

# Augmented Causal Diagrams for Measurement Error

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Observational studies often plagued by multiple biases such as from **measurement error (ME)**, selection, and unmeasured confounders.

Yet, these biases are rarely quantitatively assessed or even acknowledged.

ME easily the most difficult of the biases to handle.

Here, this presentation demonstrates how to

1. Depict ME using augmented directed acyclic graphs (DAGs)
2. Visualize the biasing paths induced by ME
3. Visualize ME adjustment or modeling methods



# Notation

**(V) denotes unmeasured true variable V  
 $\varepsilon_V$  is the disturbance term in V**

**V\* is measured or misclassified V  
 $\varepsilon_{V^*}$  is the disturbance term in V\***

**Solid arrow: true (unmeasured) association  
between any two variables**

**Dashed arrow: measured association  
(perhaps externally available)**

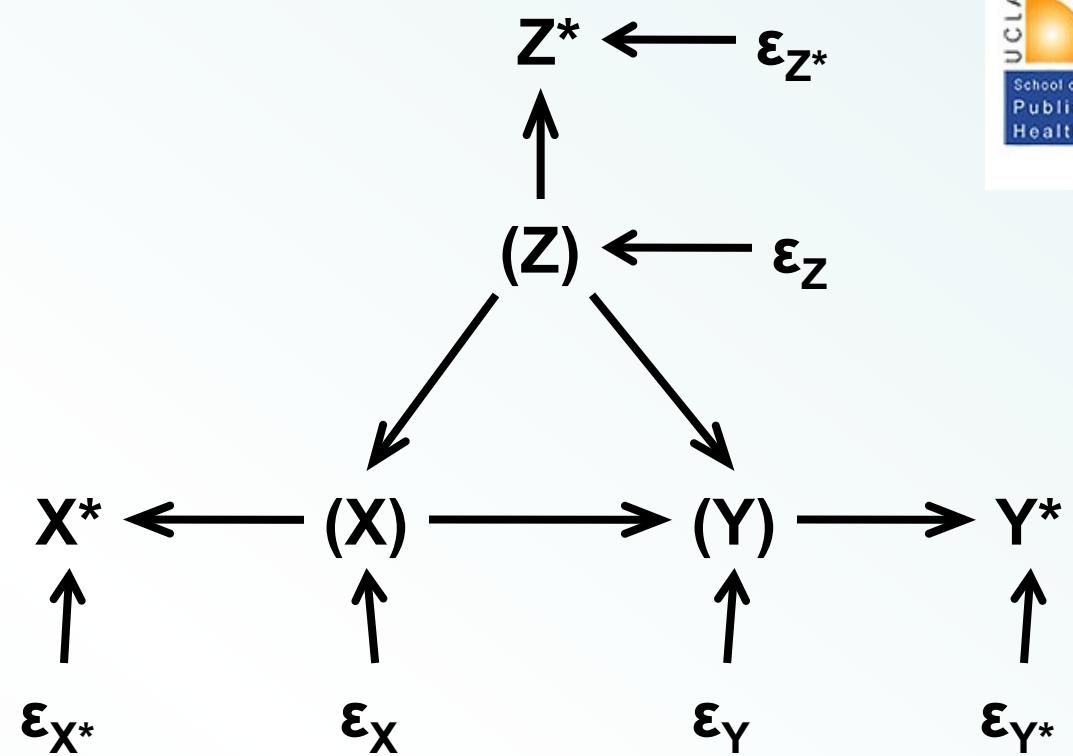
**Bidirected dashed arc: common cause  
present**

**X is exposure, Z confounder, and Y outcome** 4

# Depicting and Visualizing Independent Non-differential Measurement Error

Although typically omitted from DAGs, disturbance terms are important in measurement error DAGs.

ME is **independent**: the disturbance terms are (marginally) uncorrelated.



