

Enumeration, Coding, and Complexity of Linear Reaction Mechanisms

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All topologically distinct linear mechanisms (i.e., mechanisms containing one reaction intermediate on both the left-hand and right-hand sides) of chemical reactions involving up to 16 elementary steps, up to 12 intermediates, and up to 6 reaction routes were computer enumerated and generated. The methodology previously developed for classifying, coding, and analyzing the complexity of such mechanisms was further developed. The complexity analysis of the topological structure of these mechanisms is extended here to all 390 mechanisms that incorporate 4 reaction routes and up to 6 reaction intermediates; these mechanisms are presented with their kinetic graphs, codes, and complexity indexes. Topological patterns that increase or preserve complexity were analyzed in detail and generalized in a complexity flow chart of potential use in the computerized elucidation of reaction mechanisms.

I. INTRODUCTION

The rapid increase in the mechanistic complexity of chemical reactions during the past few decades has led to numerous attempts to systematize or classify reaction mechanisms. Empirical schemes are of limited importance for such aims. It is not surprising then that the first studies along this avenue have been based on more rigorous mathematical formalisms. Sellers¹⁻⁴ used group theory to enumerate and generate the mechanisms that emerge for synthesis and substitution reactions. The stability approach of Clarke,^{5,6} the works of Snagovskii and Ostrovskii,⁷ Barone et al.,⁸⁻¹⁰ Zefirov and Trach,^{11,12} Brouk and Temkin,¹³ and others contributed to these developments. Sinanoğlu and Lee¹⁴⁻¹⁶ proposed network-based methodology for computer-assisted synthesis design. Very recently, Sinanoğlu¹⁷ made use of general networks and topology for the systematic generation of mechanisms and reaction pathways.

Another approach based on graph theory has been developed by Temkin, Bonchev, and others.¹⁸⁻²⁶ Unlike most of the above-mentioned studies, which proceed from the **chemical** information on reaction mechanism (types of reactions, number and type of reactants, etc.), this approach introduced the concept for **reaction mechanism topology**. The topological component of a reaction mechanism mirrors the interrelations within the space of reaction intermediates, including the number and kind of reaction-route interconnections. This formalism makes use of the cyclic graphs introduced in 1965 by Temkin;^{27,28} we have termed these graphs **kinetic graphs (KGs)**. The KG vertexes represent reaction intermediates only, while edges represent the intermediate interconversions (elementary reactions). Cycles in KGs correspond to reaction routes (independent stoichiometric equations). When all reaction steps are reversible, the KGs are simple graphs. Digraphs are useful when irreversible reaction steps take place.

Any number of reagents or products may be associated with any of the KGs. Then, by a systematic increase in the number of reactants, one can combine the topological and chemical information on reaction mechanisms and make their enumeration complete.

This methodology was intensively used for **linear reaction mechanisms**, which incorporate one intermediate left-hand side and right-hand side of each reaction step: $X_i \rightleftharpoons X_j$. Hierarchical classification and code^{18,20} has been developed for this large group of reaction mechanisms, as well as methods for evaluating their complexity.^{19,21} The analysis was recently extended to nonlinear mechanisms.^{23,25} In the present paper, we conclude our studies on linear mechanisms by discussing their computer enumeration, an improvement in their classification and coding, and further complexity analysis.

II. CLASSIFICATION, CODING, AND ENUMERATION OF LINEAR MECHANISMS

Proceeding from the one-to-one correspondence between linear mechanisms and KGs, we proposed a hierarchical classification of these reaction mechanisms in an earlier paper.²⁰ However, the enumeration of the linear mechanisms and their computer storage and retrieval indicated the need for some changes in both the classification and coding systems. The final hierarchical set of classification criteria is as follows:

- (i) number of reaction routes (KG cycles), $M = 1, 2, 3, \dots$
 - (ii) number of intermediates (KG vertexes), $N = 2, 3, 4, \dots$
 - (iii) types of interconnection of a pair of KG cycles (classes of two-route mechanisms)
 - class A = bridging of cycles
 - class B = cycles sharing a common vertex
 - class C = cycles sharing a common edge
 - class Z = disjoint cycles (linkage via other cycles)
- prefix n = number of KG vertexes with degree $a \geq 3$

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Table 1. Total Number of KGs for $M = 2-6$ and $N = 2-12^a$

M	$N = 2$	$N = 3$	$N = 4$	$N = 5$	$N = 6$	$N = 7$	$N = 8$	$N = 9$	$N = 10$	$N = 11$	$N = 12$
2	1	2	4	7	10	14	19	24	30	37	44
3	1	3	12	27	65	129	245	422	710	1 113	1 710
4	1	5	23	85	276	764	1 935	4 466	9 583	19 291	36 859
5	1	6	43	210	924	3 403	11 242	33 156	89 789	224 621	526 346
6	1	8	72	469	2652	12 644	52 727	194 909	651 008	CE	CE

^a CE = combinatorial explosion.

 Table 2. Total Number of Classes for $M = 2-6$ and $N = 2-12^a$

M	$N = 2$	$N = 3$	$N = 4$	$N = 5$	$N = 6$	$N = 7$	$N = 8$	$N = 9$	$N = 10$	$N = 11$	$N = 12$
2	1	1	1	0	0	0	0	0	0	0	0
3	1	2	6	3	2	1	0	0	0	0	0
4	1	4	14	24	33	19	11	4	1	0	0
5	1	5	30	85	192	249	250	153	77	26	7
6	1	7	55	239	798	1746	2800	3082	2576	CE	CE

^a N for a class includes vertices with $a_i \geq 2$, as well as all loops. CE = combinatorial explosion.

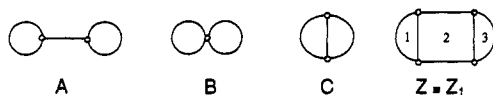


Figure 1. Four basic classes of linear mechanisms. Class Z refers to the nonadjacent pair of cycles 1 and 3. Substituting any loop for a cycle of arbitrary size preserves the class.

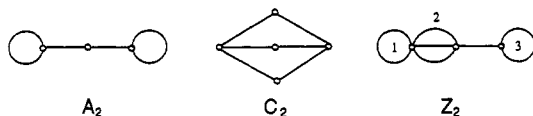


Figure 2. Examples of the A_i , C_k , and Z_v subclasses: there is a two-edge bridge in A_2 , two edges shared by the two cycles in C_2 , and two-edge distance between cycles 1 and 3 in Z_2 (the complete code for the last KG is ABZ_2).

- (iv) subclasses of mechanism (number of elements connecting a pair of KG cycles)
 - subclasses A_1, A_2, A_3, \dots (the length of a bridge, I)
 - subclasses C_1, C_2, C_3, \dots (the number of common edges, K)
 - subclasses Z_0, Z_1, Z_2, \dots (the number of edges V separating a pair of cycles lacking connections of type A, B , or C)
- (v) number of vertexes in each cycle, N_i

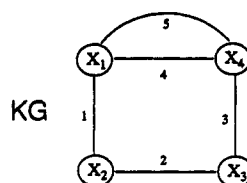
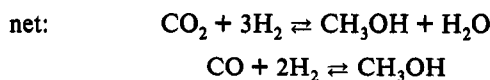
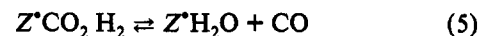
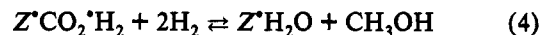
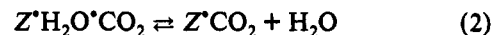
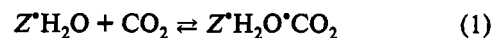
The linear code that results from the above classification criteria is

$$M - N - n - A_i^i B^j C^k Z_v^v - N_1, N_2, \dots, N_M$$

It describes simple (nondirected) graphs. For digraphs, which refer to mechanisms containing irreversible steps, the code is supplemented by the list of all edge types.²⁰ The class notation in the linear code is abbreviated; it stands for the **generalized** classes and contains superscripts that show the number of times this particular type of cycle linkage occurs. Instead, one can use **specific** class notation, which is not shortened, and list all pairwise cycle linkages (A, B, C , or Z) following their canonical numbering (see Table III, *vide infra*). Kinetic **supergraphs** (**KSGs**) are used to facilitate the canonical numbering of KG cycles, vertexes, and edges.²⁰ Each vertex in the KSG represents a cycle in the initial KG, while a KSG edge represents a KG cycle linkage of type A, B , or C . The lack of an edge between two KSG vertexes means no A, B , or C type of linkage for the respective pair of cycles in KG (class Z).

