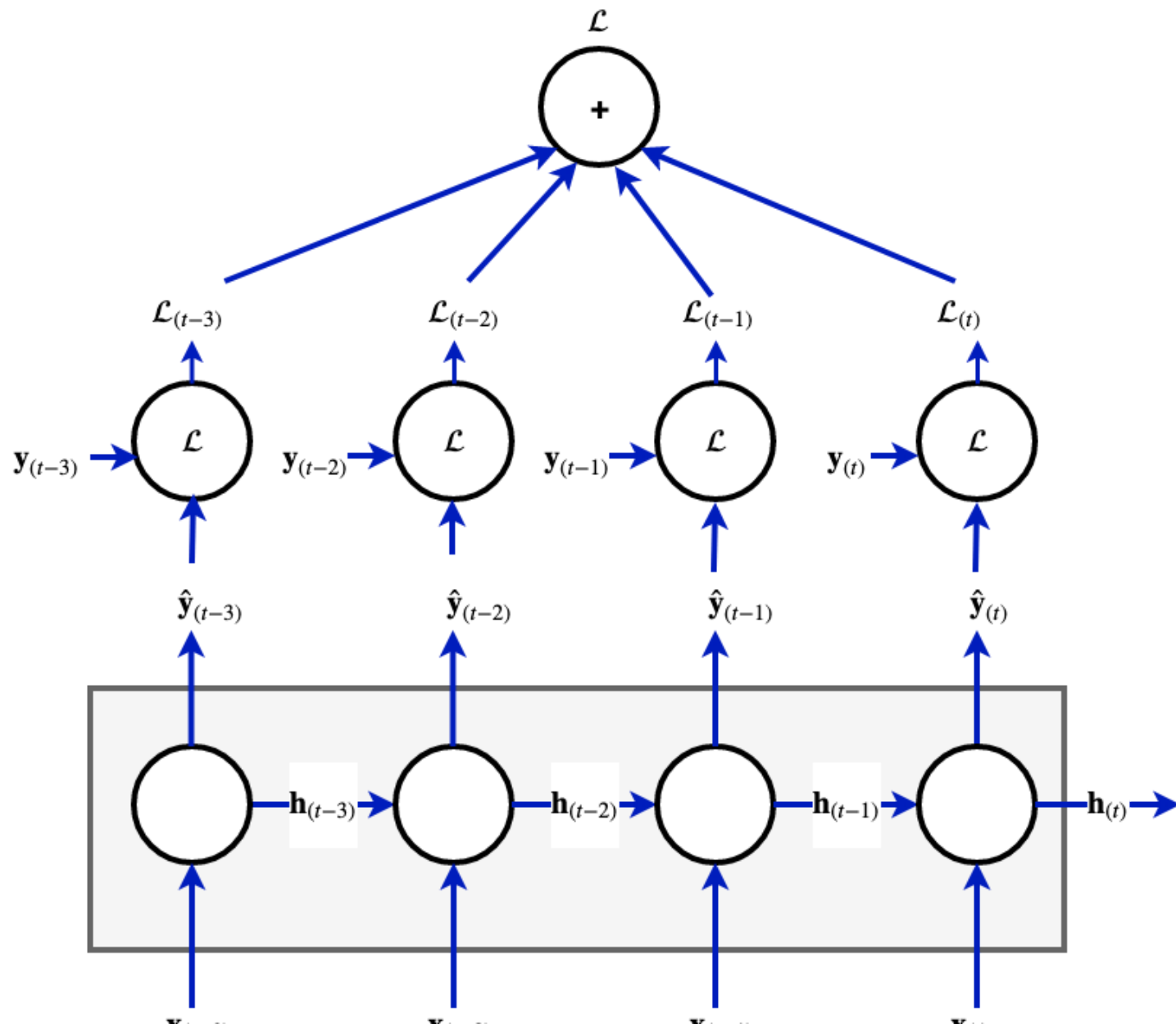
When dealing with unrolled RNN's

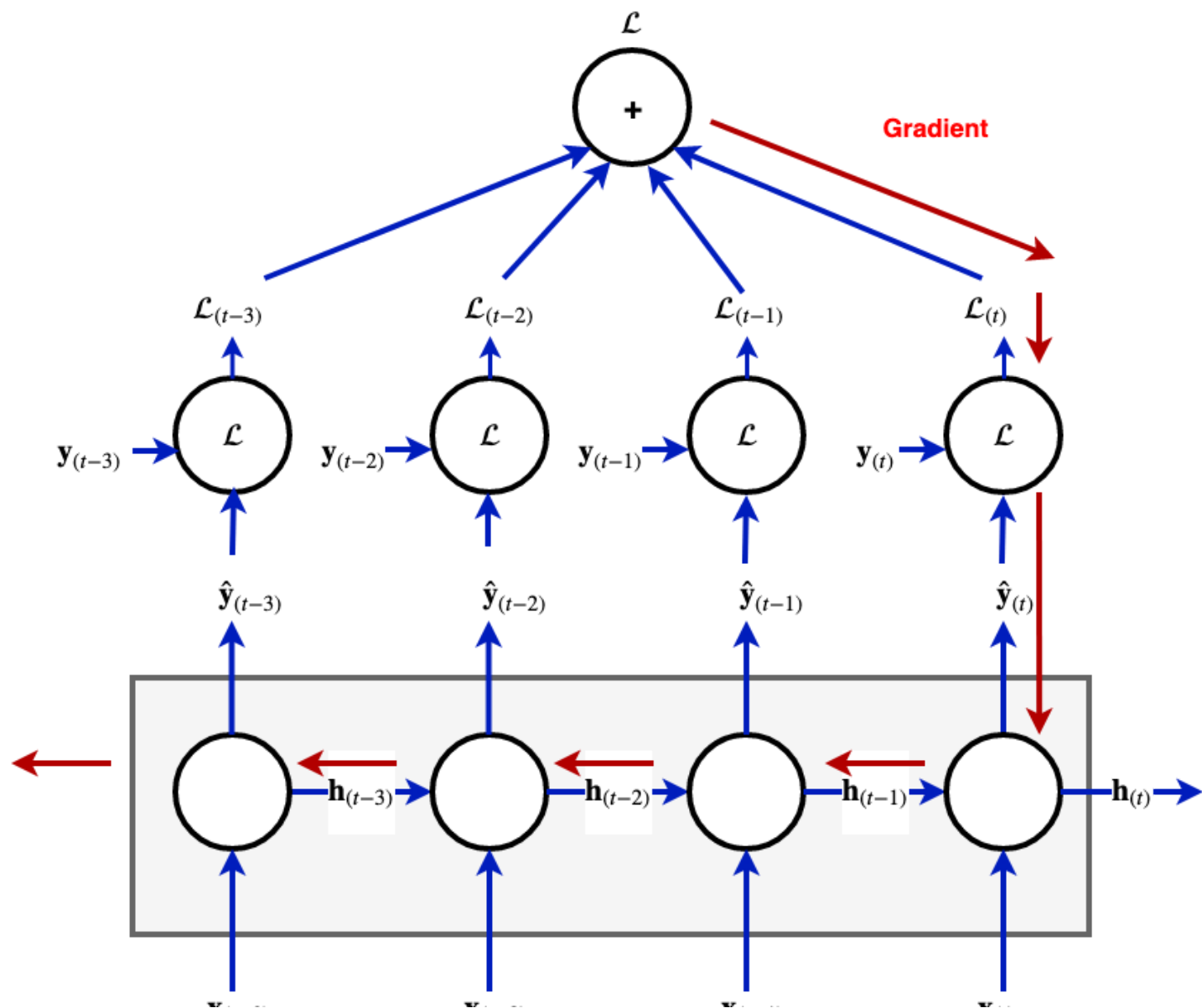
- We will index the "unrolled layers" with time steps, denoted by the label t
- Rather than l , which we use to index layers

This process is called *Back Propagation Through Time* (BPTT).

