# ECE 340 Lab 2

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### 1 Intro to Convolution

Given the two discrete functions:

$$x[k] = \begin{cases} k, & 0 \le k \le 4\\ 0, & \text{otherwise} \end{cases}$$
 (1)

$$h[k] = \begin{cases} 2 - k, & 0 \le k \le 3\\ 0, & \text{otherwise} \end{cases}$$
 (2)

They were be plotted on the same page in MATLAB using the following code:

```
figure(1);
% plot x[k]
subplot(2, 1, 1);
k = -5:10;
 = zeros(size(k));
x(0 \le k \& k \le 4) = k(0 \le k \& k \le 4);
stem(k, x, 'r', 'DisplayName', 'x[k]');
title('Plot of x[k]')
xlabel('k')
ylabel('x[k]')
% plot h[k]
subplot(2, 1, 2);
h = zeros(size(k));
h(0 \le k \& k \le 3) = 2 - k(0 \le k \& k \le 3);
stem(k, h, 'b', 'DisplayName', 'h[k]');
title('Plot of h[k]')
xlabel('k')
ylabel('h[k]')
```

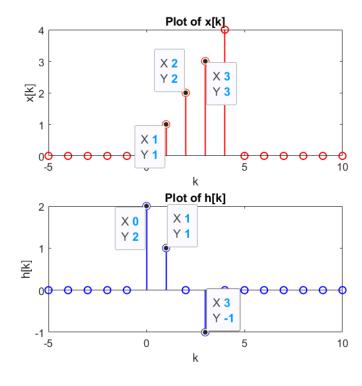


Figure 1: Plot of x[k] and h[k] defined above.

To convolve these to functions with MATLAB's conv function the following script was used:

```
figure(2);

% convolve using 'conv' and plot the result
subplot(2, 1, 1);
y = conv(x, h);
k_conv = (min(k) + min(k)) : (max(k) + max(k)); % convolution range
stem(k_conv, y, 'LineWidth', 1, 'Color', '#036b30');
title('Plot of x[k] * h[k], Calculated Using conv.');
xlabel('k');
ylabel('x[k] * h[k]');
```

To compare to the results of the conv function, the convolution was computed manually with the following script:

```
% manually compute the convolution and plot the result
subplot(2, 1, 2);
len_x = length(x);
len_h = length(h);
len_y = len_x + len_h - 1;  % length of the result
y_manual = zeros(1, len_y);
for k = 1:len_y
  for n = 1:len_x
    if (k-n+1 > 0) && (k-n+1 \le len_h)
      y_{manual}(k) = y_{manual}(k) + x(n) * h(k-n+1);
    end
  end
stem(k_conv, y_manual, 'LineWidth', 1, 'Color', '#010a87');
title('Plot of x[k] * h[k], Calculated Manually.');
xlabel('k');
xlabel('x[k] * h[k]');
```

The results of the two convolutions were as follows.

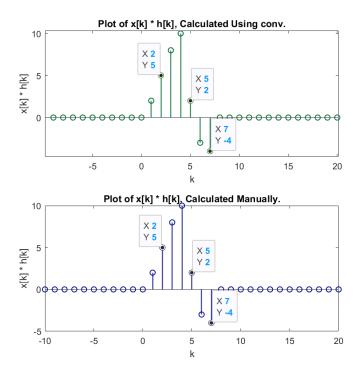


Figure 2: Plot of x[k] \* h[k].

By checking the values of several points on both plots, it was clear that the results of the manual convolution and the *conv* match.

### 2 Convolution of Audio

Given a system with the following impulse response:

$$h[k] = \begin{cases} 0.3 \text{sinc}(0.3(k-25)) \left(0.54 - 0.46 \cos\left[\frac{2\pi k}{50}\right]\right) & 0 \le k \le 50\\ 0 & \text{otherwise} \end{cases}$$
 (3)

The impulse response can be plotted using the following MATLAB script:

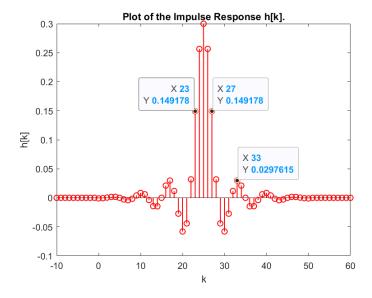


Figure 3: Plot of the impulse response h[k].