The modifications of our previously adopted classification and coding systems include the **type** of reaction mechanism, which was previously denoted in the code by the serial number introduced for each KSG. The computer elucidation of the linear mechanisms, however, would require that standard tables be stored with the serial numbers of all KSGs, whose number increases rapidly for more complex reactions. The retrieval of the mechanisms coded is facilitated by the use of the new class Z introduced in the foregoing, and the class prefix n , which is equal to the number of vertexes in the smallest homeomorphic image of all KGs of the class under consideration. The new code does not contain any symbol for the mechanism type. Yet, the defining of the latter makes sense from the viewpoint of classification. Types of KGs with increased complexity may be denoted by $L = 1, 2, 3, 4, \dots$, an integer indicating the total number of pairwise cycle linkages of type A, B , or C in the KG (see Table III, *vide infra*). The upper limit of the L value is the number of edges in the complete KSG.

An example illustrating the use of KGs and their coding is given as follows with the catalytic reaction of methanol synthesis. One of the mechanisms proposed²⁹ incorporates two reaction routes with a total of five reaction steps and four intermediates. Hence, it is represented by a KG containing two cycles, four vertexes, and five edges. The mechanism code includes the class prefix $n = 2$ (the two vertexes of degree 2 are omitted).



CODE: 2-4-2-C-2,4

N	Graph	N	Graph	N	Graph	N	Graph
1		15		32		48	
2		16		33		49	
3		17		34		50	
4		18		35		51	
5		19		36		52	
6		20		37		53	
7		21		38		54	
8		22		39		55	
9		23		40		56	
10		24		41		57	
11		25		42		58	
12		26		43		59	
13		27		44		60	
14		28		45		61	
		29		46		62	
		30		47			
		31		48			

N	Graph	N	Graph	N	Graph	N	Graph
63		77		91		105	
64		78		92		106	
65		79		93		107	
66		80		94		108	
67		81		95		109	
68		82		96		110	
69		83		97		111	
70		84		98		112	
71		85		99		113	
72		86		100		114	
73		87		101		115	
74		88		102		116	
75		89		103		117	
76		90		104			

N	Graph	N	Graph	N	Graph	N	Graph
118		132		145		161	
119		133		146		162	
120		134		147		163	
121		135		148		164	
122		136		149		165	
123		137		150		166	
124		138		151		167	
125		139		152		168	
126		140		153		169	
127		141		154		170	
128		142		155		171	
129		143		156		172	
130		144		157		173	
131				158		174	
				159		175	
				160			

N	Graph	N	Graph	N	Graph	N	Graph
176		190		203		217	
177		191		204		218	
178		192		205		219	
179		193		206		220	
180		194		207		221	
181		195		208		222	
182		196		209		223	
183		197		210		224	
184		198		211		225	
185		199		212		226	
186		200		213		227	
187		201		214		228	
188		202		215		229	
189				216			

N	Graph	N	Graph	N	Graph	N	Graph	N	Graph	N	Graph	N	Graph	N	Graph
230		244		259		273		286		300		313		326	
231		245		260		274		287		301		314		327	
232		246		261		275		288		302		315		328	
233		247		262		276		289		303		316		329	
234		248		263		277		290		304		317		330	
235		249		264		278		291		305		318		331	
236		250		265		279		292		306		319		332	
237		251		266		280		293		307		320		333	
238		252		267		281		294		308		321		334	
239		253		268		282		295		309		322		335	
240		254		269		283		296		310		323		336	
241		255		270		284		297		311		324		337	
242		256		271		285		298		312		325		338	
243		257		272				299						339	
		258													

N	Graph	N	Graph	N	Graph	N	Graph
340		354		367		381	
341		355		368		382	
342		356		369		383	
343		357		370		384	
344		358		371		385	
345		359		372		386	
346		360		373		387	
347		361		374		388	
348		362		375		341	
349		363		376			
350		364		377			
351		365		378			
352		366		379			
353				380			

Figure 3. Four-route mechanisms having two to six intermediates.

The linear mechanisms were enumerated by our original program KING (KINetic Graphs), which generates exhaustively all nonredundant KGs for a given number of cycles and vertexes. The KING program is written in C language, under MS-DOS. It runs on an IBM PC or compatible machine and

is very inexpensive since it requires relatively little RAM and hard drive space. The combinatorial algorithm used for KG enumeration is similar to that used in the GENESIS program,³⁰ and it employs an approach to graph enumeration developed by Faradzhev et al.³¹

Table 3. Classification, Codes, and Complexity Indexes of Linear Four-Route Mechanisms with Two to Six Intermediates