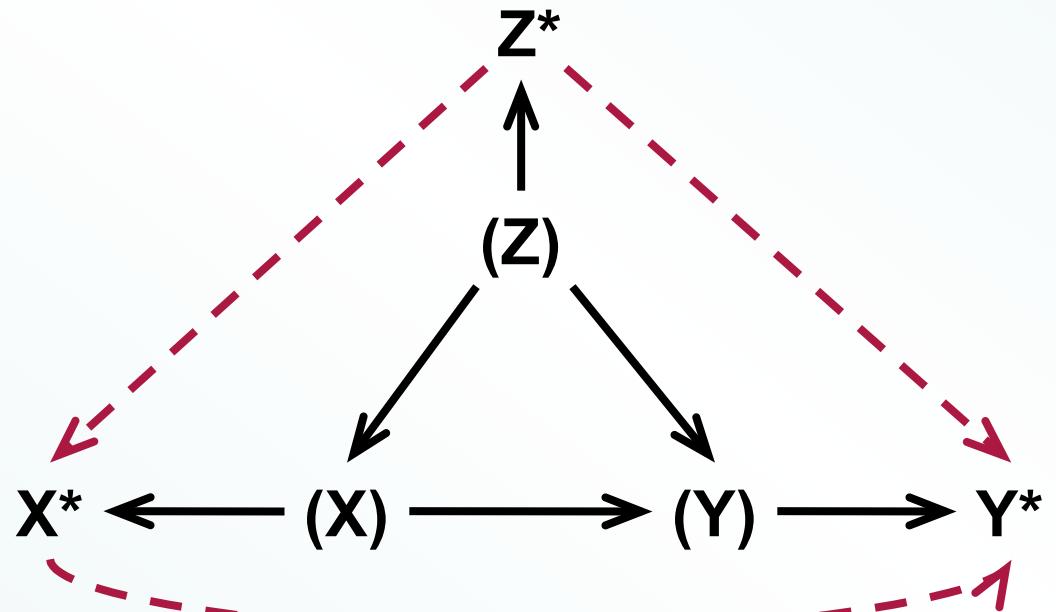
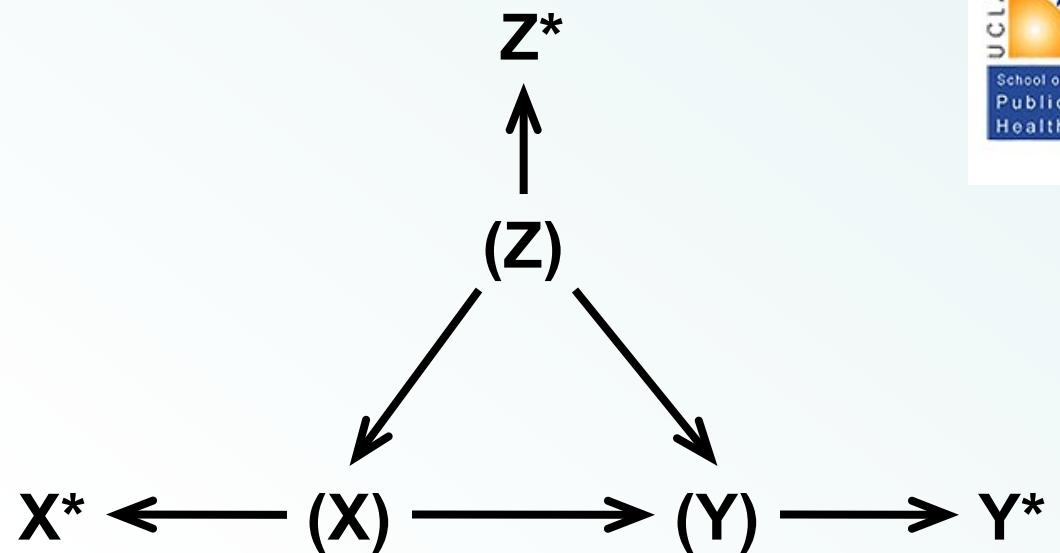
ME is **nondifferential**: the only arrows into  $V^*$  are from the disturbance term and true unmeasured variable.

**Each red dashed arrow  
is equivalent to all the  
open paths between  
the two variables  
connected by the red  
arrow.**

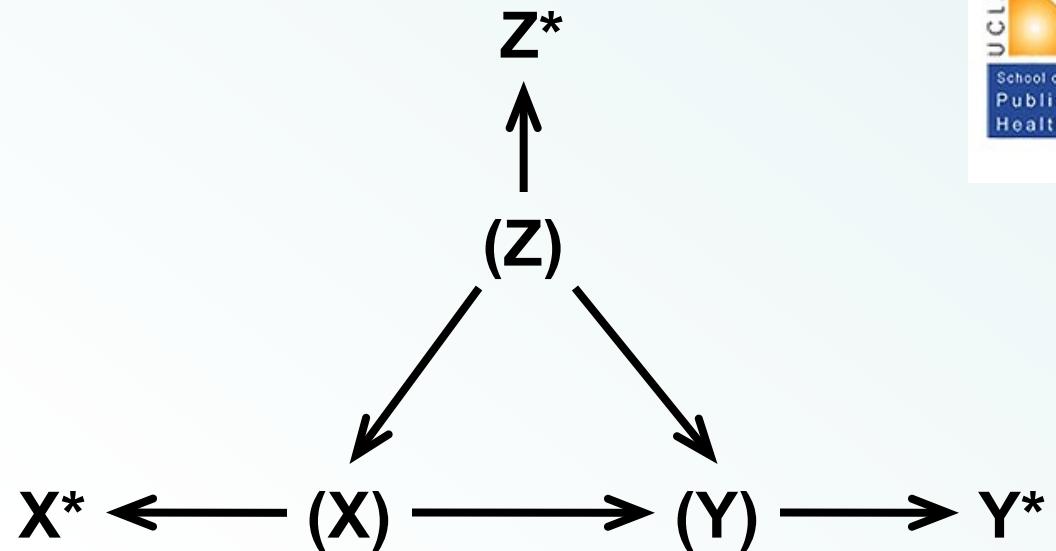
**Z\*-X\* association is  
given by:**  
 1. Z\*-(Z)-(X)-X\*.

**Z\*-Y\* association by:**  
 1. Z\*-(Z)-(Y)-Y\*  
 2. Z\*-(Z)-(X)-(Y)-Y\*.

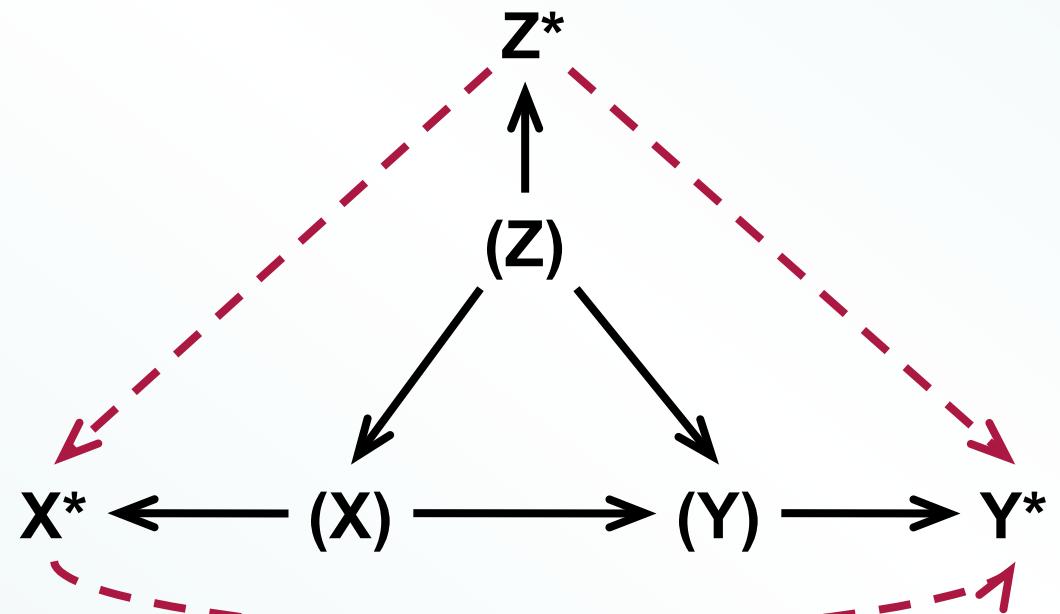
**X\*-Y\* association by:**  
 1. X\*-(X)-(Y)-Y\*  
 2. X\*-(X)-(Z)-(Y)-Y\*.