Given the audio file baila.wav, the convolution of its signal and the impulse response h[k] can be calculated and written to a new file  $baila\_filtered.wav$  using the following MATLAB script:

```
% read baila.wav audio file
[x3, Fs] = audioread('baila.wav');
t = (0:length(x3) - 1) / Fs;
x3f = conv(x3, h, 'same');
audiowrite('baila_filtered.wav', x3f, Fs);
```

The result of the following convolution was a grainier and muffled version of the original baila.wav file.

## 3 Effects of Aliasing on 1D Sinusoidal Signals

Given the two continuous-time sinusoidal signals  $x_1(t) = \cos(20\pi t)$  and  $x_2(t) = \cos(180\pi t)$ , along with a sampling frequency of  $f_{s_1} = 100\,\text{Hz}$ , the resulting discrete-time signals  $y_1[n]$  and  $y_2[n]$  for  $0 \le n \le 30$  can be computed and plotted using the following MATLAB script:

```
% get y1 and y2
fs1 = 100; % sampling frequency of 100hz
n1 = 0:30; \% index from 0 to 30
t1 = n1 / fs1; % time-vector for continuous-time signals
y1 = cos(20 * pi * t1);
y2 = cos(180 * pi * t1);
figure(1);
% subplot for y1[n]
subplot(2, 1, 1);
stem(n1, y1, 'LineWidth', 1, 'Color', 'r');
title('Stem Plot of y_1[n] = cos(20\pi i)');
xlabel('n');
ylabel('y_1[n]');
% subplot for y2[n]
subplot(2, 1, 2);
stem(n1, y2, 'LineWidth', 1, 'Color', 'b');
title('Stem Plot of y_2[n] = cos(180\pi t)');
xlabel('n');
ylabel('y_2[n]');
```

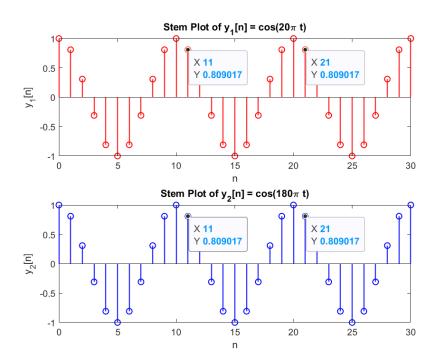


Figure 4: Plots of discrete-time signals  $y_1[k]$  and  $y_2[k]$ .

Looking at the plots side-by-side, and when several points are compared, it was clear that  $y_1[n]$  and  $y_2[n]$  with a sampling frequency  $f_{s_1} = 100Hz$  have an identical output. This was because  $y_2[n]$  can be seen as being equal to  $y_1[n-2\pi*n]$ :

$$y_2[n] = \cos(\frac{20\pi n}{100} - \frac{200\pi n}{100}) = \cos(\frac{180\pi n}{100})$$

If the sampling frequency of  $x_1(t)$  and  $x_2(t)$  was set to  $f_{s_2} = 1000Hz$ , the resulting discrete-time signals  $z_1[n]$  and  $z_2[n]$  for  $0 \le n \le 300$  can be calculated and plotted using the following MATLAB script:

```
% plot z1 and z2
figure(2);
```

```
fs2 = 1000; % sampling frequency of 100hz
n2 = 0:300; \% Time index for z1 and z2
t2 = n2 / fs2;
z1 = cos(20 * pi * t2);
z2 = cos(180 * pi * t2);
% subplot for z1[n]
subplot(2, 1, 1);
stem(n2, z1, 'LineWidth', 1, 'Color', 'r');
title('Stem Plot of z_1[n] = cos(20\pi i)');
xlabel('n');
ylabel('z_1[n]');
% subplot for z2[n]
subplot(2, 1, 2);
stem(n2, z2, 'LineWidth', 1, 'Color', 'b');
title('Stem Plot of z_2[n] = cos(180\pi t)');
xlabel('n');
ylabel('z_2[n]');
```

