

**Lecture 6:**

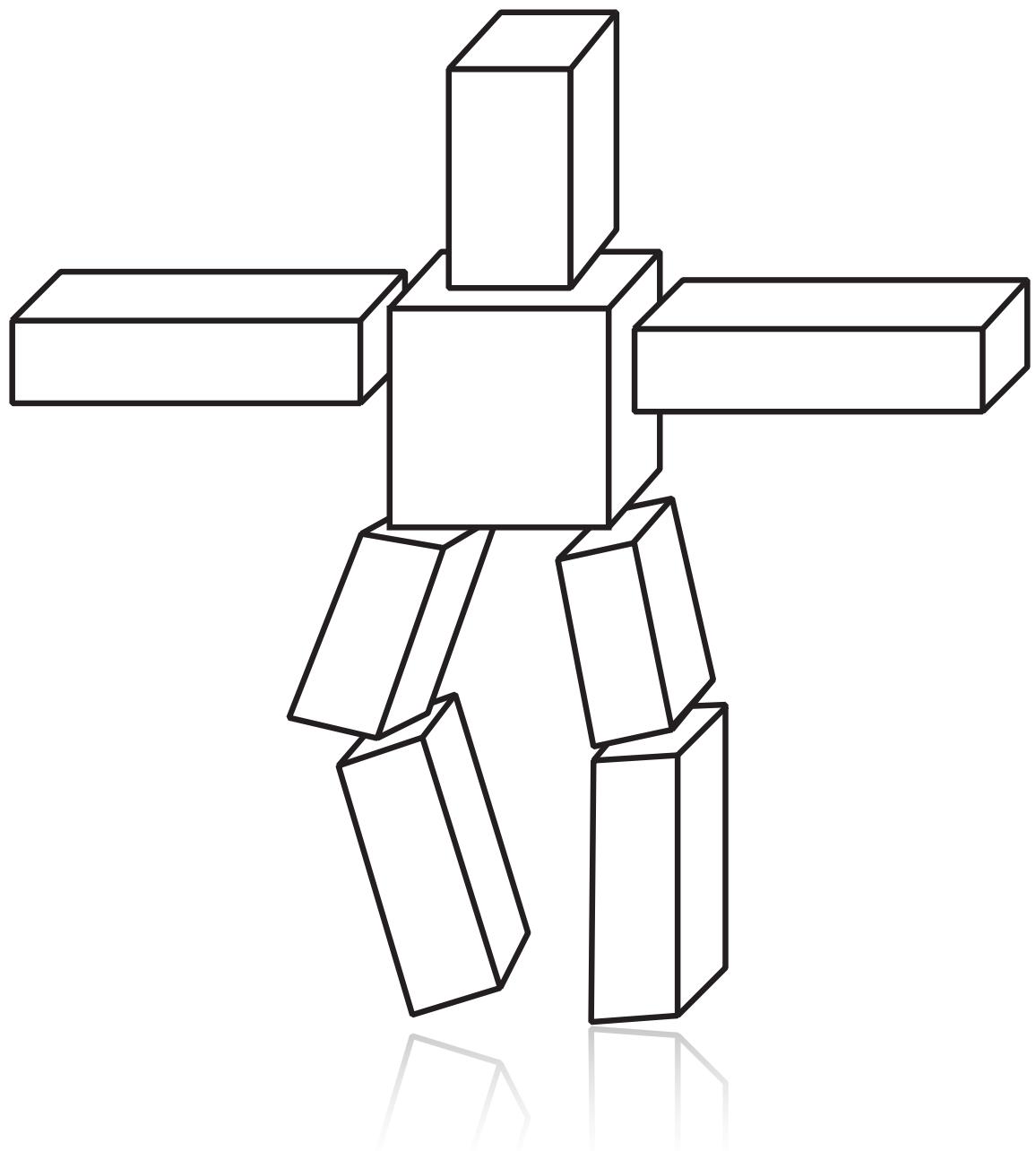
# **Introduction to Geometry**

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**Computer Graphics**  
**CMU 15-462/15-662, Fall 2015**

# Increasing the complexity of our models

Transformations



Geometry



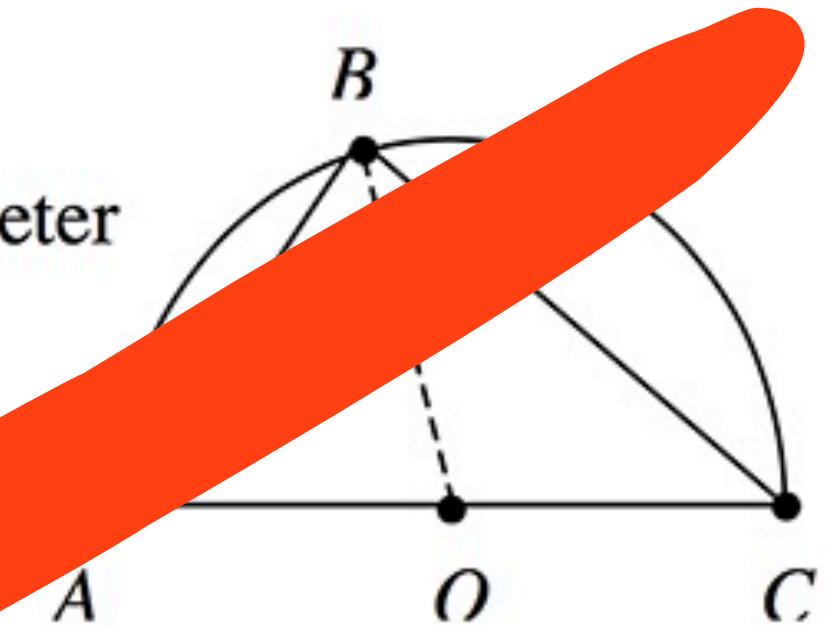
Materials, lighting, ...



# What is geometry?

THEOREM 9.5. Let  $\triangle ABC$  be inscribed in a semicircle with diameter  $\overline{AC}$ .

Then  $\angle ABC$  is a right angle.



*Proof:*

Statement

1. Draw radius  $OB$ . Then  $OB = OC = OA$
2.  $m\angle OBC = m\angle BCA$   
 $m\angle OBA = m\angle BAC$
3.  $m\angle ABC = m\angle OBA + m\angle OBC$
4.  $m\angle ABC + m\angle BCA + m\angle BAC = 180$
5.  $m\angle ABC + m\angle BCA + m\angle OBA = 180$
6.  $2m\angle ABC = 180$
7.  $m\angle ABC = 90$
8.  $\angle ABC$  is a right angle

Given

Isosceles Triangle Theorem

3. Angle Addition Postulate
4. The sum of the interior angles of a triangle is 180
5. Substitution (line 2)
6. Substitution (line 3)
7. Division Property of Equality
8. Definition of Right Angle

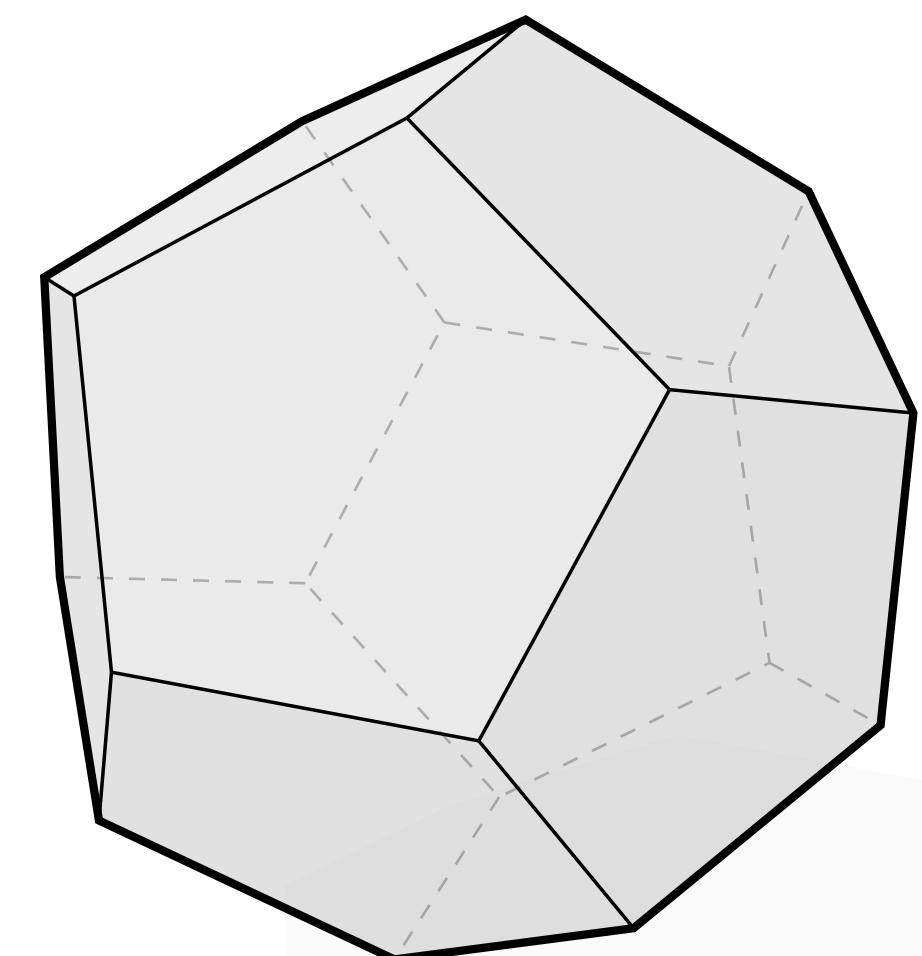
Ceci n'est pas géométrie.

# What is geometry?

“Earth”    “measure”

ge•om•et•ry /jē'ämətrē/ n.

1. The study of shapes, sizes, patterns, and positions.
2. The study of spaces where some quantity (lengths, angles, etc.) can be *measured*.



Plato: "...the earth is in appearance like one of those balls which have leather coverings in twelve pieces..."

# How can we describe geometry?

**IMPLICIT**

$$x^2 + y^2 = 1$$

**LINGUISTIC**

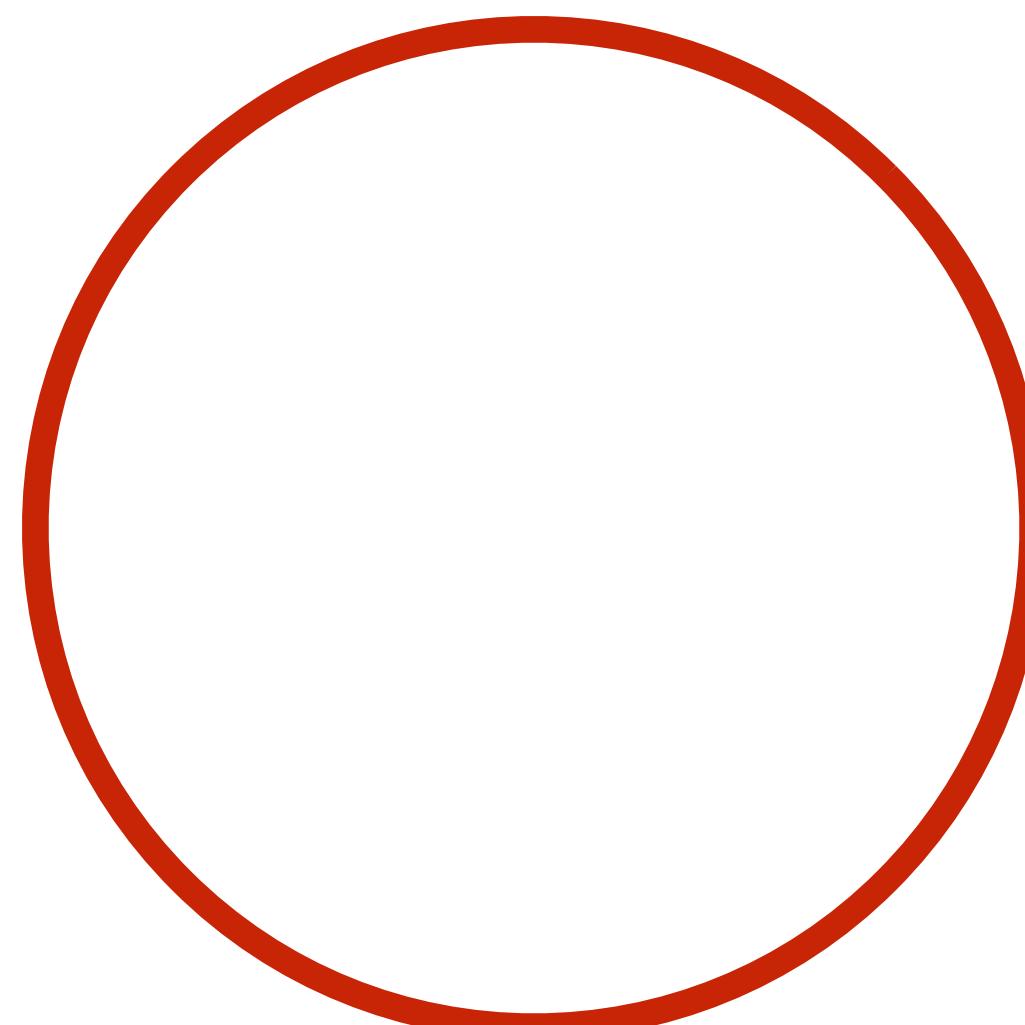
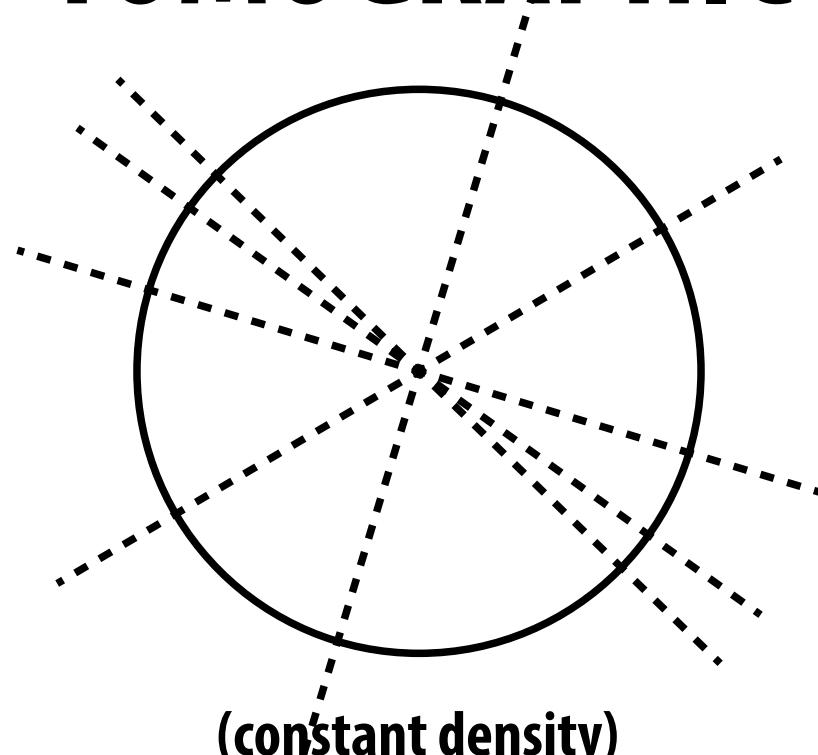
“unit circle”

**EXPLICIT**

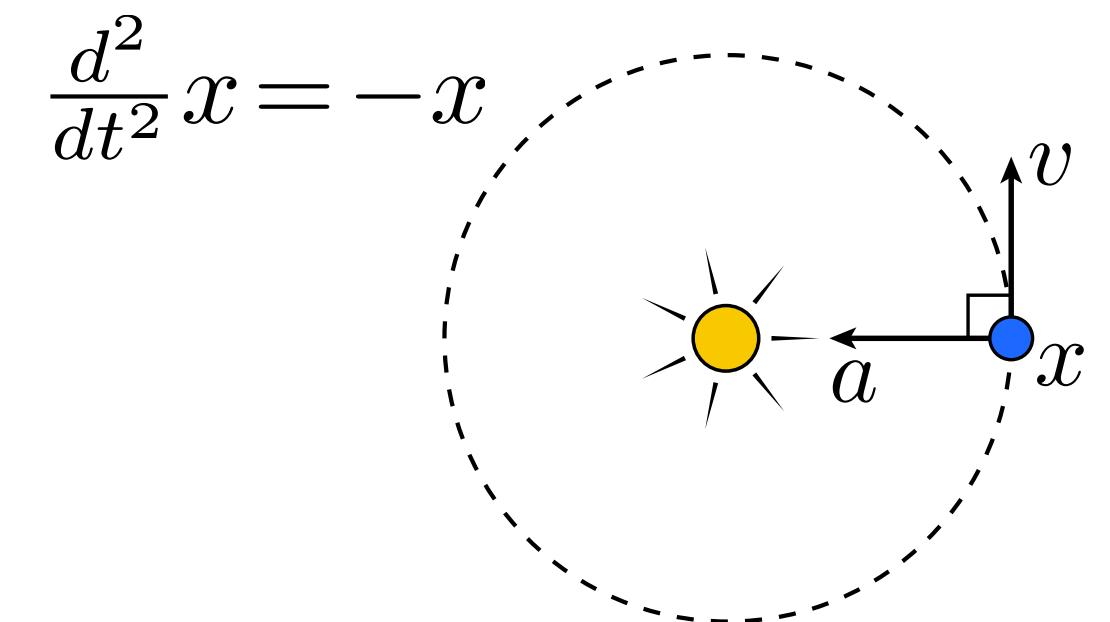
$$(\underbrace{\cos \theta}, \underbrace{\sin \theta})$$