L = 3				L = 4				L = 4				
Generalized Class AB ²				Generalized Class AB ³				Class 4-B ² CZCZ				
Class 4-ABZ ² BZ				Class 3-AB ² Z ² B				98	4-6-4-B ² CZCZ-3,2,2,4		5364	
1	4-6-4-ABZ ² BZ-2,2,2,2	2304	42	4-6-3-AB ² Z ² B-2,2,2,2	2304	99	4-6-4-B ² CZCZ-3,2,3,3		5520			
Class 4-ABZ ³ B				Generalized Class AB ² C				100	4-6-4-B ² CZCZ-3,3,2,3		5892	
2	4-6-4-ABZ ² Z ₂ B-2,2,2,2	2304		Class 4-AB ² Z ² C				Class 4-B ² ZC ² Z				
Generalized Class ABC				4-5-4-AB ² Z ² C-2,2,2,2	1240	101	4-5-4-B ² ZC ² Z-2,4,2,2		2400			
Class 5-ABZ ² CZ				4-6-4-AB ² Z ² C-2,3,2,2	2628	102	4-6-4-B ² ZC ² Z-2,5,2,2		4560			
3	4-6-5-ABZ ² CZ-2,3,2,2	2880	45	4-6-4-AB ² Z ² C-3,2,2,2	2628	103	4-6-4-B ² ZC ² Z-2,5,2,2		4560			
Class 5-ABZ ³ C				4-6-4-AB ² Z ² C-2,2,2,3	2880	104	4-6-4-B ² ZC ² Z-3,4,2,2		5112			
4	4-6-5-ABZ ² Z ₂ C-2,2,3,2	2880	47	4-6-4-A ₂ B ² Z ² C-2,2,2,2	1776	105	4-6-4-B ² ZC ² Z-2,4,2,3		5364			
Generalized Class AC ²				Class 4-ABCZ ² B				106	4-6-4-B ² ZC ² Z-2,4,3,2		5364	
Class 6-ACZ ² CZ				4-6-4-ABCZ ² B-3,2,2,2	2880		Class 4-BC ² Z ² B					
5	4-6-6-ACZ ² CZ-2,3,3,2,2	3600	48	Generalized Class ABC ²				107	4-5-4-BC ² Z ² B-4,2,2,2		2400	
Generalized Class B ³				Class 5-ABCZ ² C				108	4-6-4-BC ² Z ² B-5,2,2,2		4560	
Class 3-B ³ Z ³				4-6-5-ABCZ ² C-2,2,2,3	3732	109	4-6-4-BC ² Z ² B-4,3,2,2		5112			
6	4-6-3-B ³ Z ³ -3,2,2,2	3408	48'	Class 5-AC ² Z ² B				110	4-6-4-BC ² Z ² B-4,2,2,3		5364	
Class 3-B ² Z ² BZ				4-6-5-AC ² Z ² B-4,2,2,2	3456		Generalized Class BC ³					
7	4-5-3-B ² Z ² BZ-2,2,2,2	1600	49	Generalized Class AC ³				Class 5-BC ³ Z ²				
8	4-6-3-B ² Z ² BZ-2,2,2,3	3408		Class 4-AC ² Z ² C				111	4-5-5-BC ³ Z ² -4,2,3,2		3090	
9	4-6-3-B ² Z ² BZ-2,3,2,2	3408	50	4-5-4-AC ² Z ² C-3,2,2,2	1470	112	4-6-5-BC ³ Z ² -5,2,3,2		5832			
Generalized Class B ² C				4-6-4-AC ² Z ² C-3,3,2,2	3108	113	4-6-5-BC ³ Z ² -5,2,3,2		5832			
Class 4-B ² CZ ³				4-6-4-AC ² Z ² C-3,2,2,3	3480	114	4-6-5-BC ³ Z ² -4,2,4,2		6360			
10	4-6-4-B ² CZ ³ -4,2,2,2	3984	53	4-6-4-A ₂ C ² Z ² C-3,2,2,2	2100	115	4-6-5-BC ³ Z ² -4,2,3,3		6900			
Class 4-BCZ ³ B				4-6-4-AC ² Z ² C-4,2,2,2	2952	116	4-6-5-BC ³ Z ² -4,3,3,2		7020			
11	4-6-4-BCZ ³ Z ₂ B-3,2,3,2	4512	54	Generalized Class B ⁴				117	4-6-5-BC ³ Z ² -5,2,4,2		6684	
Class 4-B ² Z ² CZ				Class 2-B ⁴ Z ²				Class 3-BC ² Z ² C				
12	4-5-4-B ² Z ² CZ-2,3,2,2	2000	55	4-5-2-B ⁴ Z ² -2,2,2,2	1600	118	4-4-3-BC ² Z ² C-3,2,2,2		952			
13	4-6-4-B ² Z ² CZ-2,4,2,2	3984	56	4-6-2-B ⁴ Z ² -2,2,2,3	3408	119	4-5-3-BC ² Z ² C-4,2,2,2		2060			
14	4-6-4-B ² Z ² CZ-2,3,3,2	4260	57	4-6-2-B ⁴ Z ² -2,2,3,2	3408	120	4-5-3-BC ² Z ² C-3,3,2,2		2170			
15	4-6-4-B ² Z ² CZ-3,3,2,2	4260	58	4-6-2-B ⁴ Z ² -3,2,2,2	3408	121	4-5-3-BC ² Z ² C-3,2,2,3		2420			
16	4-6-4-B ² Z ² CZ-2,3,2,3	4512		Generalized Class B ³ C				122	4-6-3-BC ² Z ² C-5,2,2,2		3804	
Generalized Class BC ²				Class 3-B ³ CZ ²				123	4-6-3-BC ² Z ² C-5,2,2,2		3804	
Class 5-BC ² Z ³				4-4-3-B ³ CZ ² -2,2,2,2	800	124	4-6-3-BC ² Z ² C-3,4,2,2		4116			
17	4-6-5-BC ² Z ³ -5,2,2,2	4560	60	4-5-3-B ³ CZ ² -2,2,2,3	1830	125	4-6-3-BC ² Z ² C-4,3,2,2		4368			
Class 5-BCZ ³ C				4-5-3-B ³ CZ ² -3,2,2,2	1830	126	4-6-3-BC ² Z ² C-3,2,2,4		4860			
18	4-6-5-BCZ ³ Z ₂ C-3,2,4,2	5364	61	4-5-3-B ³ CZ ² -2,2,3,2	2000	127	4-6-3-BC ² Z ² C-4,2,2,3		4860			
Class 5-BCZ ³ CZ				4-6-3-B ³ CZ ² -2,2,2,4	3480	128	4-6-3-BC ² Z ² C-3,3,2,3		5148			
19	4-5-5-BCZ ³ CZ-3,3,2,2	2500	64	4-6-3-B ³ CZ ² -4,2,2,2	3480	129	4-6-3-BC ² Z ² C-3,2,3,3		5712			
20	4-6-5-BCZ ³ CZ-3,4,2,2	4980	65	4-6-3-B ³ CZ ² -4,2,2,2	3480		Class 5-BC ² Z ² C					
21	4-6-5-BCZ ³ CZ-3,3,2,3	5640	66	4-6-3-B ³ CZ ² -3,2,2,3	3888	130	4-6-5-BC ² Z ² C-4,2,3,3		6768			
Generalized Class C ³				4-6-3-B ³ CZ ² -2,2,4,2	3984		Class 5-BCZCZC					
Class 6-C ³ Z ³				4-6-3-B ³ CZ ² -2,2,3,3	4260	131	4-5-5-BCZCZC-2,2,5,2		2800			
22	4-6-6-C ³ Z ³ -6,2,2,2	5136	69	4-6-3-B ³ CZ ² -3,2,3,2	4260	132	4-6-5-BCZCZC-2,2,6,2		5136			
Class 6-C ² Z ² CZ				4-6-3-B ³ CZ ² -2,3,3,2	4512	133	4-6-5-BCZCZC-2,2,5,3		6216			
23	4-6-6-C ² Z ² CZ-2,4,4,2	6360	70	Class 3-B ² CBZ ²				134	4-6-5-BCZCZC-2,3,5,2		6216	
L = 4				4-5-3-B ² CBZ ² -3,2,2,2	2000		Generalized Class C ⁴					
24	4-6-4-A ³ CZ ² -2,2,2,2	1776	72	4-6-3-B ² CBZ ² -4,2,2,2	3984		Class 4-C ⁴ Z ²					
Class 5-A ³ CZ ²				4-6-3-B ² CBZ ² -3,2,3,2	4260	135	4-6-4-C ⁴ Z ² -4,3,3,2		6852			
25	4-6-5-Z ³ CZ ² -2,2,2,2	1776	74	4-6-3-B ² CBZ ² -3,2,2,3	4512	136	4-4-4-C ⁴ Z ² -4,2,2,2		1152			
Generalized Class A ² B ²				Class 3-B ² CZBZ				137	4-5-4-C ⁴ Z ² -5,2,2,2		2370	
Class 3-A ² B ² Z ²				4-5-3-B ² CZBZ-3,2,2,2	2000	138	4-5-4-C ⁴ Z ² -4,2,2,3		2760			
26	4-6-3-A ² B ² Z ² -2,2,2,2	2304	76	4-6-3-B ² CZBZ-4,2,2,2	3984	139	4-5-4-C ⁴ Z ² -4,2,3,2		2920			
Class 3-A ² ZB ² Z				4-6-3-B ² CZBZ-4,2,2,2	3984	140	4-6-4-C ⁴ Z ² -6,2,2,2		4248			
27	4-6-3-A ² ZB ² Z-2,2,2,2	2304	78	4-6-3-B ² CZBZ-3,2,2,2	4260	141	4-6-4-C ⁴ Z ² -6,2,2,2		4248			
Generalized Class A ² BC				4-6-3-B ² CZBZ-3,3,2,2	4260	142	4-6-4-C ⁴ Z ² -5,2,2,3		5220			
Class 4-A ² BCZ ²				4-6-3-B ² CZBZ-3,2,2,3	4512	143	4-6-4-C ⁴ Z ² -4,2,2,4		5376			
28	4-5-4-A ² BCZ ² -2,2,2,2	1240	81	Generalized Class B ² C ²				144	4-6-4-C ⁴ Z ² -5,2,3,2		5580	
29	4-6-4-A ² BCZ ² -2,2,2,2	2628	82	Class 4-B ² C ² Z ²				145	4-6-4-C ⁴ Z ² -4,2,4,2		5856	
30	4-6-4-A ² BCZ ² -3,2,2,2	2628	83	4-4-4-B ² C ² Z ² -3,2,2,2	1000	146	4-6-4-C ⁴ Z ² -4,2,3,3		6528			
31	4-6-4-A ² BCZ ² -2,2,3,2	2880	84	4-5-4-B ² C ² Z ² -4,2,2,2	2140	147	4-6-4-C ⁴ Z ² -5,2,2,4		5820			
32	4-6-4-A ² BCZ ² -2,2,2,2	1776	85	4-5-4-B ² C ² Z ² -3,2,2,3	2420		Class 6-C ⁴ Z ²					
Class 4-A ² ZBCZ				4-5-4-B ² C ² Z ² -3,2,3,2	2500	148	4-6-6-C ⁴ Z ² -5,3,3,2		7896			
33	4-6-4-A ² ZBCZ-2,3,2,2	2880	86	4-6-4-B ² C ² Z ² -5,2,2,2	3924		L = 5					
Class 4-A ² CBZ ²				4-6-4-B ² C ² Z ² -5,2,2,2	3924		Generalized Class A ⁴ C					
34	4-6-4-A ² CBZ ² -3,2,2,2	2880	87	4-6-4-B ² C ² Z ² -3,2,2,4	4740		Class 4-A ² CZ ⁴					
Class 4-A ² ZCBZ				4-6-4-B ² C ² Z ² -4,2,2,3	4740	149	4-6-4-A ² CZ ⁴ -2,2,2,2		1776			
35	4-6-4-A ² ZCBZ-2,3,2,2	2880	89	4-6-4-B ² C ² Z ² -4,2,3,2	4980	150	4-6-4-A ² CZ ⁴ -2,2,2,2		1776			
Generalized Class A ² C ²				4-6-4-B ² C ² Z ² -3,2,4,2	4980		Generalized Class A ² B ² C					
Class 5-A ² C ² Z ²				4-6-4-B ² C ² Z ² -3,2,3,3	5640		Class 3-A ² ZCB ²					
36	4-5-5-A ² C ² Z ² -3,2,2,2	1550	92	4-6-4-B ² C ² Z ² -3,3,3,2	5640	151	4-5-3-A ² ZCB ² -2,2,2,2		1240			
37	4-6-5-A ² C ² Z ² -4,2,2,2	3072	93	4-6-4-B ² C ² Z ² -4,2,2,4	5184	152	4-6-3-A ² ZCB ² -3,2,2,2		2628			
38	4-6-5-A ² C ² Z ² -3,2,2,3	3480		Class 4-B ² CZCZ				153	4-6-3-A ² ZCB ² -2,2,2,3		2628	
39	4-6-5-A ² C ² Z ² -3,2,3,2	3600	94	4-5-4-B ² CZCZ-3,2,2,3	2590	154	4-6-3-A ² ZCB ² -2,2,3,2		2880			
40	4-6-5-A ² C ² Z ² -3,2,2,2	2220	95	4-6-4-B ² CZCZ-4,2,2,3	5112	155	4-6-3-A ² ZCB ² -2,2,2,2		1776			
Class 5-A ² ZC ² Z				4-6-4-B ² CZCZ-4,2,2,3	5112							
41	4-6-5-A ² ZC ² Z-2,4,2,2	3456	97	4-6-4-B ² CZCZ-4,2,2,4	5592							

