



MeqTrees at 1,000,000:1 & Other Tales

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Introduction:

Calibration In MeqTrees

- MeqTrees is (mostly) about building measurement equations, e.g.:

$$\mathbf{V}_{pq} = \mathbf{G}_p \left(\sum_s \mathbf{E}_p^{(s)} \mathbf{Z}_p^{(s)} \mathbf{K}_p^{(s)} \mathbf{B}^{(s)} \mathbf{K}_q^{(s)\dagger} \mathbf{Z}_q^{(s)\dagger} \mathbf{E}_q^{(s)\dagger} \right) \mathbf{G}_q^\dagger$$

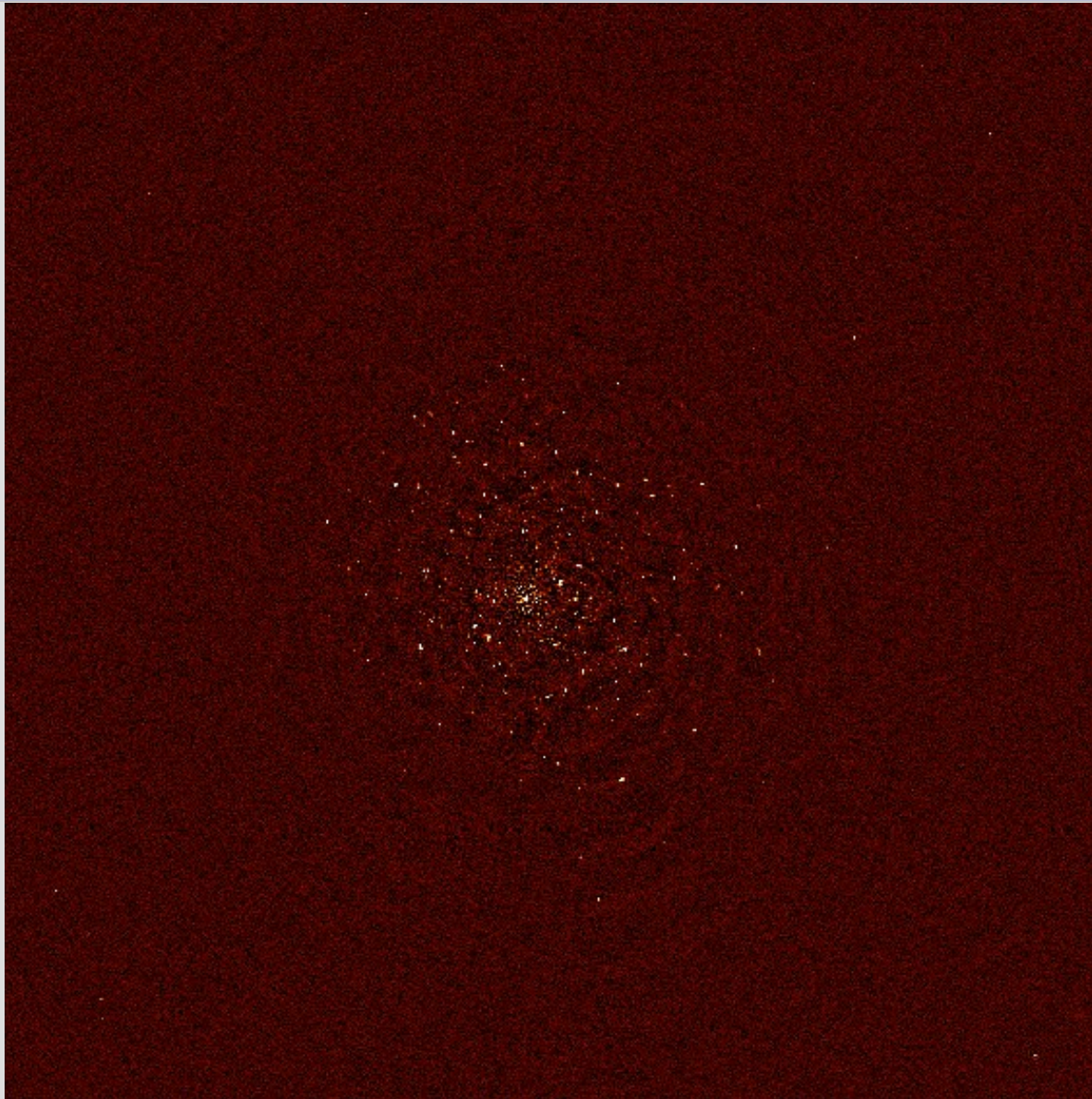
- An m.e. decomposes the observed visibility \mathbf{V}_{pq} into intrinsic source properties and per-antenna *Jones terms*.
- Can describe an endless variety of (linear) physics.

The Project Formerly Known As “Beat NEWSTAR”

- Aim: demonstrate the advantages of ME-based calibration
 - by doing better than a legacy package
 - pick the right target...
- NEWSTAR (Netherlands East-West Synthesis Telescope Array Reduction)
 - not a terribly wide user base
 - ...but a very tall one!
 - WR holder in dynamic range (→2 million)