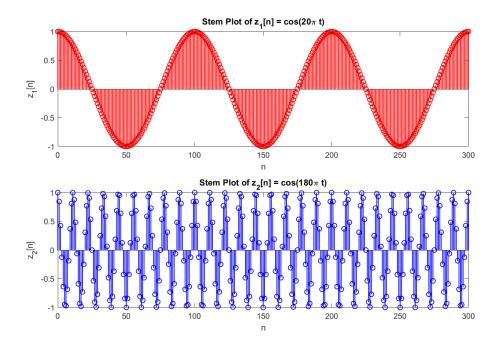


Figure 5: Plot of  $y_1[n]$  and  $z_1[n]$ , and  $y_1[n]$  and  $z_1[n]$ 

Now to compare  $y_1[n]$  and  $y_2[n]$  with  $z_1[n]$  with  $z_2[n]$  by plotting them together using the following MATLAB code:

```
% plotting z1 and y1 and z2 and y2
figure(3)
% Create the first subplot
subplot(2,1,1);
plot(n2/fs2, z1, 'r-', n1/fs1, y1, 'b+', 'LineWidth', 1);
xlabel('n'); ylabel('y_1[n] and z_1[n]');
legend('z_1[n]', 'y_1[n]');
title('Plot of y_1[n] and z_1[n]');
% Create the second subplot
subplot(2,1,2);
```

```
plot(n2/fs2, z2, 'r-', n1/fs1, y2, 'b+', 'LineWidth', 1);
xlabel('n'); ylabel('y_2[n] and z_2[n]');
legend('z_2[n]', 'y_2[n]');
title('Plot of y_2[n] and z_2[n]');
```

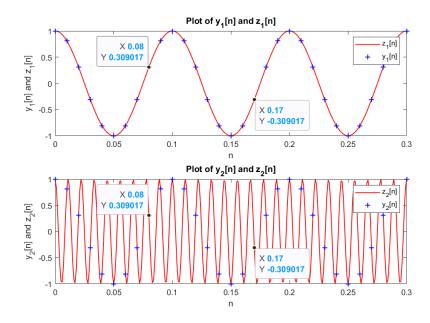


Figure 6: Plot of  $y_1[n]$  and  $z_1[n]$ , and  $y_1[n]$  and  $z_1[n]$ 

When observing the two plots, it was clear that when sampling at a lower frequency, such as  $f_{s_1} = 100Hz$ , the sampling points can be spaced out far enough to make it difficult to accurately represent the system. This illustrates the phenomenon of aliasing, where higher frequency components overlap/fold back into lower frequencies. As a result one cannot distinguish between the higher and lower frequency signals.

To find another continuous-time sinusoidal signal with different analog frequencies (in addition to  $20\pi$  and  $180\pi$ ) whose discrete-time signal  $y_3[n]$  will be the same as  $y_1[n]$  after sampling with a frequency of  $f_s = 100Hz$ , a period shift can be performed:

$$y_3[n] = \cos(\frac{20\pi n}{100} + 2\pi n * \frac{100}{100}) = \cos(\frac{220\pi n}{100}) \to x_3(t) = \cos(220\pi t)$$

To confirm that  $y_3[n]$  was identical to  $y_1[n]$  the following MATLAB script was ran:

```
figure(4)

% plot y3
y3 = cos(220 * pi * t1);
subplot(2,1,1);
stem(n1, y3, 'LineWidth', 1, 'Color', 'b');
title('Stem Plot of y_3[n] = cos(220\pi t)');
xlabel('n');
ylabel('y_3[n]');

% plot y1
subplot(2,1,2);
stem(n1, y1, 'LineWidth', 1, 'Color', 'r');
title('Stem Plot of y_1[n] = cos(20\pi t)');
xlabel('n');
ylabel('y_1[n]');
```

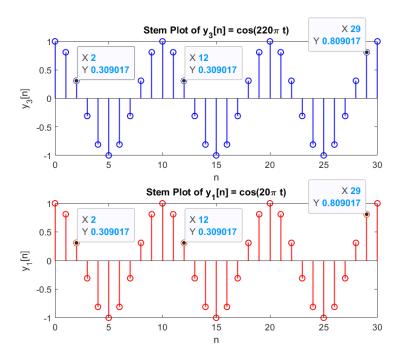


Figure 7: Plot of  $y_3[n]$  (top) and  $y_1[n](bottom)$ .