Table 3. (Continued)

L = 5				L = 5				L = 6			
Generalized Class A ² BC ²				Generalized Class BC ⁴				Generalized Class B ⁴ C ²			
Class 4-A ² ZCBC				Class 5-BC ³ ZC				Class 3-B ⁴ C ²			
156	4-5-4-A ² ZCBC-2,2,3,2	1640	219	4-5-5-BC ³ ZC-3,2,4,3	3980	271		4-4-3-B ⁴ C ² -2,2,2,3	1056		
157	4-6-4-A ² ZCBC-2,2,4,2	3456	220	4-6-5-BC ³ ZC-3,2,5,3	7896	272		4-5-3-B ⁴ C ² -2,2,2,4	2400		
158	4-6-4-A ² ZCBC-3,2,3,2	3480	221	4-6-5-BC ³ ZC-3,2,4,4	8304	273		4-5-3-B ⁴ C ² -3,2,2,3	2420		
159	4-6-4-A ² ZCBC-2,2,3,3	3732	222	4-6-5-BC ³ ZC-4,2,4,3	8304	274		4-5-3-B ⁴ C ² -2,2,3,3	2590		
160	4-6-4-A ² ZCBC-2,3,3,2	3732	223	4-6-5-BC ³ ZC-3,3,4,3	8976	275		4-6-3-B ⁴ C ² -2,2,2,5	4560		
161	4-6-4-A ² ZCBC-2,2,3,2	2352	224	4-6-5-BCC ₂ CZC-4,2,4,4	9024	276		4-6-3-B ⁴ C ² -4,2,2,3	4608		
Generalized Class A ² C ³				Generalization Class C ⁵				4-6-3-B ⁴ C ² -2,2,4,3			
Class 5-A ² ZC ³				Class 6-C ⁵ Z				4-6-3-B ⁴ C ² -3,2,2,4			
162	4-6-5-A ² ZC ³ -2,3,3,3	4608	225	4-6-6-C ⁵ Z-4,4,3,3	10560	277		4-6-3-B ⁴ C ² -2,2,3,4	5112		
Generalized Class B ⁴ C				L = 6				4-6-3-B ⁴ C ² -2,2,3,4			
Class 2-B ² CZB ²				Generalized Class A ⁴ B ²				4-6-3-B ⁴ C ² -3,2,3,3			
163	4-4-2-B ² CZB ² -2,2,2,2	800		4-6-2-A ² B ² A ² -2,2,2,2	2304	282		4-6-3-B ⁴ C ² -2,2,4,4	5520		
164	4-5-2-B ² CZB ² -2,2,3,2	1830	226	Generalized Class A ⁴ BC				4-6-3-B ⁴ C ² -2,3,3,3	5892		
165	4-5-2-B ² CZB ² -2,2,2,3	2000		Class 3-A ² BCA ²				4-6-3-B ⁴ CC ₂ -2,2,4,4	5592		
166	4-6-2-B ² CZB ² -2,2,4,2	3480		4-5-3-A ² BCA ² -2,2,2,2	1240	283		Class 3-B ² C ² B ²			
167	4-6-2-B ² CZB ² -2,3,3,2	3888	227	4-6-3-A ² BCA ² -2,2,2,3	2628	284		4-3-3-B ² C ² B ² -2,2,2,2	360		
168	4-6-2-B ² CZB ² -2,2,2,4	3984	228	4-6-3-A ² BCA ² -2,2,3,2	2880	285		4-4-3-B ² C ² B ² -2,2,2,3	1000		
169	4-6-2-B ² CZB ² -2,2,3,3	4260	229	4-6-3-A ² BCA ² -2,2,2,2	1776	286		4-5-3-B ² C ² B ² -2,2,2,4	2140		
170	4-6-2-B ² CZB ² -3,2,2,3	4512	230	Generalized Class A ⁴ C ²				4-5-3-B ² C ² B ² -2,3,3,2	2420		
Generalized Class B ³ C ²				Class 4-A ² C ² A ²				4-5-3-B ² C ² B ² -2,2,3,3	2500		
Class 3-B ² CZBC				4-4-4-A ² C ² A ² -2,2,2,2	624	287		4-6-3-B ² C ² B ² -2,2,2,5	3924		
171	4-4-3-B ² CZBC-2,2,2,3	1056	231	4-5-4-A ² C ² A ² -2,2,2,3	1550	288		4-6-3-B ² C ² B ² -2,3,4,2	4740		
172	4-5-3-B ² CZBC-2,2,2,4	2400	232	4-6-4-A ² C ² A ² -2,2,2,4	3072	289		4-6-3-B ² C ² B ² -2,2,3,4	4980		
173	4-5-3-B ² CZBC-2,3,2,3	2420	233	4-6-4-A ² C ² A ² -2,3,3,2	3480	290		4-6-3-B ² C ² B ² -2,3,3,3	5640		
174	4-5-3-B ² CZBC-2,2,3,3	2590	234	4-6-4-A ² C ² A ² -2,2,3,3	3600	291		4-6-3-B ² CC ₂ B ² -2,4,4,2	5184		
175	4-5-3-B ² CZBC-3,2,2,3	2590	235	4-5-4-A ² C ² A ² -2,2,2,2	960	292		Generalized Class B ³ C ³			
176	4-6-3-B ² CZBC-2,2,2,5	4560	236	4-6-4-A ² C ² A ² -2,2,2,3	2220	293		Class 2-B ³ C ³			
177	4-6-3-B ² CZBC-2,4,2,3	4608	237	4-6-4-A ² C ² A ² -2,2,2,3	2220	294		4-3-2-B ³ C ³ -2,2,2,2	336		
178	4-6-3-B ² CZBC-2,2,4,3	5112	238	4-6-4-A ² C ² A ² -3,2,2,2	1368	295		4-4-2-B ³ C ³ -3,2,2,2	848		
179	4-6-3-B ² CZBC-2,3,2,4	5112		Generalized Class A ³ B ³				4-4-2-B ³ C ³ -2,2,2,3	952		
180	4-6-3-B ² CZBC-4,2,2,3	5112		4-6-2-A ³ B ³ -2,2,2,2	2304	296		4-5-2-B ³ C ³ -4,2,2,2	1720		
181	4-6-3-B ² CZBC-2,2,3,4	5364	239	Generalized Class A ³ B ² C				4-5-2-B ³ C ³ -2,2,2,4	2060		
182	4-6-3-B ² CZBC-3,2,2,4	5364		Class 3-A ³ B ² C				4-5-2-B ³ C ³ -2,2,2,3	2170		
183	4-6-3-B ² CZBC-2,3,3,3	5520		4-5-3-A ³ B ² C-2,2,2,2	1240	297		4-5-2-B ³ C ³ -2,2,3,3	2420		
184	4-6-3-B ² CZBC-3,3,2,3	5520	240	4-6-3-A ³ B ² C-2,3,2,2	2628	298		4-6-2-B ³ C ³ -5,2,2,2	3048		
185	4-6-3-B ² CZBC-3,2,3,3	5892	241	4-6-3-A ³ B ² C-3,2,2,2	2628	300		4-6-2-B ³ C ³ -2,2,2,5	3804		