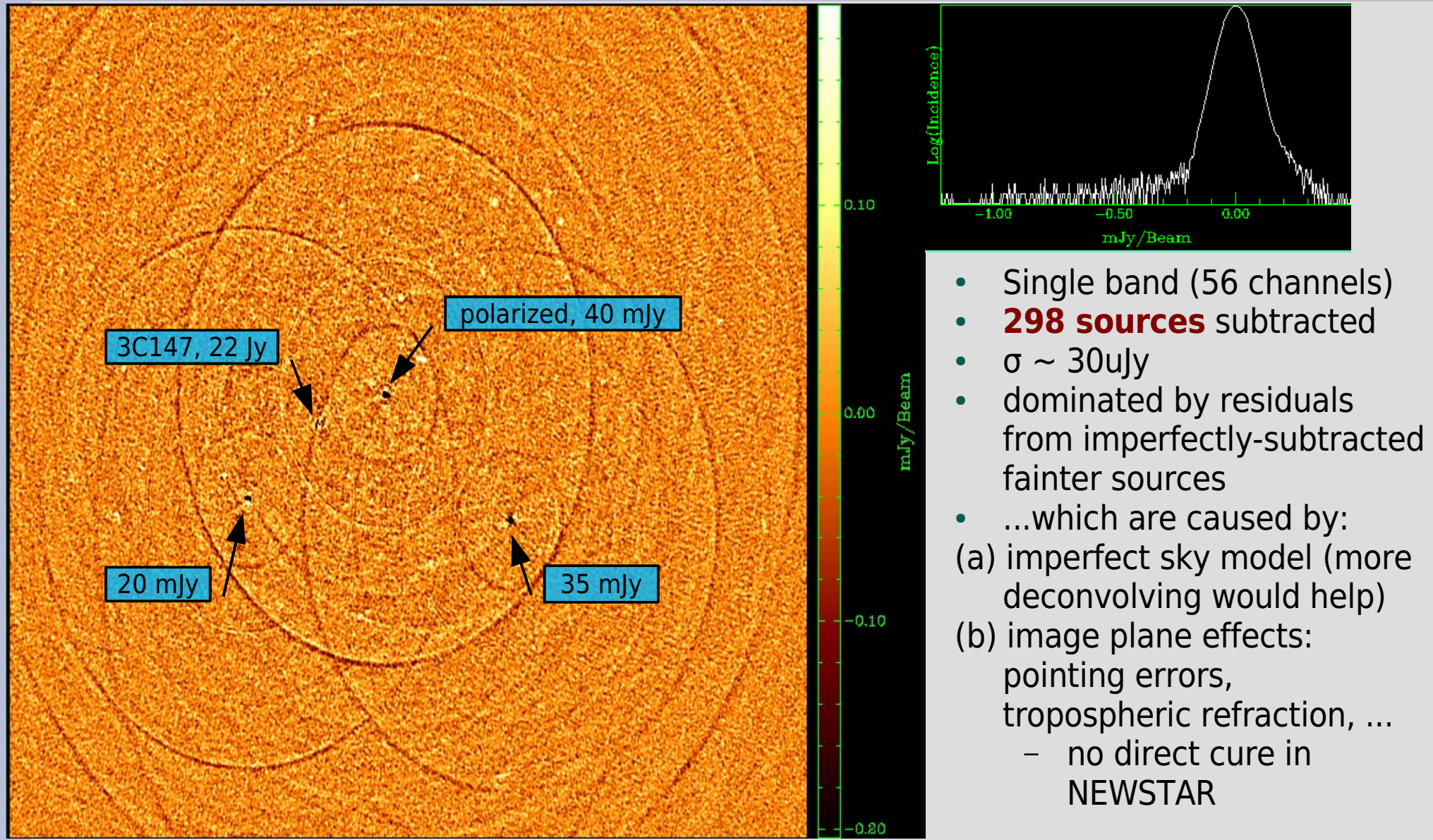


The 3C147 Field



- 1x12 hr WSRT
21cm observation
- 30sec. integration
- 8x64 channels
21cm B=160 MHz
- 3C147 is 22Jy
- NEWSTAR DR:
 - 1.5 million on-axis
 - 1000 off-axis