*x*      *y*

**TOMOGRAPHIC**



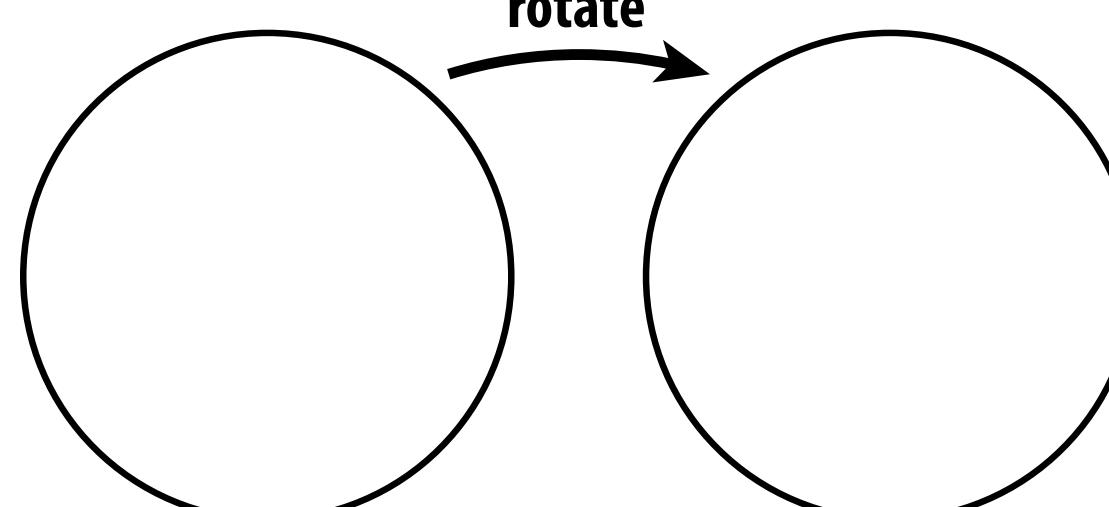
**DYNAMIC**



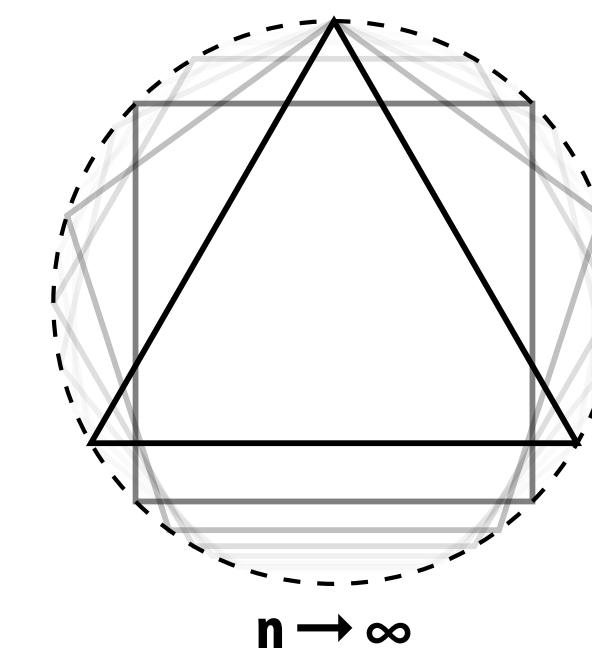
**CURVATURE**

$$\kappa = 1$$

**SYMMETRIC**



**DISCRETE**

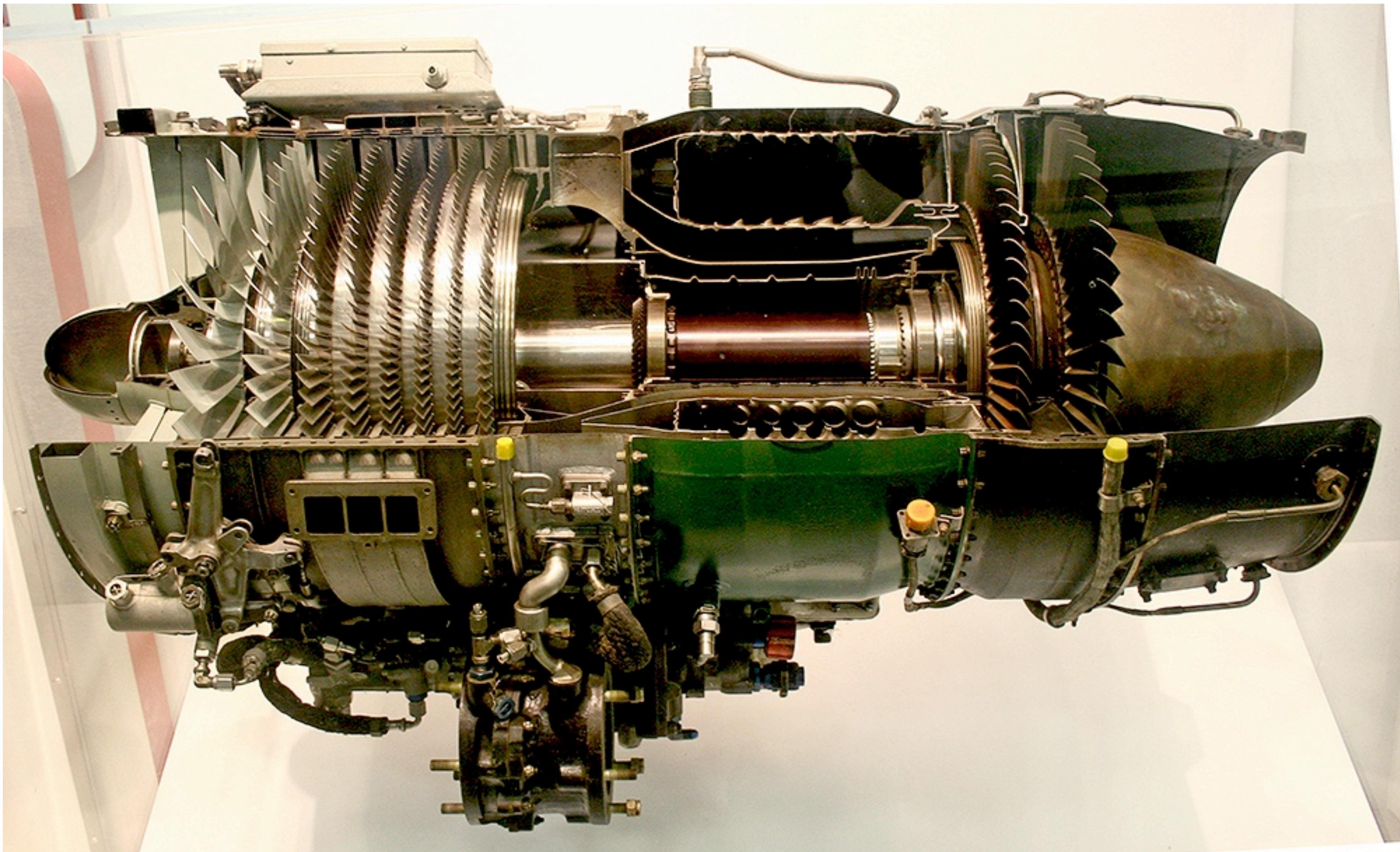


**Given all these options, what's the best  
way to encode geometry on a computer?**

# Examples of geometry



# Examples of geometry



# Examples of geometry



# Examples of geometry



# Examples of geometry



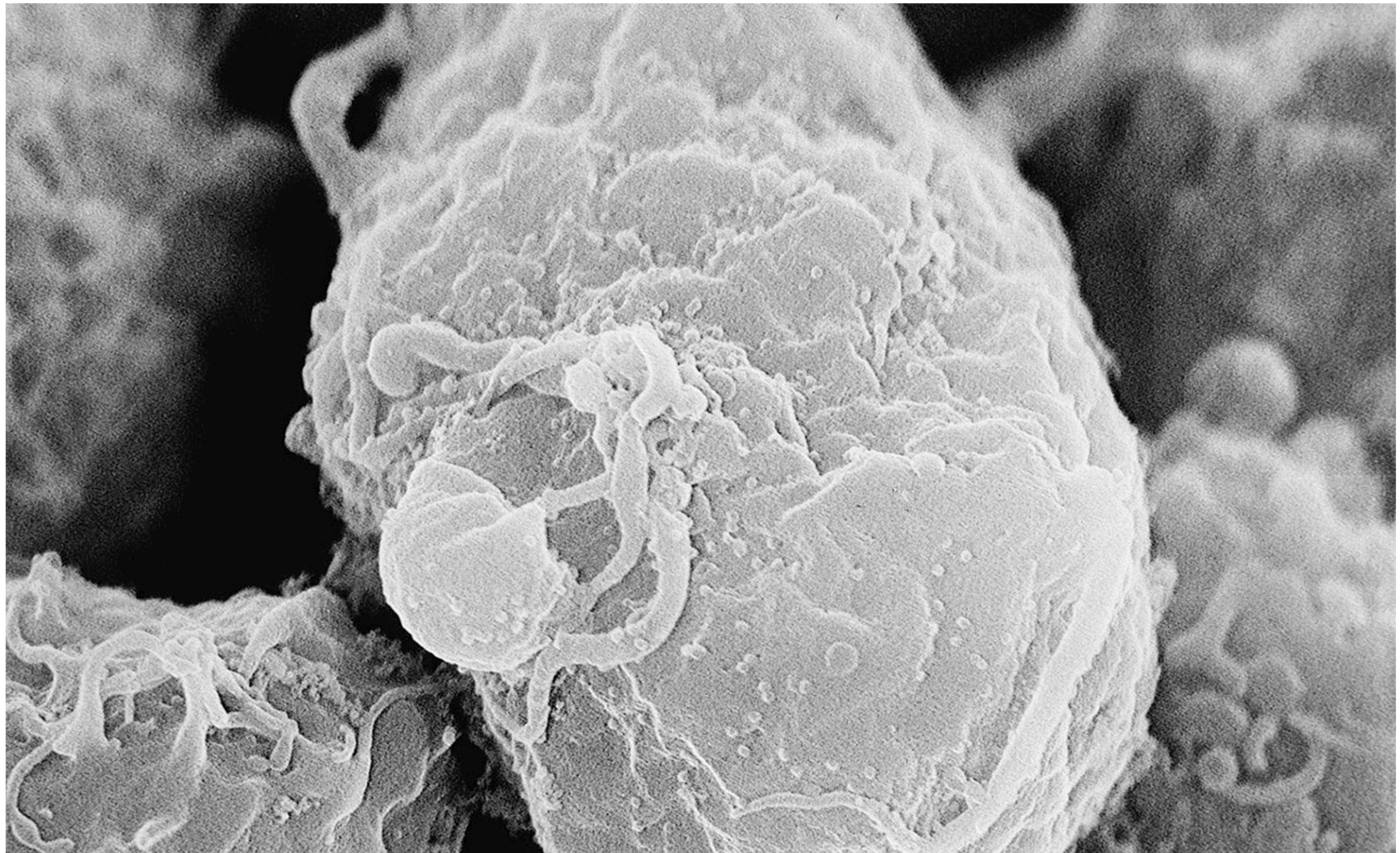
# Examples of geometry



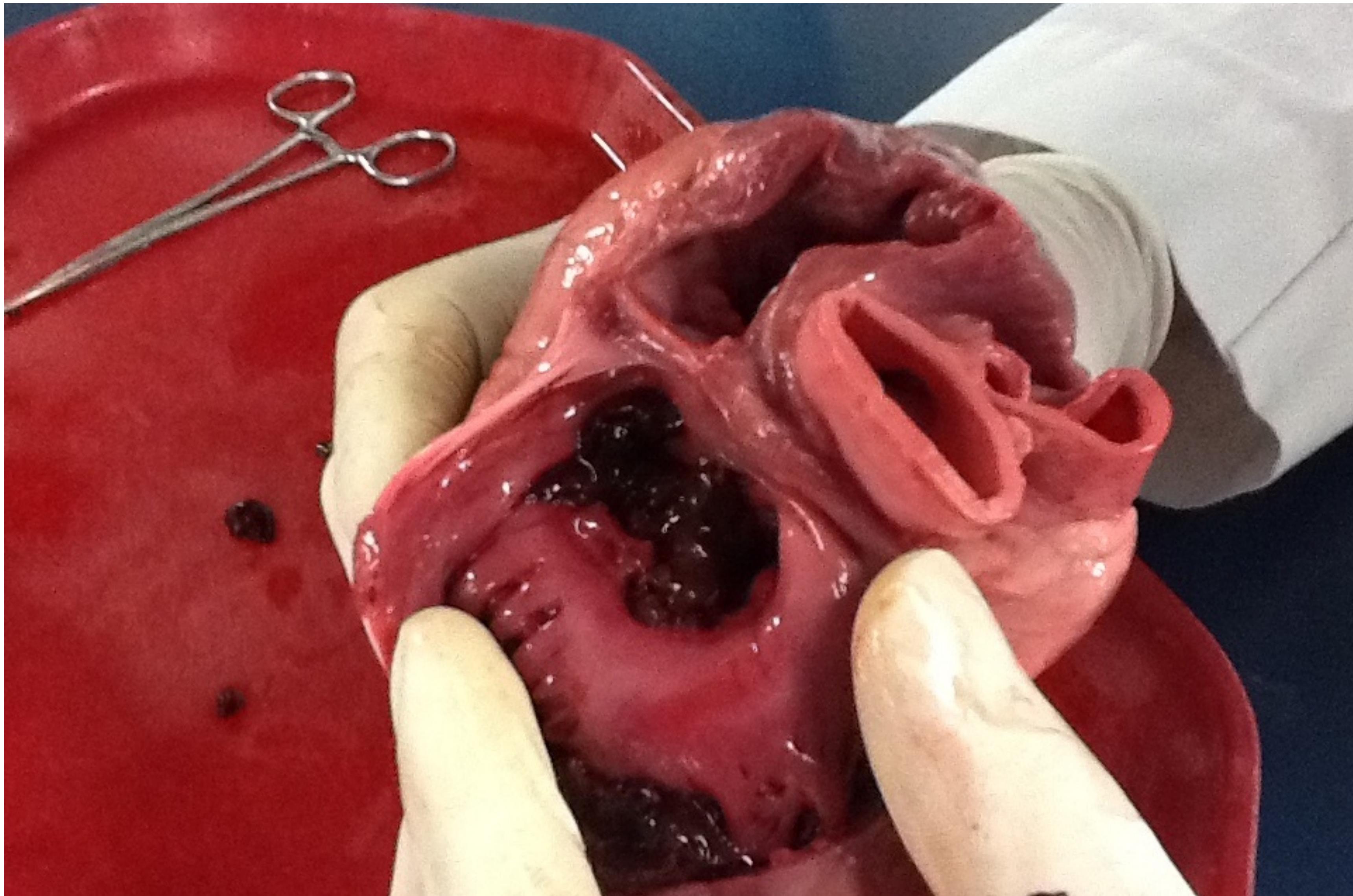
# Examples of geometry



# Examples of geometry



# Examples of geometry



# Examples of geometry



# No one “best” choice—geometry is hard!

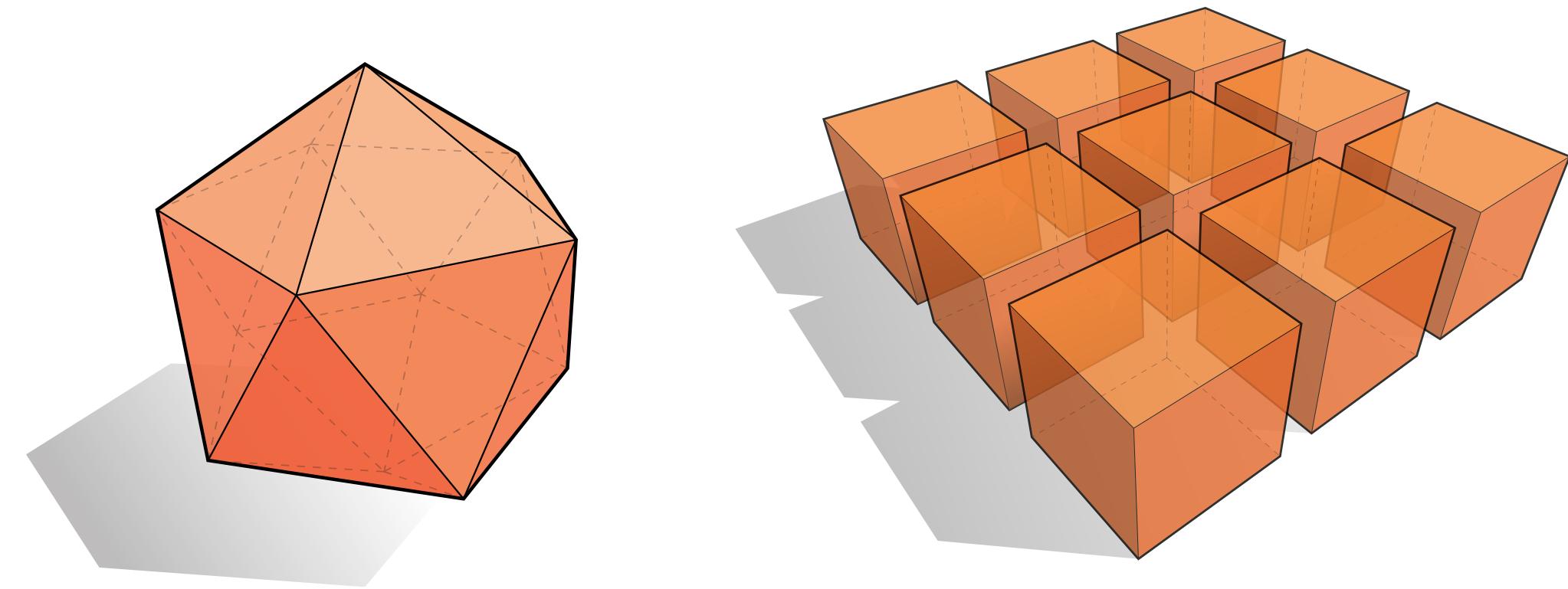
*“I hate meshes.  
I cannot believe how hard this is.  
Geometry is hard.”*

—David Baraff  
**Senior Research Scientist**  
**Pixar Animation Studios**

# *Many ways to digitally encode geometry*

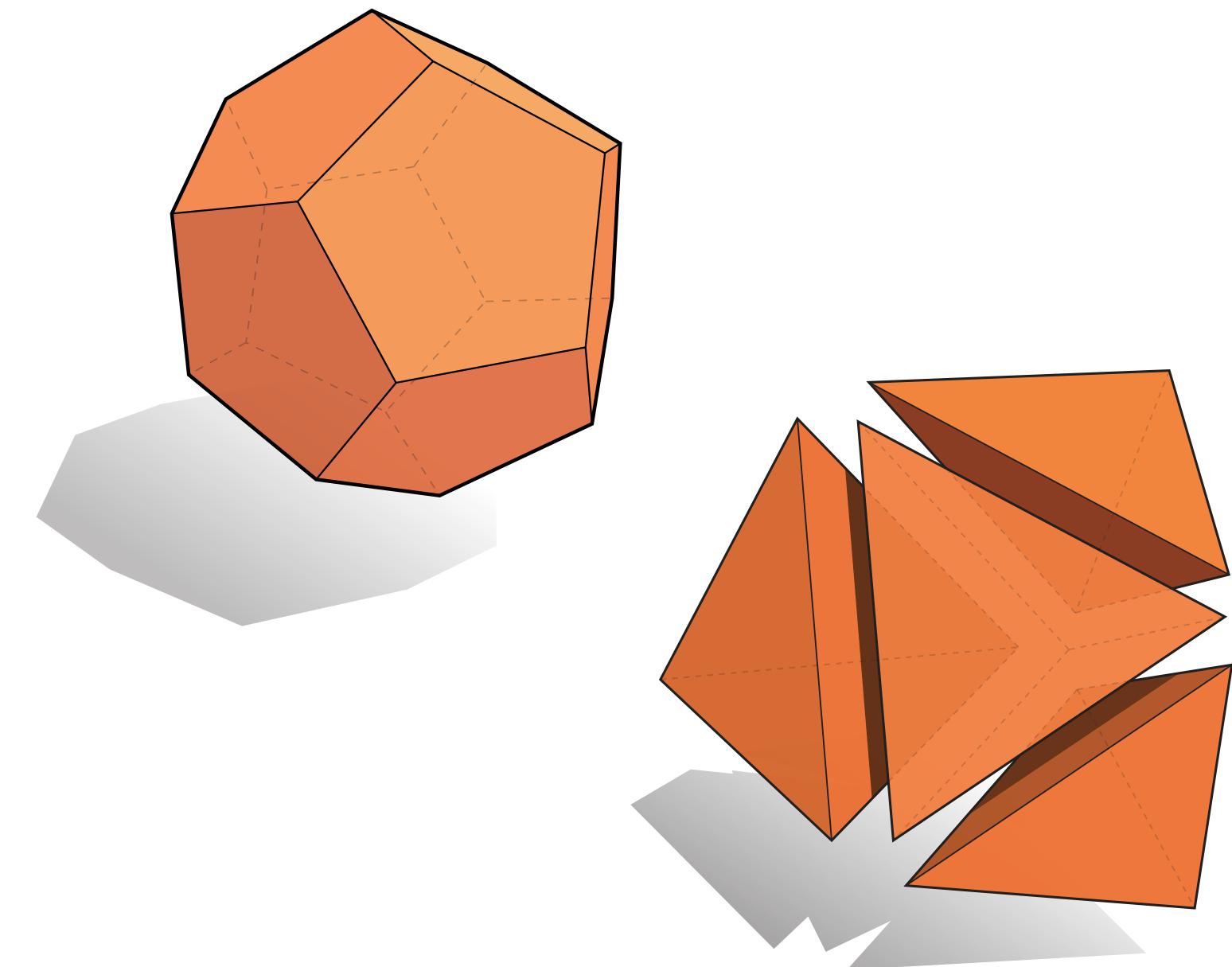
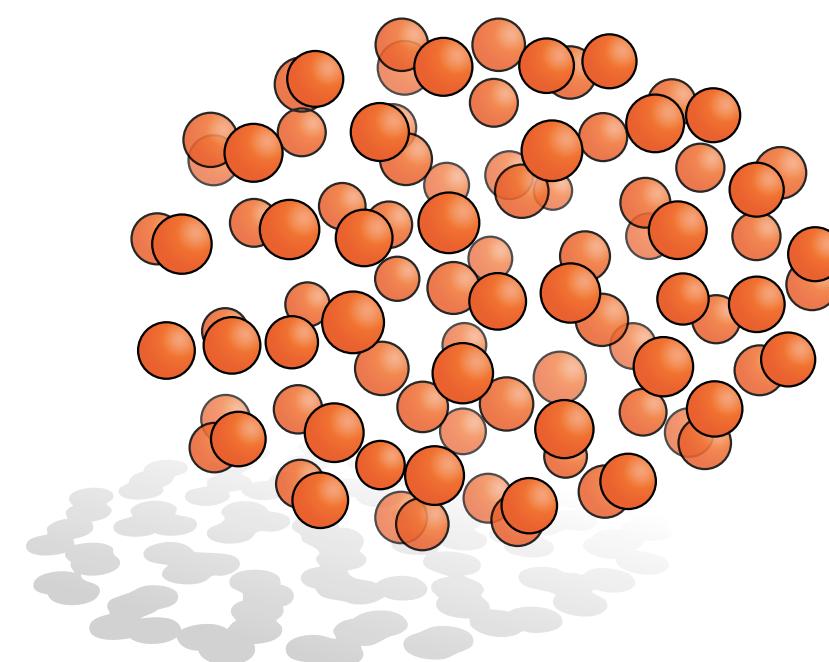
## ■ EXPLICIT

- point cloud
- polygon mesh
- subdivision, NURBS
- L-systems
- ...



## ■ IMPLICIT

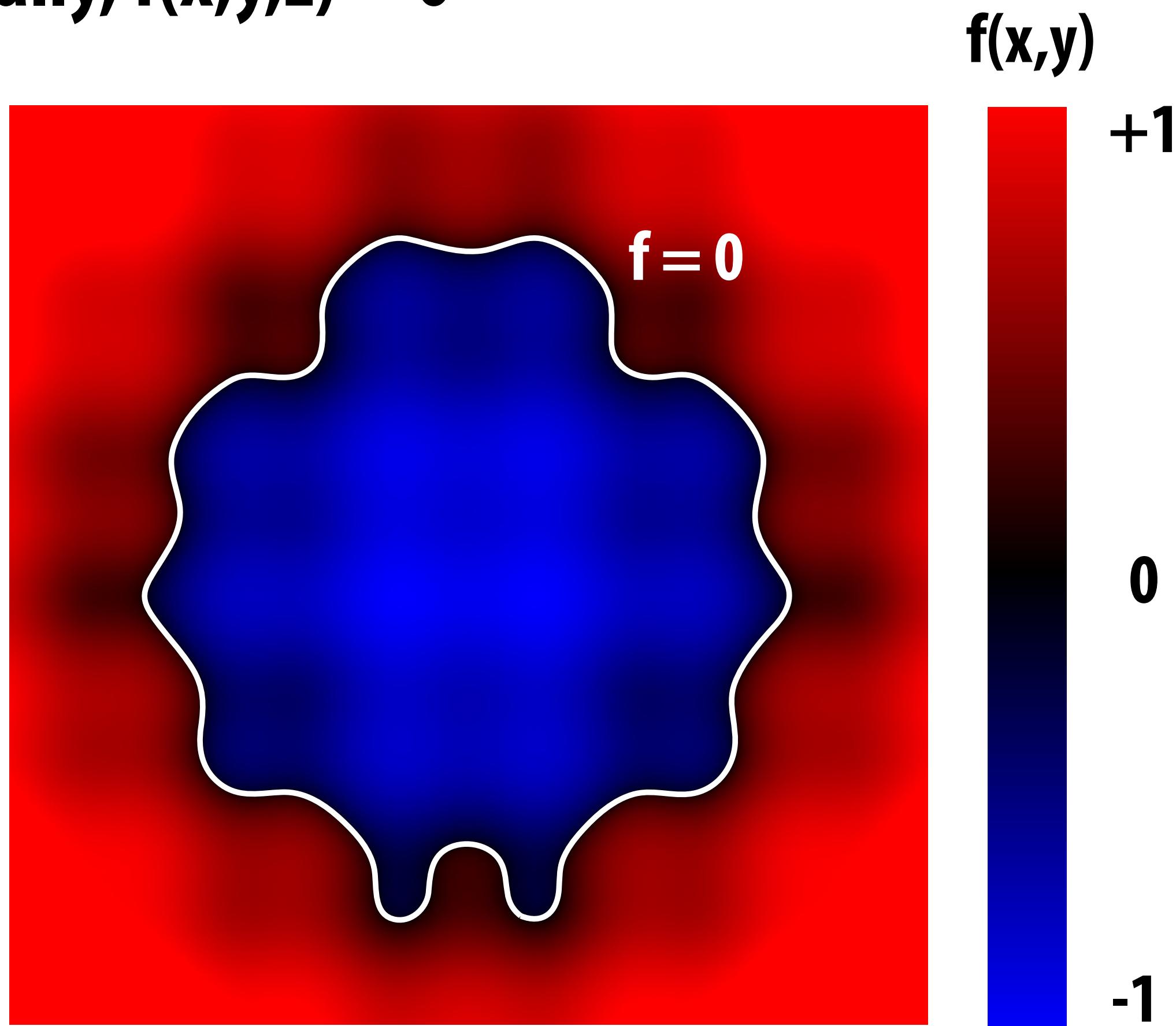
- level set
- algebraic surface
- ...



## ■ Each choice best suited to a different task/type of geometry

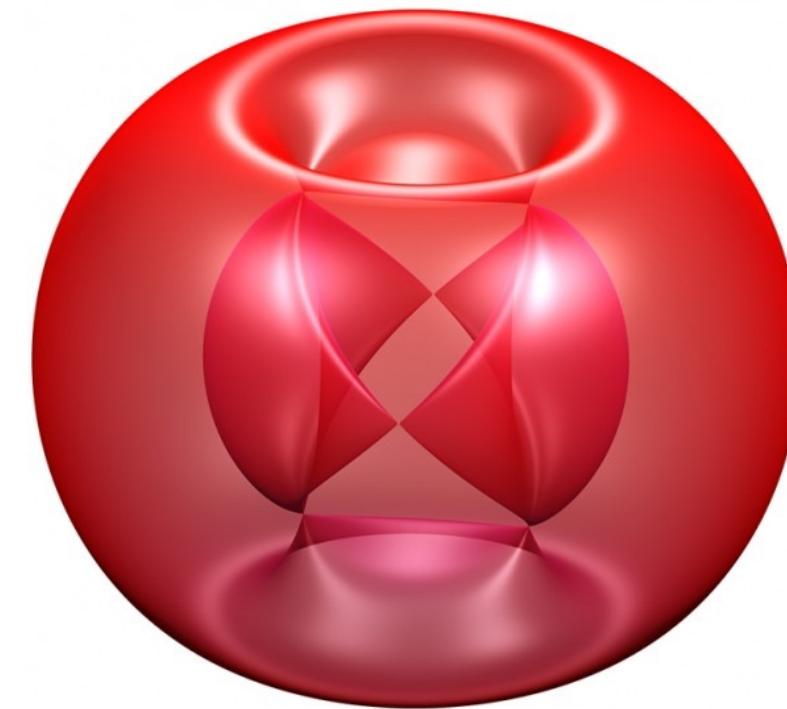
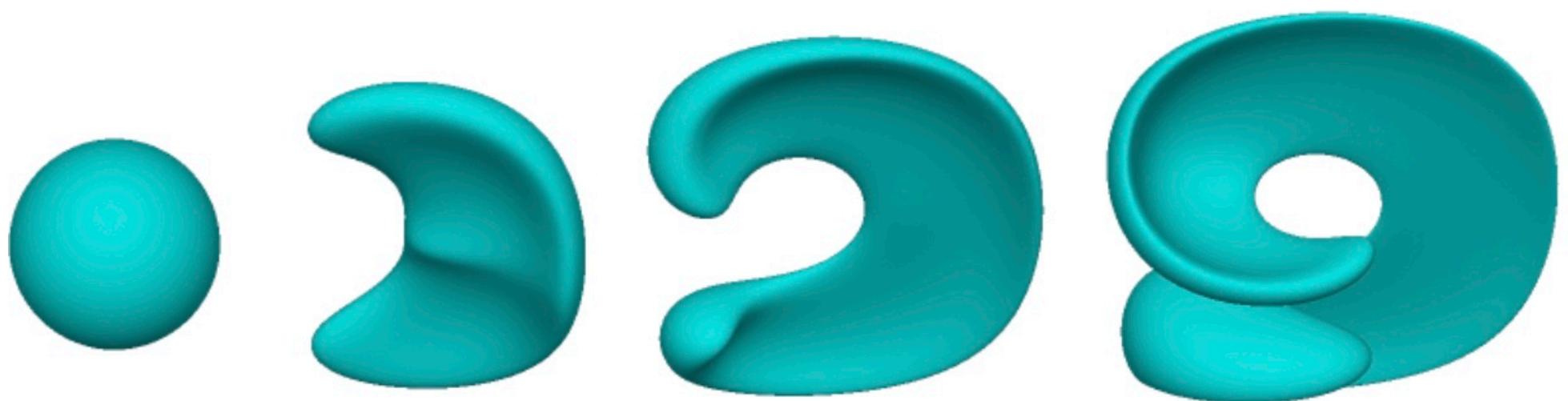
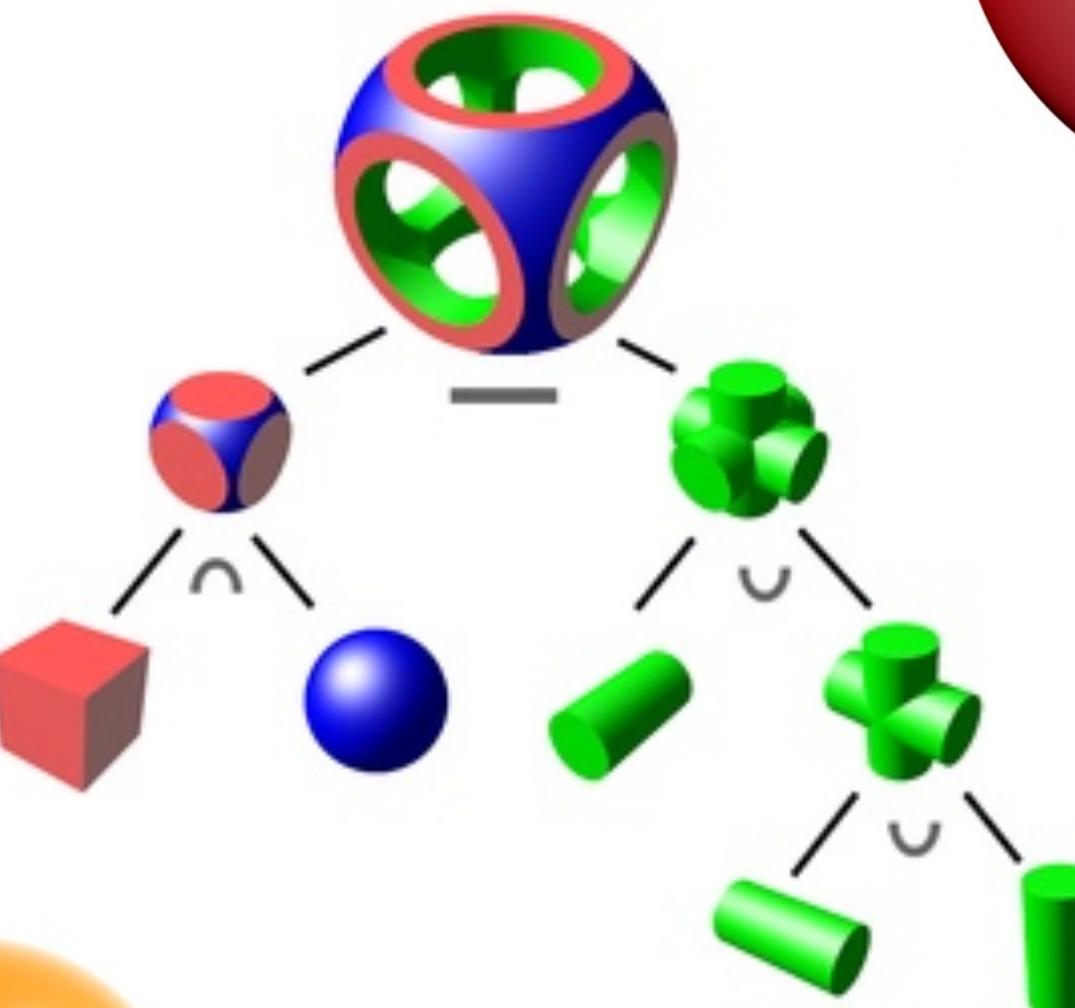
# “Implicit” Representations of Geometry

- Points aren't known directly, but satisfy some relationship
- E.g., unit sphere is all points  $x$  such that  $x^2+y^2+z^2=1$
- More generally,  $f(x,y,z) = 0$



# Many implicit representations in graphics

- algebraic surfaces
- constructive solid geometry
- level set methods
- blobby surfaces
- fractals
- ...



