# Noah Zipin

Towson, MD | noahzipin@gmail.com | 443.422.5292 | www.linkedin.com/in/noahzipin Engineering Portfolio: https://github.com/nzipin/Engineering-Portfolio

### **EDUCATION**

# University of Maryland, College Park, MD

B.S. Mechanical Engineering

Expected May 2023

GPA: 3.90

- Clark Scholars Program Selected as one of ten students; combines engineering, business, and leadership
- College Park Scholars, Science & Global Change merit-based program on impact of climate change

Coursework: Materials Science, Dynamics, Statics, Mechanics of Materials, Engineering Design, Diff. Equations

#### **SKILLS**

Engineering: CAD [SolidWorks, Inventor, AutoCAD] (300 hrs), FEA, 3D Printing (~200 prints), GD&T Software: C++, Java, Python, Arduino, Excel, MATLAB, Simulink, Abaqus (exposure), Photoshop, After Effects WORK & PROJECT EXPERIENCE

# Bioinspired Advanced Manufacturing Lab – Student Researcher

Oct 2019 - March 2020

- Worked on a team of three undergraduate students under direction of PhD candidate to make 3D printed multi-material flexible actuators with variable stiffness achieved by developing new layer jamming structures
- Utilized SolidWorks (~100 hrs) to create mechanisms for multi-material additive manufacturing on Connex3 poly jet printer to integrate rigid and flexible materials in actuators, and simulated using FEA
- Designed and tested an agitation mechanism for the soft actuator to prevent jamming layers from sticking together as support material from 3D printing is dissolved with sodium hydroxide solution

## Independent Project: Self-Balancing Robot

May 2020 – Aug 2020

- Designed, manufactured, and controlled systems (mechanical, electrical, software) to make a robot that balances on two wheels, using an inertial measurement unit and hall effect sensors to read system data
- Employed Fusion 360, MATLAB, Simulink (~70 hrs) to model and simulate the self-balancing robot, which mimics the inverted pendulum on a cart dynamic system. Documented and presented project on <u>YouTube</u>
- Coded control systems for the robot in C++; sets motor velocity based on robot angle using PID controller
- Manufactured robot with 15 custom 3D printed components, aluminum extrusion, and polycarbonate sheet

## Ridgely Robotics & Technology Summer Camp – Head Camp Counselor

Summer 2020

- Transformed traditional summer camp into an online environment in the era of COVID-19 by developing new curriculums that engaged over 100 middle-school aged students to supplement online education
- Taught ~200 hrs of novel courses in Intro to Robotics (VEX IQ Platform), Introduction to 3D Modeling (TinkerCAD, Autodesk Inventor), Flight & Space (model rockets) and Video Editing (Adobe Premiere Pro)
- Led the creation of a new and interactive <u>Facebook Page</u> so parents can easily access all information online

## UMD Over Sand Vehicle Project – Mechanical Team Lead

Feb 2020 – May 2020

- Collaborated in a group of 8 students to design, build, and test and autonomous over sand vehicle
- Created full CAD model, technical drawings, and .dxf/.stl files in SolidWorks (~50 hrs) for manufacturing on laser cutter and FDM 3D printer
- Ensured that the design was under the \$350 budget and adhered to the size and weight specifications

#### **VOLUNTEER EXPERIENCE**

## Cromwell Valley Elementary Robotics Team - Founder and Coach

Oct 2017 - Mar 2019

- Founded robotics program at local elementary school by presenting plans to Baltimore County Public School Board members and Recruiting students to educate the local community and inspire future engineers
- Coached two teams twice per week and prepared parents and teachers for competition events

#### **ACTIVITES**

- Maryland Discourse community of UMD students for productive dialogue about complex issues to share ideas and develop new perspectives
- RC Flying Terps club for students to fly racing quadcopters in a safe and controlled environment
- Robotics at Maryland team that works on autonomous underwater vehicles for RoboSub competition