186	4-6-3-B ² CZBC ₂ -2,2,4,4	5592	242	4-6-3-A ³ B ² C-2,2,2,3	2880	301		4-6-2-B ³ C ³ -4,2,2,3	4116		
187	4-6-3-B ² C ₂ ZBC-4,2,2,4	5592	243	4-6-3-A ³ B ² C-2,2,2,2	1776	302		4-6-2-B ³ C ³ -3,2,2,4	4368		
Generalized Class B ² C ³				4-6-3-A ³ B ² C-2,2,2,2	1776	303		4-6-2-B ³ C ³ -2,2,3,4	4860		
Class 4-B ² CZC ²				Generalized Class A ³ BC ²				4-6-2-B ³ C ³ -3,2,3,3	5148		
188	4-4-4-B ² CZC ² -2,2,2,4	1312		Class 4-A ³ BC ²				4-6-2-B ³ C ³ -2,3,3,3	5712		
189	4-5-4-B ² CZC ² -2,2,3,4	3180	245	4-5-4-A ³ BC ² -2,2,2,3	1640	304		Class 3-B ² CBC ²			
190	4-5-4-B ² CZC ² -3,2,2,4	3180	246	4-6-4-A ³ BC ² -2,2,2,4	3456	305		4-3-3-B ² CBC ² -2,2,2,3	480		
191	4-5-4-B ² CZC ² -2,2,2,5	2800	247	4-6-4-A ³ BC ² -3,2,2,3	3480	306		4-4-3-B ² CBC ² -2,2,3,3	1328		
192	4-6-4-B ² CZC ² -2,2,2,6	5136	248	4-6-4-A ³ BC ² -2,2,3,3	3732	307		4-5-3-B ² CBC ² -2,2,4,3	2840		
193	4-6-4-B ² CZC ² -3,2,2,5	6216	249	4-6-4-A ³ BC ² -2,2,2,3	2352	308		4-5-3-B ² CBC ² -2,3,3,3	3290		
194	4-6-4-B ² CZC ² -2,2,3,5	6216		Generalized Class A ³ C ³				4-6-3-B ² CBC ² -2,2,5,3	5208		
195	4-6-4-B ² CZC ² -2,2,4,4	6240		Class 3-A ³ C ³				4-6-3-B ² CBC ² -2,3,4,3	6528		
196	4-6-4-B ² CZC ² -4,2,2,4	6240	250	4-4-3-A ³ C ³ -2,2,2,2	576	309		4-6-3-B ² CBC ² -3,3,3,3	7560		
197	4-6-4-B ² CZCC ₂ -2,2,4,5	6816	251	4-5-3-A ³ C ³ -3,2,2,2	1300	310		4-5-3-B ² CBCC ₂ -2,2,4,4	3240		
198	4-6-4-B ² C ₂ ZC ² -4,2,2,5	6816	252	4-5-3-A ³ C ³ -2,2,2,3	1470	311		4-6-3-B ² CBCC ₂ -2,3,4,4	7380		
199	4-6-4-B ² CZC ² -2,3,3,4	7152	253	4-6-3-A ³ C ³ -4,2,2,2	2448	312		Class 4-B ² C ² BC			
200	4-6-4-B ² CZC ² -3,2,3,4	7152	254	4-6-3-A ³ C ³ -2,2,2,4	2952	313		4-4-4-B ² C ² BC-2,2,3,3	1376		
Class 4-B ² ZC ³				4-6-3-A ³ C ³ -3,2,2,3	3108	314		4-5-4-B ² C ² BC-2,2,3,4	3090		
201	4-5-4-B ² ZC ³ -2,3,3,3	3200	255	4-6-3-A ³ C ³ -2,2,3,3	3480	315		4-5-4-B ² C ² BC-2,3,3,3	3370		
202	4-6-4-B ² ZC ³ -2,3,3,4	6768	256	4-5-3-A ³ C ³ -2,2,2,2	880	316		4-6-4-B ² C ² BC-2,2,3,5	5832		
203	4-6-4-B ² ZC ³ -2,3,4,3	6768	257	4-6-3-A ³ C ³ -2,2,2,2	1848	317		4-6-4-B ² C ² BC-2,2,4,4	6360		
204	4-6-4-B ² ZC ³ -3,3,3,3	6816	258	4-6-3-A ³ C ³ -3,2,2,3	2100	318		4-6-4-B ² C ² BC-2,4,3,3	6648		
Class 4-BC ³ ZB				4-6-3-A ³ C ³ -2,2,2,2	1248	319		4-6-4-B ² C ² BC-2,3,4,3	6900		
205	4-4-4-BC ³ ZB-3,2,3,2	1376		Generalized Class B ⁶				4-6-4-B ² C ² BC-2,3,3,4	7020		
206	4-5-4-BC ³ ZB-3,2,4,2	3090		Class 1-B ⁶				4-6-4-B ² C ² BC-3,3,3,3	7680		
207	4-5-4-BC ³ ZB-3,2,3,3	3370	261	4-5-1-B ⁶ -2,2,2,2	1600	320		4-5-4-B ² C ² BC ₂ -2,2,4,4	3320		
208	4-6-4-BC ³ ZB-3,2,5,2	5832	262	4-6-1-B ⁶ -2,2,2,3	3408	321		4-6-4-B ² C ² BC ₂ -2,2,5,5	6480		
209	4-6-4-BC ³ ZB-4,2,4,2	6360		Generalized Class B ⁵ C				4-6-4-B ² C ² BC ₂ -2,2,4,5	6684		
210	4-6-4-BC ³ ZB-3,2,3,4	6648		Class 2-B ⁵ C				4-6-4-B ² C ² BC ₂ -2,3,4,4	7500		
211	4-6-4-BC ³ ZB-3,3,4,2	6900	263	4-4-2-B ⁵ C-2,2,2,2	800	322		4-6-4-B ² CC ₂ BC-2,4,4,3	7368		
212	4-6-4-BC ³ ZB-3,2,4,3	7020	264	4-5-2-B ⁵ C-2,3,2,2	1830	323		Generalized Class B ⁴ C ⁴			
213	4-6-4-BC ³ ZB-3,3,3,3	7680	265	4-5-2-B ⁵ C-2,2,2,3	2000	324		Class 3-B ² C ⁴			
214	4-6-4-BC ₂ C ₂ ZB-3,4,4,2	7368	266	4-6-2-B ⁵ C-2,4,2,2	3480	325		4-3-3-B ² C ⁴ -2,2,2,3	450		
215	4-5-4-BC ₂ C ₂ ZB-4,2,4,2	3320	267	4-6-2-B ⁵ C-3,3,2,2	3888	326		4-4-3-B ² C ⁴ -2,2,2,4	1152		
216	4-6-4-BC ₂ C ₂ ZB-4,2,5,2	6684	268	4-6-2-B ⁵ C-2,2,2,4	3984	327		4-4-3-B ² C ⁴ -3,2,2,3	1224		
217	4-6-4-BC ₂ C ₂ ZB-4,2,4,3	7300	269	4-6-2-B ⁵ C-2,3,2,3	4260	328		4-4-3-B ² C ⁴ -2,2,3,3	1272		
218	4-6-4-BC ₃ C ₂ ZB-5,2,5,2	6480	270	4-6-2-B ⁵ C-2,2,3,3	4512	329		4-5-3-B ² C ⁴ -2,2,2,5	2370		
						330		4-5-3-B ² C ⁴ -4,2,2,3	2590		
								4-5-3-B ² C ⁴ -2,2,4,3	2750		