(Will see some of these a bit later.)

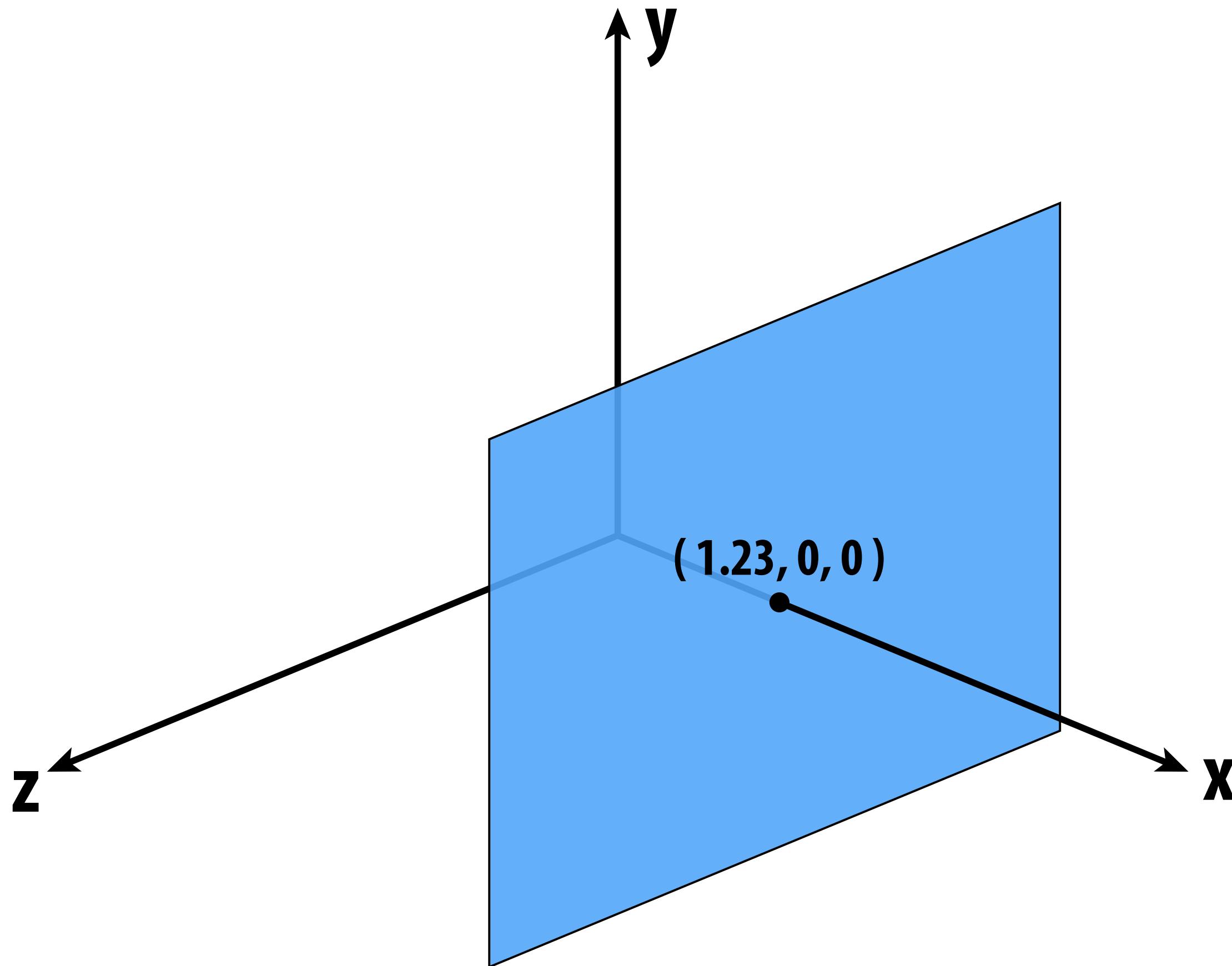
**But first, let's play a game:**

**I'm thinking of an implicit surface  $f(x,y,z)=0$ .**

**Find *any* point on it.**

# Give up?

My function was  $f(x,y,z) = -1.23$  (a plane):



Implicit surfaces make some tasks hard (like sampling).

**Let's play another game.**

I have a new surface  $f(x,y,z) = x^2 + y^2 + z^2 - 1$

I want to see if a point is *inside* it.

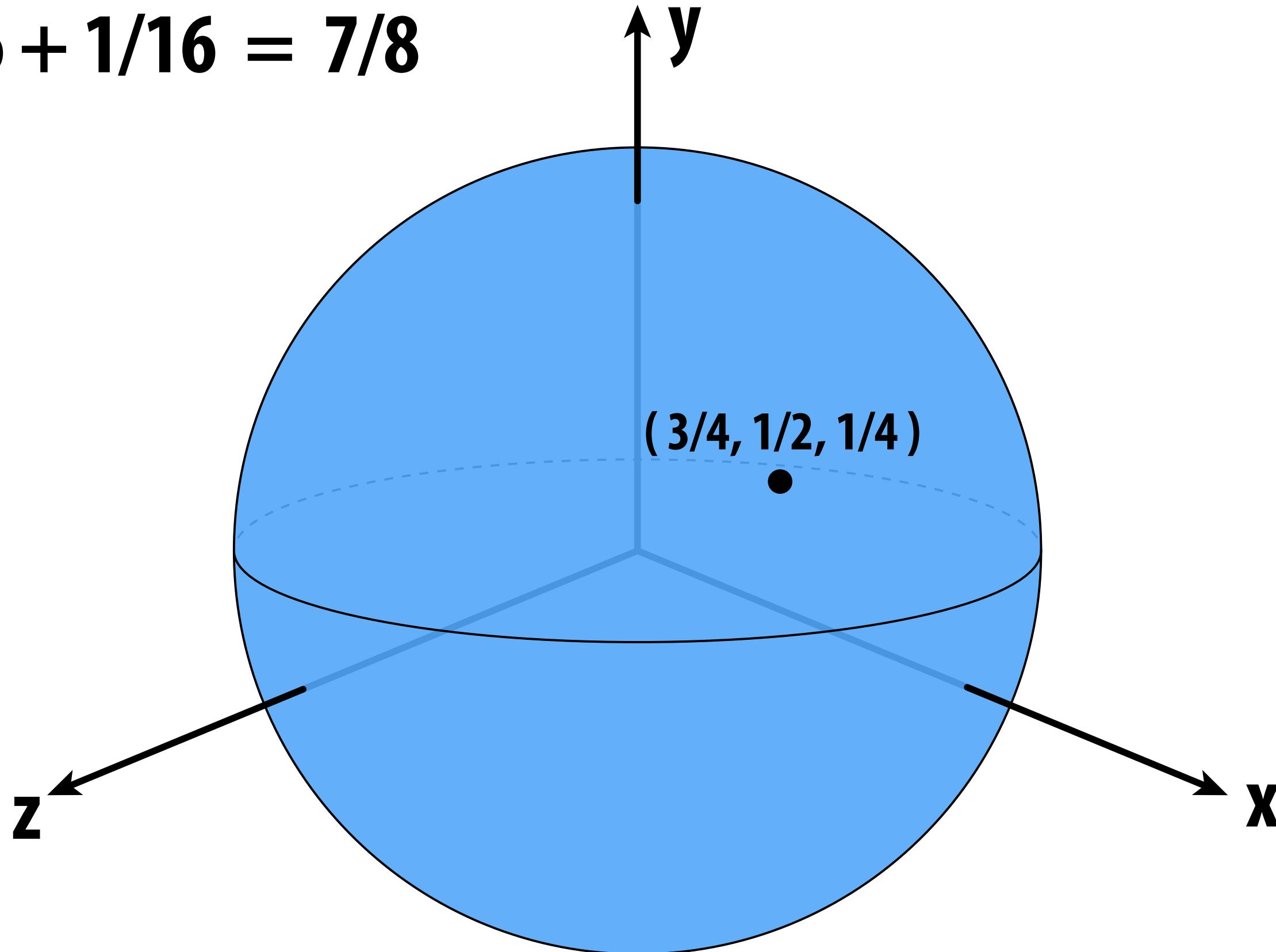
# Check if this point is inside the unit sphere

How about the point (  $3/4, 1/2, 1/4$  )?

$$9/16 + 4/16 + 1/16 = 7/8$$

$$7/8 < 1$$

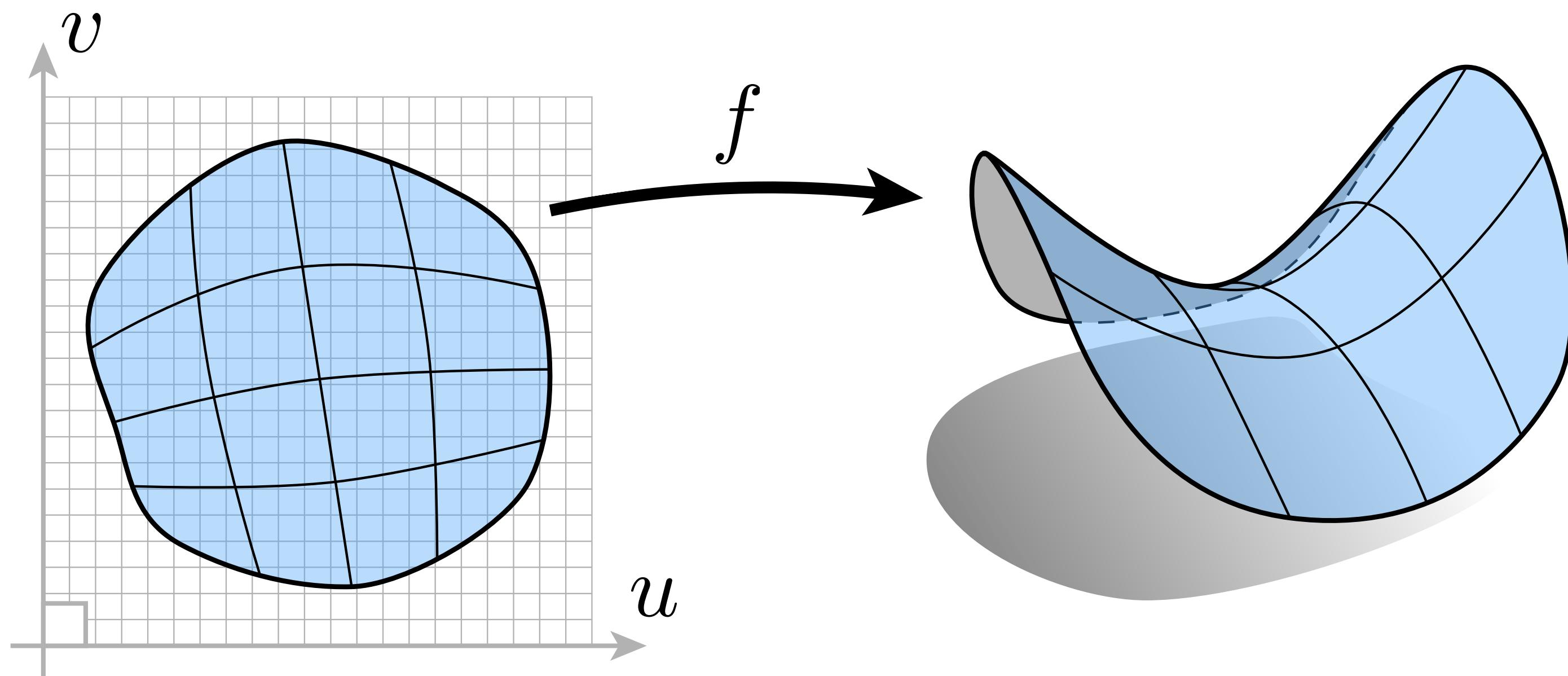
YES.



Implicit surfaces make other tasks easy (like inside/outside tests).

# “Explicit” Representations of Geometry

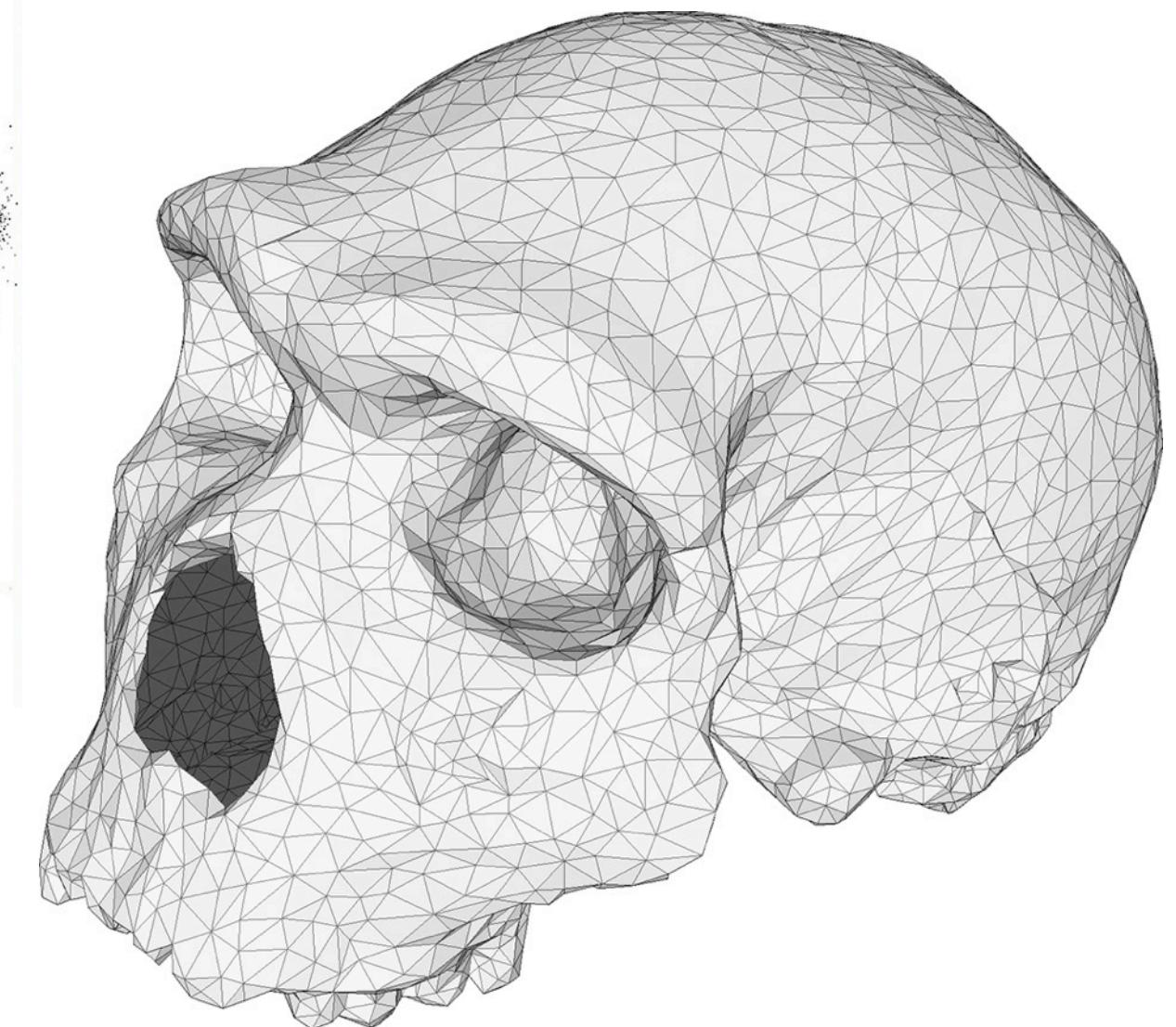
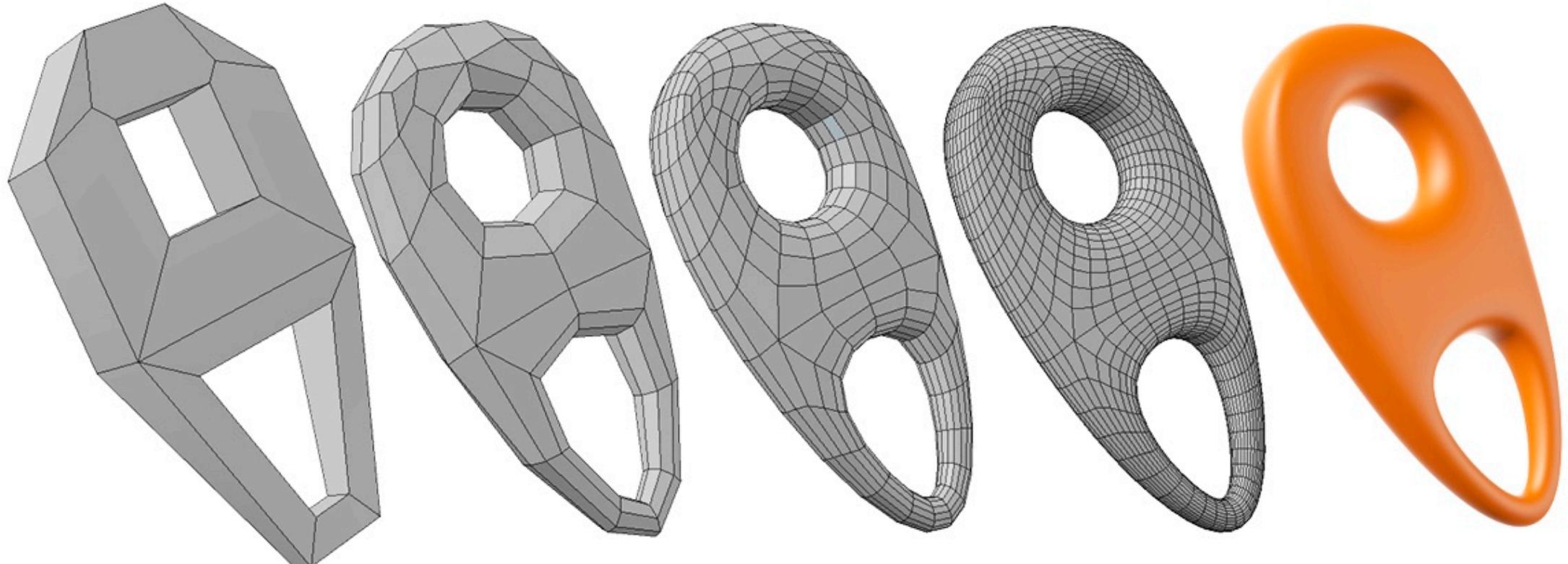
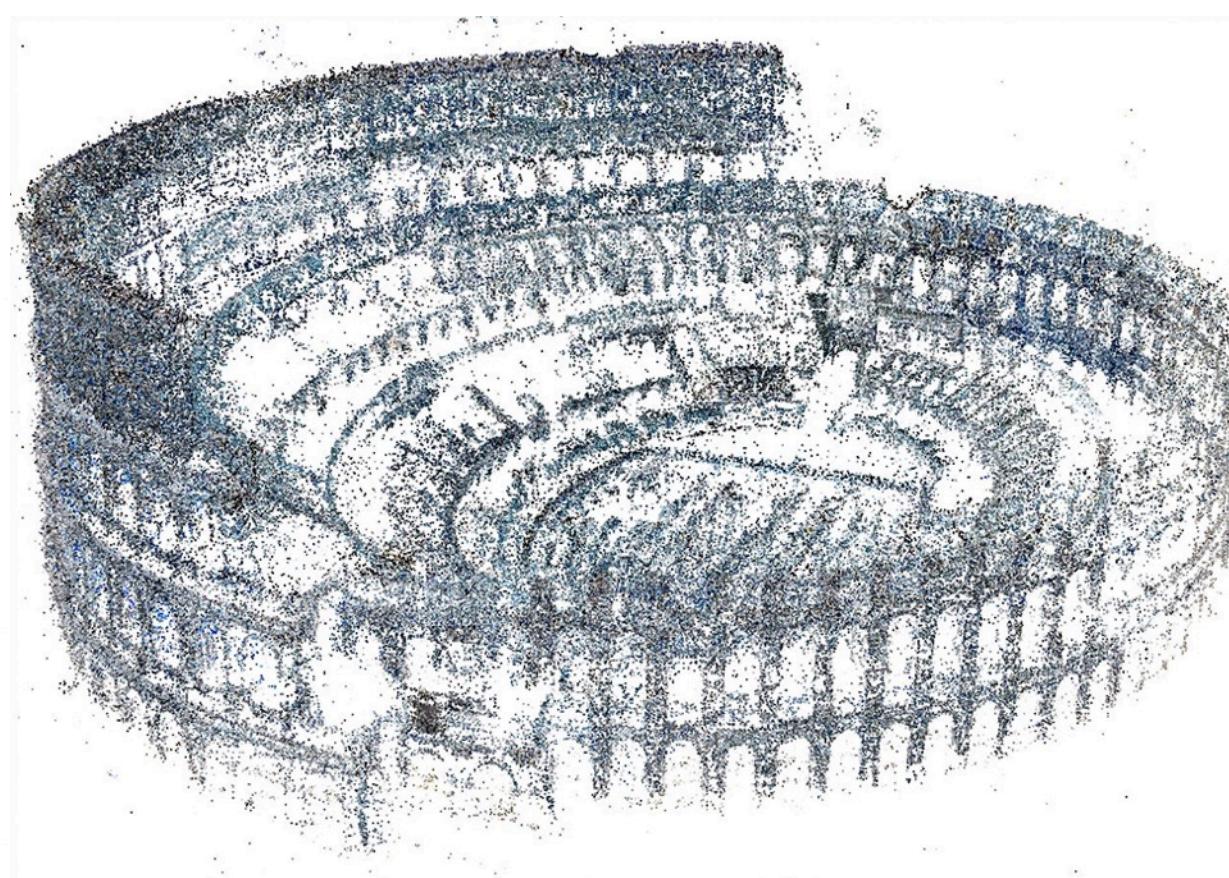
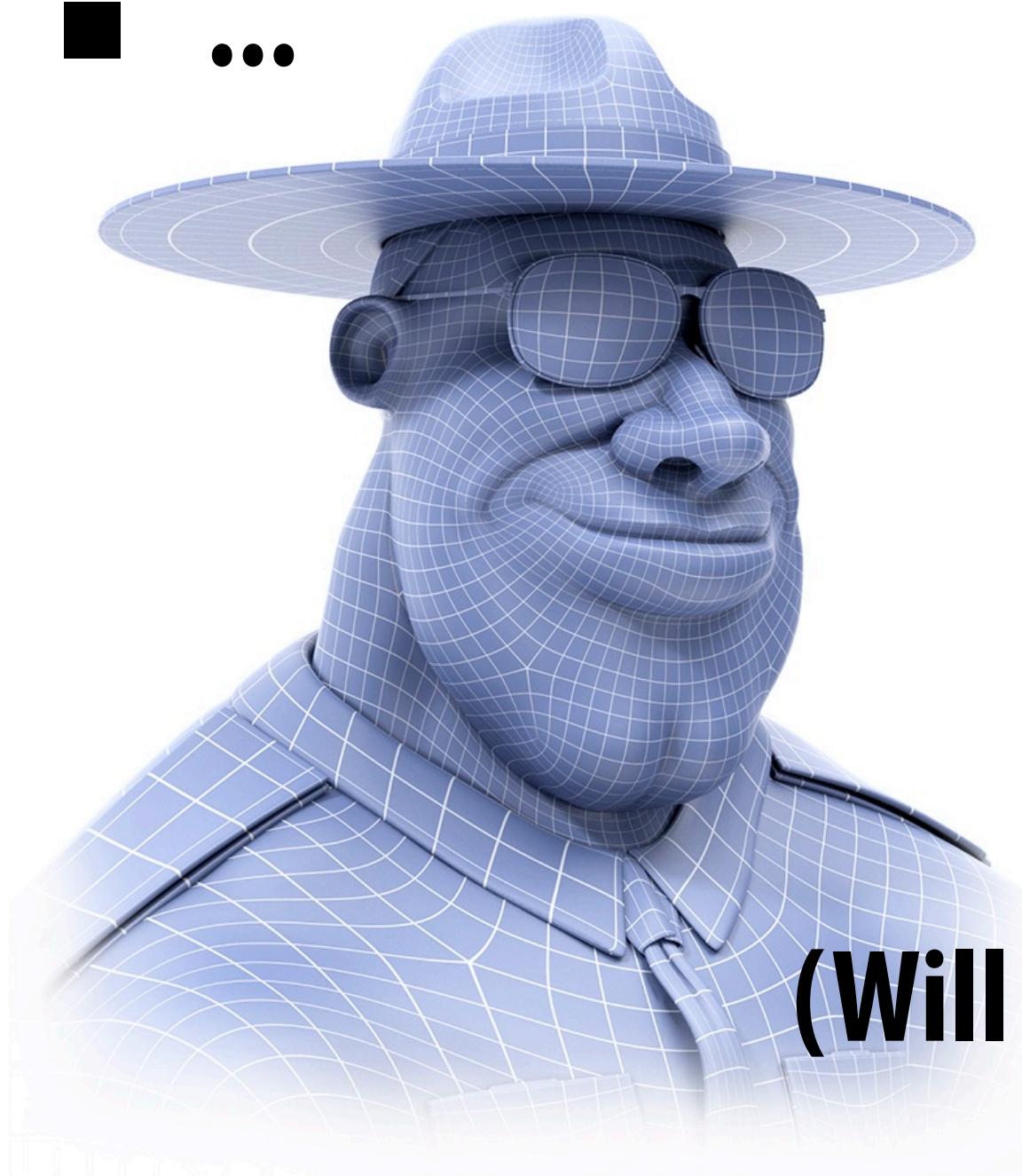
- All points are given directly
- E.g., points on sphere are  $(\cos(u) \sin(v), \sin(u) \sin(v), \cos(v))$ ,  
for  $0 \leq u < 2\pi$  and  $0 \leq v \leq \pi$
- More generally:  $f : \mathbb{R}^2 \rightarrow \mathbb{R}^3; (u, v) \mapsto (x, y, z)$