The only special thing to note about BPTT is that the Loss function is more complex

- There is a Loss
- Per example (as in non-recurrent layers)
- **and Per time-step** (unique to recurrent layers)





Truncated back propagation through time (TBPTT)

An unrolled RNN layer turns into a T layer network where T is the number of elements in the input sequence.

For long sequences (large T) this may not be practical.

First, there is the computation *time*

- t steps to compute $\mathcal{L}_{(t)}^{(i)}$, the loss due to the t^{th} output $\mathbf{y}_{(t)}^{(i)}$ of example i
- For each $1 \leq t \leq T$

Less obvious is the *space* requirement

- As we saw in the module "How a Neural Network Toolkit works"
- We may store information in each layer of the Forward pass (so storage for T layers)
- To facilitate computation of analytical derivatives on the Backward pass
 - For example: the Multiply layer stored the multiplicands in the forward pass
 - Because they are needed for the derivatives

Moreover, as we shall shortly see

- Derivatives may vanish or explode as we proceed further backwards from the Loss layer to the Input layer

So, in theory, the weights $\mathbf{W}_{(t)}$ for small t (close to the input) may not get updated.

- This is certainly a problem in a non-recurrent network
- But is **fatal** in a recurrent layer
- Since there is a **single** weight matrix \mathbf{W} that is shared across *all time steps*

$$\mathbf{W}_{(t)} = \mathbf{W} \text{ for all } 1 \leq t \leq T$$

The solution to these difficulties

- Is to *truncate* the unrolled RNN
- To a fixed number of time steps
- From the loss layer backwards
- The truncated graph is a suffix of the fully unrolled graph

This process is known as *Truncated Back Propagation Through Time* (TBPTT).

Note that *truncation only occurs in the backward pass*.

There is *no truncation* of the forward pass of the RNN !

Because the unrolled graph is less than T steps

- Gradient computation takes fewer steps
- So weight updates can occur more often

The obvious downside to truncation is that

- Gradients are only approximate

But there is a subtle and more impactful difference

- The RNN layer *cannot capture long-term dependencies*

Suppose we unrolled the layer for only τ time steps (the "window" size)

- The loss for the t^{th} time step ($\mathcal{L}_{(t)}^{(i)}$)
- Flows backwards only to steps
 $(t - \tau + 1), \dots, t$

So the "error signal" from time t does not affect time steps $t' < (t - \tau + 1)$

Consider a long sentence or document (sequence of words)

- If the gender of the subject is defined by the early words in the sentence
- An incorrect "prediction" late in the sentence
- May not be able to be corrected

"Z was the first woman who ... **he** said ..."

In other words

- Truncation may affect the ability of an RNN to encode *long-term* dependencies
- Vanishing gradients may cause a similar impact

TBPTT variants

There are several common ways to decide on how many unrolled time steps to keep.

Let t'' denote the index of the *smallest* time step in the unrolled layer for step t .

- $t'' = (t - \tau + 1)$

Plain, untruncated BPTT defines

- $t'' = 0$
- Unroll all the way to the Input Layer

k -truncated BPTT defines window size $\tau = k$

- $t'' = \max(0, t - k)$

Subsequence truncated BPTT defines

- $t'' = k * \lfloor t/k \rfloor$

That is, it breaks the sequence into "chunks" of size k

$$\begin{aligned} & \mathbf{x}_{(1)}^{(i)}, \dots, \mathbf{x}_{(k)}^{(i)} \\ & \mathbf{x}_{(k+1)}^{(i)}, \dots, \mathbf{x}_{(2*k)}^{(i)} \\ & \vdots \\ & \mathbf{x}_{((i'*k)+1)}^{(i)}, \dots, \mathbf{x}_{((i'+1)*k)}^{(i)} \\ & \vdots \end{aligned}$$

- Gradients flow *within* chunks
- But *not between* chunks

Subsequence TBPTT is very common as it fits well into the design of current toolkits

See the Deep Dive on [How to deal with long sequences \(RNN Long Sequences.ipynb\)](#) for how to arrange your training examples.