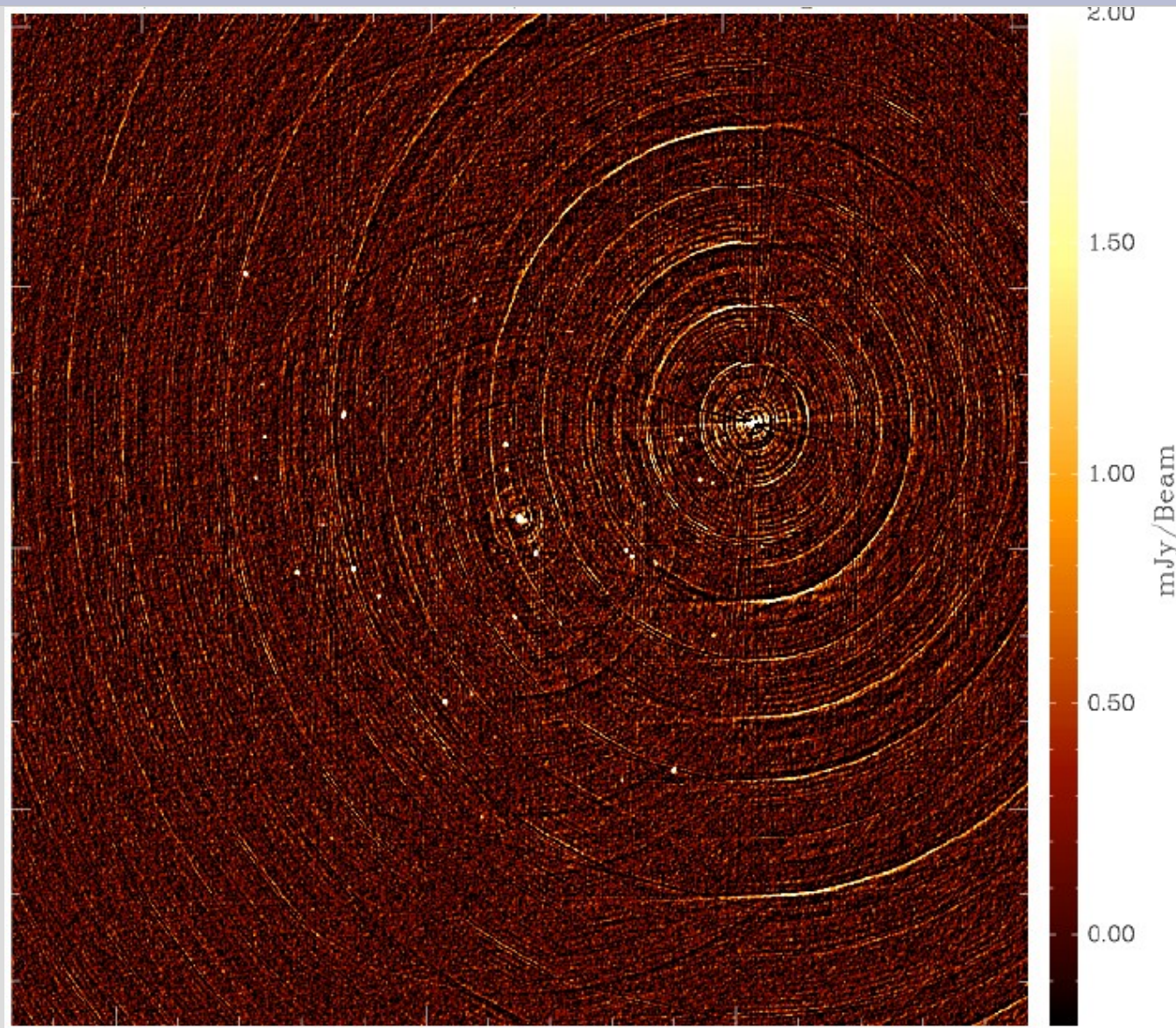
Best NEWSTAR Image



Calibrating For Image-Plane Effects I

- “Peeling” is different things to different people, but here we'll define it as:
 - selfcal on brightest source, subtract source
 - shift phase center to next source
 - selfcal, subtract, rinse & repeat
- Proven to work...
 - 3C343, 3C84, 3C196, etc. (Ger de Bruyn, Tom Oosterloo, Michiel Brentjens – NEWSTAR, Miriad)
- ...but cumbersome to use (miles of scripts)

3C343: A Typical Peeling Candidate



Calibrating For Image-Plane Effects II

- Weakness of peeling: interacting solutions when sources have comparable flux
 - need to iterate back and forth
- Alternative: simultaneous off-axis gain solutions (some call it “peeling” too.)
 - 3C343 (Michiel Brentjens -- MeqTrees)
- Alternative: solving for pointing errors
 - Sanjay Bhatnagar – CASA?
 - EVLA Memo 84, and this conference

The MeqTree Approach

- All sorts of ME's can be implemented. Let's start with this one:

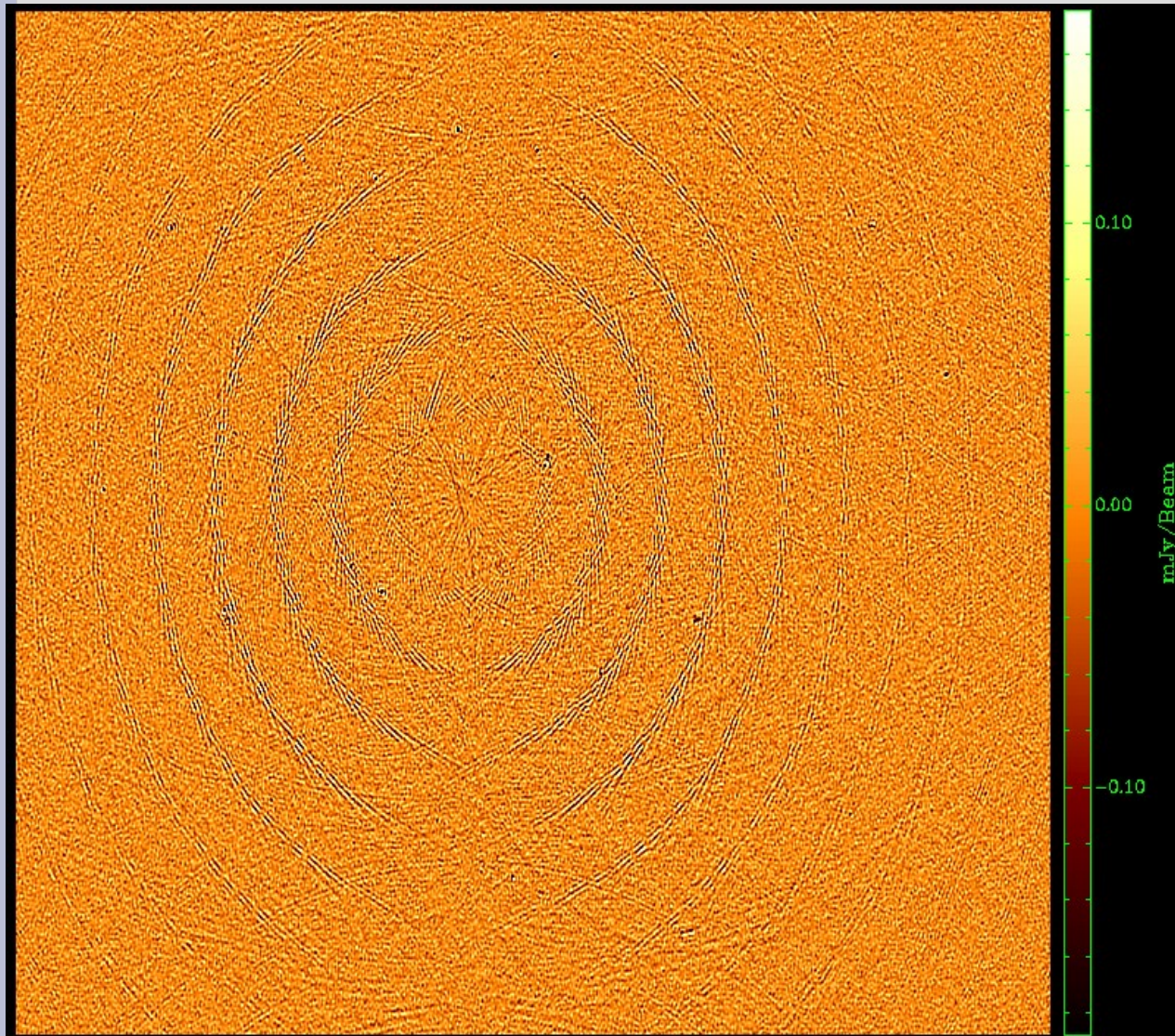
$$\mathbf{V}_{pq} = \overbrace{\mathbf{B}_p}^{\text{bandpass}} \overbrace{\mathbf{G}_p}^{\text{gain}} \underbrace{\left(\sum_s \overbrace{\mathbf{E}_p^{(s)}}^{\text{beam}} \overbrace{\mathbf{X}_{pq}}^{\text{source coherency}} \mathbf{E}_q^{(s)\dagger} \right)}_{\text{sum over sources}} \mathbf{G}_q^\dagger \mathbf{B}_q^\dagger$$

$\mathbf{E}_p^{(s)}$ is an analytic expression, $E(l, m, \nu) = \cos^3(C \nu \sqrt{l^2 + m^2})$

$\mathbf{G}_p(t)$ is a solvable

$\mathbf{B}_p(\nu)$ is a solvable (with a long-scale time variation)

Bandpass Artifacts



- Residual pattern from 3C147 due to *bandpass instability*.
- We do a separate **B** solution every 30 min.
- Error pattern caused by variations in actual bandpass over the solution interval
 - error $\sim 1/10,000$
- We can mitigate this by making **B** a 1st-degree polynomial in time
 - error $\sim 1/500,000$
 - close to noise level but plainly visible
- Further increase polynomial degree?
 - or spline?