Table 3. (Continued)

L = 6 Generalized Class B ² C ⁴ Class 3-B ² C ⁴			L = 6 Generalized Class B ² C ⁴ Class 3-BC ⁴ B			L = 6 Generalized Class B ² C ⁴ Class 5-B ² C ⁴		
338	4-5-3-B ² C ⁴ -3,2,2,4	2760	356	4-6-3-B ² C ₂ C ³ -4,2,2,5	5820	373	4-5-5-BC ⁴ B-3,3,3,3	4440
339	4-5-3-B ² C ⁴ -2,2,3,4	2920	357	4-6-3-B ² C ₂ C ³ -4,2,3,4	6876	374	4-6-5-BC ⁴ B-3,3,3,4	9228
340	4-5-3-B ² C ⁴ -3,2,3,3	3120	358	4-6-3-B ² CC ³ -2,2,4,4,4	7632	375	4-6-5-BC ³ C ₂ B-3,4,3,4	9744
341	4-5-3-B ² C ⁴ -2,3,3,3	3250		Class 4-B ² C ⁴			Generalized Class C ⁶	
341'	4-5-3-B ² C ₂ C ³ -4,2,2,4	2900	359	4-4-4-B ² C ⁴ -2,3,3,3	1616		Class 2-C ⁶	
342	4-6-3-B ² C ⁴ -2,2,2,6	4248	360	4-5-4-B ² C ⁴ -2,3,4,3	3730	376	4-2-2-C ⁶ -2,2,2,2	120
343	4-6-3-B ² C ⁴ -5,2,2,3	4716	361	4-5-4-B ² C ⁴ -3,3,3,3	4020	377	4-3-2-C ⁶ -2,2,2,3	396
344	4-6-3-B ² C ⁴ -2,2,5,3	5076	362	4-6-4-B ² C ⁴ -2,3,5,3	7152	378	4-4-2-C ⁶ -2,2,2,4	944
345	4-6-3-B ² C ⁴ -3,2,2,5	5220	363	4-6-4-B ² C ⁴ -2,4,4,3	7812	379	4-4-2-C ⁶ -2,2,3,3	1120
346	4-6-3-B ² C ⁴ -4,2,2,4	5376	364	4-6-4-B ² C ⁴ -4,3,3,3	7992	380	4-5-2-C ⁶ -2,2,2,5	1860
347	4-6-3-B ² C ⁴ -2,2,3,5	5580	365	4-6-4-B ² C ⁴ -3,3,4,3	8604	381	4-5-2-C ⁶ -2,2,3,4	2420
348	4-6-3-B ² C ₂ C ³ -5,2,2,4	5568	366	4-6-4-B ² C ³ C ₂ -2,4,4,4	8700	382	4-6-2-C ⁶ -2,2,2,6	3240
349	4-6-3-B ² C ⁴ -2,2,4,4	5856	367	4-5-4-B ² CC ₂ C ² -2,4,4,3	3700	383	4-6-2-C ⁶ -2,2,3,5	4464
350	4-6-3-B ² C ⁴ -4,2,3,3	6156	368	4-6-4-B ² C ³ C ₂ -2,3,5,4	8028	384	4-6-2-C ⁶ -2,2,4,4	4872
351	4-6-3-B ² C ⁴ -3,2,4,3	6276	369	4-6-4-B ² CC ₂ C ² -2,4,5,3	7776	385	4-5-2-C ⁶ -2,3,3,3	2960
352	4-6-3-B ² C ⁴ -3,2,3,4	6528	370	4-6-4-B ² CC ₂ C ² -3,4,4,3	8208	386	4-6-2-C ⁶ -2,3,3,4	5928
353	4-6-3-B ² C ⁴ -2,3,3,4	6852	371	4-6-4-B ² CC ₂ C ² -2,5,5,3	8220	387	4-6-2-C ⁶ -3,3,3,3	7056
354	4-6-3-B ² C ⁴ -2,3,4,3	6840	372	4-6-4-B ² C ₂ C ³ -4,3,3,4	9120		Class 6-C ⁶	
355	4-6-3-B ² C ⁴ -3,3,3,3	7404				388	4-6-6-CC ₂ C ⁴ -4,4,4,4	11616

All mechanisms having up to six reaction routes and up to 12 vertexes were enumerated, except in the case of $M = 6$ for $N = 11$, and $N = 12$, for which the computational time was unreasonably high (Table 1). The number of classes was also enumerated (Table 2). We found that, at a constant number of reaction routes and an increasing number of intermediates, the number of classes passes through a maximum and behaves close to the normal distribution. Both tables give evidence for the potential existence of a tremendously large variety of topologically distinct linear mechanisms. This result is in sharp contrast to some estimates based on mechanistic chemical but not topological information.^{3,4} Besides the incompleteness of the purely chemical approach, such comparisons may also indicate that some mechanisms that are topologically allowed might be chemically forbidden. The elucidation of this important question needs further studies.

III. COMPLEXITY OF LINEAR MECHANISMS

1. Complexity Index K . A quantitative measure for the complexity of reaction mechanisms may play an important role in their computer handling. It allows one to introduce a complexity based mechanistic hierarchy and, therefore, can help in both the generation and the discrimination of the totality of hypotheses for the mechanisms of complex reactions. In previous publications^{19,21} we developed such a complexity measure based on the complexity of the steady-state kinetic model, which can readily be obtained for linear mechanisms by making use of graph theory. Calculated by means of the spanning trees of the KG and some of its subgraphs, this complexity index reflects the complexity of kinetic graphs as well and may be of use for complexity analysis of any cyclic graphs.

