# Sparsity in images, a basis better than Fourier basis

### **Background knowlege: Cooley-Tukey FFT**

The Fourier basis in  $\mathbb{R}^n$  is given by the DFT matrix  $(F_n)_{i,j}=\omega^{(i-1)(j-1)}$ , where  $\omega=e^{-2\pi i/n}$  is the primitive n-th root of unity.  $F_n$  is a Vandermonde matrix:

$$F_{n} = \begin{pmatrix} 1 & 1 & 1 & \dots & 1 & 1 & \dots & 1 & 1 \\ 1 & \omega & \omega^{2} & \dots & \omega^{\frac{n}{2}-1} & \omega^{\frac{n}{2}} & \dots & \omega^{n-2} & \omega^{n-1} \\ 1 & \omega^{2} & \omega^{4} & \dots & \omega^{n-2} & \omega^{n} & \dots & \omega^{2n-4} & \omega^{2n-2} \\ \vdots & \vdots & \vdots & \ddots & \vdots & \vdots & \ddots & \vdots & \vdots \\ 1 & \omega^{\frac{n}{2}-1} & \omega^{n-2} & \dots & \omega^{\left(\frac{n}{2}-1\right)^{2}} & \omega^{\left(\frac{n}{2}-1\right)\frac{n}{2}} & \dots & \omega^{\left(\frac{n}{2}-1\right)(n-2)} & \omega^{\left(\frac{n}{2}-1\right)(n-1)} \\ 1 & \omega^{\frac{n}{2}} & \omega^{n} & \dots & \omega^{\frac{n}{2}\left(\frac{n}{2}-1\right)} & \omega^{\left(\frac{n}{2}\right)^{2}} & \dots & \omega^{\frac{n}{2}(n-2)} & \omega^{\frac{n}{2}(n-1)} \\ \vdots & \vdots & \vdots & \ddots & \vdots & \vdots & \ddots & \vdots & \vdots \\ 1 & \omega^{n-1} & \omega^{2n-2} & \dots & \omega^{(n-1)\left(\frac{n}{2}-1\right)} & \omega^{(n-1)\frac{n}{2}} & \dots & \omega^{(n-1)(n-2)} & \omega^{(n-1)^{2}} \end{pmatrix}.$$
 (1)

The Cooley-Tukey FFT is a divide-and-conquer algorithm for computing the DFT. For simplicity, we assume n is a power of 2, such that we can divide the matrix into 4 blocks:

• The odd columns (blue background), top half:

$$F_{\text{odd, top}} = \begin{pmatrix} 1 & 1 & \dots & 1 \\ 1 & \omega^2 & \dots & \omega^{n-2} \\ \vdots & \vdots & \ddots & \vdots \\ 1 & \omega^{n-2} & \dots & \omega^{(\frac{n}{2}-1)(n-2)} \end{pmatrix} = \begin{pmatrix} 1 & 1 & \dots & 1 \\ 1 & (\omega^2) & \dots & (\omega^2)^{\frac{n}{2}-1} \\ \vdots & \vdots & \ddots & \vdots \\ 1 & (\omega^2)^{\frac{n}{2}-1} & \dots & (\omega^2)^{(\frac{n}{2}-1)(\frac{n}{2}-1)} \end{pmatrix} = F_{\frac{n}{2}}$$
 (2)

• The even columns (white background), top half:

$$F_{\text{even, top}} = D_{\frac{n}{2}} F_{\frac{n}{2}} \tag{3}$$

where  $D_n = \text{diag}(1, \omega, \omega^2, ..., \omega^{n-1})$ .

• The odd columns (blue background), bottom half:

$$F_{\text{odd, bottom}} = F_{\frac{n}{2}}.$$
 (4)

Note  $\omega^n = 1$  is ignored.

• The even columns (white background), bottom half:

$$F_{\text{even, bottom}} = -D_{\frac{n}{2}} F_{\frac{n}{2}}, \tag{5}$$

where the minus sign comes from  $\omega^{\frac{n}{2}} = -1$ .

Finally, we arrive at the Cooley-Tukey FFT given by:

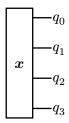
$$F_n \boldsymbol{x} = \begin{pmatrix} I_{\frac{n}{2}} & D_{\frac{n}{2}} \\ I_{\frac{n}{2}} & -D_{\frac{n}{2}} \end{pmatrix} \begin{pmatrix} F_{\frac{n}{2}} & 0 \\ 0 & F_{\frac{n}{2}} \end{pmatrix} \begin{pmatrix} \boldsymbol{x}_{\text{odd}} \\ \boldsymbol{x}_{\text{even}} \end{pmatrix}$$
(6)

where  $x_{\mathrm{odd}}$  and  $x_{\mathrm{even}}$  contain the odd and even indexed elements of x, respectively. It indicates that the discrete Fourier transormation in  $\mathbb{R}^n$  can be decomposed into two smaller discrete Fourier transormations in  $\mathbb{R}^{\frac{n}{2}}$  with a diagonal matrix  $D_n$  in between. Note applying diagonal matrices can be done in O(n) operations, this decomposition leads to the recurrence relation  $T(n) = 2T(\frac{n}{2}) + O(n)$ , which solves to  $O(n \log n)$  total operations.

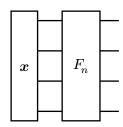
The inverse transformation is given by  $F_n^{\dagger} x/n$ . The DFT matrix is unitary up to a scale factor:  $F_n F_n^{\dagger} = nI$ .