Calculating gradients in an RNN

There is an important subtlety we have ignored regarding Back Propagation in an unrolled RNN

- There is a **single** weight matrix \mathbf{W} that is shared across *all time steps*
 $\mathbf{W}_{(t)} = \mathbf{W}$ for all $1 \leq t \leq T$

This

- Makes the derivative computation slightly more complex
- Creates an *additional* exposure to the problem of vanishing/exploding gradients

A simple picture will illustrate.

Consider the loss at time step t of example i

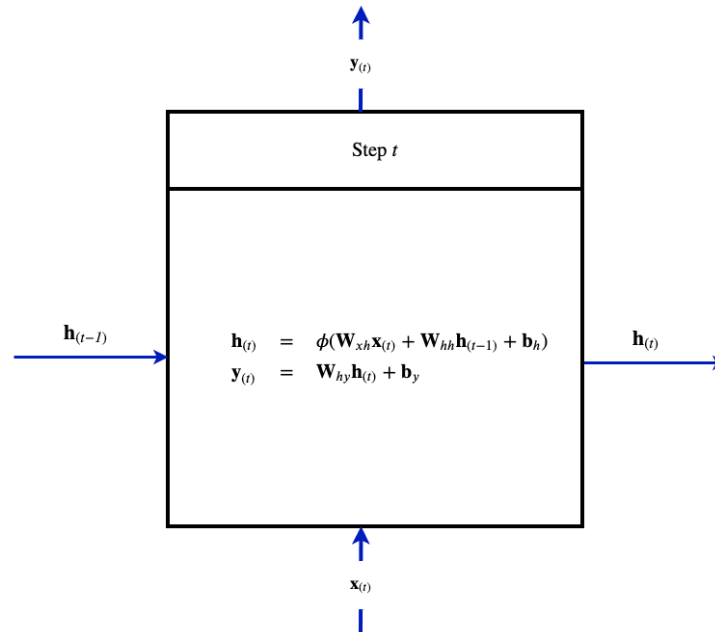
- $\mathcal{L}_{(t)}^{(i)} = L(\hat{\mathbf{y}}_{(t)}^{(i)}, \mathbf{y}_{(t)}^{(i)}; \mathbf{W})$
- The loss is a function of
 - $\hat{\mathbf{y}}_{(t)}^{(i)}$: The t^{th} element of the output sequence $\hat{\mathbf{y}}^{(i)} = \mathbf{y}_{(T)}$ for example i
 - The $\mathbf{y}_{(t)}^{(i)}$: The t^{th} element of the **target** sequence $\mathbf{y}^{(i)}$ for example i

The derivative

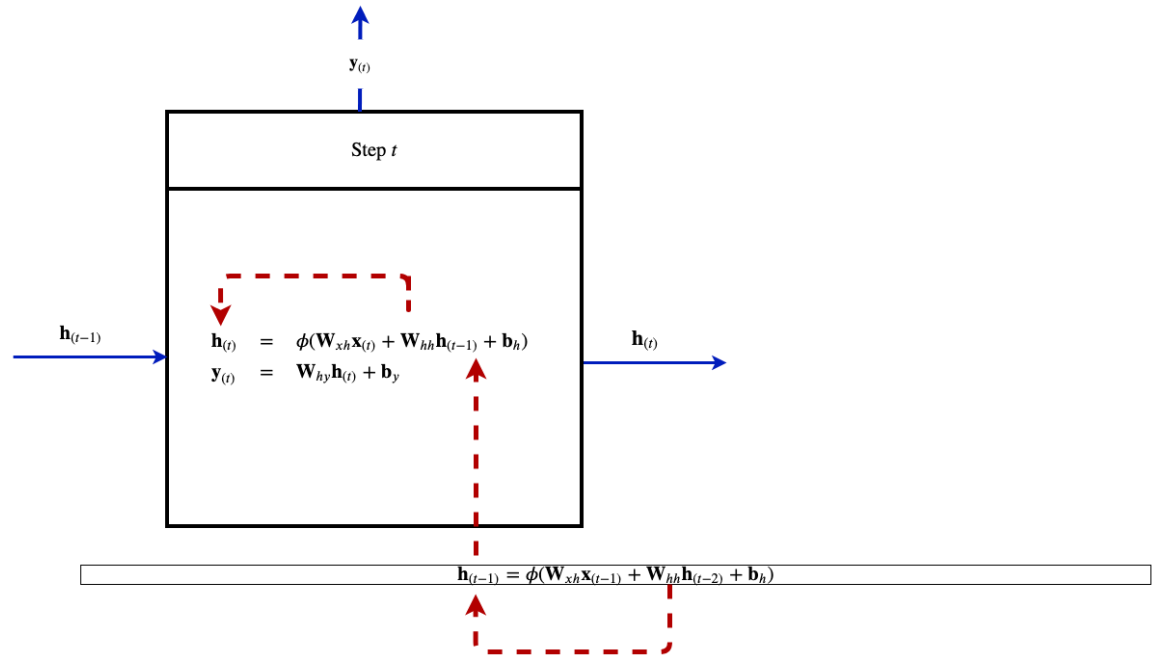
$$\frac{\partial \mathcal{L}_{(t)}}{\partial \mathbf{W}}$$