Our complexity index K is based on the fractional-rational form of the rate laws for reaction routes within the framework of the Vol'kenshtein-Gol'dshtein algorithm.^{32,33} More specifically, K is defined as the total number of weights (rate constants) of the elementary steps (KG edges) included in the kinetic laws for all M routes of a multiroute reaction. For mechanisms containing reversible steps only, it is calculated by eq 6, where T_i is the number of spanning trees in vertex

$$K = MN(N-1)T_i + 2N \sum_{p=1}^M \sum_{k=0}^{k=\max} D_{pk} \quad (6)$$

i (this number is the same for every vertex in the KG); the double sum counts the number of spanning trees of the KG subgraphs obtained after subsequently contracting each of the graph cycles p and its encompassing cycles pk to a vertex.

In a previous publication²¹ we discussed the complexity of mechanisms with two and three reaction routes. Here, we extend this analysis to mechanisms incorporating four independent routes. Instead of using general methods for enumerating spanning trees,³⁴ we made use of an explicit formula derived earlier:¹⁹

$$T_4 = N_1N_2N_3N_4 - (E_{12}^2N_3N_4 + E_{13}^2N_2N_4 + E_{14}^2N_2N_3 + E_{23}^2N_1N_4 + E_{24}^2N_1N_3 + E_{34}^2N_1N_2) - (2E_{12}E_{13}E_{23}N_4 + 2E_{12}E_{14}E_{24}N_3 + 2E_{13}E_{14}E_{34}N_2 + 2E_{23}E_{24}E_{34}N_1) - (2E_{13}E_{14}E_{23}E_{24} + 2E_{12}E_{13}E_{24}E_{34} + 2E_{12}E_{14}E_{23}E_{34}) + (E_{12}^2E_{34}^2 + E_{13}^2E_{24}^2 + E_{14}^2E_{23}^2) \quad (7)$$

Equations 6 and 7 provide fast calculation of the spanning trees and the complexity index directly from the mechanism linear code, where one can find both the cycle size N_p and the number of edges two cycles have in common E_{ij} . The latter is obviously zero for classes A and B , while for class C it is equal to the subclass subscript (1 for $C = C_1$, 2 for C_2 , etc.).

2. Standard Tables with the Complexities of All Topologically Distinct Four-Route Mechanisms Having Two to Six Intermediates. Before proceeding with a complexity analysis, we present here in Figure 3 and Table 3 all 390 four-route mechanisms having two to six intermediates, as generated by the KING program together with their codes and complexity indexes. These are mechanisms containing reversible elementary steps only. However, each of the mechanisms presented can be used to generate a certain number of mechanisms with irreversible steps, as well as an additional number of mechanisms incorporating intermediates that are involved only in an equilibrium elementary step (KGs with pendant vertexes).

3. Trends Increasing Mechanism Complexity. The complexity analysis we performed confirmed the trends toward a higher complexity of linear mechanisms found previously for two-route and three-route mechanisms.²¹ Clearly, the complexity index K of the four-route mechanisms is considerably higher than that of the three-route mechanisms with the same number of intermediates. Similarly, at $M = 4 = \text{constant}$, the

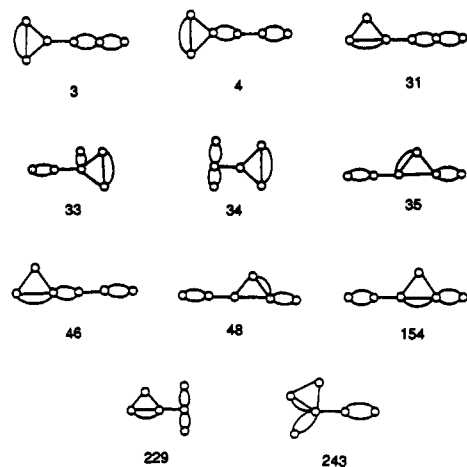


Figure 4. 11 isocomplex KGs with complexity index $K = 2880$. The KG numbers correspond to those in Figure 3 and Table 3.

Table 4. Degeneracy of the Complexity Index of Linear Reaction Mechanisms Having One to Four Reaction Routes

no. of routes	total no. of mechanisms	total no. of the different index values	degree of degeneracy
1	5	5	1
2	24	23	1.04
3	104	65	1.60
4	390	171	2.28

increase in the number of intermediates greatly increases the mechanism complexity. The subtle topological patterns enhancing complexity are reflected by the following series of classes and subclasses ordered with respect to the increase in K :

$$A_3 < A_2 < A < B < C < C_2 < C_3 < \dots \quad (8)$$

At a constant number of reaction routes and intermediates, as well as within the same class and subclass, K increases with equalizing cycle sizes, thus manifesting an entropylike behavior. As an illustration, compare KGs 123, 126, and 129 from Figure 3 which have six intermediates and belong to the same class $3\text{-}BC^2Z^2C$ but differ in cycle sizes, which are respectively 5,2,2,2; 3,2,2,4; and 3,2,3,3. The cycle-size equalizing results in an increase in the complexity index from 3804 to 4860 to 5712, respectively.

Another trend of increasing mechanistic complexity is easily proved. It refers to the increase in the newly introduced class prefix n in the mechanism code. Since n , by definition, is equal to the number of vertexes in the smallest homeomorphic image of the KGs from a certain class of mechanisms, then the larger this number, the more complex the mechanism. This trend can be illustrated by comparing in Table 3 the three specific classes belonging to the same generalized class B^3C^3 : $2\text{-}B^3C^3 \rightarrow 3\text{-}B^2CBC^2 \rightarrow 4\text{-}B^2C^2BC$ (graphs 293 to 306, 307 to 316, and 317 to 330, respectively).

IV. ISOCOMPLEXITY

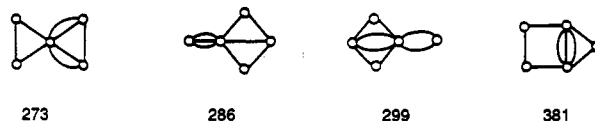
1. Complexity Index Degeneracy. Albeit closely related to the unique linear code, the complexity index of the linear mechanisms is not entirely discriminating. The number of distinct KGs with the same value of the K index increases rapidly with the increase in the number of reaction routes. This is illustrated in Table 4, where the degree of degeneracy of the complexity index is calculated as the ratio of the total number of mechanisms and that of the mechanisms with different K values.

The high degeneracy found for four-route mechanisms reflects the higher degree of similarity of the graphs having four cycles. The difficulties involved in discriminating the highly connected KGs parallel those involved in discriminating the kinetic hypotheses for four-route reaction mechanisms. Thus, the complexity index K helps explain why it is so difficult to discriminate some mechanisms, the reason being the high similarity of topological structure among mechanisms.

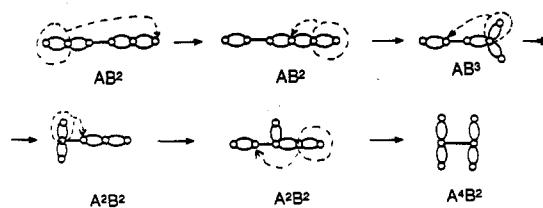
2. Isocomplexity Levels. The phenomenon of isocomplexity encompasses not only mechanisms differing in minor structural details but also covers all classification levels of mechanisms: types, generalized classes, specific classes, subclasses, and different distributions of cycle sizes.