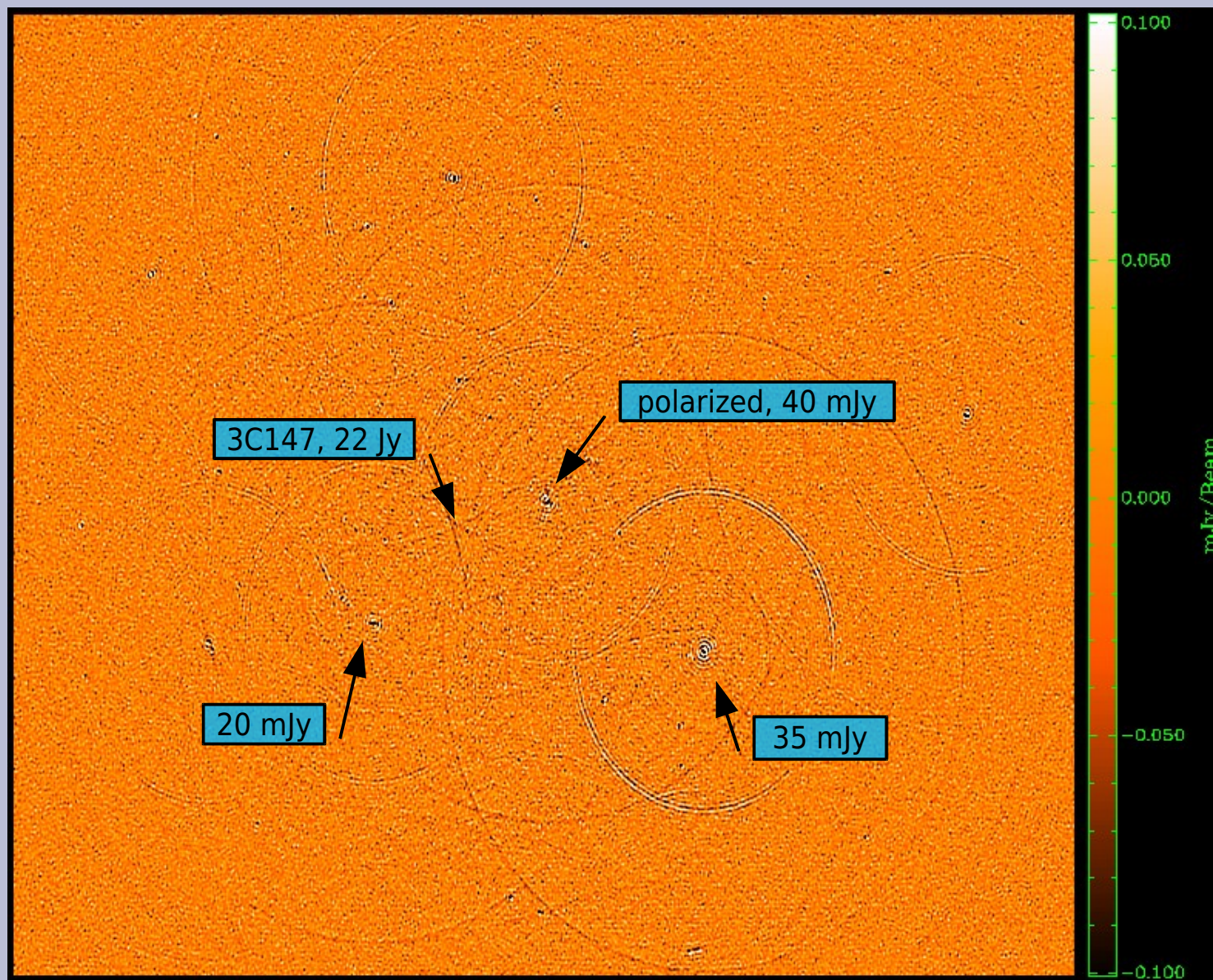
Dropping The Bandpass

- Do a per-channel selfcal
 - with sufficient S/N, why not?
 - this is what Ger does in NEWSTAR
- In M.E. terms:

$$\mathbf{V}_{pq} = \overbrace{\mathbf{G}_p}^{\text{gain \& bandpass}} \underbrace{\left(\sum_s \overbrace{\mathbf{E}_p^{(s)}}^{\text{beam}} \overbrace{\mathbf{X}_{pq}}^{\text{source coherency}} \mathbf{E}_q^{(s)\dagger} \right)}_{\text{sum over sources}} \mathbf{G}_q^\dagger$$

$\mathbf{G}_p(\nu, t)$ solved separately at each ν, t point.

Seeing The Pointing Errors



- Residual image, 298 sources subtracted
- Per-channel selfcal + closure errors
- Qualitatively similar to NEWSTAR map (uniform vs. radial weighting was used)
- Dominant feature is residuals from off-axis sources

Solving For Pointing Errors

- Bhatnagar's approach, in terms of our ME:

$$\mathbf{V}_{pq} = \overbrace{\mathbf{G}_p}^{\text{gain \& bandpass}} \underbrace{\left(\sum_s \overbrace{\mathbf{E}_p^{(s)}}^{\text{beam}} \overbrace{\mathbf{X}_{pq}}^{\text{source coherency}} \mathbf{E}_q^{(s)\dagger} \right)}_{\text{sum over sources}} \mathbf{G}_q^\dagger$$

Instead of using $\mathbf{E}_p^{(s)} \equiv E(l, m, \nu)$ for all p ,
 offset the beam pattern at each antenna p by $\Delta l_p, \Delta m_p$:
 $\mathbf{E}_p(l, m, \nu) = E(l + \Delta l_p, m + \Delta m_p, \nu)$

...and solve for the offsets.