- Which is used in Gradient Descent to update the estimate for weights \mathbf{W}
- Is the sensitivity of $\mathcal{L}_{(t)}$ to a change in \mathbf{W}

RNN Time step



RNN multiple dependence on W



The red lines show **two** different ways that **W** affects $\mathbf{h}_{(t)}$

- And thus $\hat{\mathbf{y}}_{(t)} = \mathbf{W}_{hy}\mathbf{h}_{(t)} + \mathbf{b}_y$
- By its indirect effect on $\mathbf{h}_{(t)}$ **through** $\mathbf{h}_{(t-1)}$ (lower line)
- By its direct effect on $\mathbf{h}_{(t)}$ (upper line)
- Both using the part of **W** denoted by \mathbf{W}_{hh}

So

$$\begin{aligned}\frac{\partial \mathbf{h}_{(t)}^{(i)}}{\partial \mathbf{W}_{hh}} &= \frac{d\mathbf{h}_{(t)}^{(i)}}{d\mathbf{W}_{hh}} + \frac{\partial \mathbf{h}_{(t)}^{(i)}}{\partial \mathbf{h}_{(t-1)}^{(i)}} \frac{\partial \mathbf{h}_{(t-1)}^{(i)}}{\partial \mathbf{W}_{hh}} \\ &= \frac{d(\mathbf{W}_{hh} \mathbf{h}_{(t-1)}^{(i)})}{d\mathbf{W}_{hh}} + \frac{\partial \mathbf{h}_{(t)}^{(i)}}{\partial \mathbf{h}_{(t-1)}^{(i)}} \frac{\partial \mathbf{h}_{(t-1)}^{(i)}}{\partial \mathbf{W}_{hh}}\end{aligned}$$

(Each addend reflect a different path through which \mathbf{W}_{hh} affects $\mathbf{h}_{(t)}$)

So

$$\frac{\partial \mathcal{L}_{(t)}^{(i)}}{\partial \mathbf{W}} = \mathcal{L}'_{(t)} \frac{\partial \mathbf{y}_{(t)}^{(i)}}{\partial \mathbf{W}}$$

and

$$\frac{\partial \mathbf{y}_{(t)}^{(i)}}{\partial \mathbf{W}}$$

depends on all time steps from 1 to t .

Thus, the derivative update for \mathbf{W} cannot be computed without the gradient (for each time step t) flowing all the way back to time step 0.

Conclusion

Updating the weights of a Recurrent layer appears, at first glance, to be straight forward

- Unroll the loop
- Use ordinary Back Propagation

We have discovered some complexity

- Full unrolling is expensive
- Gradient computation is complicated by shared weights

Fortunately, we have solutions to these complexities.

In [3]: `print("Done")`

Done