DTC	C1243/43	MALFUNCTION IN DECELERATION SENSOR
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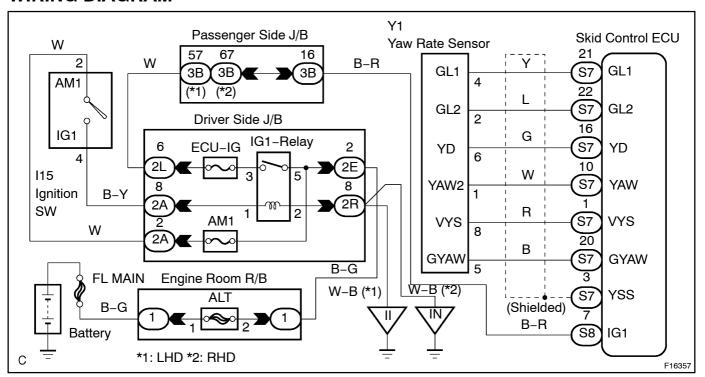
DTC C1245/45 MALFUNCTION IN DECELERATION SENSOR

DTC C1336/39 ZERO POINT CALIBRATION OF DECELERATION SENSOR UNDONE

## **CIRCUIT DESCRIPTION**

DTC No.	DTC Detecting Condition	Trouble Area	
C1243/43	While vehicle speed gets to 0 km/h (0 mph) from 30 km/h (18 mph), and the condition that GL1 and GL2 signals of ECU terminals did not change 2 LSB or more continued in a sequence 16 times.	Developer	
C1245/45	At the vehicle speed of 30 km/h (18 mph) or more, and the condition that the difference between acceleration and deceleration values of computation from deceleration sensor and vehicle speed becomes more than 0.35 G continues for 60 sec. or more.	Deceleration sensor     Wire harness for deceleration sensor system	
C1336/39	At the initial time after replacing the computer, or after erasing the deceleration sensor memory by operating the terminals Ts and CG of DLC3, the ignition is turned ON and the vehicle is driven in any mode except for the test mode.	Deceleration sensor  Deceleration sensor circuit  Zero point calibration no done	

## **WIRING DIAGRAM**



# **INSPECTION PROCEDURE**

HINT:

After[step] [and[2,[go[]o[step[3]]n[case[]o[]ne]hand-held[]ester,[and[]o[]o[]o[]step[3]]n[case[]o[]nchand-held[]ester,[and[]o[]o[]o[]step[3]]n[case[]o[]n[

1 PERFORM DECELERATION SENSOR ZERO POINT CALIBRATION (See page 05-511)

2 | RECONFIRM[DTC(See[page[05-511])

A	Malfunction <u>Code</u>				
В	Normal[ <b>C</b> ode				
B <sub>□</sub> END					

\_\_A\_\_

- 3 | READ[VALUE[OF[HAND-HELD[TESTER(DECELERATION[\$ENSOR[OUTPUT VALUE)
- (a) Select[he]tem[DECELERAT[SEN, DECELERAT[SEN2"]n[he[DATA[LIST[and]read[]ts[value[displayed]]he]hand-held[ester.
- (b) Check[that[the[deceleration[value[bf[the[deceleration[sensor[bbserved[]n[the[hand-held[tester[]s changing[when[the[vehicle[is[tilted].

OK:

Deceleration[value[must[be[changing.

OK Go[to[step[5

NG

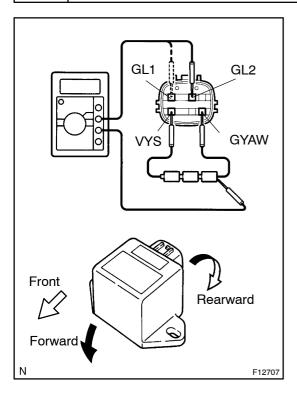
4 CHECK HARNESS AND CONNECTOR(YAW RATE SENSOR(DECELERATION SENSOR) - SKID CONTROL ECU ASSY) (See page 01-31)

NG REPAIR OR REPLACE HARNESS OR CONNECTOR

OK

**REPLACE YAWRATE SENSOR** 

# 5 INSPECT|YAWRATE|\$ENSOR(INCLUDE|DECELERATION|\$ENSOR)



- (a) Remove the consol box.
- (b) Connect [3 dry batteries of 1.5 Vin series.
- (c) Connect[VYS[]erminal[]o[]he[]batteries'[]positive[]+)[]erminal, []and[GYAW[]erminal[]o[]he[]batteries'[]hegative[]-)[]erminal. []Apply[]about[]4.5[V[]between[]VYS[]and[GYAW[]]erminals

#### NOTICE:

# Do[not[apply[voltage[of[6]V[or[more[to[terminals[VYS[and GYAW.

(d) Check[the] output[voltage] of GL1 and GL2[terminals] when the sensor is titled forward and fearward.

#### OK:

Symbols	Condition	Standard[ <b>V</b> alue
GL1	Horizontal	About[2.3[V
GL1	Lean[ <b>]</b> orward	0.4[V -[about[2.3[V
GL1	Lean[rearward	About[2.3[V -[4.1[V
GL2	Horizontal	About[2.3[V
GL2	Lean[ <b>]</b> orward	About[2.3[V -[4.1[V
GL2	Lean[rearward	0.4[V -[about[2.3[V

#### HINT:

- If the sensor is tilted too much it may show the wrong value.
- If dropped, the sensor should be replaced with a mew one.
- •□ The[s@nsor[r@m@ved[fr@m[fr]e[vehicle[sr]ould[not[be placed upside down.

## NG > REPLACE YAWRATE SENSOR

OK

6

CHECK HARNESS AND CONNECTOR (YAW RATE SENSOR (DECELERATION SENSOR) - [\$KID[CONTROL[ECU[ASSY](See[page[01-31])]

NG REPAIR OR REPLACE HARNESS OR CONNECTOR

OK

**CHECK AND REPLACE SKID CONTROL ECU ASSY**