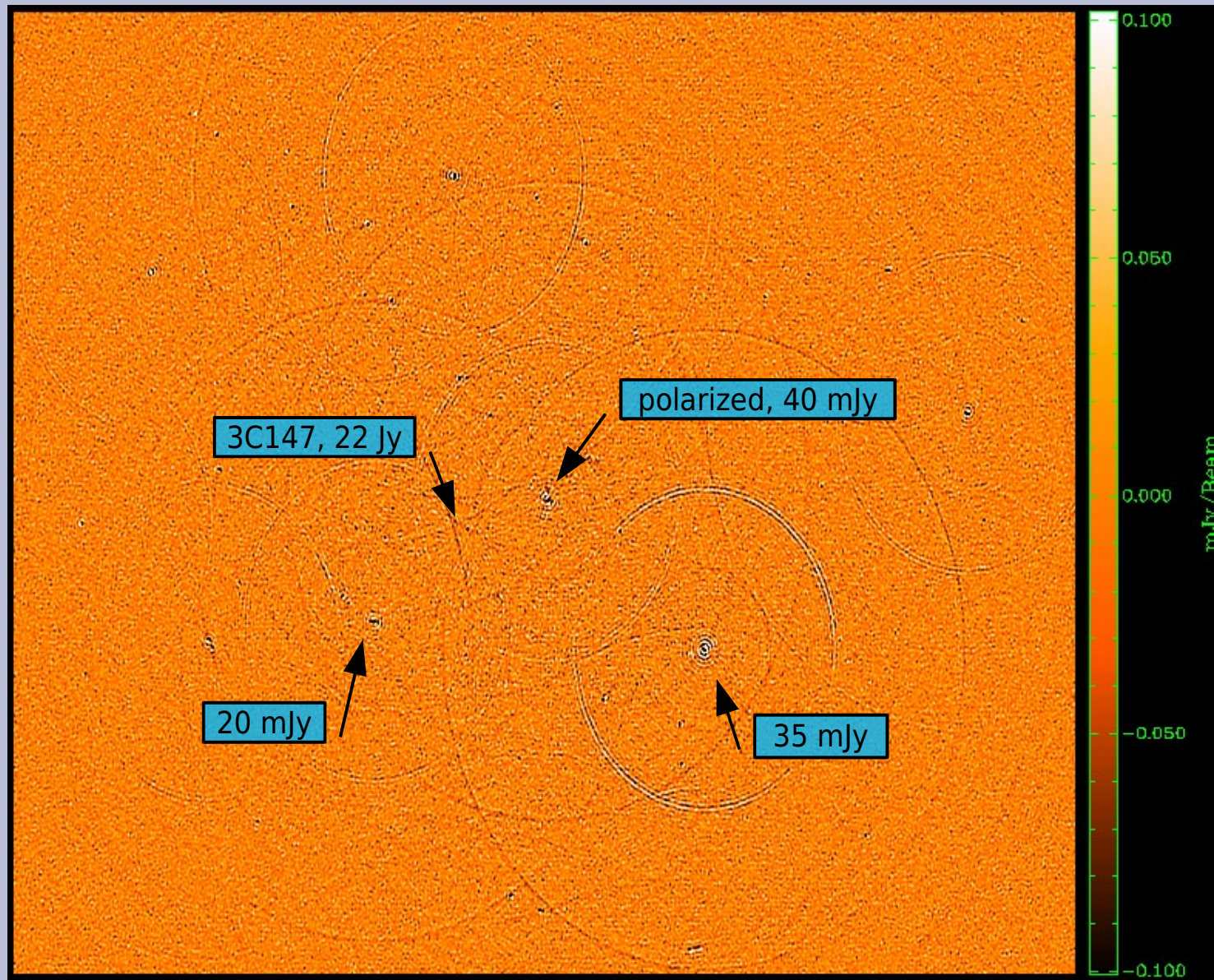
Differential Gains

- Or we can introduce differential gains:

$$\mathbf{V}_{pq} = \overbrace{\mathbf{G}_p}^{\text{gain \& bandpass}} \underbrace{\left(\sum_s \overbrace{\Delta \mathbf{E}_p^{(s)}}^{\text{differential gain}} \overbrace{\mathbf{E}_p^{(s)}}^{\text{beam}} \overbrace{\mathbf{X}_{pq}}^{\text{source coherency}} \mathbf{E}_q^{(s)\dagger} \Delta \mathbf{E}_q^{(s)\dagger} \right)}_{\text{sum over sources}} \mathbf{G}_q^\dagger$$

