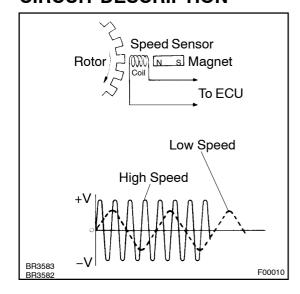
DTC	C0200/31	RIGHT FRONT SPEED SENSOR CIRCUIT
DTC	C0205/32	LEFT FRONT SPEED SENSOR CIRCUIT
	•	
DTC	C1235/35	FOREIGN MATTER IS ATTACHED ON TIP OF RIGHT FRONT SENSOR
DTC	C1236/36	FOREIGN MATTER IS ATTACHED ON TIP OF LEFT FRONT SENSOR

CIRCUIT DESCRIPTION



The speed sensor detects wheel speed and sends the appropriate signals to the ECU. These signals are used for control of the ABS control system. The front and rear rotors each have 48 serrations.

When the rotors rotate, the magnetic field emitted by the permanent magnet in the speed sensor generates an AC voltage. Since the frequency of this AC voltage changes in direct proportion to the speed of the rotor, the frequency is used by the ECU to detect the speed of each wheel.

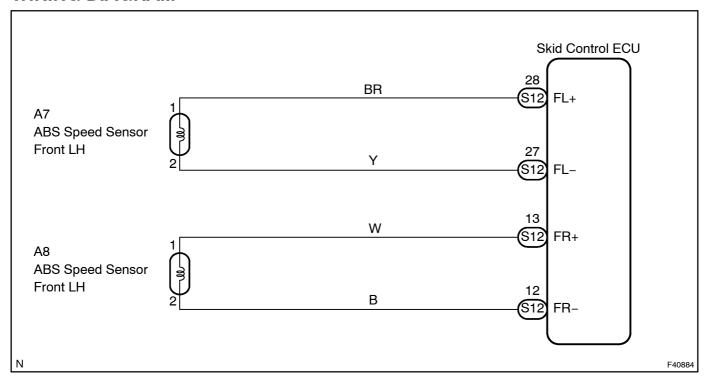
DTC No.	DTC Detecting Condition	Trouble Area
C0200/31 C0205/32	 Detection of any of conditions from 1. through 4.: With vehicle speed at 10 km/h or more, sensor signal circuit of faulty wheel is open or short for 15 sec. or longer. Momentary interruption of sensor signal of faulty wheel has occurred 7 times or more. With vehicle speed at 20 km/h or more, sensor signal of faulty wheel generated noise for 5 sec. or longer. Sensor signal circuit is open for 0.025 sec. or longer. 	Right front, left front speed sensor Speed sensor circuit Sensor installation Sensor rotor
C1235 / 35 C1236 / 36	Continuous noise occurs in to the speed sensor signals with the vehicle speed at 20 km/h (12 mph) or more continues for 5 sec or more.	Right front, left front speed sensor Speed sensor rotor

HINT:

DTC No. C0200/31 and C1235/35 is the right front speed sensor.

DTC No. C0205/32 and C1236/36 is the left front speed sensor.

WIRING DIAGRAM



INSPECTION PROCEDURE

HINT:

Start the inspection from step 1 in case of using the hand-held tester and start from step 2 in case of not using hand-held tester.

- 1 READ VALUE OF TOYOTA HAND-HELD TESTER(SPEED SENSOR OUTPUT VALUE)
- (a) Select the item "WHEEL SPEED FL (FR)" in the DATA LIST and read its value displayed on the hand-held tester.
- (b) Check that there is no difference between the speed value output from the speed sensor displayed on the hand-held tester and the speed value displayed on the speedometer when driving the vehicle. **OK:**

There is almost no difference from the displayed speed value.

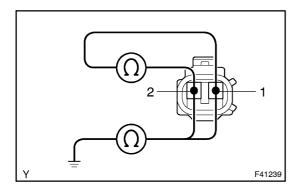
HINT:

There is tolerance of \pm 10 % in the speedometer indication.