**Notice that conditioning on  $Z^*$  or  $X^*$  tends to partially block paths containing their true versions provided those are not colliders as seen in the DAGs here.**



**For example, conditioning on  $Z^*$  partially blocks the backdoor between  $(X)$  and  $(Y)$  via  $Z$ , thus leaving residual confounding of  $(X)$ - $(Y)$ .**



# Independent Differential Measurement Error

## First DAG:

**Z\*-X\* association now reflects these biasing paths:**

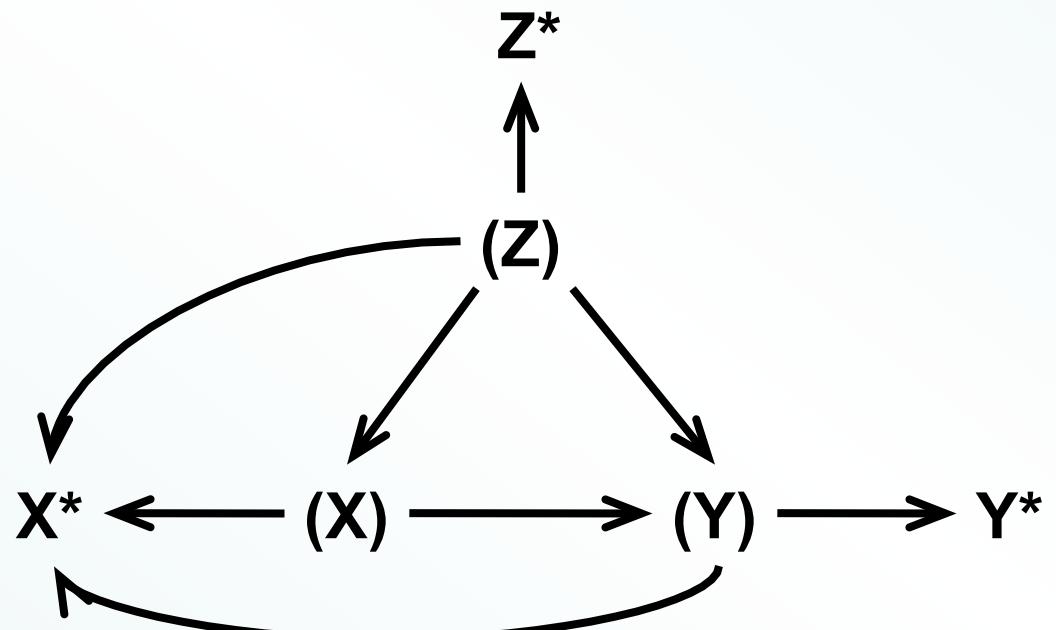
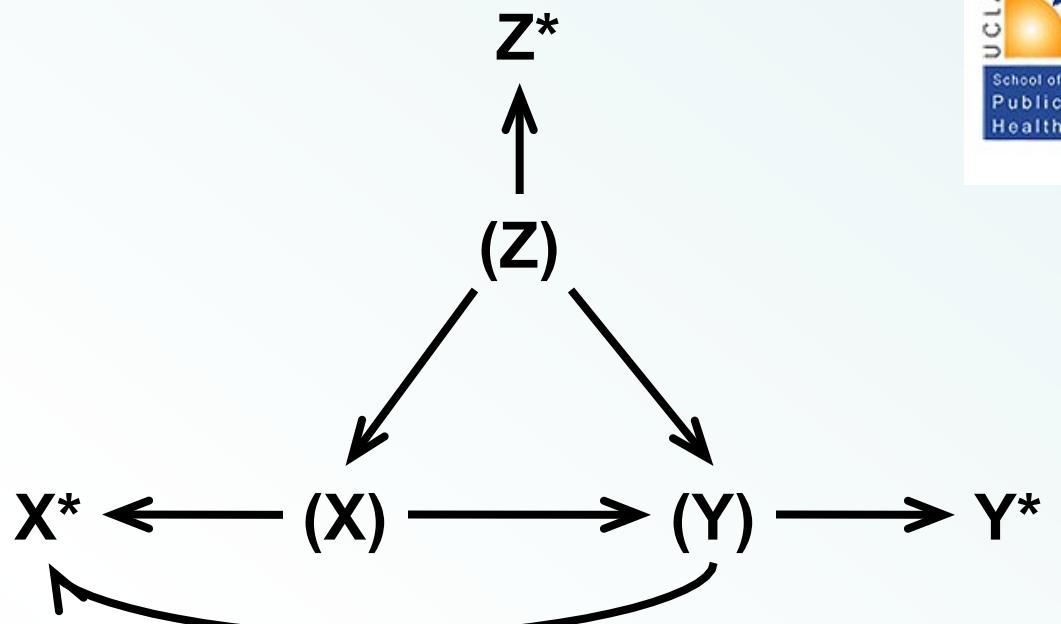
1. Z\*-(Z)-(X)-X\*
2. Z\*-(Z)-(Y)-X\*.