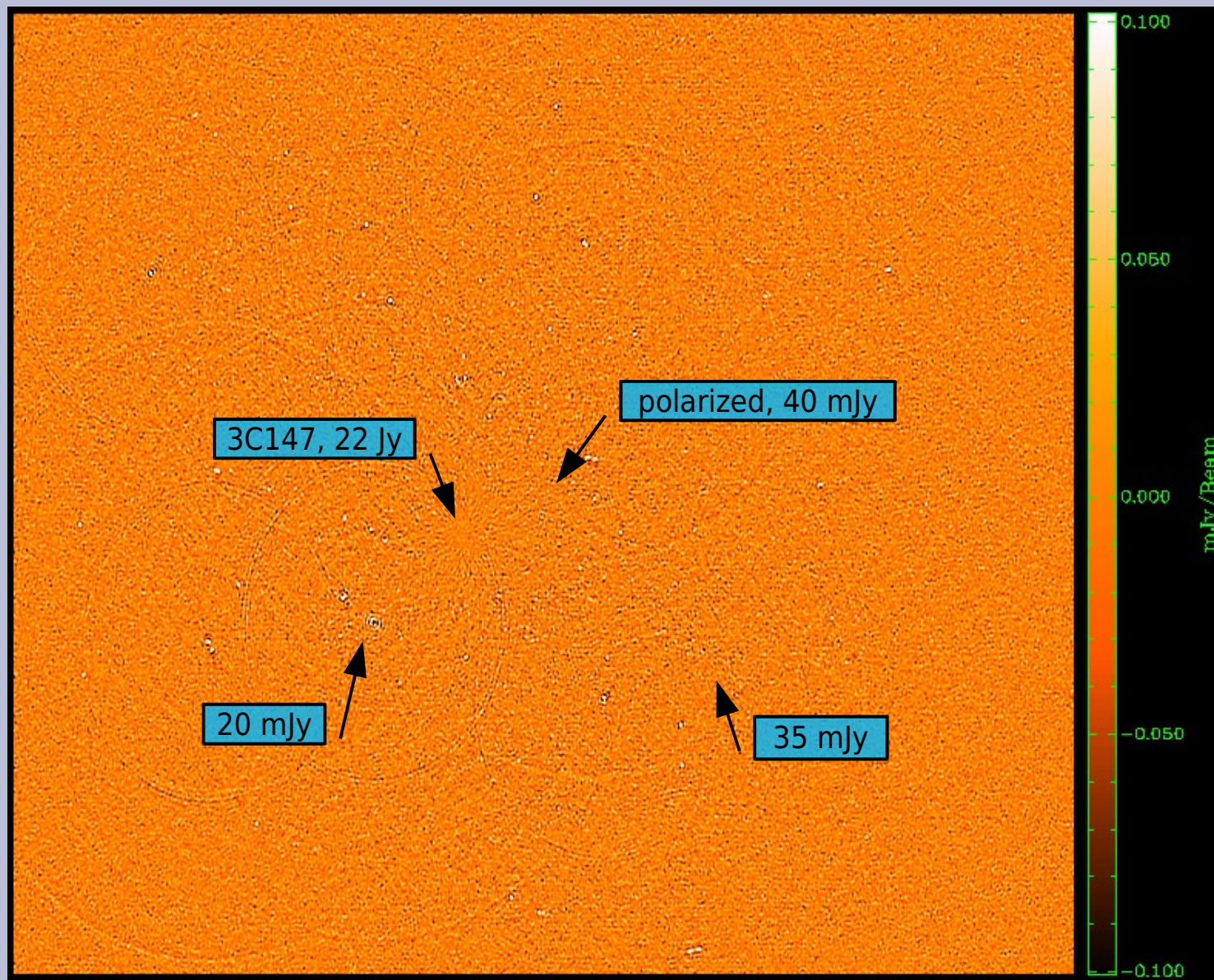
$\Delta \mathbf{E}_p^{(s)}$ is frequency-independent, slowly varying in time.
 Solvable for a handful of "troublesome" sources,
 and set to unity for the rest.

Flyswatter I



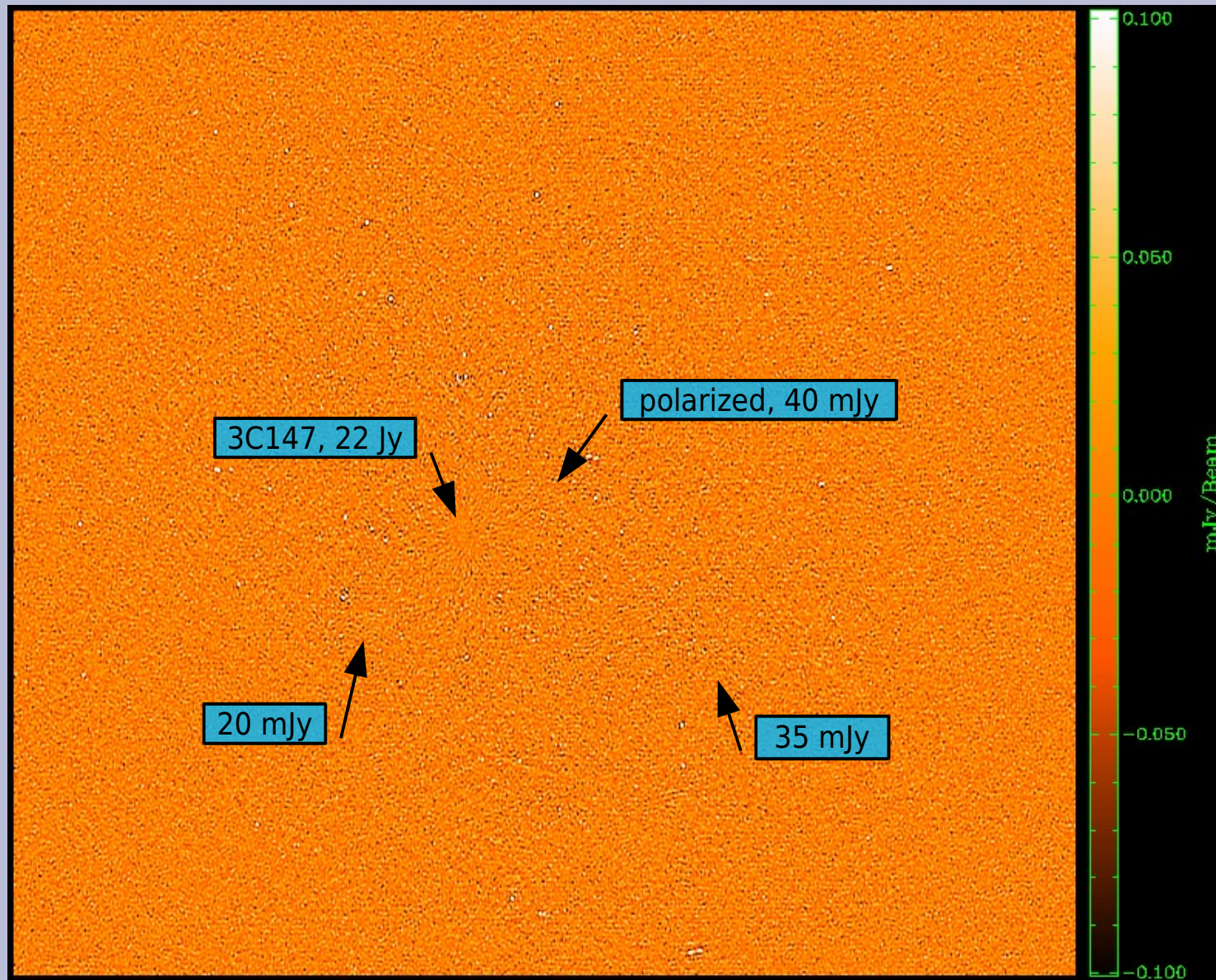
- The “before” image.