OK REPLACE SKID CONTROL ECU ASSY

NG

2 | INSPECT[FRONT[\$PEED[\$ENSOR



- (a) Remove the front ender iner.
- (b) Make sure that there sho oseness at the connector lock part and connecting part of the connector.
- (c) Disconnect the speed sensor connector.
- (d) Measure resistance between reminals and 全向保护中的sensor connector.

OK: $1.4 - 1.8 \text{ k}\Omega \text{ at } 20 \text{ C}$

(e) Measure resistance between terminals and 2 ft speed sensor connector and body ground.

OK: 1Mpp or higher

A	OK
В	NG[[Right[]ront[speed[sensor)
С	NG[[Left[]ront[]speed[]sensor)

B[] REPLACE[\$PEED[\$ENSOR[FRONT[RH

C | REPLACE | RE

NOTICE:

Check[the[speed[sensor[signal[]ast[[See[page[]05-451]).

Α

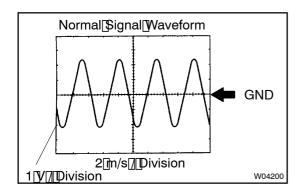
3∏

CHECK[HARNESS[AND[CONNECTOR(SPEED[\$ENSOR -[\$KID[CONTROL[ECU ASSY)(See[page[01-31)]

NG REPAIR OR REPLACE HARNESS AND CONNECTOR

ОК

4 | CHECK| SPEED| SENSOR| AND | SENSOR| ROTOR| SERRATIONS



(REFERENCE)[INSPECTION[USING[OSCILLOSCOPE

- (a) Remove[the[skid[control[ECU[with[connectors[still[connected.
- (b) Connect[the@scilloscope[to[the[terminals[FR+-[FR-,[FL+-[FL-[f]f]the[skid]control[ECU.
- (c) Drive the yehicle with about 20 km/h 12 mph), and theck the signal waveform.

HINT:

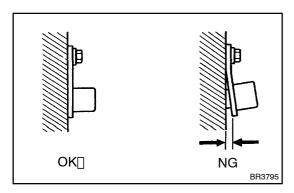
- As[the[vehicle[speed[(rpm[of[the[wheels)]]ncreases,[a cycle[of[t]]he[waveform[becomes[shorter[and[t]]he[f]]lucturation[in[the[output[voltage[becomes[g]]reater.]]
- •□ When noise sidentified nthe waveform on the oscilloscope, error signals are generated due to the speed sensor otor scratches, so seness or foreign natter deposited on it.



CHECK[AND[REPLACE[SKID[CONTROL[ECU ASSY]

NG

5 | CHECK[FRONT[\$PEED[\$ENSOR[INSTALLATION



(a) Check the speed sensor installation.

OK:

The installation bolt is tightened properly and there is no clearance between the sensor and front steering knuckle

Torque: 8.0 N·m (82 kgf·cm, 71 in. lbf)

A	OK
В	NG[[Right[]ront[speed[sensor)
C	NG (Left front speed sensor)

B > REPLACE SPEED SENSOR FRONT RH

C REPLACE SPEED SENSOR FRONT LH

NOTICE:

Check[the[speed[sensor[signal[last](See[page[05-451)]).

A

6 | CHECK[\$PEED[\$ENSOR[ROTOR[AND[\$ENSOR[TIP

NG

 $\begin{cal} CLEAN []{\tt OR} []{\tt REPLACE} []{\tt SPEED} []{\tt SENSOR} []{\tt AND} \\ {\tt SENSOR} []{\tt ROTOR} []{\tt SERRATIONS} \\ \end{cal}$

NOTICE:

Check[he[speed[sensor[signal[]ast[[See[page[]05-451]].

OK

CHECK AND REPLACE SKID CONTROL ECU ASSY