**Z\*-Y\* association:**

1. Z\*-(Z)-(Y)-Y\*
2. Z\*-(Z)-(X)-(Y)-Y\*
3. Z\*-(Z)-(X)-X\*-(Y)-Y\*.

**X\*-Y\* association:**

1. X\*-(X)-(Y)-Y\*
2. X\*-(X)-(Z)-(Y)-Y\*
3. X\*-(Y)-Y\*.

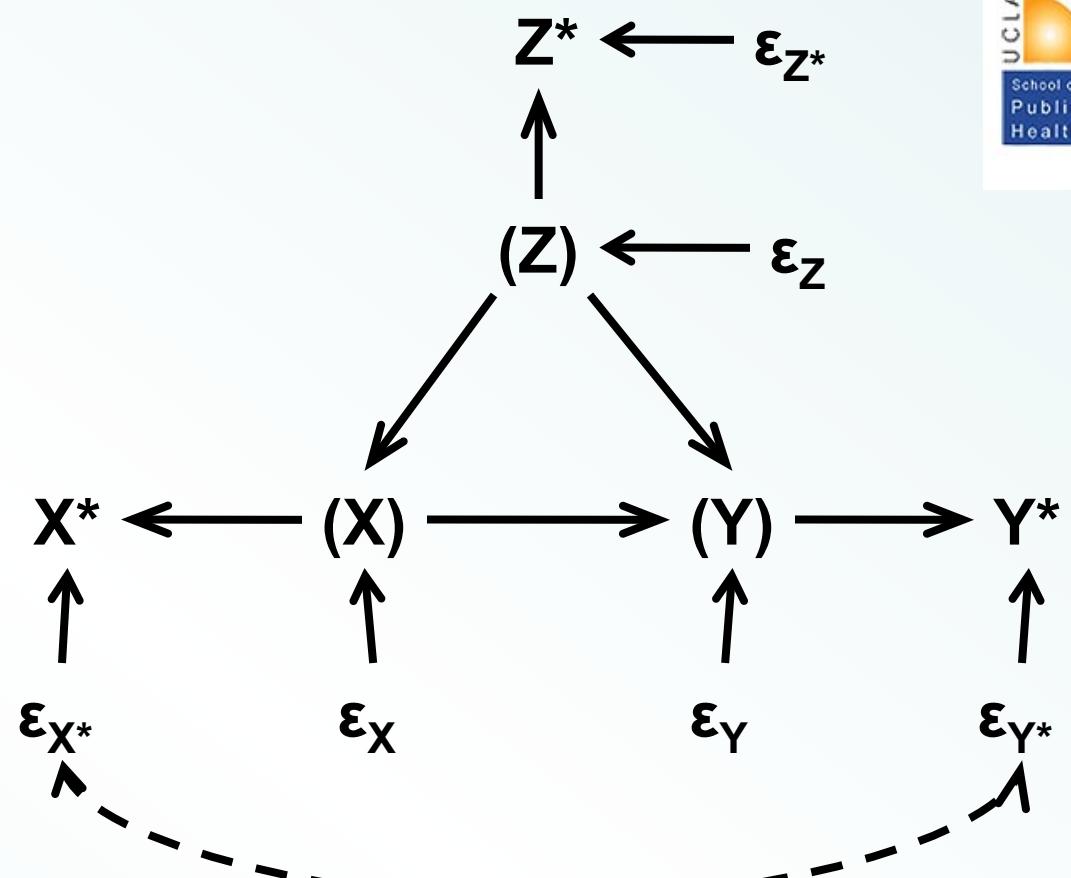


# Dependent Non-differential Measurement Error

**X\*-Y\* association now reflects these biasing paths:**

1. X\*-(X)-(Y)-Y\*
2. X\*-(X)-(Z)-(Y)-Y\*
3. X\*- $\epsilon_{X^*}$ - $\epsilon_{Y^*}$ -Y\*.

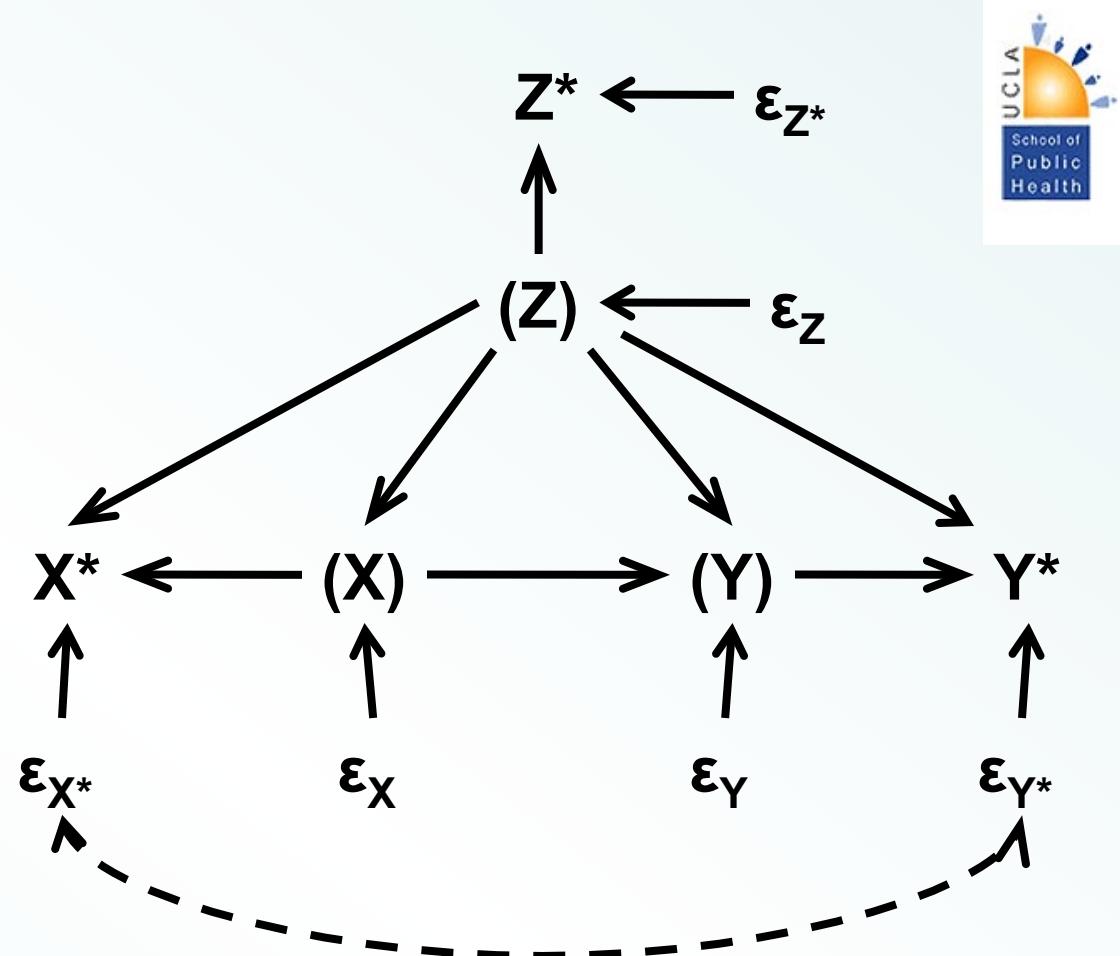
We note that, given this DAG,  $\epsilon_{X^*}$  and  $\epsilon_{Z^*}$  (or  $\epsilon_{X^*}$  and  $\epsilon_X$ ) are correlated, unlike  $\epsilon_X$  and  $\epsilon_Z$ , in corresponding multivariable adjustment.