Flyswatter II



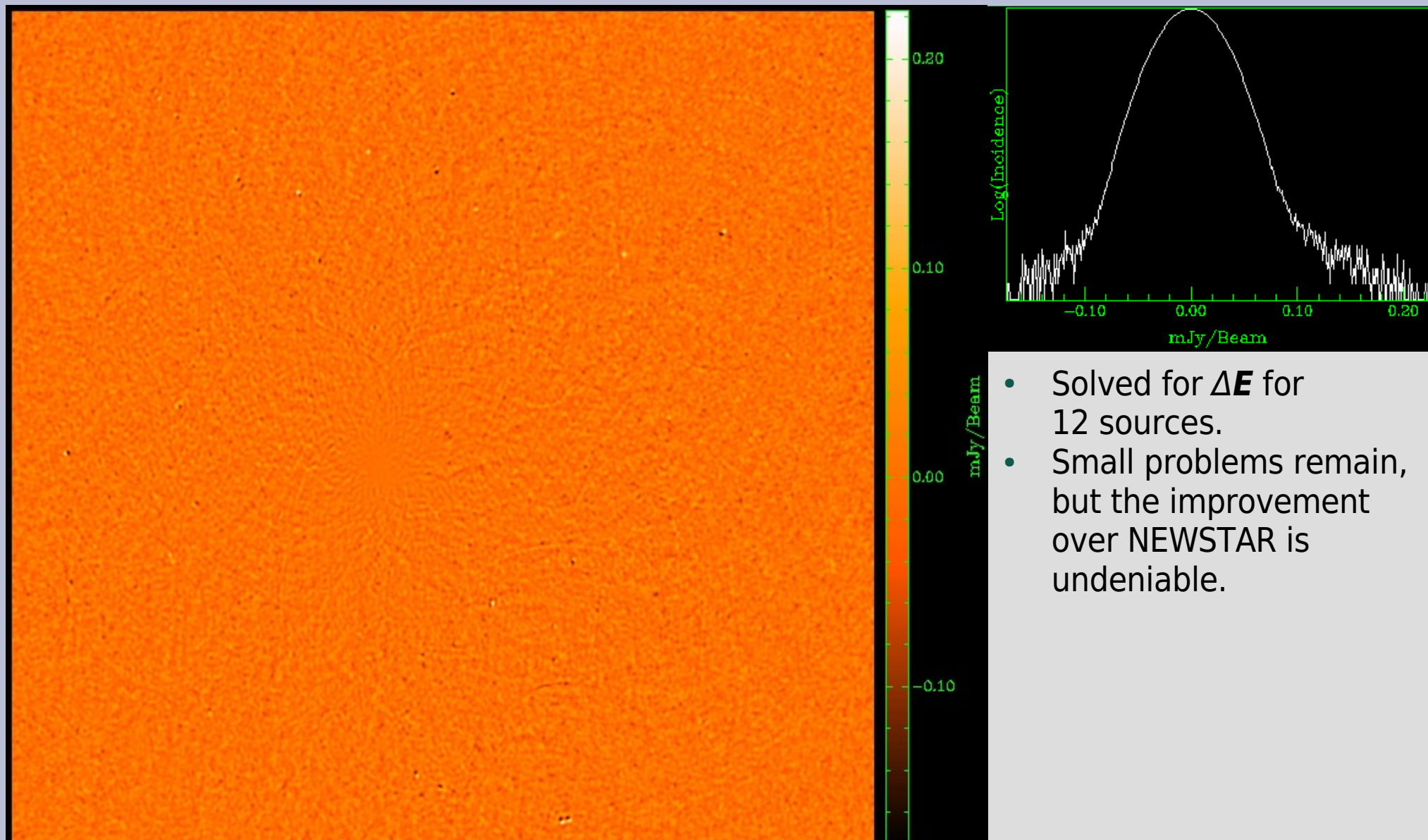
- Solved for ΔE for 5 sources.

Flyswatter III



- Solved for ΔE for 10 sources.

The Best Map So Far



Some Parameter Counts

- We're throwing extra degrees of freedom (the $\Delta \mathbf{E}$'s) at the model, how bad is this?
- Per-channel selfcal (14 antennas, 70 baselines, 30 frequency channels):
2*14 complex gains per t/v point,
2*70 complex measurements per t/v point
- One extra $\Delta \mathbf{E}$ term:
2*14 complex gains **per 30*60 t/v points**,
~.015 of a parameter per t/v point!
- But with bandpass calibration:
2*14 **G**-gains per 30 t/v points ~ 1 per t/v point
2*30 **B**-gains per 60 t/v points ~ 1 per t/v point

MeqTrees Status

<http://www.astron.nl/meqwiki>

- Binary release 1.0: March 5 (4 days early!)
 - Chris Williams, Stef Salvini (OeRC)
 - .deb packages for Ubuntu 8.04, 8.10 32/64 bit
 - other distros to be added according to demand
- Can be checked out & built from source
 - Debian, RH & derivatives, SuSE, Gentoo
- OSX port done by Mike Sipior
 - see wiki for details
 - dependency libraries & toolchain currently THE major roadblock
 - will be added to binary release eventually...