- (Might have a bunch of these maps, e.g., one per triangle.)

# Many explicit representations in graphics

- triangle meshes
- polygon meshes
- subdivision surfaces
- NURBS
- point clouds
- ...



(Will see some of these a bit later.)

**But first, let's play a game:**

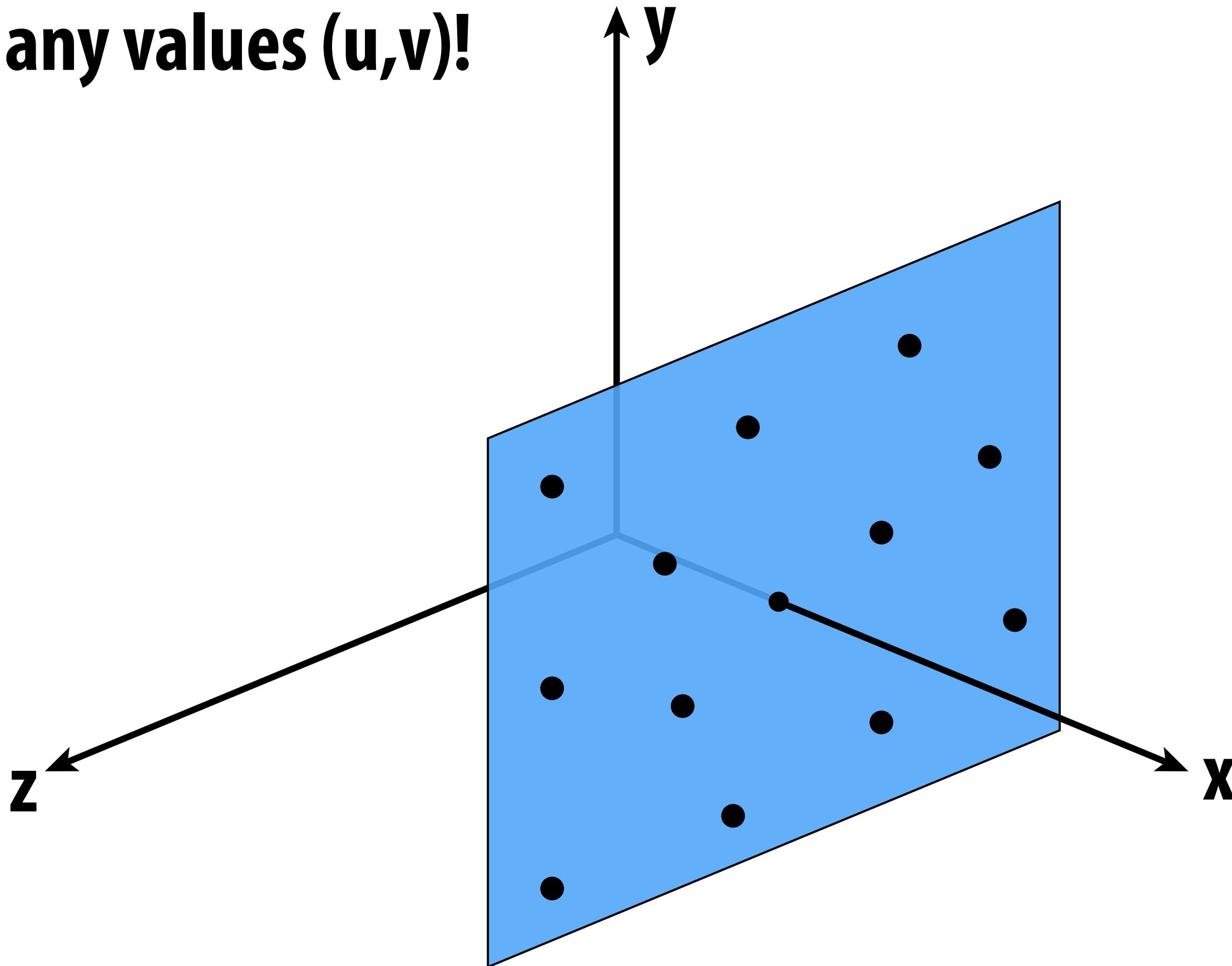
**I'll give you an explicit surface.**

**You give me some points on it.**

# Sampling an explicit surface

My surface is  $f( u, v ) = ( 1.23, u, v ).$

Just plug in any values  $(u,v)!$



Explicit surfaces make some tasks easy (like sampling).

**Let's play another game.**

**I have a new surface  $f(u,v)$ .**

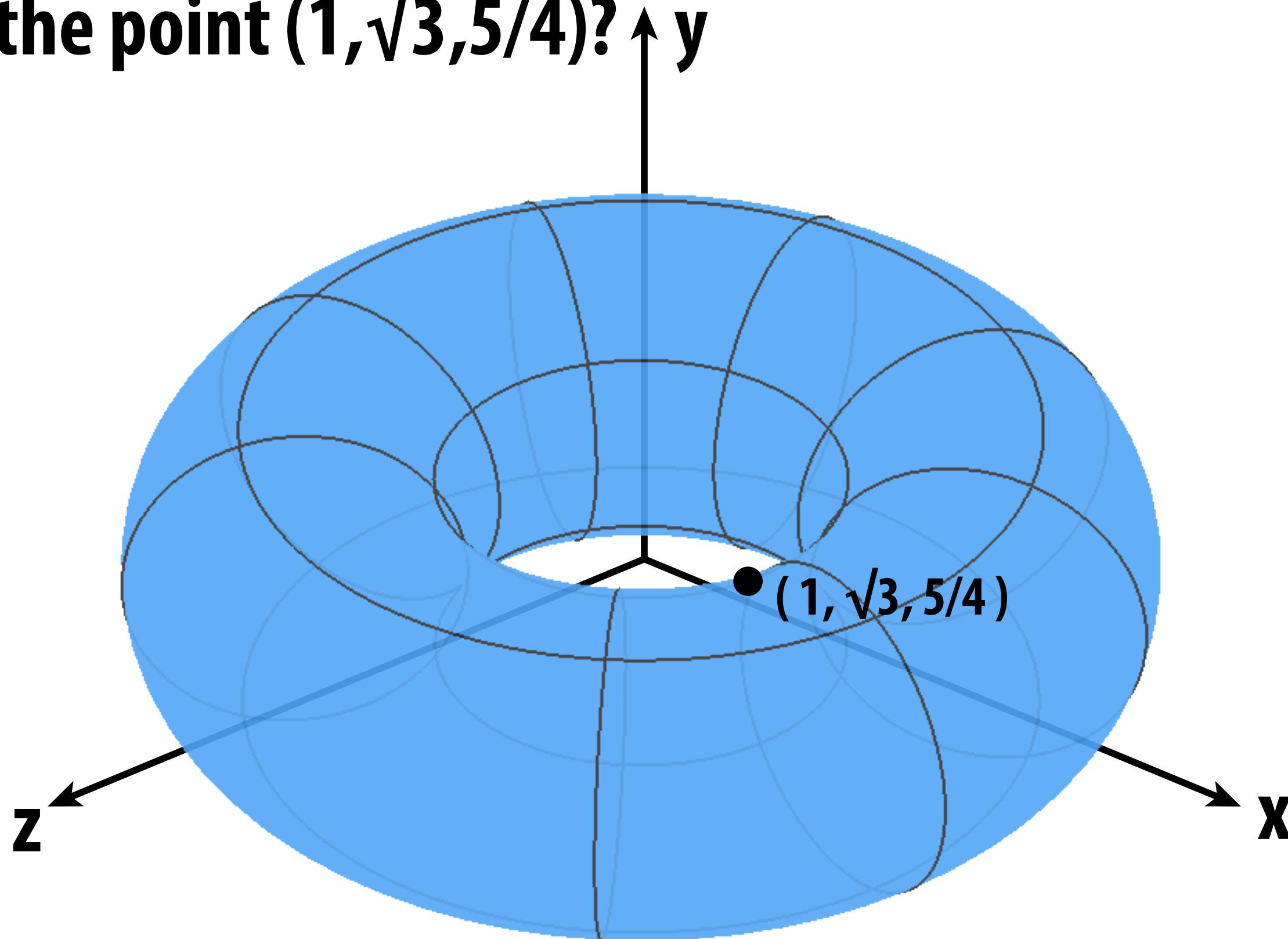
**I want to see if a point is *inside* it.**

# Check if this point is inside the torus

My surface is  $f(u,v) = (2+\cos(u))\cos(v), 2+\cos(u)\sin(v), \sin(u)$

How about the point  $(1, \sqrt{3}, 5/4)$ ?

...NO!



Explicit surfaces make other tasks hard (like inside/outside tests).

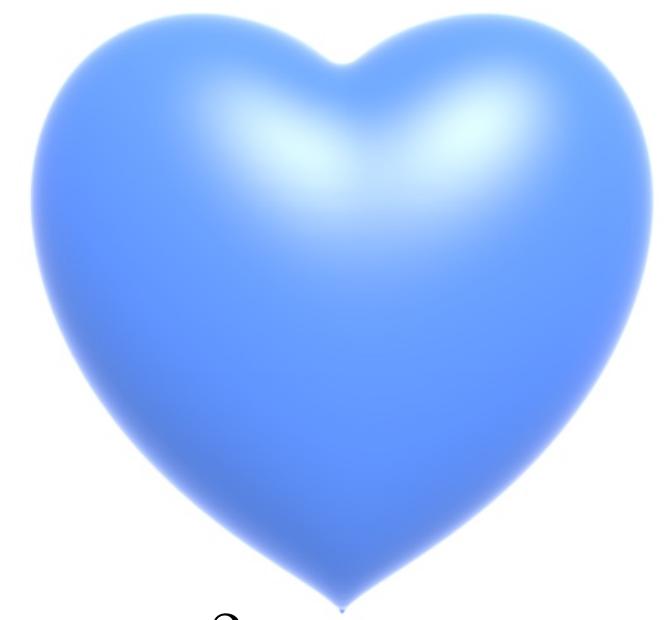
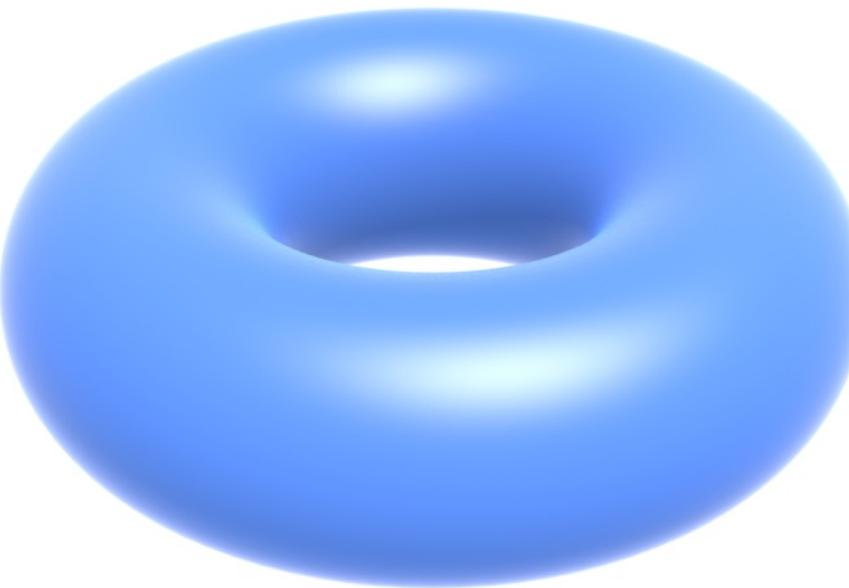
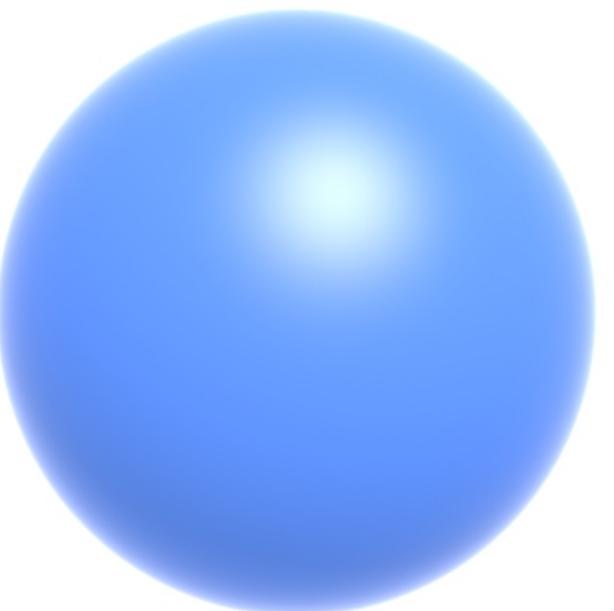
**CONCLUSION:**  
**Some representations work better  
than others—depends on the task!**

**Different representations will also be better suited to different types of geometry.**

**Let's take a look at some common representations used in computer graphics.**

# Algebraic Surfaces (Implicit)

- Surface is zero set of a polynomial in  $x, y, z$  (“algebraic variety”)
- Examples:



$$x^2 + y^2 + z^2 = 1$$

$$(R - \sqrt{x^2 + y^2})^2 + z^2 = r^2$$

$$(x^2 + \frac{9y^2}{4} + z^2 - 1)^3 =$$

- What about more complicated shapes?

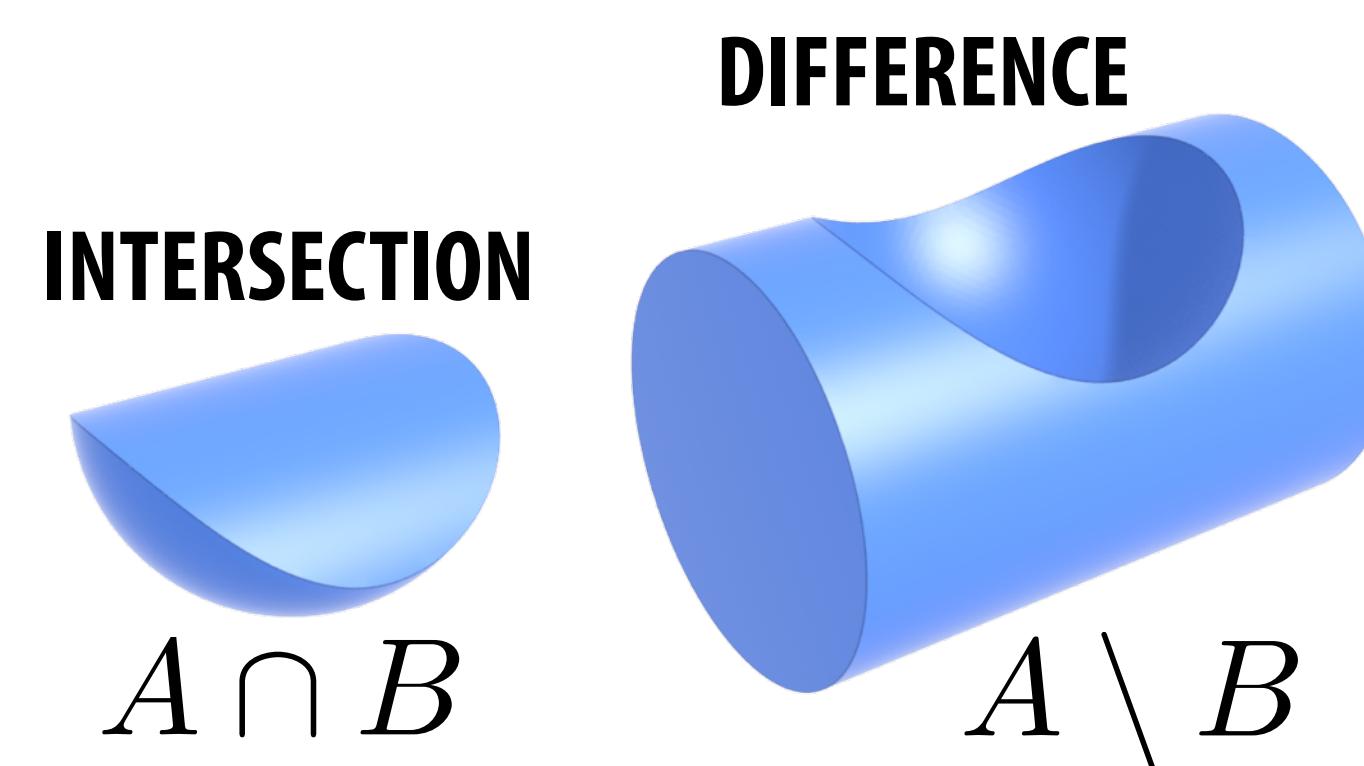
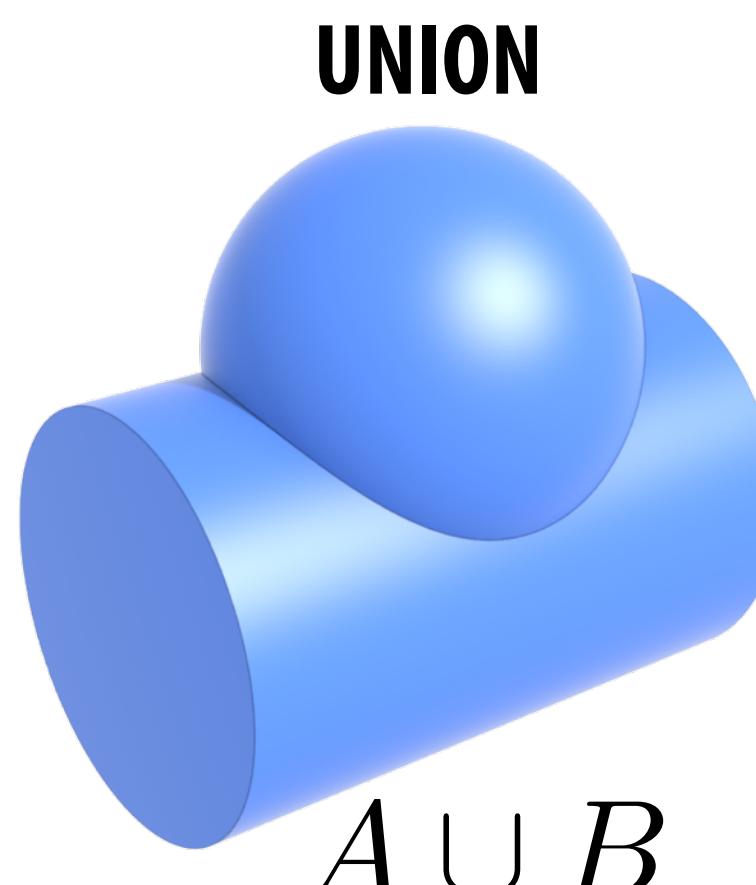
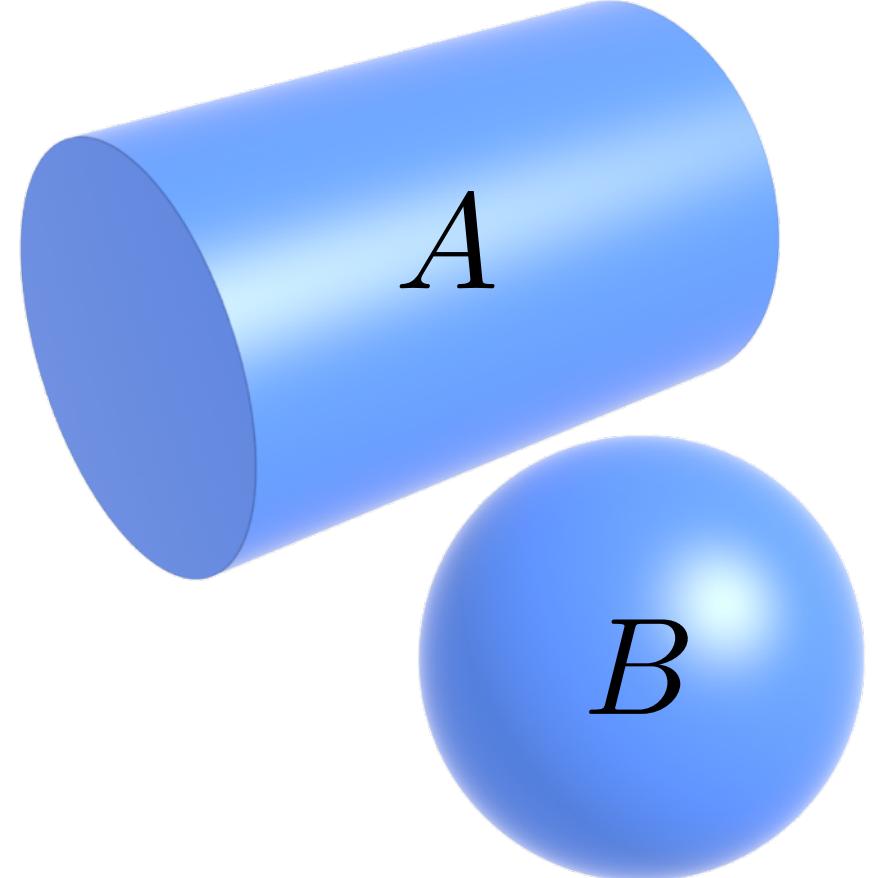
$$x^2 z^3 + \frac{9y^2 z^3}{80}$$