# Dependent Differential Measurement Error

**X\*-Y\* association now reflects these biasing paths:**

1. X\*-(X)-(Y)-Y\*
2. X\*-(X)-(Z)-(Y)-Y\*
3. X\*-(Z)-(X)-(Y)-Y\*
4. X\*-(Z)-(Y)-Y\*
5. X\*-(Z)-Y\*
6. X\*- $\epsilon_{X^*}$ - $\epsilon_{Y^*}$ -Y\*



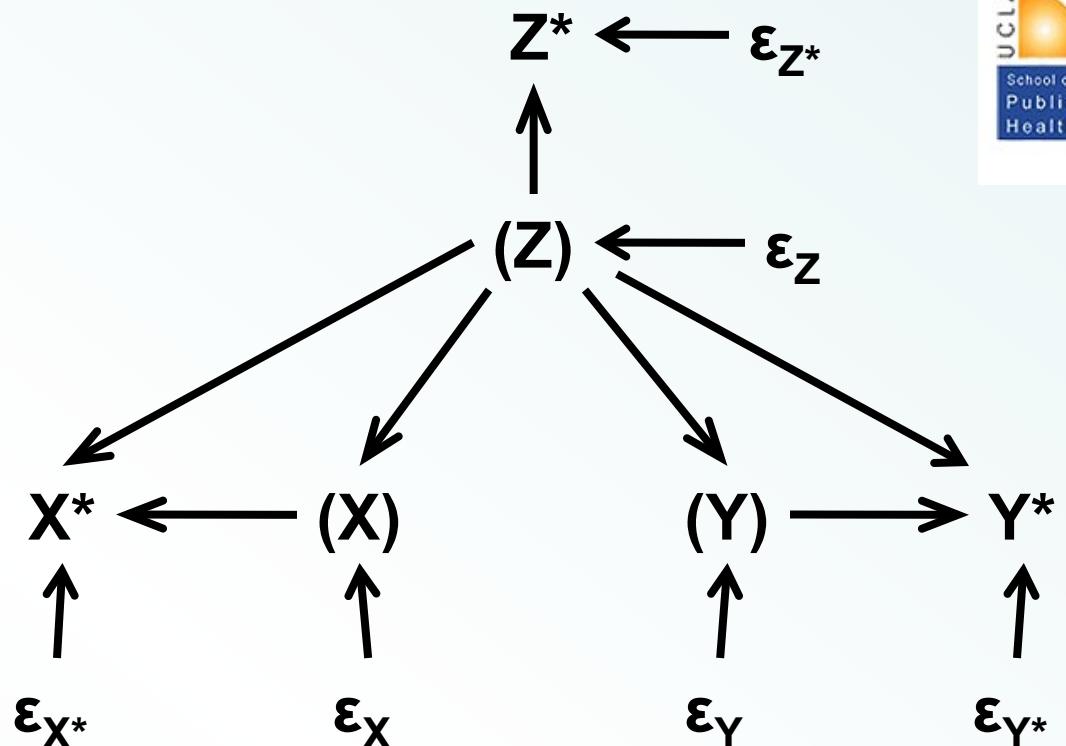
# Notable results of ME when true effect is null:

1. ME in confounders
2. Uncontrolled confounding
3. Selection bias
4. Longitudinal (time-varying) data setting

## ME in confounder:

If no true X-Y effect,  
then  $X^*$ - $Y^*$  association  
will be null if and only if