### Tensor network representation of the Cooley-Tukey FFT

This section requires preliminary knowledge of tensor networks (TODO: add reference). In tensor network diagram, a vector of size  $n=2^k$  can be represented as a tensor with k indices, denoting the basis index  $i=2^0q_0+2^1q_1+\ldots+2^{k-1}q_{k-1}$ .



In the following, we aim to find a tensor network decomposition for the linear map  $F_n$ :



Step 1: To start, the equation Equation 6 can be represented as the following tensor network:

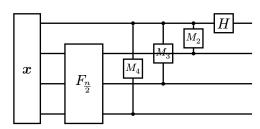
$$F_{n}\boldsymbol{x} = \begin{pmatrix} \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix} \otimes I_{\frac{n}{2}} \end{pmatrix} \begin{pmatrix} I_{\frac{n}{2}} & 0 \\ 0 & D_{\frac{n}{2}} \end{pmatrix} \begin{pmatrix} F_{\frac{n}{2}}\boldsymbol{x}_{\text{odd}} \\ F_{\frac{n}{2}}\boldsymbol{x}_{\text{even}} \end{pmatrix}, \tag{7}$$

where  $H = \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix}$  is a Hadamard matrix (upto a constant factor).

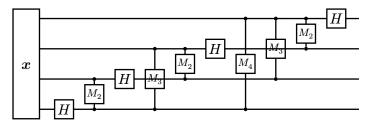
Step 2: Then, we will decompose the diagonal matrix  $\begin{pmatrix} I_{\frac{n}{2}} & 0 \\ 0 & D_{\frac{n}{2}} \end{pmatrix}$  into a tensor network. This diagonal matrix corresponds to operation: if  $q_0$  is 0 (odd index), the no operation is applied, otherwise (even index) the operation  $D_{\frac{n}{2}}$  is applied. Observe that  $D_n = \mathrm{diag} \big(1, \omega^{\frac{n}{2}}\big) \otimes \mathrm{diag} \big(1, \omega, \omega^2, ..., \omega^{\frac{n}{2}-1}\big) = \mathrm{diag} \big(1, \omega^{\frac{n}{2}}\big) \otimes \mathrm{diag} \big(1, \omega^{\frac{n}{4}}\big) \otimes ... \otimes \mathrm{diag} (1, \omega)$ . We have

$$\begin{pmatrix} I_{\frac{n}{2}} & 0 \\ 0 & D_{\frac{n}{2}} \end{pmatrix} = \operatorname{ctrl}_0 \left( \operatorname{diag} \left( 1, \omega^{\frac{n}{4}} \right)_1 \right) \operatorname{ctrl}_0 \left( \operatorname{diag} \left( 1, \omega^{\frac{n}{8}} \right)_2 \right) \dots \operatorname{ctrl}_0 \left( \operatorname{diag} \left( 1, \omega \right)_{\log_2 n} \right),$$
 (8)

where  $\operatorname{ctrl}_i(A_j)$  means the target operation applied on  $A_j$  is applied only if bit  $q_i$  is 1. Here, since the controlled gate is diagonal, it can be represented as a matrix connecting two variables:



In this diagram,  $M_k = \begin{pmatrix} 1 & 1 \\ 1 & e^{i\pi/2^{k-1}} \end{pmatrix}$  connects the two qubits involved in the controlled operation, which effectively multilies a phase factor  $e^{i\pi/2^{k-1}}$  if two bit are both in state 1. By recursively decomposing the  $F_{\frac{n}{2}}$  tensor, we can obtain the following tensor network.



Direct evaluation of this tensor network takes  $O(n \log^2 n)$  operations. By respecting the fact that the *controlled phase* operation is a diagonal matrix, we can merge these operations and further reduce the complexity to  $O(n \log(n))$ .

## Learning a better Fourier basis

Observing that in this representation, tensor parameters can be tuned without affecting the computational complexity, e.g. the parameters in  $M_k$  and H. Can we find a transformation better than the Fourier basis? Or is Fourier basis already optimal for image processing?

Intuitively, the fourier basis is not optimal for image processing, because:

- the fourier basis assumes periodic boundary condition, which is not suitable for image processing.
- the 2d fourier basis assumes the X and Y coordinates are independent, which is not suitable for image processing.

#### **Tasks**

- Create an image dataset  $\mathcal{D} = \left\{ \boldsymbol{x}_i \right\}_{i=1}^{N}.$
- Create a tensor network transformation based on the above QFT circuit, denoted as  $\mathcal{T}(\theta)$ , where  $\theta$  is the parameters of the tensor network.
- Variationally optimize the circuit parameters to capture the sparsity of the image. The cost function is

$$\mathcal{L}(\boldsymbol{\theta}) = \sum_{i=1}^{N} \lVert \boldsymbol{x}_i - \mathcal{T}(\boldsymbol{\theta})^{-1}(\text{truncate}(\mathcal{T}(\boldsymbol{\theta})(\boldsymbol{x}_i), k)) \rVert_2^2 \tag{9}$$

Here, we can choose a different loss function to capture details in the image, e.g. the edges. For simplicity, we use the  $l_1$ -norm instead:

$$\mathcal{L}(\boldsymbol{\theta}) = \sum_{i=1}^{N} \lVert \mathcal{T}(\boldsymbol{\theta})(\boldsymbol{x}_i) \rVert_1 \tag{10}$$

This loss will encourage the tensor network to output a sparse pattern in the "moment space". It is a standard trick that widely used in *compressed sensing*.

- In the 2D Fourier transformation, the X and Y coordinates are independent. Here we allow X and Y coordinates to correlate with each other in the tensor network basis.
- Add edge detection features.
- Compare the performance with the Fourier basis.