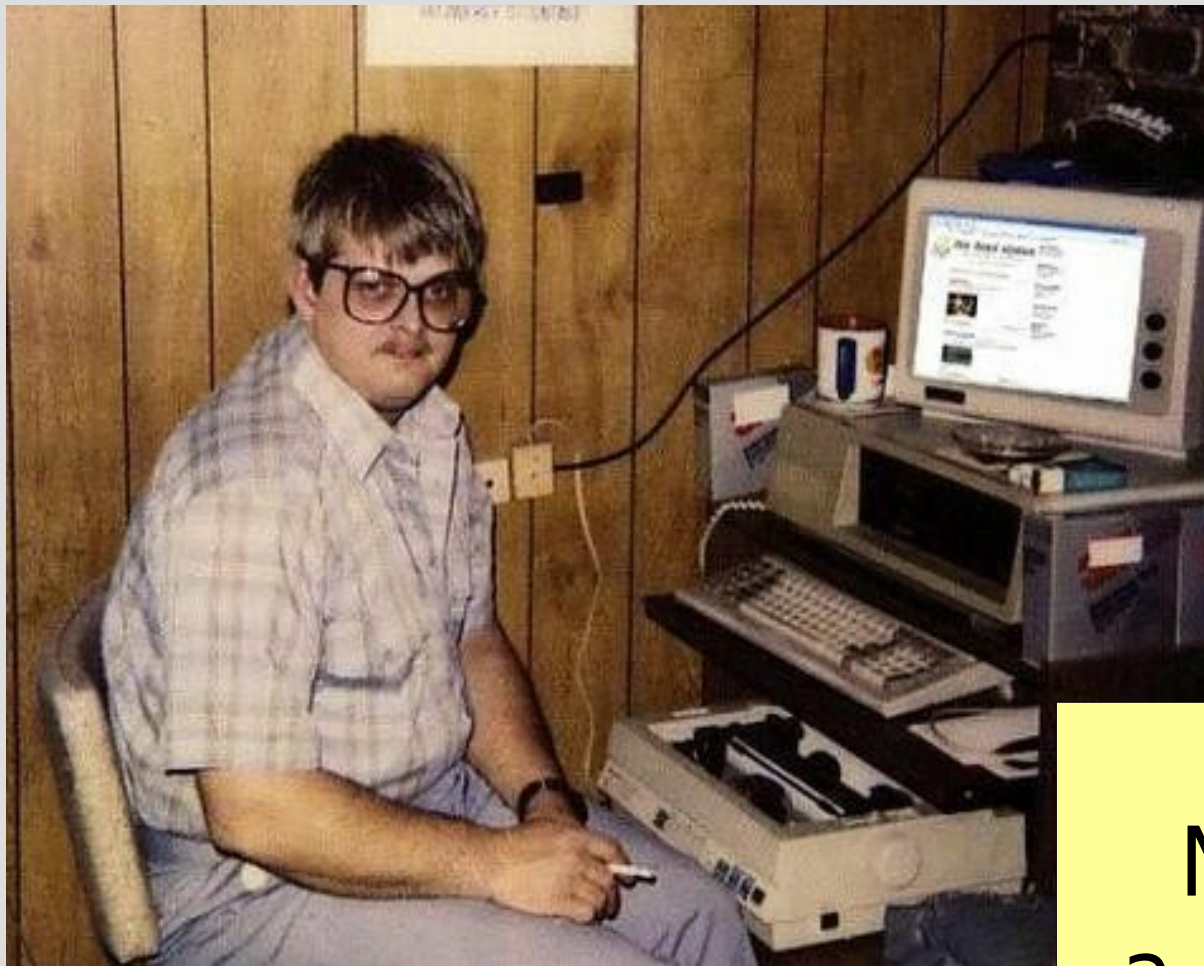
The TTU

- Inspired by the BTU – The Brouw Time Unit ($\approx \frac{1}{2}$ quiet afternoon)
- 1 Tree Time Unit \approx 45 minutes
 - which is how long a Sony extended capacity laptop battery lasts under decent CPU load.
- ...by a fortunate coincidence, is also how long it takes (me) to try something out in MeqTrees, from idea to image.
 - differential gains
 - tropospheric refraction

PURR

- “PURR is Useful for Remembering Reductions”
- Disciplined people keep notes.
- Undisciplined people write software to keep notes for them.
- For a typical Purrr product, see the “3C147 Calibration Tutorial” on **<http://www.astron.nl/meqwiki>**

Group 1: Developers



Developers:

- overworked
- underpaid
- grouchy
- ...but covered in reflected glory

NB: this is not a picture of Oleg

Group 2: Power Users



Power Users:

- have more fun
- steal glory from developers

NB: this is also not a picture of Oleg

Group 3: Button-Pushing Astronomers



NB: this picture is meant to be purely representative

The ideal astronomer UI (Tony Willis):

GO

GO FASTER

**DO WHAT
I MEAN!**

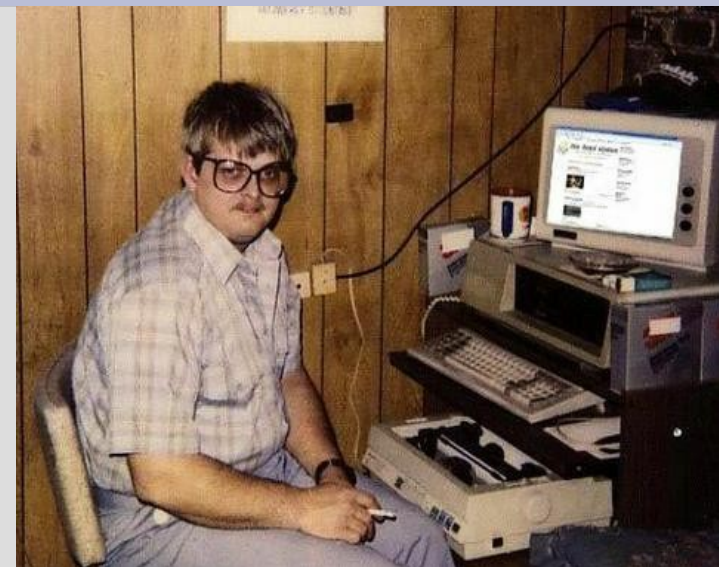
Who Is Going To Solve The SKA Calibration Problem?



a million
astronomers at a
million keyboards?



or power users who
come up with clever
new algorithms?



a few developers in
smoke-filled
cubicles?

Powering The Power Users

- How do we turn button-pushers into power users?
- The TTU: really rapid experimentation
 - and no emotional attachment
- Purr
 - effortless log-keeping
 - ...and sharing!

Conclusions

- MeqTrees is installable.
- We can do better than NEWSTAR.
- Differential gains boldly go where no peeling has gone before:
 - cleans up sources 1000 fainter than 3C147,
 - ...whose discernible effects are close to noise,
 - with very few extra parameters.
- Noordam Conjecture: “If it's bright enough to cause trouble, it's bright enough to be solved for.”
- Smirnov Corollary: usually within 1 TTU.