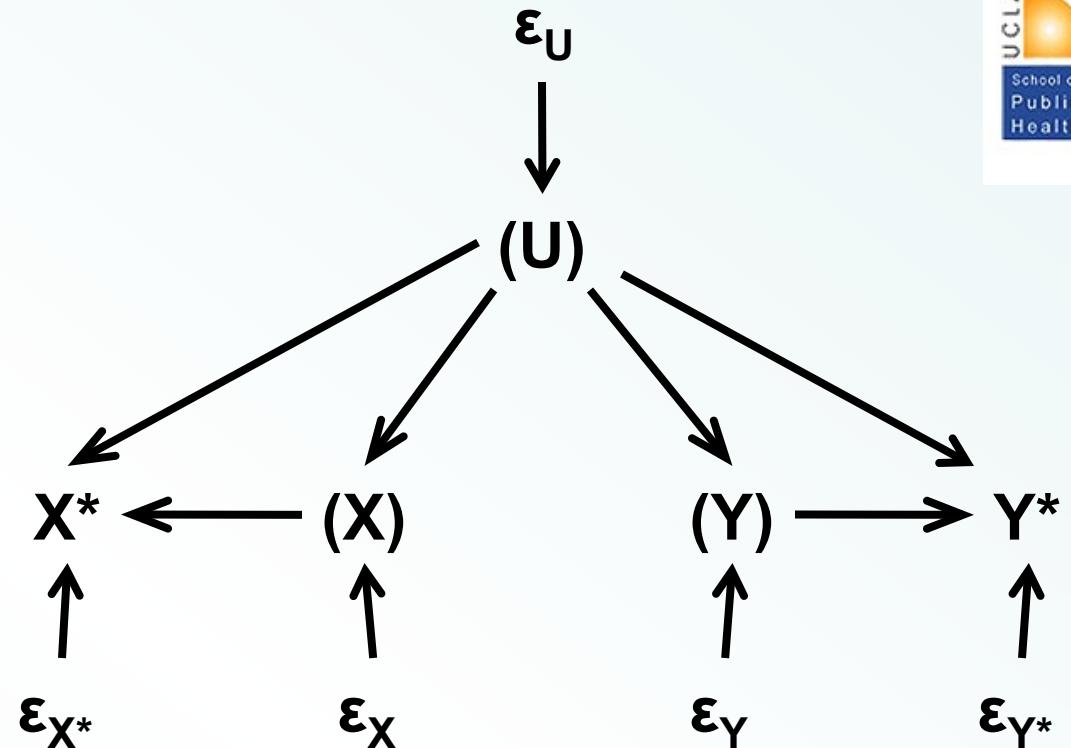
1. No uncontrolled confounding
2. No ME in confounders
3. No dependent ME
4. All causes of differential ME are controlled for, or no differential ME



## Uncontrolled confounding:

If no true X-Y effect,  
then  $X^*$ - $Y^*$  association  
will NOT be null even if

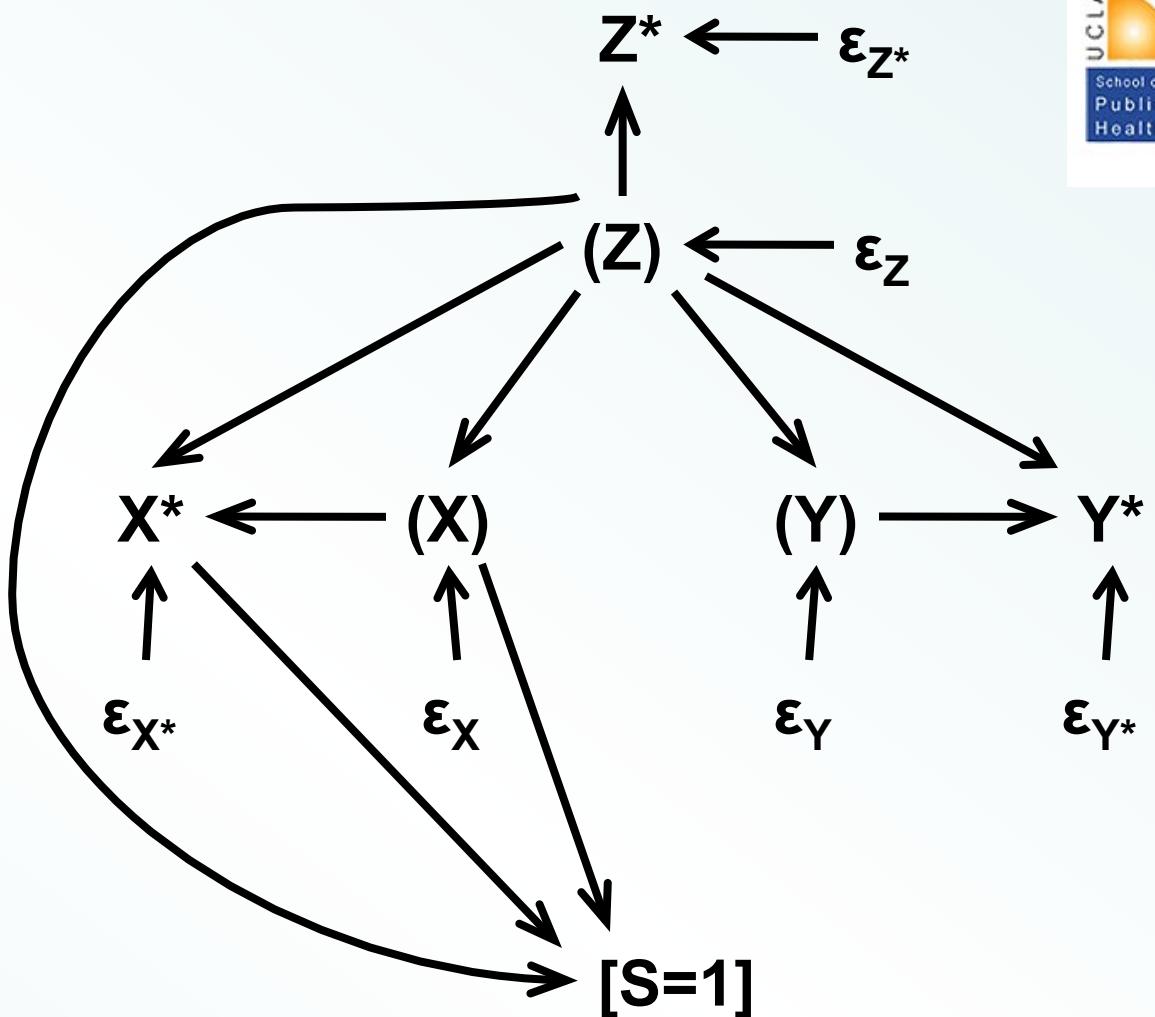
1. No ME in measured confounders
2. No differential ME
3. No dependent ME