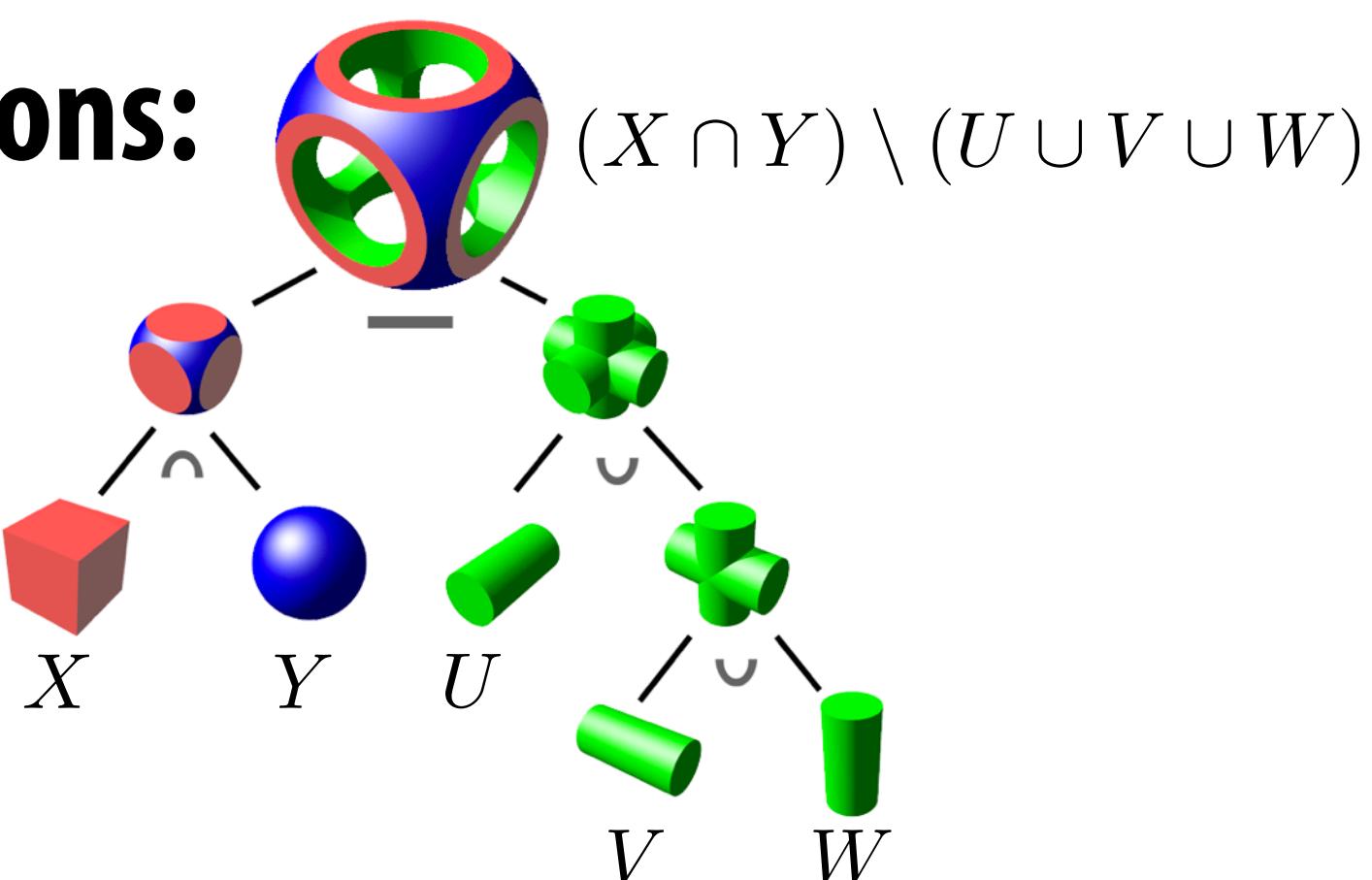
- Very hard to come up with polynomials!

# Constructive Solid Geometry (Implicit)

- Build more complicated shapes via Boolean operations
- Basic operations:

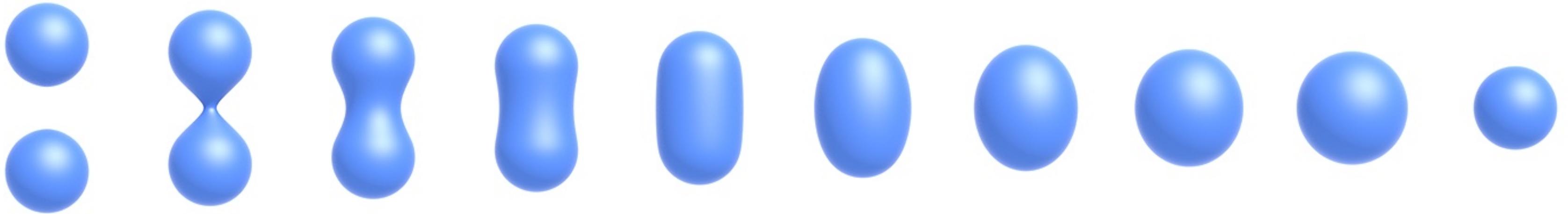


- Then chain together expressions:



# Blobby Surfaces (Implicit)

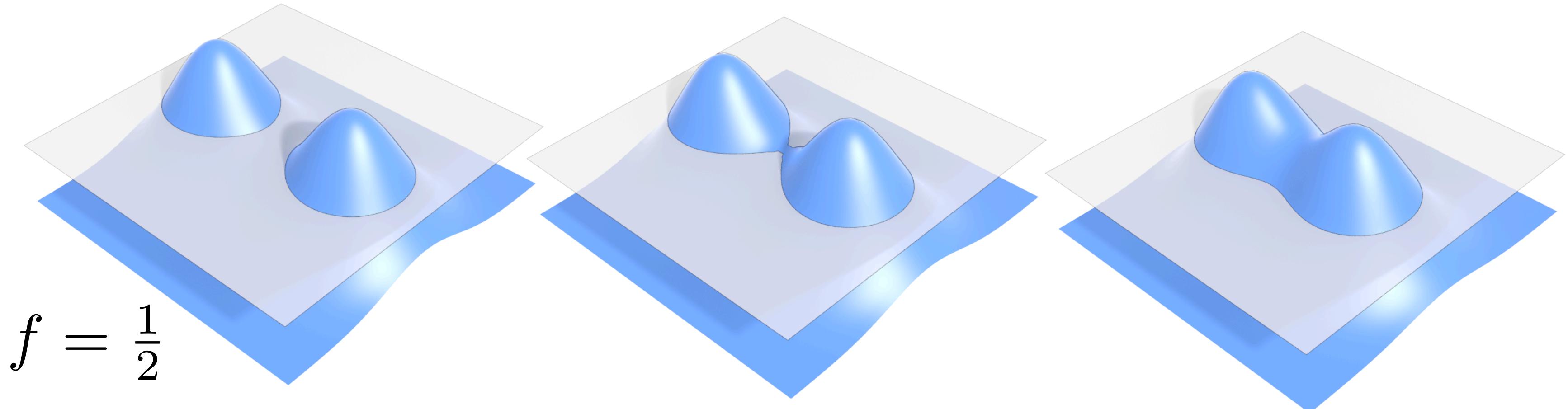
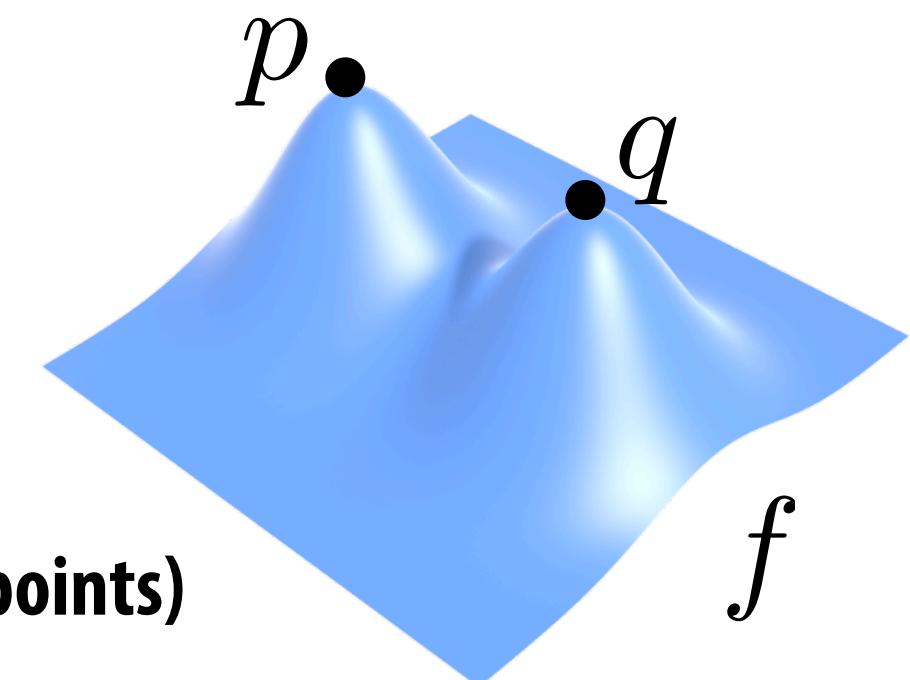
- Instead of Booleans, gradually blend surfaces together:



- Easier to understand in 2D:

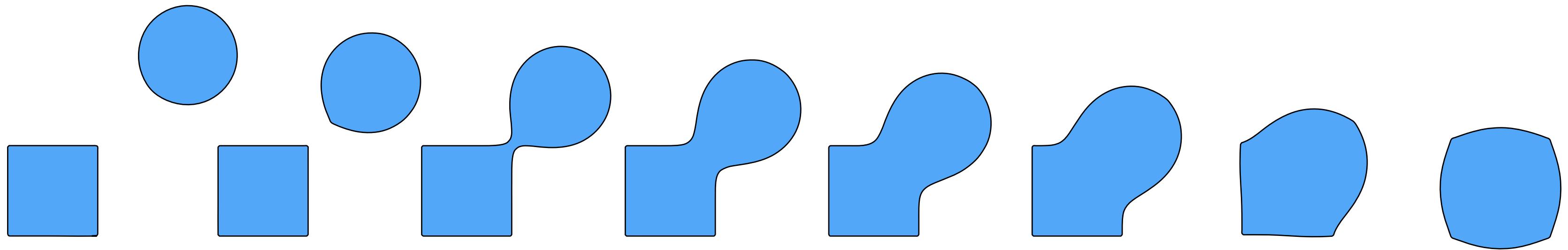
$$\phi_p(x) := e^{-|x-p|^2} \quad (\text{Gaussian centered at } p)$$

$$f := \phi_p + \phi_q \quad (\text{Sum of Gaussians centered at different points})$$



# Blending Distance Functions (Implicit)

- A *distance function* gives distance to closest point on object
- Can blend any two distance functions  $d_1, d_2$ :



- Similar strategy to points, though many possibilities. E.g.,

$$f(x) := e^{-d_1(x)^2} + e^{-d_2(x)^2} - \frac{1}{2}$$

- Appearance depends on exactly how we combine functions
- Q: How do we implement a simple Boolean union?
- A: Just take the product:  $f(x) := d_1(x)d_2(x)$

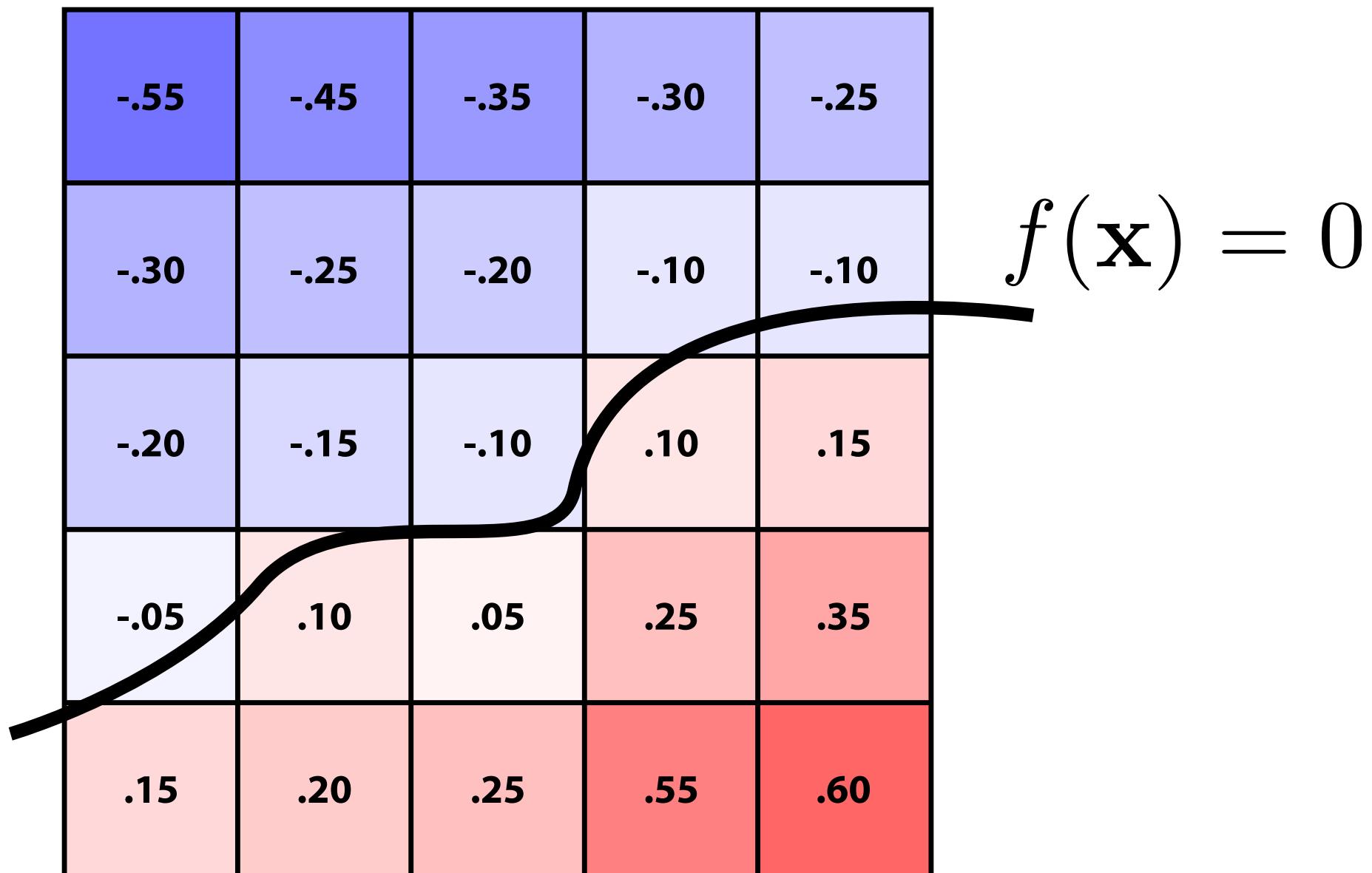
# Scene of pure distance functions (not easy!)



See <http://iquilezles.org/www/material/nvscene2008/nvscene2008.htm>

# Level Set Methods (Implicit)

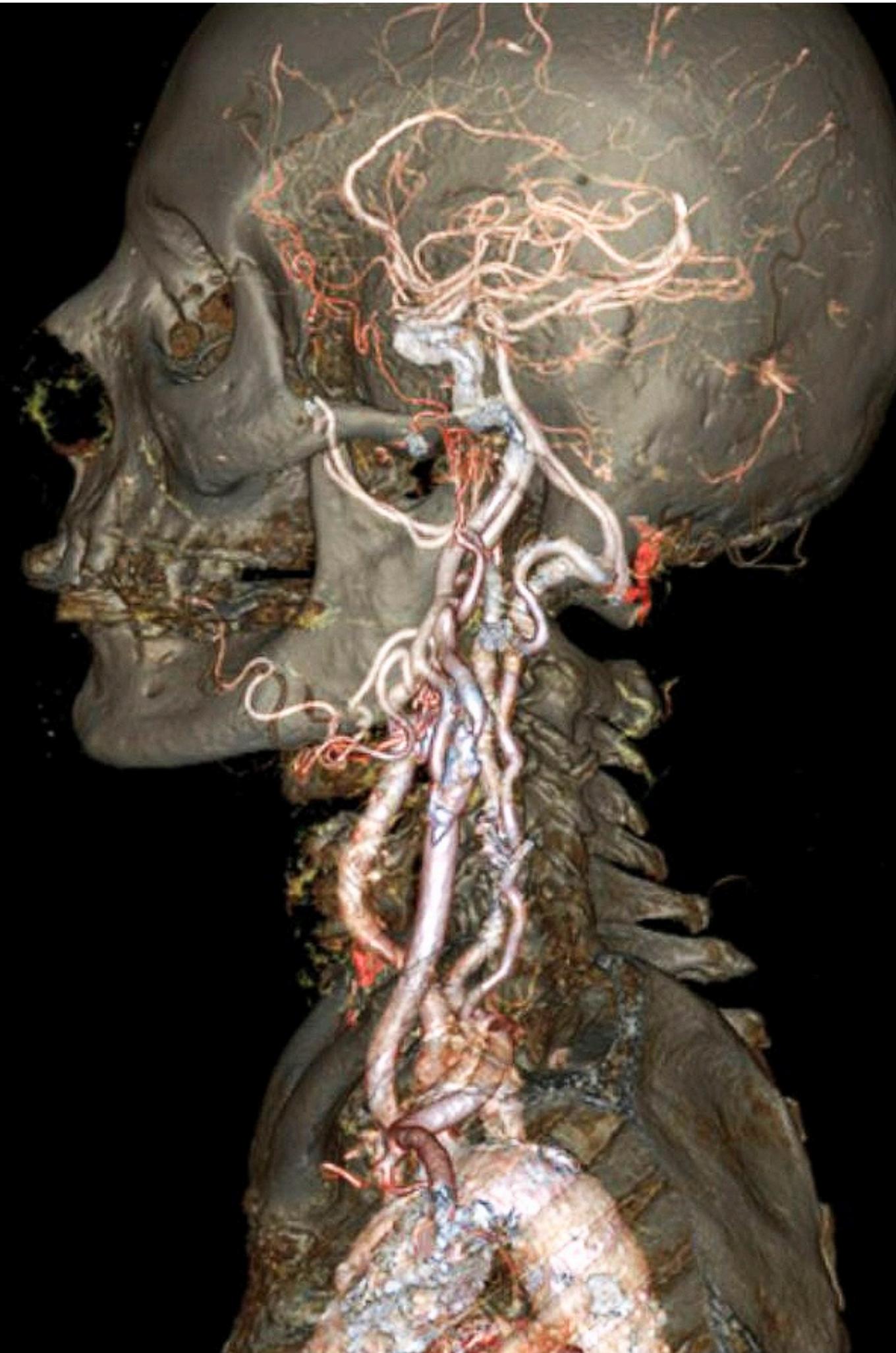
- Implicit surfaces have some nice features (e.g., merging/splitting)
- But, hard to describe complex shapes in closed form
- Alternative: store a grid of values approximating function



- Surface is found where *interpolated* values equal zero
- Provides much more explicit control over shape (like a texture)

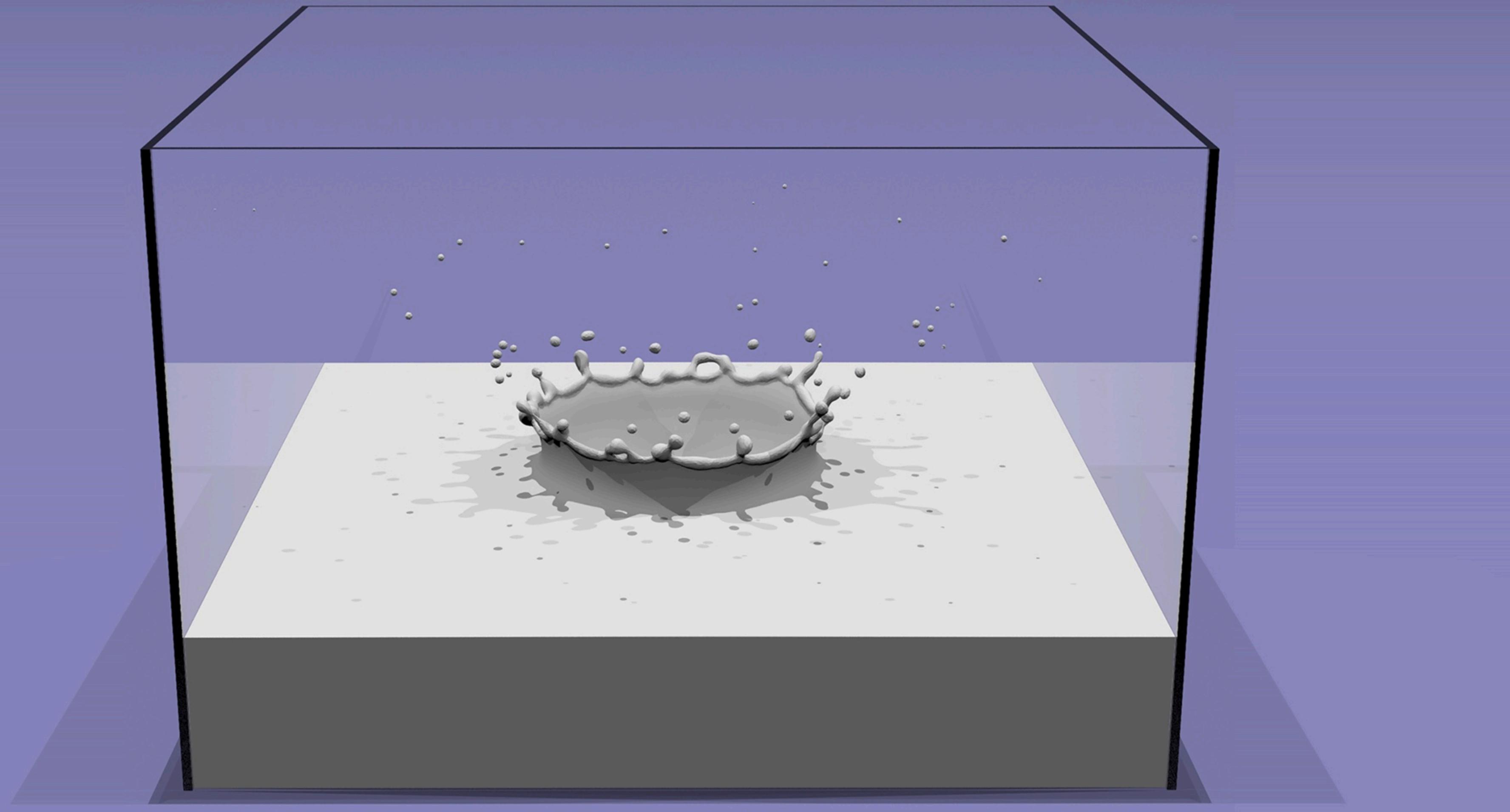
# Level Sets from Medical Data (CT, MRI, etc.)