By observing both plots and comparing the values of several points, it was clear that both  $y_3[n]$  and  $y_1[n]$  are identical.

## 4 Effects of Aliasing on 2D Signals

Given the JPEG file barbaraLarge.jpg, the following MATLAB script reads and displays the image along-side its colorbar:

```
figure(1);
% read and display the jpg file
img = imread('barbaraLarge.jpg');
imshow(img), colorbar;
```

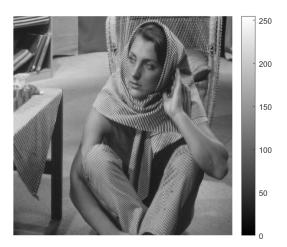


Figure 8: barbaraLarge.jpg displayed through the above script alongside its colorbar.

To compare different resizing factors with and without anti-aliasing the following MATLAB script is ran:

```
% compare different resizing factors w/ and w/o anti-aliasing
figure(2);
subplot(2, 3, 1);
rf = 0.9;
img_resized = imresize(img, rf, 'nearest', 'antialiasing', 0);
imshow(img_resized);
title('Barbara Image w/o Anti-Alieasing and RF = 0.9');
subplot(2, 3, 2);
rf = 0.7;
img_resized = imresize(img, rf, 'nearest', 'antialiasing', 0);
imshow(img_resized);
title('Barbara Image w/o Anti-Alieasing and RF = 0.7');
subplot(2, 3, 3);
rf = 0.5;
img_resized = imresize(img, rf, 'nearest', 'antialiasing', 0);
imshow(img_resized);
title('Barbara Image w/o Anti-Alieasing and RF = 0.5');
subplot(2, 3, 4);
rf = 0.9;
img_resized = imresize(img, rf, 'nearest', 'antialiasing', 1);
imshow(img_resized);
title('Barbara Image w/ Anti-Alieasing and RF = 0.9');
subplot(2, 3, 5);
rf = 0.7;
img_resized = imresize(img, rf, 'nearest', 'antialiasing', 1);
imshow(img_resized);
title('Barbara Image w/ Anti-Alieasing and RF = 0.7');
subplot(2, 3, 6);
rf = 0.5;
img_resized = imresize(img, rf, 'nearest', 'antialiasing', 1);
imshow(img_resized);
title('Barbara Image w/ Anti-Alieasing and RF = 0.5');
                              Barbara Image w/o Anti-Alieasing and RF = 0.7 Barbara Image w/o Anti-Alieasing and RF = 0.5
     Barbara Image w/o Anti-Alieasing and RF = 0.9
     Barbara Image w/ Anti-Alieasing and RF = 0.9
                               Barbara Image w/ Anti-Alieasing and RF = 0.7
                                                         Barbara Image w/ Anti-Alieasing and RF = 0.5
```

Figure 9: barbaraLarge.jpg displayed through the above script alongside its colorbar.

In the six images above, the effects of the resizing factor (rf) and anti-aliasing were clearly visible. In the top row, without anti-aliasing, as the rf gets further from 1 the clarity of the image decreases especially in high-frequency areas, which are marked by dark or black pixels. For example, at rf = 0.9, the image still maintains some of its original shape, but as the resize factor drops further to 0.7 or 0.5, the pixelation and jaggedness become more pronounced. When antialiasing is applied, the high-contrast differences between neighboring pixels are smoothed out, reducing the appearance of jagged lines. However, in low-frequency areas, like the carpet behind Barbara, there is almost no difference regardless of the resize factor or whether antialiasing is applied. The underlying cause of these jagged lines and harsh contrasts is aliasing, which occurs when the sampling frequency is lower than the Nyquist frequency, leading to high frequencies being misrepresented as lowerfrequencies. Antialiasing helps mitigate these effects, producing smoother transitions, but reducing sharpness in high-contrast regions.

In order to reduce the effects of aliasing, an image is often low-pass filtered before being resized or sampled. The low pass filter removes high frequency components that are causing the aliasing, however this is at the cost of details in the image. The script below was ran to show the effects of low-pass filtering on aliasing:







Figure 10: Results from the provided script above, displaying the effects of a low-pass filter on aliasing.