## Selection bias (special type):



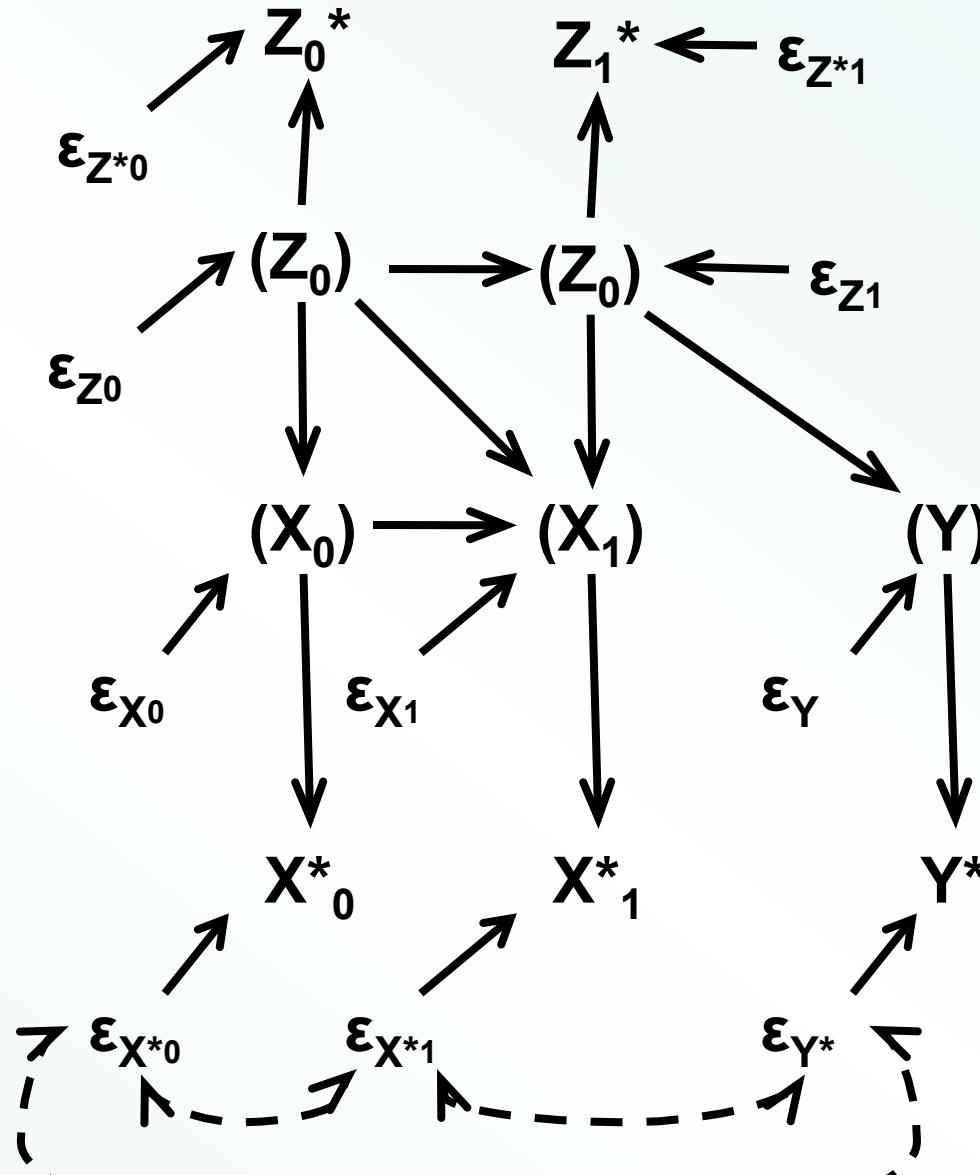
If no true  $(X)-(Y)$  effect, then  $X^*-Y^*$  association will NOT be null given  $Z^*$  because **conditioning on  $Z^*$  will not completely block the biasing paths allowed by  $(Z)$**



## Longitudinal (time-varying) data:

Several biasing paths are present in this simplistic setting even in the absence of effects of true  $X_0$  and  $X_1$  on true  $Y$ .

Worse when censoring and uncontrolled confounding are built in.

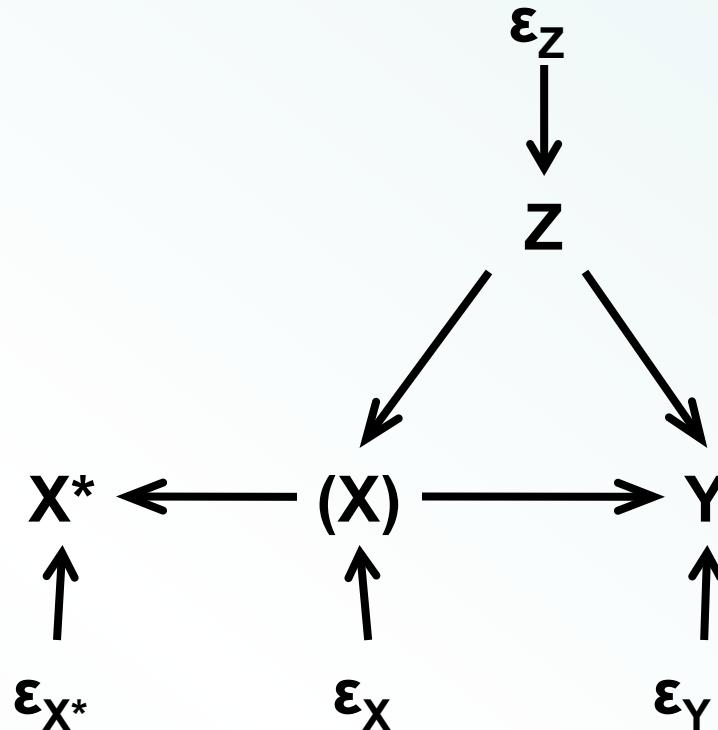




# Visualizing Adjustments for Measurement Error

## ME as missing data:

**Data on true X missing.**  
**As can be read from the DAG, to impute X we will need priors for or data on the  $X^*-(X)$ ,  $Z-(X)$ ,  $Y-(X)$  associations!**