- Level sets encode, e.g., constant tissue density



# Level Sets in Physical Simulation

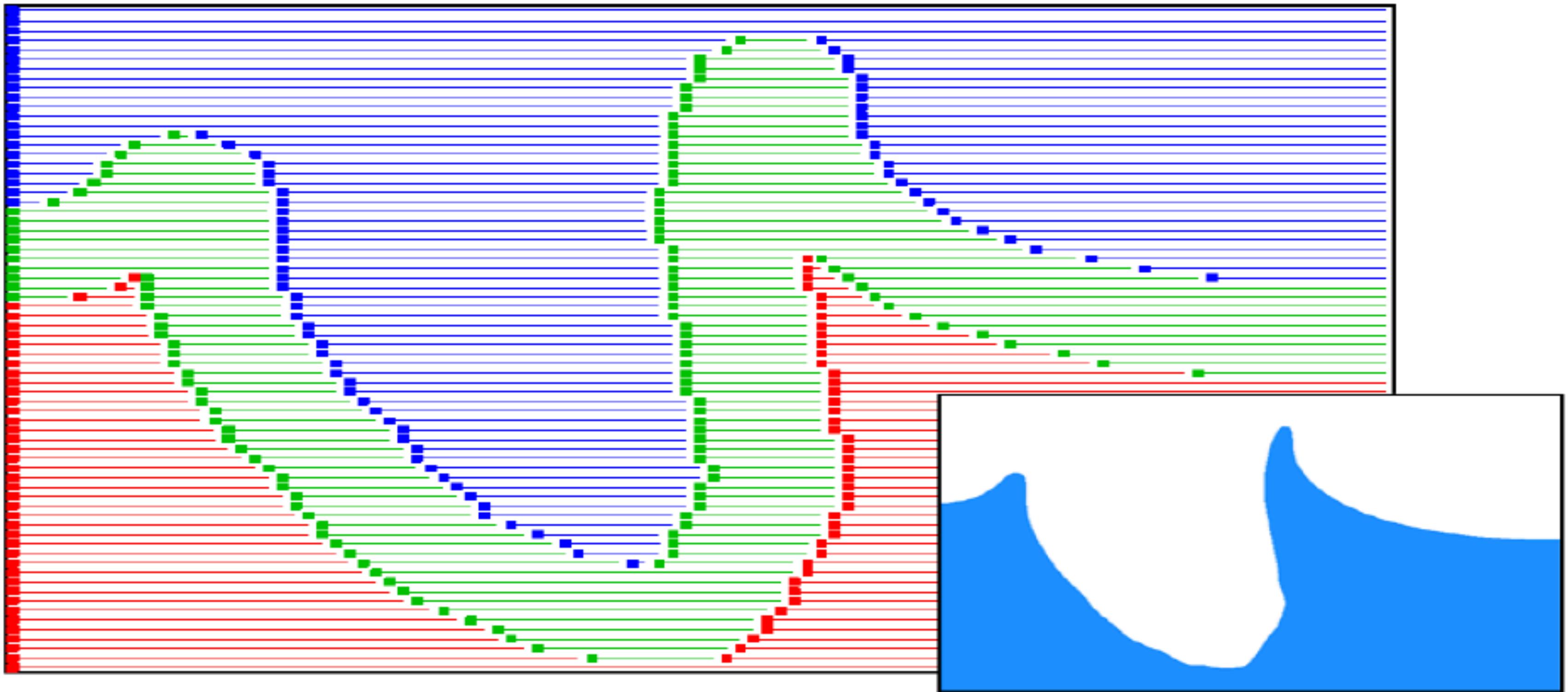
- Level set encodes distance to air-liquid boundary



See <http://physbam.stanford.edu>

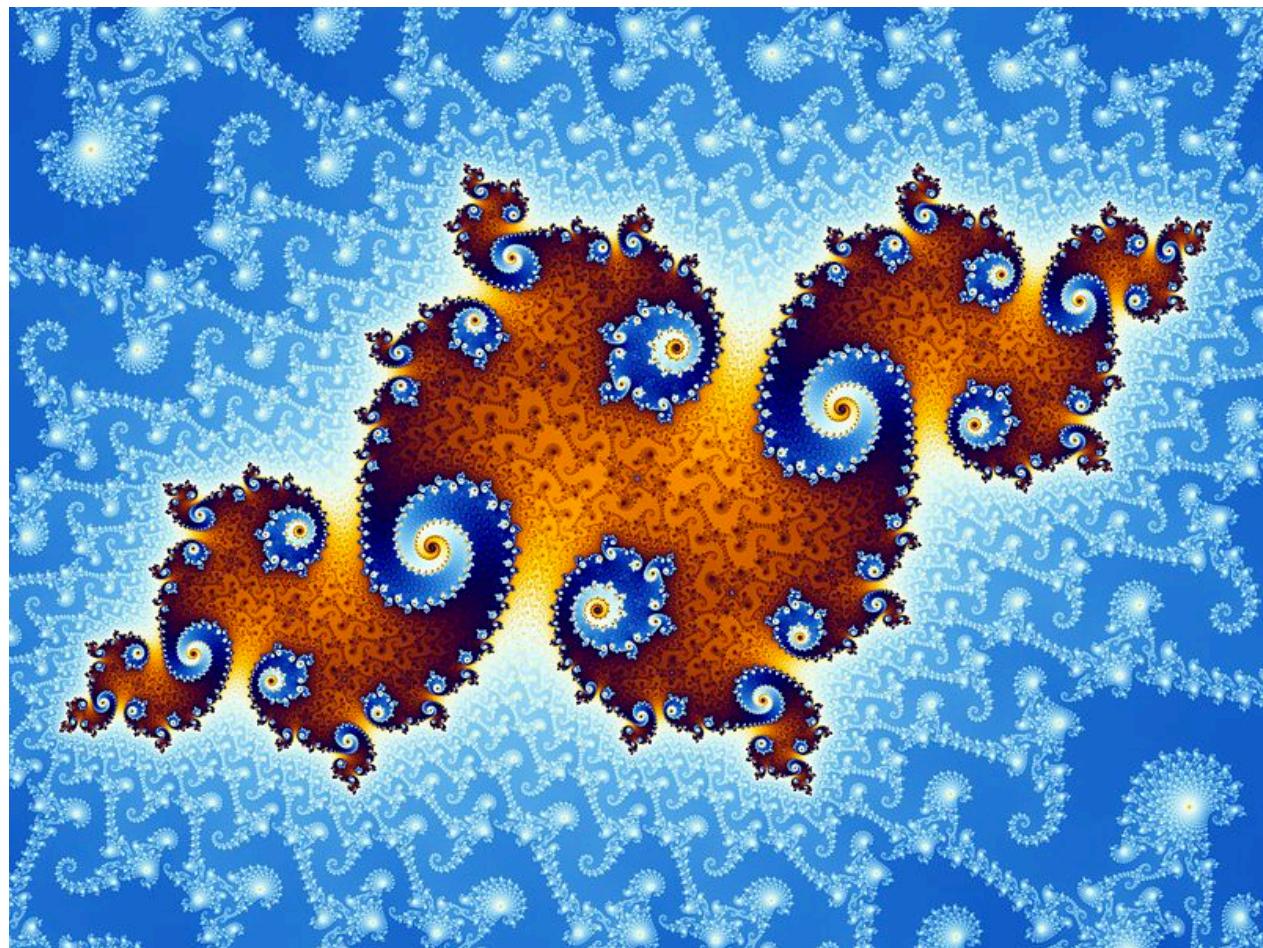
# Level Set Storage

- Drawback: storage for 2D surface is now  $O(n^3)$
- Can reduce cost by storing only a narrow band around surface:



# Fractals (Implicit)

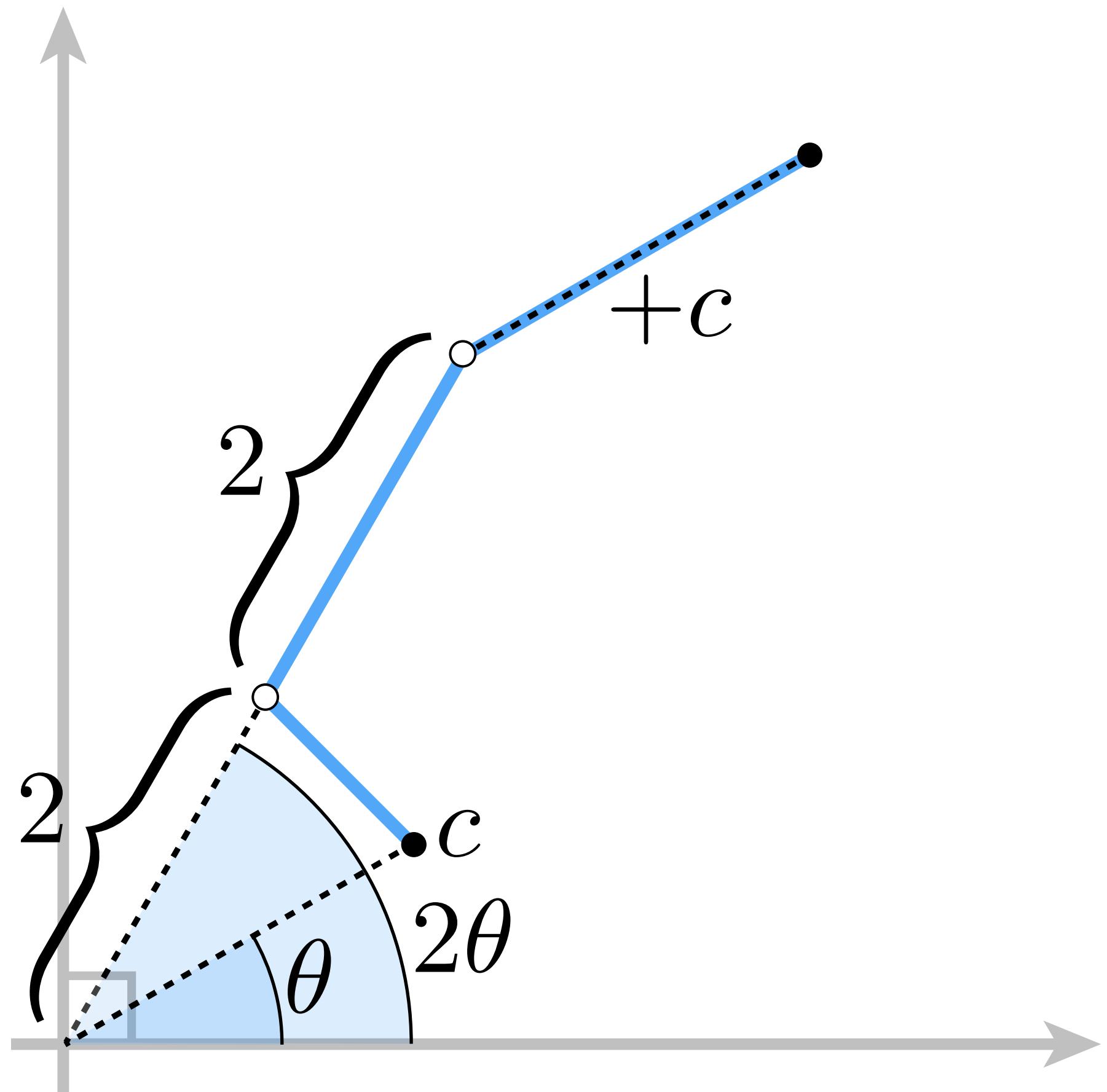
- No precise definition; exhibit self-similarity, detail at all scales
- New “language” for describing natural phenomena
- Hard to control shape!



# Mandelbrot Set - Definition

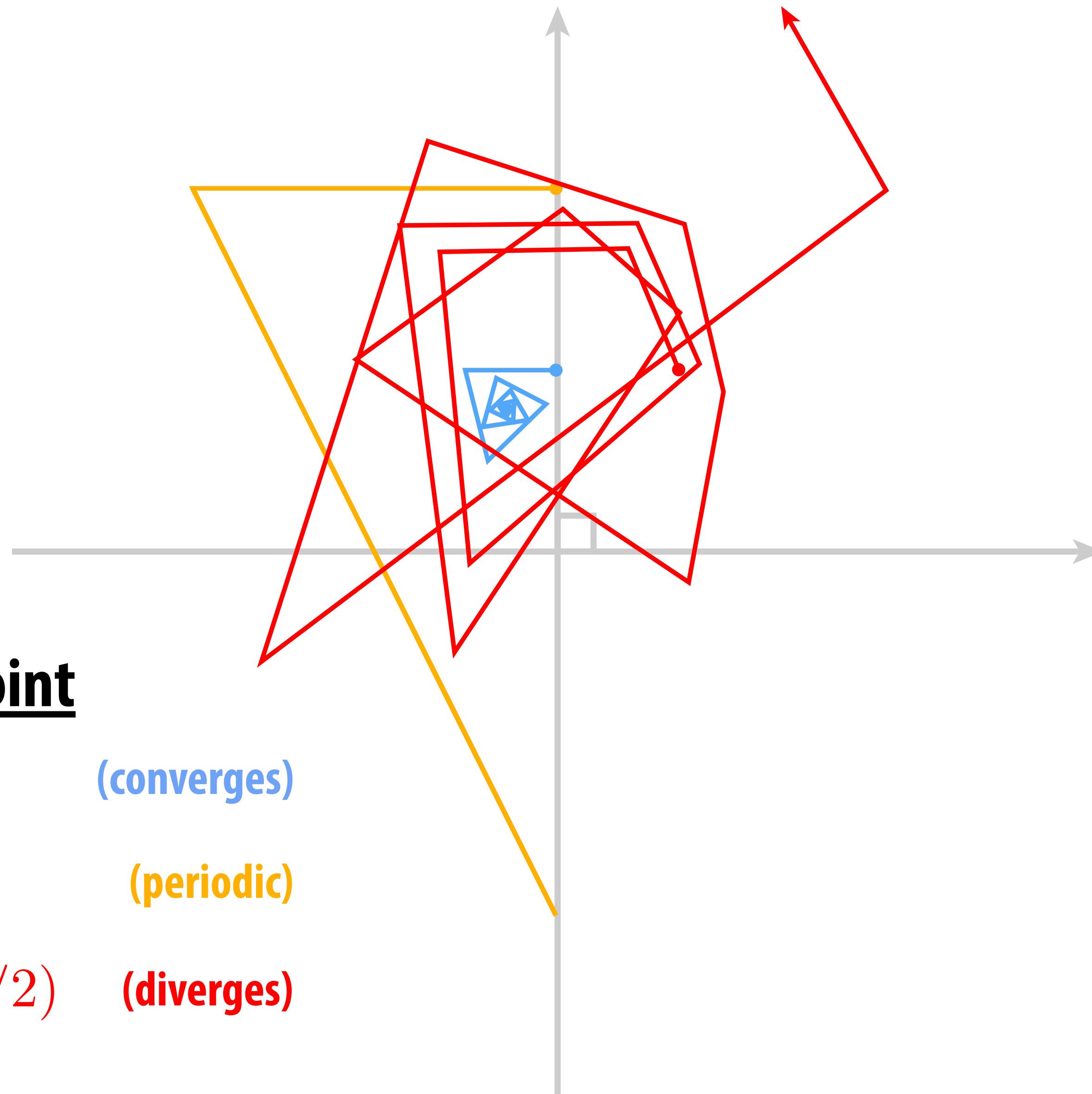
- For each point  $c$  in the plane:

- double the angle
- square the magnitude
- add the original point  $c$
- repeat



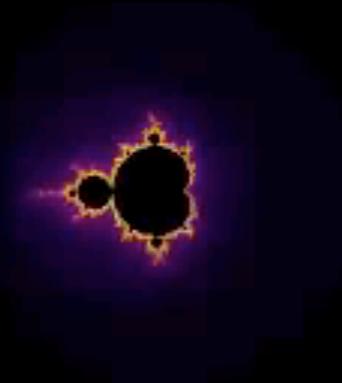
If the point remains bounded (never goes to  $\infty$ ), it's in the set.

# Mandelbrot Set - Examples



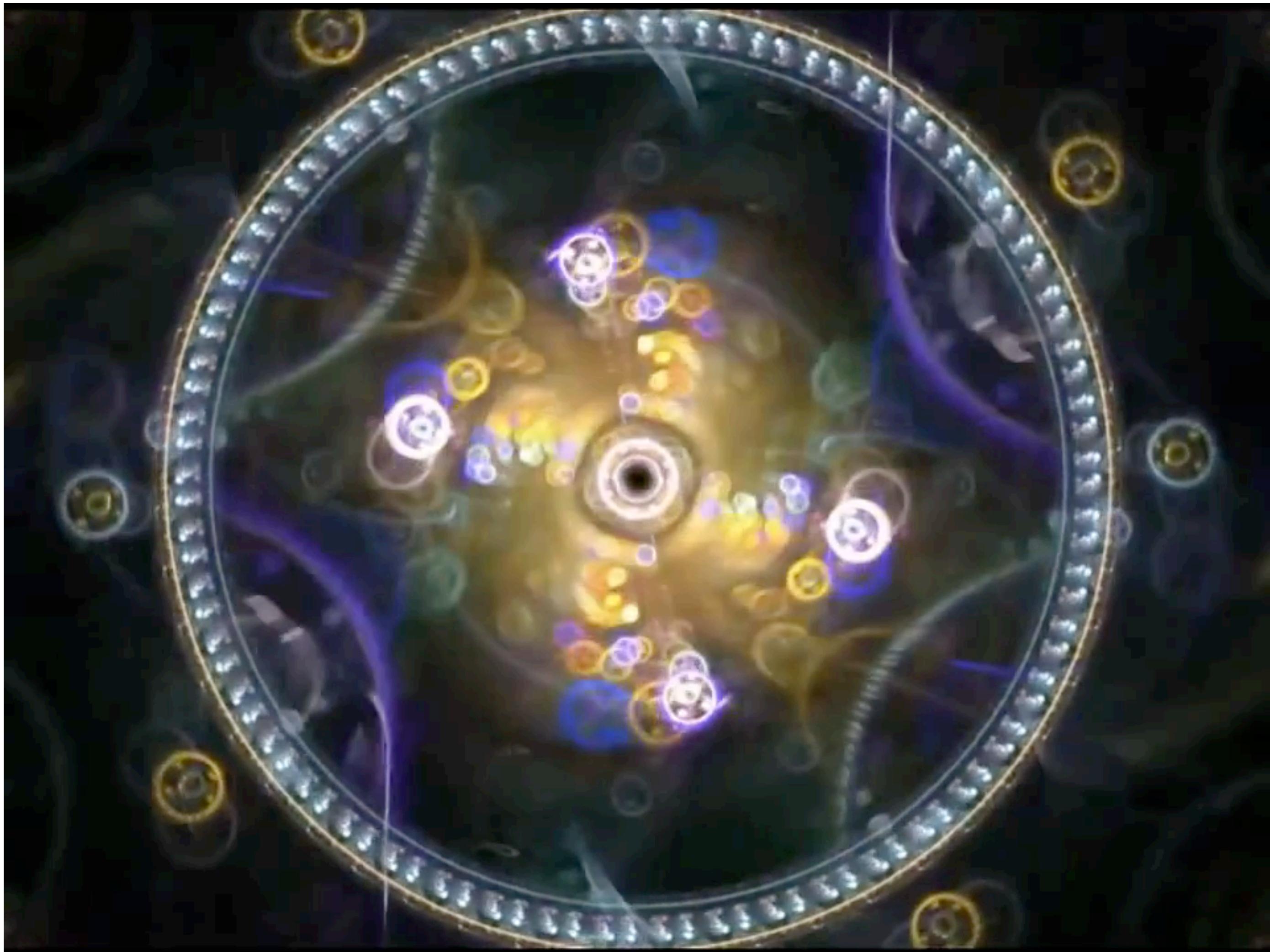
# Mandelbrot Set - Zooming In

$10^{-0}$



**(Colored according to how quickly each point diverges/converges.)**

# Iterated Function Systems



Scott Draves (CMU Alumn) - see <http://electricsheep.org>

# Implicit Representations - Pros & Cons

## ■ Pros:

- **description can be very compact (e.g., a polynomial)**
- **easy to determine if a point is in our shape (just plug it in!)**
- **other queries may also be easy (e.g., distance to surface)**
- **for simple shapes, exact description/no sampling error**
- **easy to handle changes in topology (e.g., fluid)**

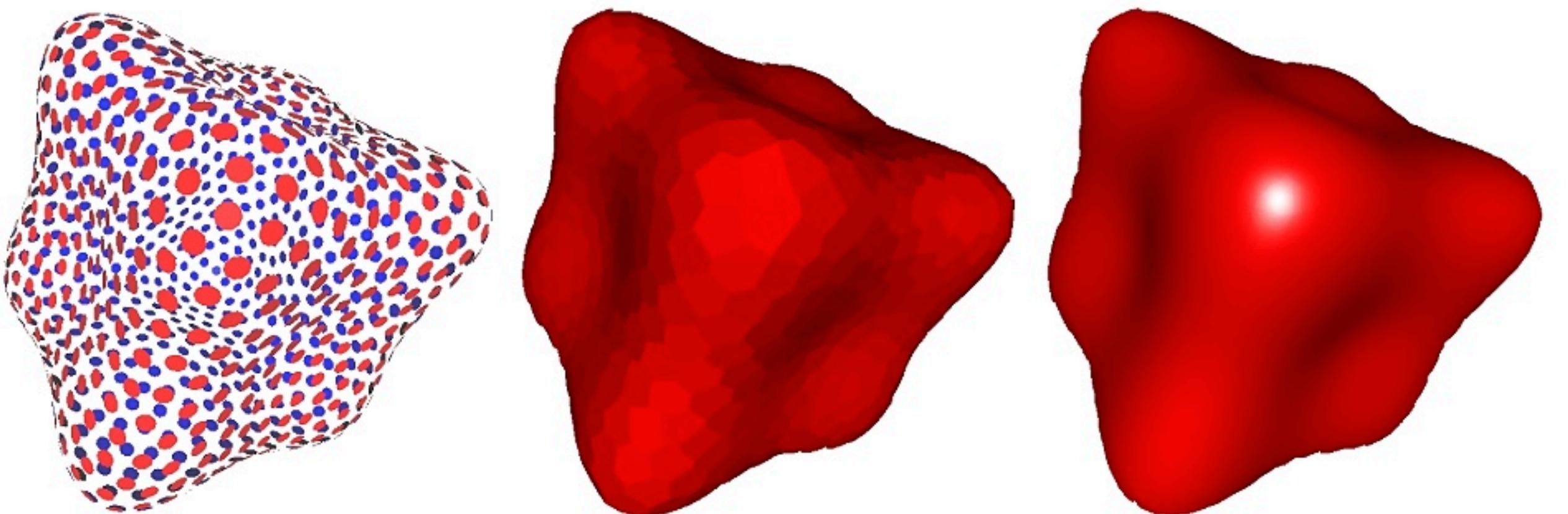
## ■ Cons:

- **expensive to find all points in the shape (e.g., for drawing)**
- ***very difficult to model complex shapes***

# **What about explicit representations?**

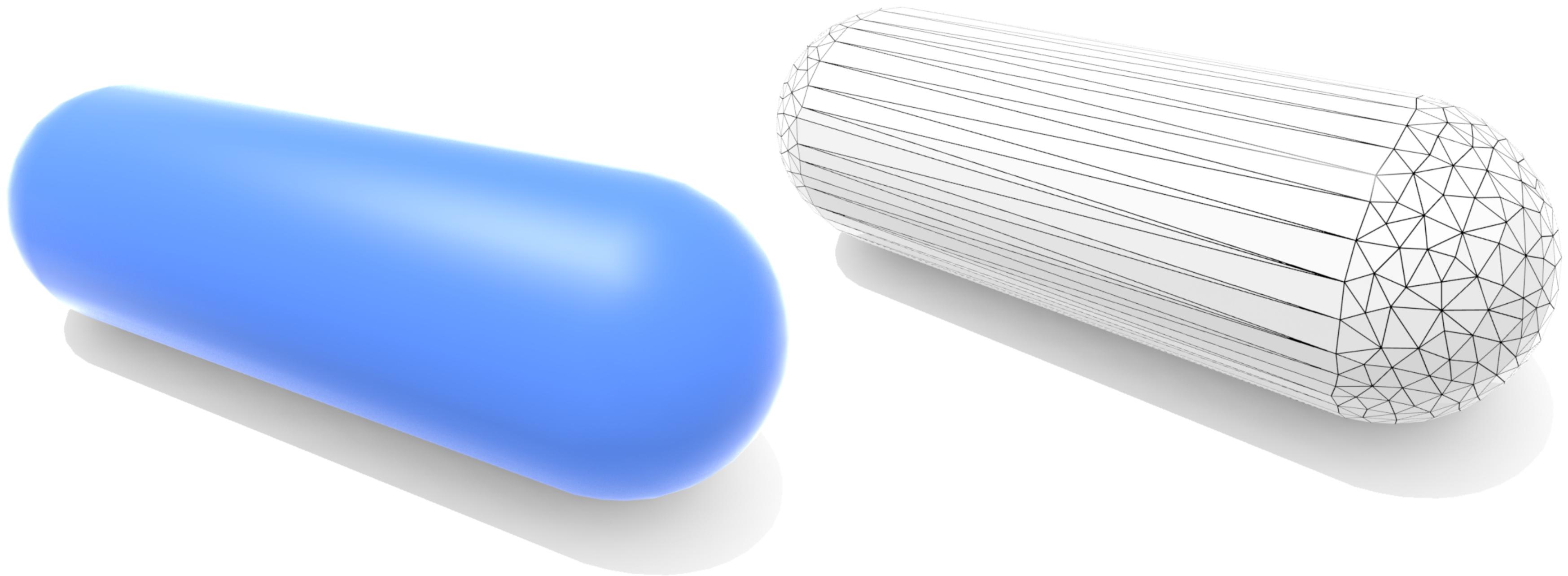
# Point Cloud (Explicit)