An illustration is presented in Figure 4, where 11 KGs belonging to 11 specific classes, 6 generalized classes, and 4 types of linear mechanism have the complexity index $K = 2880$ showing the highest degeneracy. For example, KGs 31 and 33–35 belong to the specific classes $4\text{-}A^2BCZ^2$, $4\text{-}A^2ZBCZ$, $4\text{-}A^2CBZ^2$, and $4\text{-}A^2ZCBZ$, respectively, all of which are included in the generalized class A^2BC and type $L = 4$ (four-cycle interconnections). Another generalized class, AB^2C , of the same type $L = 4$, is also represented by KGs 46 and 48 (specific classes $4\text{-}AB^2Z^2C$ and $4\text{-}ABCZ^2B$, respectively). KG 154 is of generalized class A^2B^2C and type $L = 5$, and KGs 229 and 243 are of type $L = 6$ and generalized classes A^4BC and A^3B^2C , respectively.

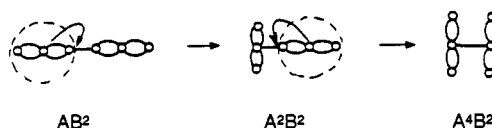
In addition to the intrinsic mechanism isocomplexity described above, it should be mentioned that 15 cases of accidental degeneracies have been found. These are cases in which the same K index value results by chance from different summands reflecting different mechanistic topology; no systematic graph transformations connect these KGs. An example is presented below, in which four linear mechanisms have the same complexity index ($K = 2420$).



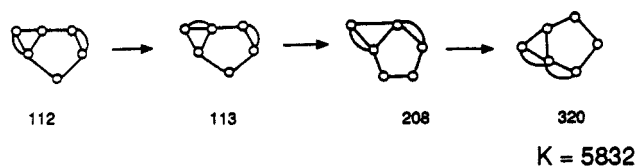
3. Graph Transformations Preserving Complexity. The analysis of eq 7 indicates that graph transformations preserving complexity are all transformations that do not change cycle sizes N_i and the number E_{ij} of the edges common for cycles i and j . Otherwise, these are different cases of "positional isomerism" that deal mainly with A and B classes (weak intercycle linkage). Upon such a graph transformation, a cycle linked by a bridge or by a common vertex is displaced so as to be connected to other cycles by any one of these weak linkages.



In general, the same type of transformation can be performed for subgraphs containing two or more weakly connected cycles:



Some transformations of strongly connected cycles (class C) also produce isocomplexity. These are displacements of an outer cycle sharing a common edge with a large cycle whose sites are nonequivalent:



4. Complexity Flow Chart. All isocomplexity relationships found for the classes of four-route mechanisms can be presented in a flow chart (Figure 5). The classes with the same complexity are connected there by vertical lines. The flow chart also shows the relationships of increasing complexity; these are shown by horizontal or diagonal lines for all generalized classes of all four types ($L = 3-6$) of the four-route mechanisms. From Figure 5 one can see that the KG transformations that increase complexity include all $B \rightarrow C$ transitions, as well as some of the $A \rightarrow B$ ones. The first trend deals with replacing the common vertex between two KG cycles with a common edge (or, otherwise, with replacing a common intermediate with a common elementary step). The second trend, the replacement of a bridge between two KG cycles with a common vertex, is weaker because both are a "weak" type of cycle linkage. The increase in complexity in such cases comes (see eq 7) from the increase by 1 in the size of one of the KG cycles in order to preserve a constant total number of KG vertexes. However, in those cases in which the $A \rightarrow B$ transformation can be performed by cycle displacements only (i.e., without any alteration of the cycle sizes), the complexity index remains unchanged.

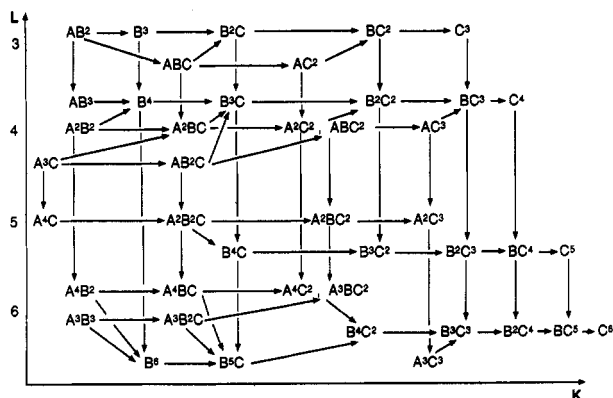


Figure 5. Complexity flow chart for the classes of four-route linear mechanisms.

V. CONCLUDING REMARKS

This study reports the first large-scale enumeration of the theoretically possible linear mechanisms of chemical reactions. On the basis of the novel concept that mechanisms have a topological structure, this is an exhaustive enumeration which indicates that the number of topologically distinct mechanisms of complex chemical reactions could be very large. This finding differs drastically from the few other known attempts^{3,4} at mechanism enumeration, which proceed from the chemical information on the reactions and produce a rather limited number of distinct mechanisms. Evidently, in order to be complete, any mechanism enumeration should take into account all possible interrelations of reactants, elementary steps, and reaction routes. The enumeration we report in Table 1 is also incomplete. It refers to mechanisms containing

only reversible steps. Indeed, a specified number of mechanisms with irreversible elementary reactions can be deduced for each of the mechanisms counted in Table 1. Graph-theoretically, this is the problem of counting the digraphs that correspond to a certain nondirected graph. A second extension of the enumeration procedure may handle mechanisms with reaction intermediates that are involved in an equilibrium elementary step only. In terms of graph theory, this problem can be reformulated as counting the number of graphs with pendant vertexes that correspond to each of the digraphs of interest. Finally, after the exhaustive topological enumeration described above, one could search for procedures that would produce an even larger number of theoretically possible mechanisms by accounting for their chemical specificity. Different classes of chemical reactions or reactants may be incorporated into our enumeration scheme by regarding graphs with weighted edges and/or vertexes. The results obtained by all these developments will be a subject of a future publication.³⁵ The large numbers of theoretically possible reaction mechanisms, revealed by our method, however, does not necessarily presuppose their real existence. One may expect some of the mechanisms that are topologically allowed to be forbidden for some chemical reasons. The search for such rules of selection in chemical kinetics might be a real challenge.

Another essential part of this study deals with the complexity analysis of linear mechanisms. The complexity index K , introduced in our previous publications, proved to be a reliable tool in assessing the complexity of both the kinetic models and cyclic graphs (KGs) used to represent them. Being derivable from the code developed for the computer storage of linear mechanisms, the K index evidences that our hierarchical mechanistic classification is associated with a systematic increase in the complexity of the types, classes, and subclasses of these mechanisms. By examining all 390 generated mechanisms having 4 reaction routes and up to 6 reaction intermediates, we were able to outline the major trends in increasing or preserving mechanistic complexity. The isocomplex mechanisms were treated in detail by specifying the different hierarchical levels of isocomplexity, as well as by determining the type of KG transformations that preserve mechanistic complexity. This analysis sheds some light on why it is so difficult to discriminate mechanisms with a larger number of reaction routes, the answer being that their complexity is frequently the same or very similar. On the other hand, it may be of theoretical interest to treat the isocomplexity problem not by using equations like eq 7 but, more generally, by finding the necessary and sufficient conditions for two cyclic graphs to have the same total number of spanning trees, as well as the same number of spanning trees in the subgraphs corresponding to the algebraic complements of the graph cycles.

Besides being of academic interest, this study is also practical. It is related to the creation in the Lomonosov Institute of Fine Chemical Technology in Moscow of a system for computer-assisted mechanism elucidation with a data base of mechanisms within a large range of reaction intermediates, elementary steps, and reaction routes. The modifications to the previously developed hierarchical classification and code of the linear mechanisms, simplified the computer storage and retrieval of mechanisms. The flow chart developed for the four-route mechanisms, along with those of the two- and three-route mechanisms,²¹ reveals the mechanism topological interrelations that increase or preserve complexity will facilitate the planning of kinetic experiments for more effective model discrimination.

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