$$P(y|x,z)P(x^*|x)P(x|z)P(z) = P(y|x,z,x^*)P(x^*|x,z)P(x|z,)P(z)$$

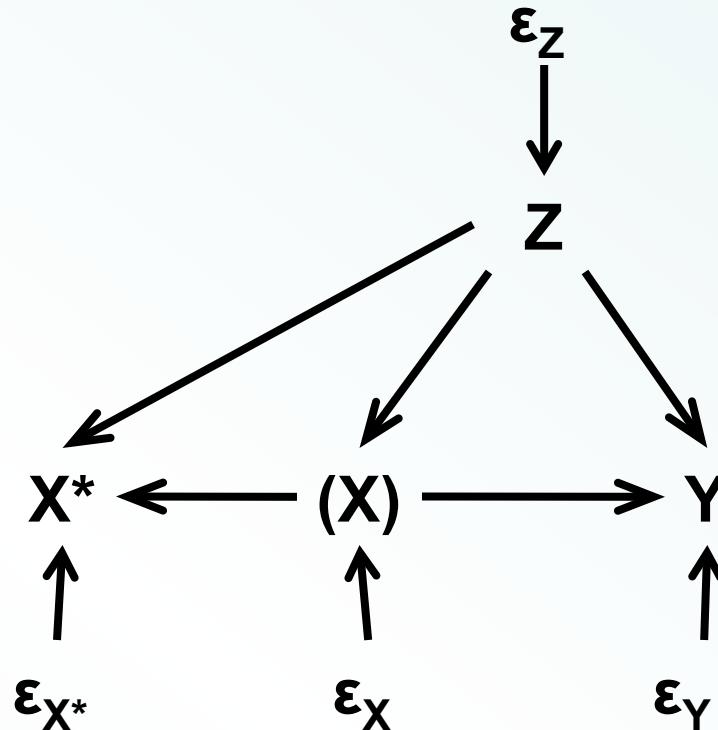
→

$$P(x|y,z,x^*)P(y,z,x^*)$$

where for a nominal  $X$  under a logistic model,  $P(x|y,z,x^*)$  can be modeled as the expit of the relevant  $X^*-(X)$ ,  $Z-(X)$  and  $Y-(X)$  coefficients

## ME as missing data:

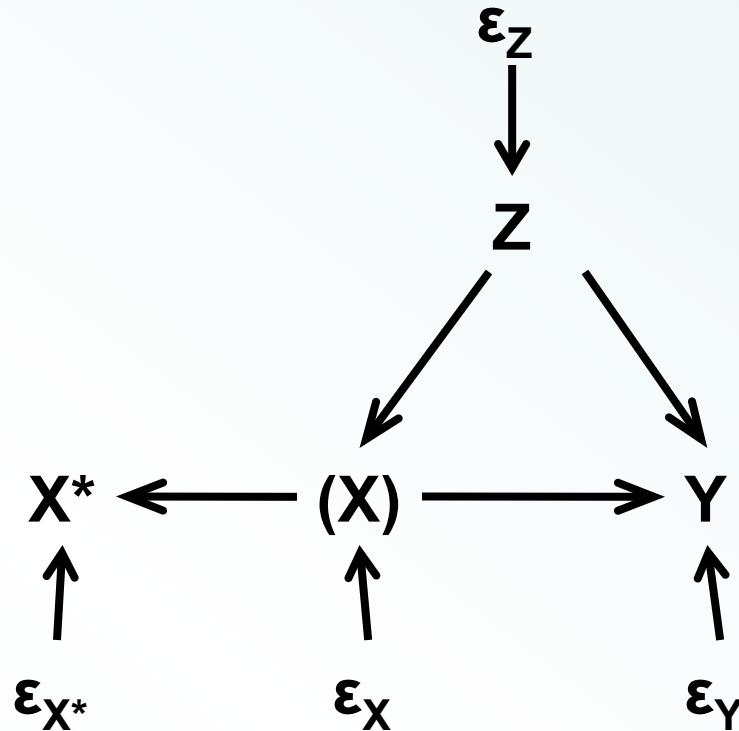
If differential ME as in the DAG here, then in addition to priors for or data on the  $X^*-(X)$  and  $Y-(X)$  associations, we will need the combined  $Z-X^*-(X)$  and  $Z-(X)$  association to impute  $X$  because conditioning on  $X^*$  will open up the extra path  $Z-X^*-(X)$  between  $Z$  and  $X$ , beyond the direct  $Z-(X)$  relation.



## Regression calibration:

$X^*$  can be seen as an instrumental variable for  $X$  even without satisfying the (causal) instrumentality requirements

$$\begin{aligned} E(Y|x,z) &= E(Y|E(X|x^*,z),z) \\ &= E(Y|E(X^*|x,z),z) \\ &= E(Y|E(X^*|x),z) \end{aligned}$$



but

$$\begin{aligned} E(Y|x,z) &\neq E(Y|E(X|x^*),z) \end{aligned}$$



# Conclusions

Augmented DAGs show that estimated parameters are biased through all paths left partially open by the unobserved true variables.

Augmented DAGs also aid in visualizing the possible methods needed to assess the quantitative impact of ME



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