- Easiest representation: list of points ( $x,y,z$ )
- Often augmented with *normals*
- Easily represent any kind of geometry
- Useful for LARGE datasets (>>1 point/pixel)
- Difficult to draw in undersampled regions
- Hard to do processing / simulation



# Polygon Mesh (Explicit)

- Store vertices *and* polygons (most often triangles or quads)
- Easier to do processing/simulation, adaptive sampling
- More complicated data structures
- Perhaps most common representation in graphics

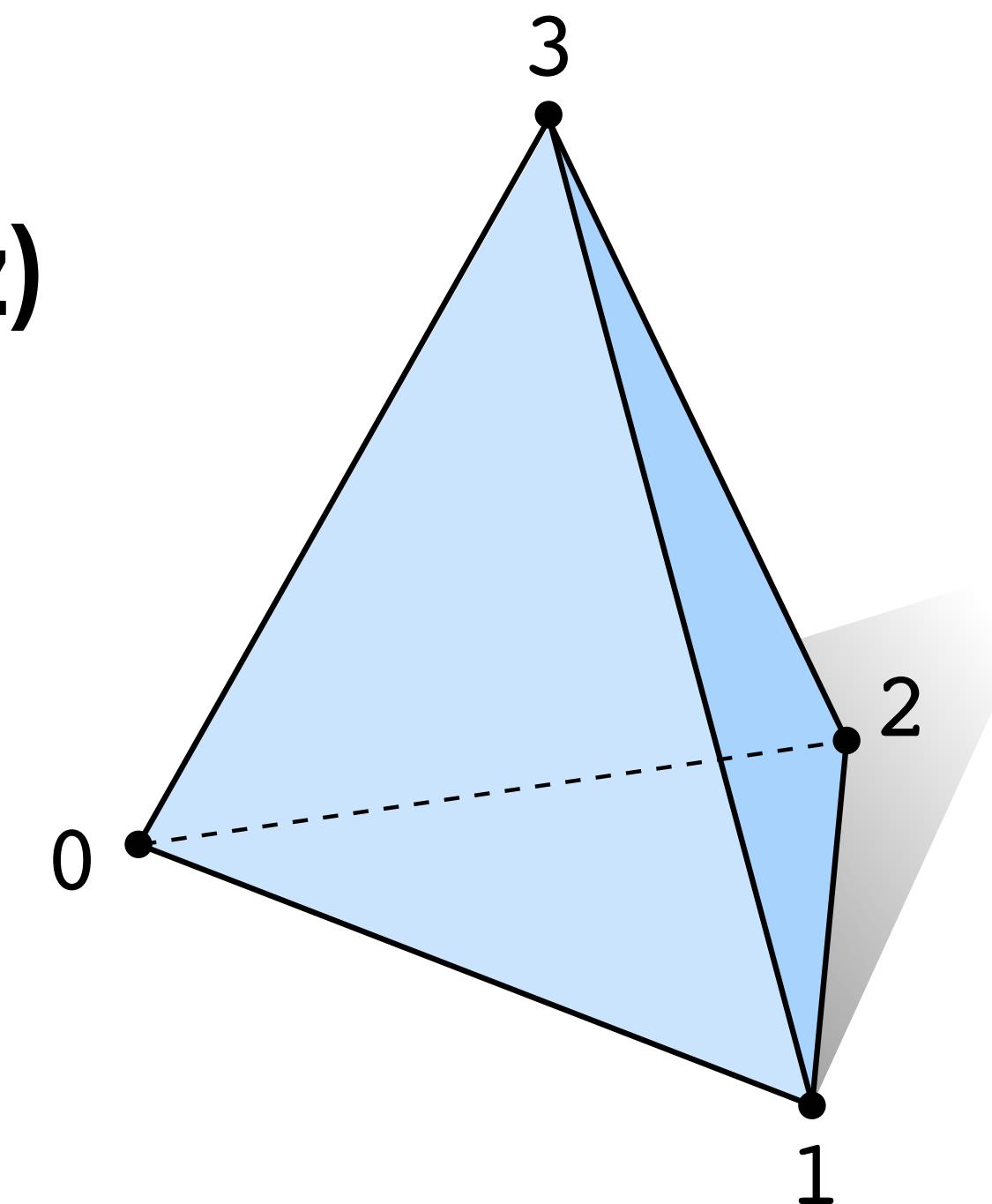


(Much more about polygon meshes in upcoming lectures!)

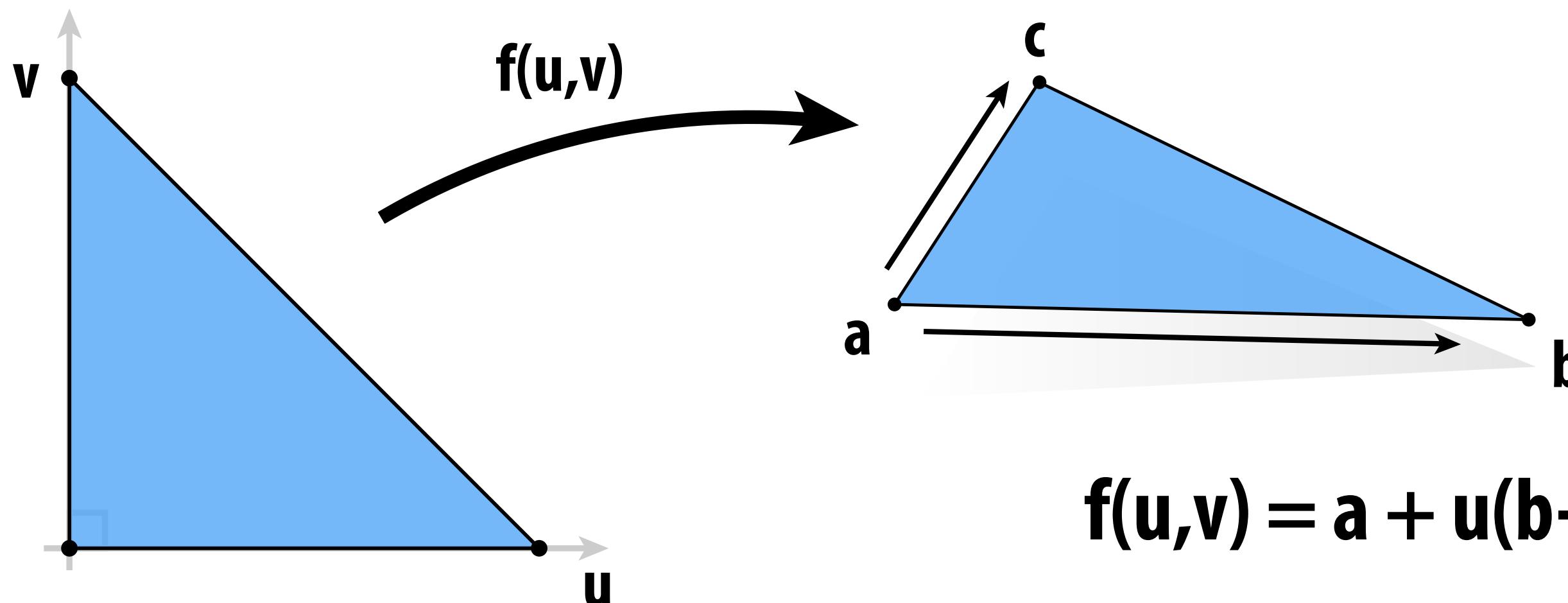
# Triangle Mesh (Explicit)

- Store vertices as triples of coordinates ( $x, y, z$ )
- Store triangles as triples of indices ( $i, j, k$ )
- E.g., tetrahedron:

	VERTICES			TRIANGLES		
	x	y	z	i	j	k
0:	-1	-1	-1	0	2	1
1:	1	-1	1	0	3	2
2:	1	1	-1	3	0	1
3:	-1	1	1	3	1	2



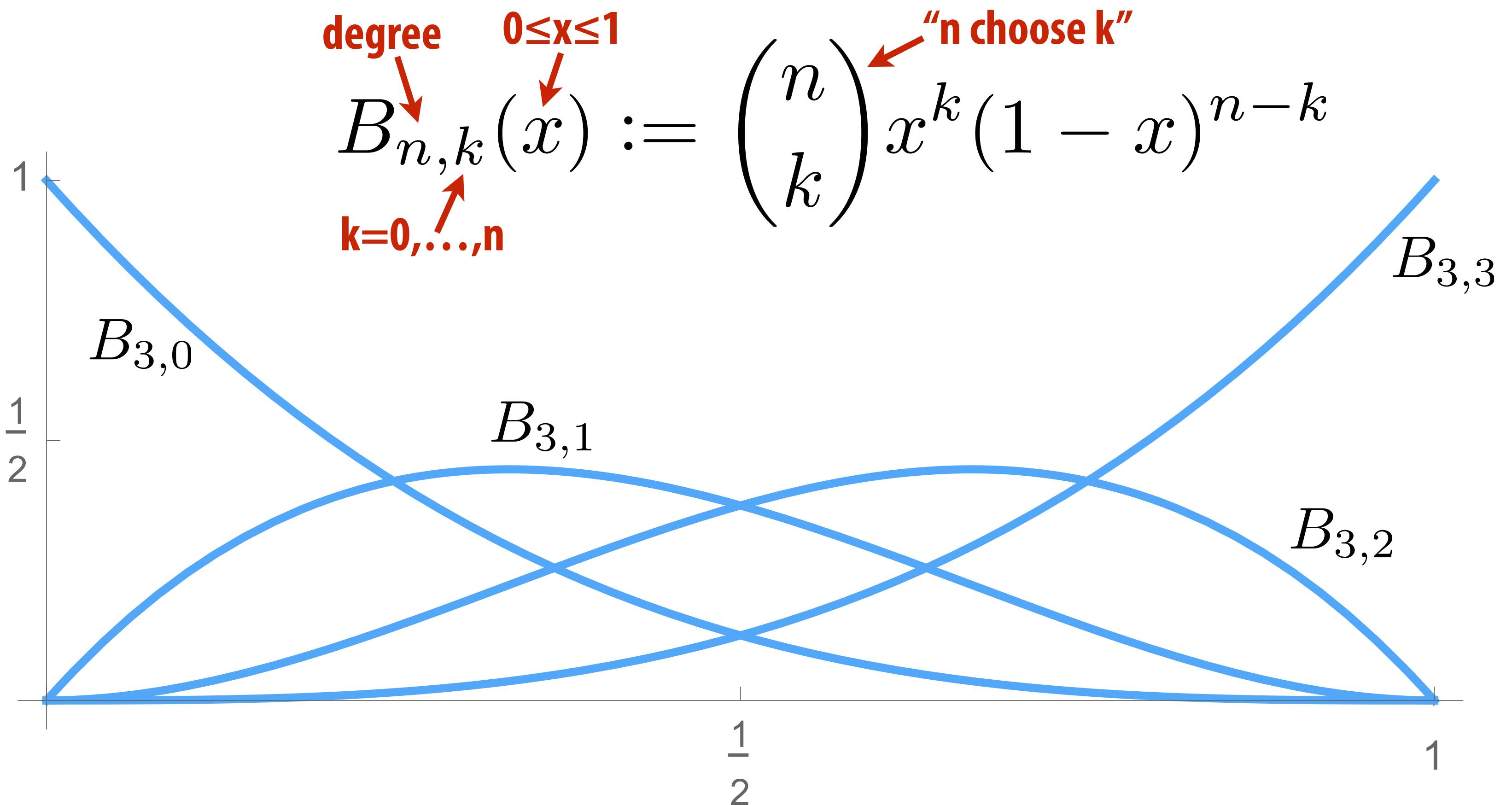
- Can think of triangle as *affine map* from plane into space:



$$f(u,v) = a + u(b-a) + v(c-a)$$

# Bernstein Basis

- Why limit ourselves to just affine functions?
- More flexibility by using higher-order polynomials
- Instead of usual basis  $(1, x, x^2, x^3, \dots)$ , use Bernstein basis:



# Bézier Curves (Explicit)

- A Bézier curve is a curve expressed in the Bernstein basis:

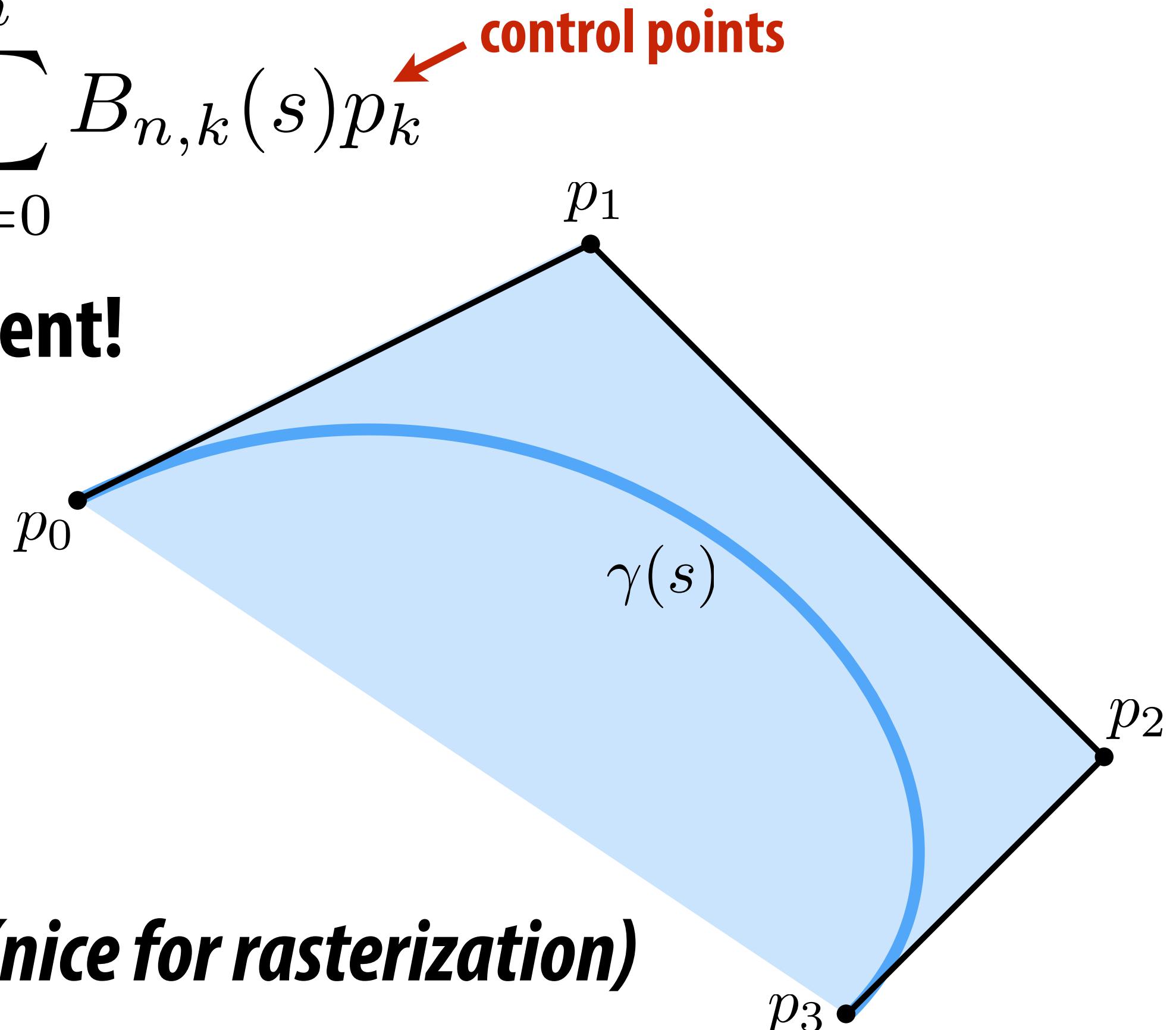
$$\gamma(s) := \sum_{k=0}^n B_{n,k}(s)p_k$$

- For  $n=1$ , just get a line segment!

- For  $n=3$ , get “cubic Bézier”:

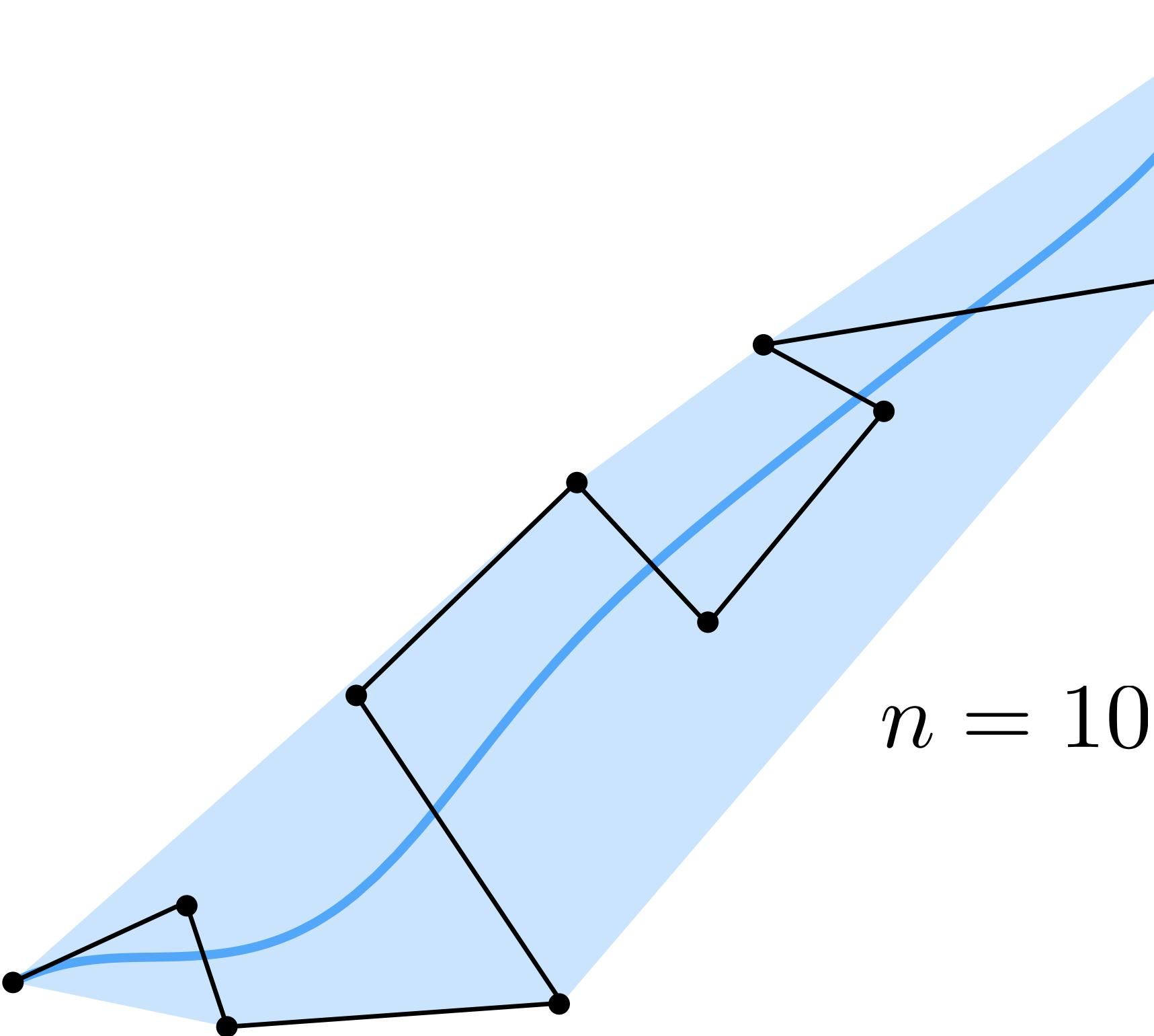
- Important features:

1. interpolates endpoints
2. tangent to end segments
3. contained in convex hull (*nice for rasterization*)



# Higher-order Bézier Curves?

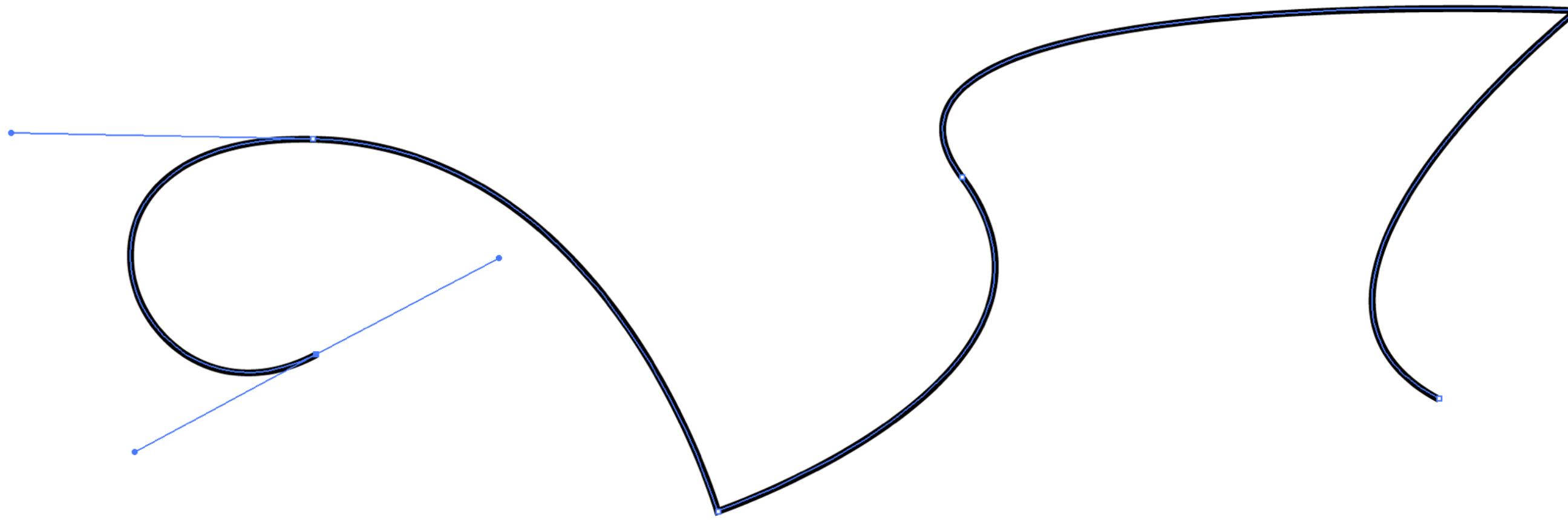
- What if we want a more interesting curve?
- High-degree Bernstein polynomials don't interpolate well:



**Very hard to control!**

# B-Spline Curves (Explicit)

- Instead, use many low-order Bézier curve (B-spline)
- Widely-used technique in software (Illustrator, Inkscape, etc.)



- Formally, piecewise Bézier curve:

B-spline

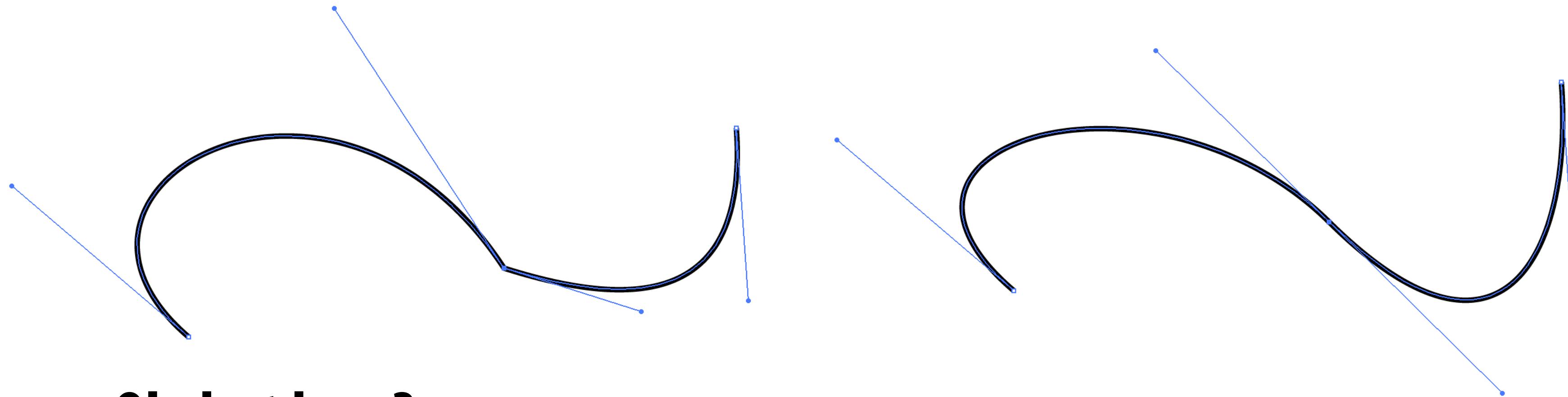
$$\gamma(u) := \gamma_i \left( \frac{u - u_i}{u_{i+1} - u_i} \right), \quad u_i \leq u < u_{i+1}$$

Bézier

- Location of  $u_i$  parameters are called “knots”

# B-Splines — tangent continuity

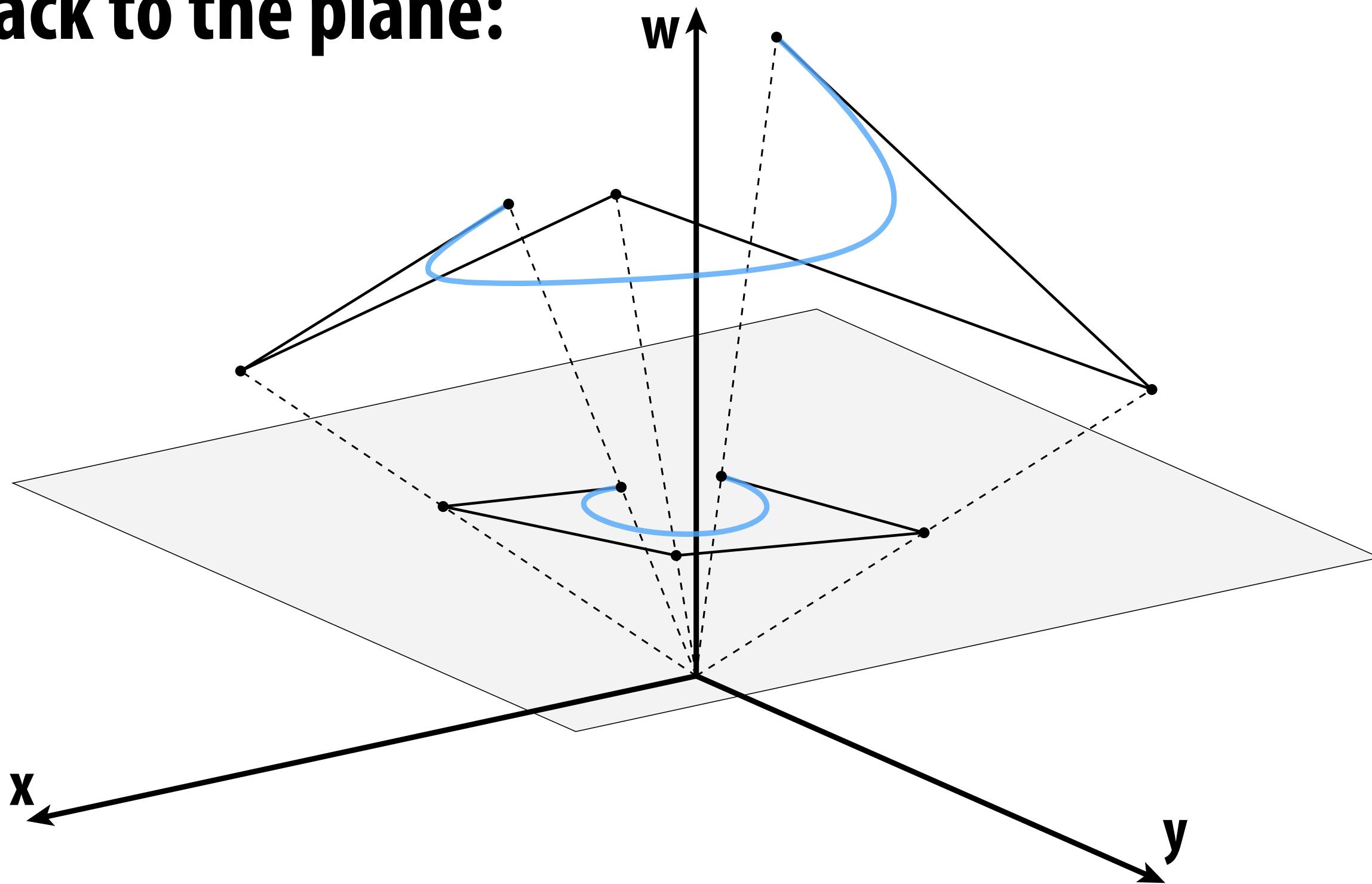
- To get “seamless” curves, want *tangents* to line up:



- Ok, but how?
- Each curve is cubic:  $u^3 p_0 + 3u^2(1-u)p_1 + 3u(1-u)^2 p_2 + (1-u)^3 p_3$
- Q: How many degrees of freedom in a single cubic Bézier
- Tangents are difference between first two & last two points
- Q: How many degrees of freedom per B-spline segment?
- Q: Could you do this with quadratic Bézier? Linear Bézier?

# Rational B-Splines (Explicit)

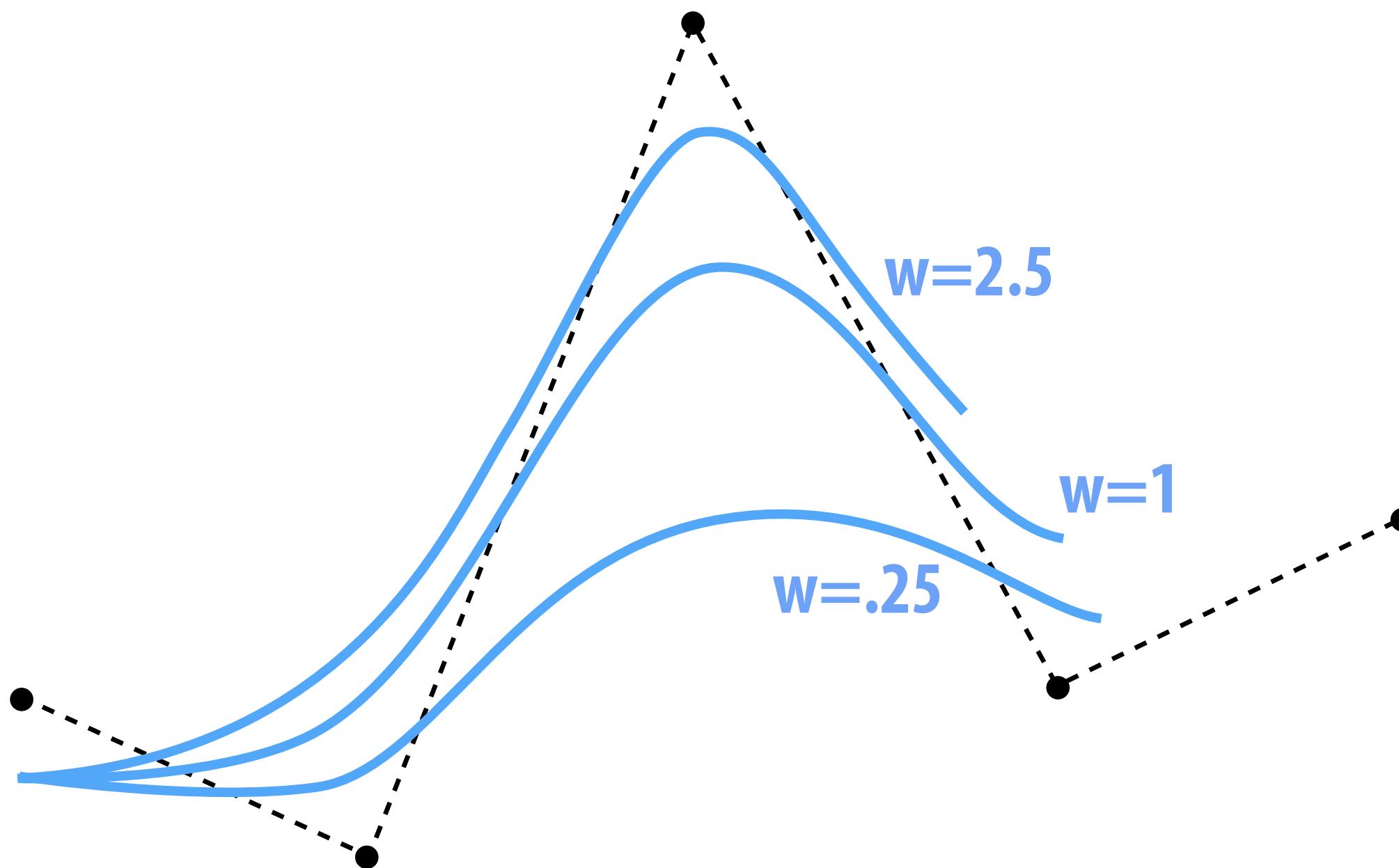
- B-Splines can't exactly represent *conics*—not even the circle!
- Solution: interpolate in homogeneous coordinates, then project back to the plane:



Result is called a *rational B-spline*.

# NURBS (Explicit)

- **(N)on-(U)niform (R)ational (B)-(S)pline**
  - knots at arbitrary locations (non-uniform)
  - expressed in homogeneous coordinates (rational)
  - piecewise polynomial curve (B-Spline)
- Homogeneous coordinate  $w$  controls “strength” of a vertex:

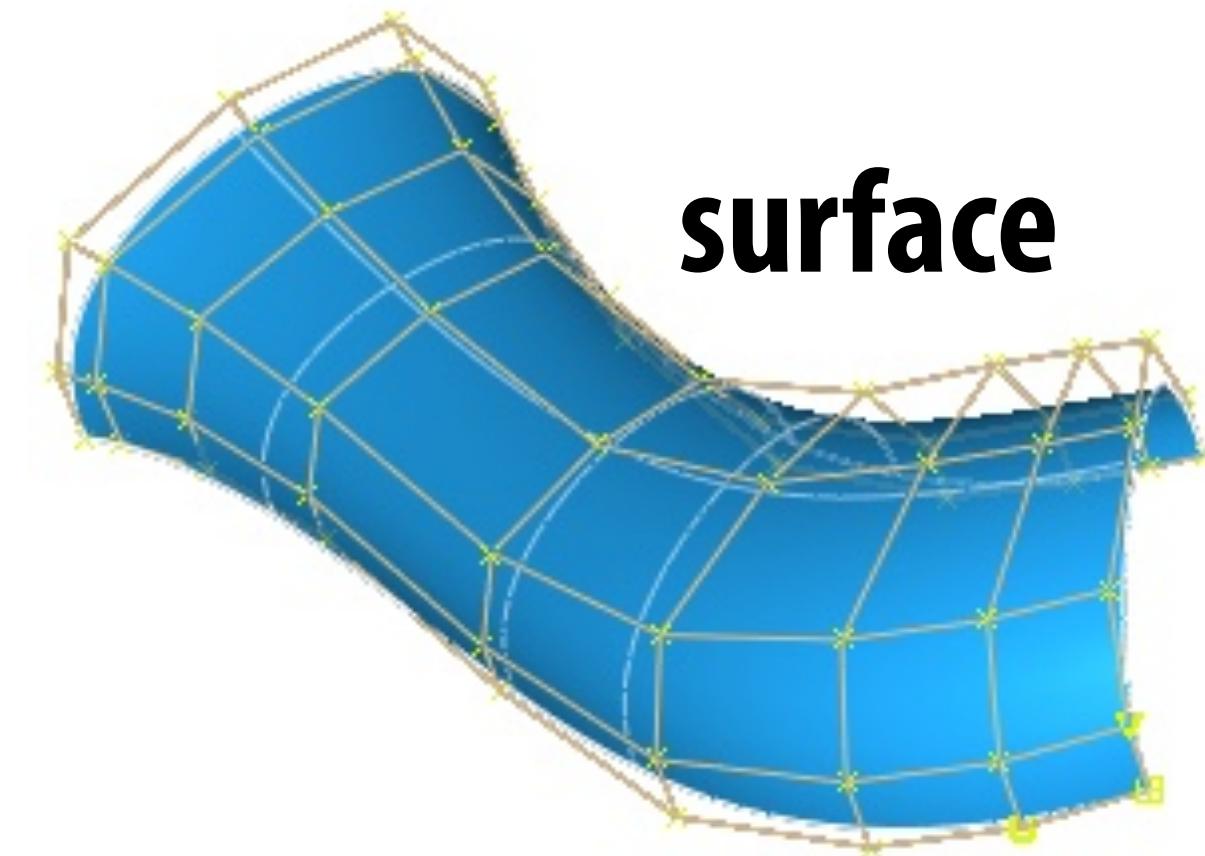
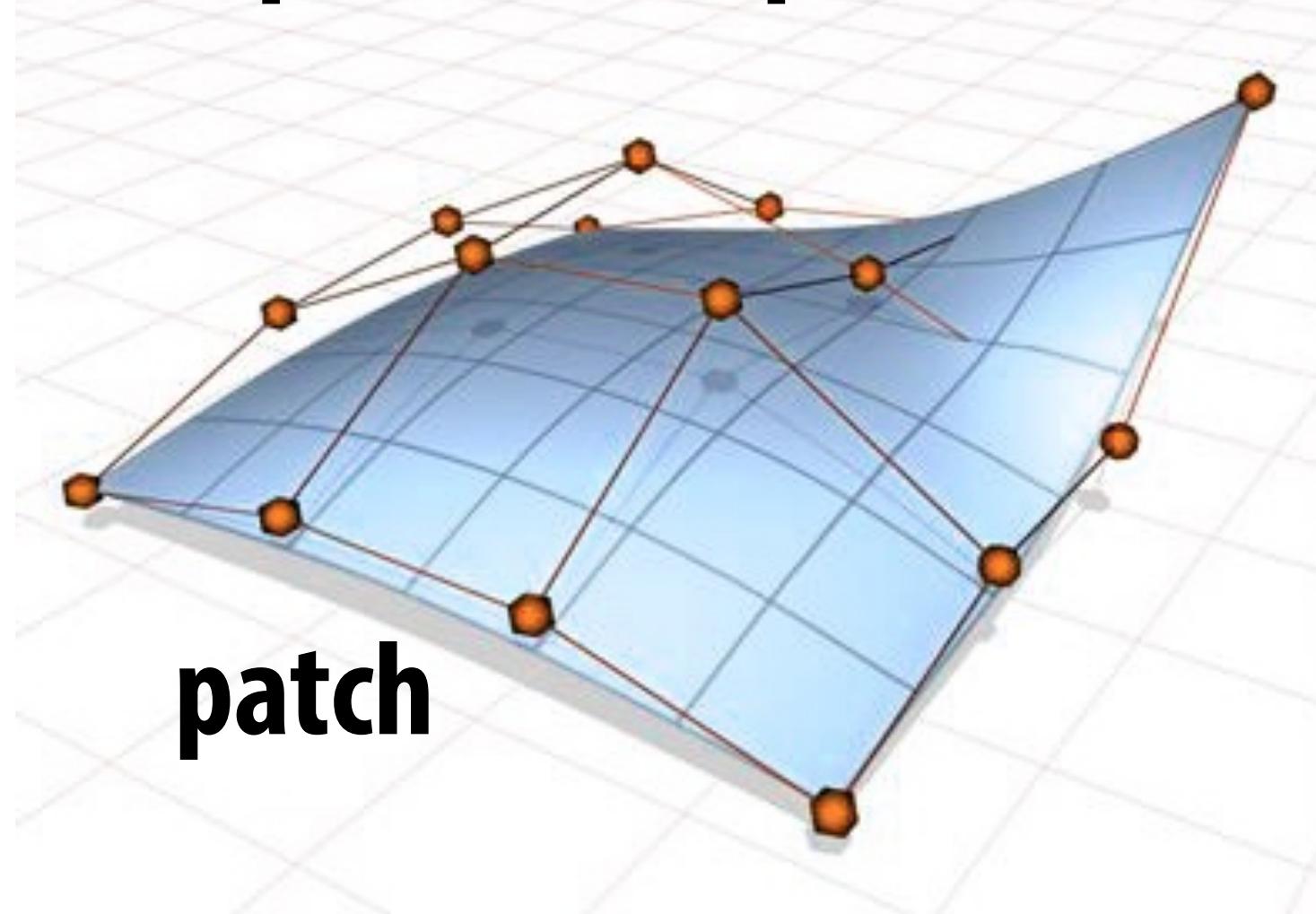


# NURBS Surface (Explicit)

- Much more common than using NURBS for curves
- Use *tensor product* of scalar NURBS curves to get a patch:

$$S(u, v) := N_i(u)N_j(v)p_{ij}$$

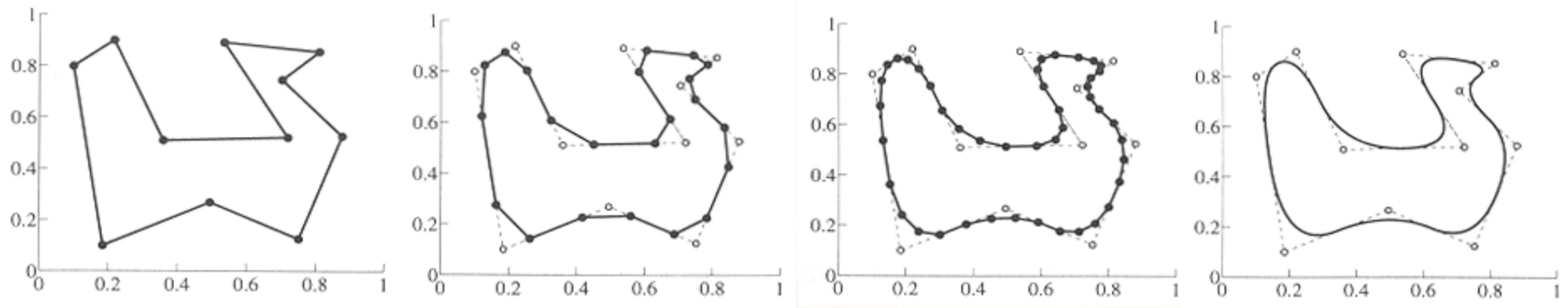
- Multiple NURBS patches form a surface



- Pros: easy to evaluate, exact conics, high degree of continuity
- Cons: Hard to piece together patches, hard to edit (many DOFs)

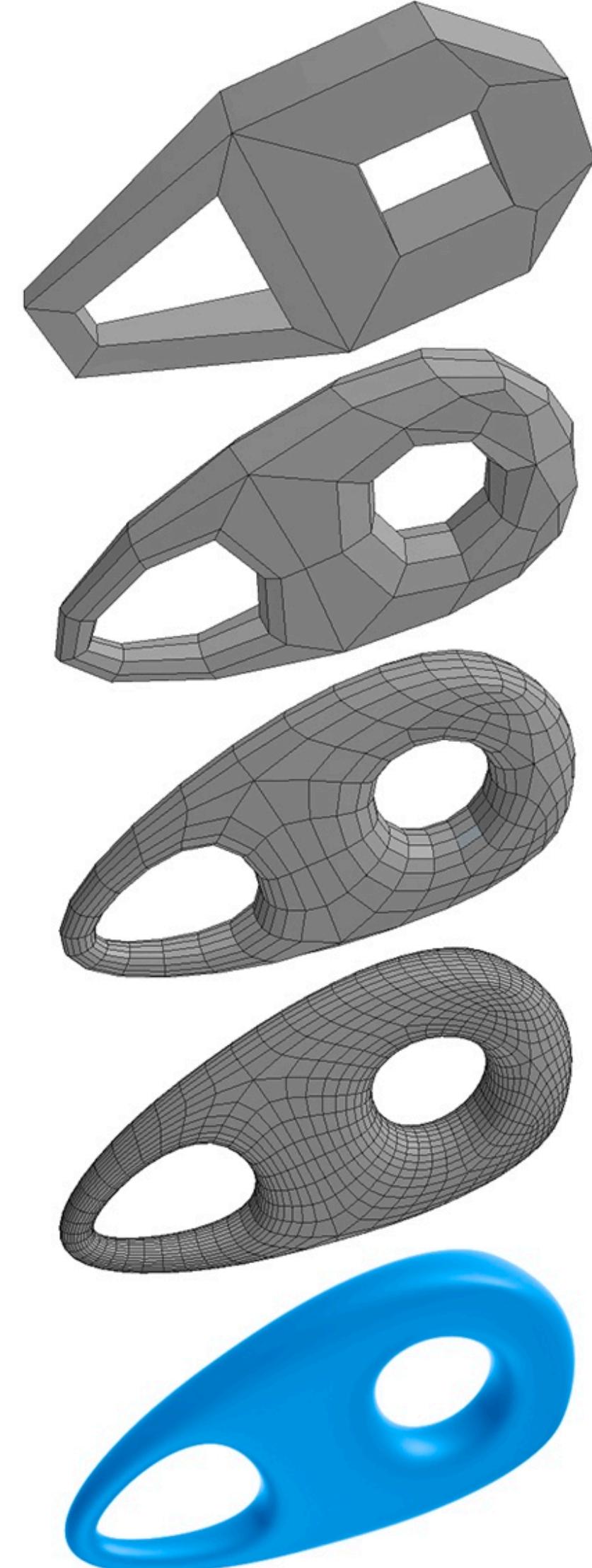
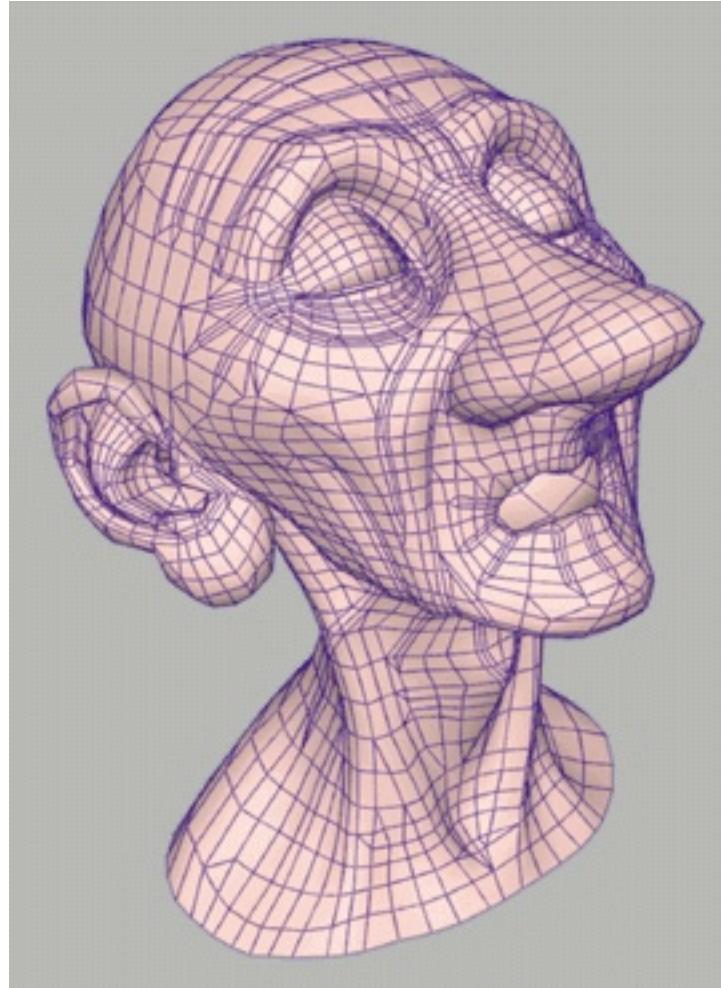
# Subdivision (Explicit)

- Alternative starting point for B-spline curves: *subdivision*
- Start with control curve
- Insert new vertex at each edge midpoint
- Update vertex positions according to fixed rule
- For careful choice of averaging rule, yields smooth curve
  - Average with “next” neighbor (Chaikin): quadratic B-spline
  - Lane-Riesenfeld: B-spline curve of any degree



# Subdivision Surfaces (Explicit)

- Start with coarse polygon mesh (“control cage”)
- Subdivide each element
- Update vertices via local averaging
- Many possible rule:
  - Catmull-Clark (quads)
  - Loop (triangles)
  - ...
- Common issues:
  - interpolating or approximating?
  - continuity at vertices?
- Easier than NURBS for modeling; harder to guarantee continuity



# Subdivision in Action (Pixar's “Geri’s Game”)

# Next time: Curves, Surfaces, & Meshes

