

Estimation of causal mediation effects for a dichotomous outcome in multiple-mediator models using the mediation formula

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Mediators are intermediate variables in the causal pathway between an exposure and an outcome. Mediation analysis investigates the extent to which exposure effects occur through these variables, thus revealing causal mechanisms. In this paper, we consider the estimation of the mediation effect when the outcome is binary and multiple mediators of different types exist. We give a precise definition of the total mediation effect as well as decomposed mediation effects through individual or sets of mediators using the potential outcomes framework. We formulate a model of joint distribution (probit-normal) using continuous latent variables for any binary mediators to account for correlations among multiple mediators. A mediation formula approach is proposed to estimate the total mediation effect and decomposed mediation effects based on this parametric model. Estimation of mediation effects through individual or subsets of mediators requires an assumption involving the joint distribution of multiple counterfactuals. We conduct a simulation study that demonstrates low bias of mediation effect estimators for two-mediator models with various combinations of mediator types. The results also show that the power to detect a nonzero total mediation effect increases as the correlation coefficient between two mediators increases, whereas power for individual mediation effects reaches a maximum when the mediators are uncorrelated. We illustrate our approach by applying it to a retrospective cohort study of dental caries in adolescents with low and high socioeconomic status. Sensitivity analysis is performed to assess the robustness of conclusions regarding mediation effects when the assumption of no unmeasured mediator-outcome confounders is violated. Copyright © 2013 John Wiley & Sons, Ltd.

Keywords: mediation analysis; multiple mediators; latent variables; overall mediation effect; decomposed mediation effects; mediation formula; sensitivity analysis

1. Introduction

Randomized clinical trials and observational studies typically evaluate an overall treatment or exposure effect on a response. Of even greater scientific interest may be to explain by what means the treatment or exposure effect occurs, a goal that invokes the idea of mediation analysis. One way that a researcher can explain the mechanism by which one variable affects another is through the identification of mediating intermediate variables (or mediators). A well-known example of a mediated relationship in psychology is the effect of attitude on behavior, which is mediated by intentions [1]. Another example is the mediation of the effect of the apolipoprotein E ϵ 4 allele on cognitive impairment through an increase in the likelihood of chronic cerebral infarction [2,3].

At least a dozen methods have been proposed for testing the simple mediation hypothesis that the effect of an independent variable T on a dependent variable Y is mediated (at least in part) by an intermediate variable M [4]. Traditionally, mediation analysis has been dominated by linear regression

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(association) model paradigms, and the mediation effect assessed by difference in coefficients [5] or product of coefficients approaches [4]. More recently, causal mediation analysis, namely methods based on a causal model (usually, potential outcomes) framework, have been developed [6, 7]. In one such causal model approach, Pearl [8] proposed a mediation formula, applicable to nonlinear models for discrete or continuous outcome variables, which permits the evaluation of natural direct and indirect (or mediation) effects. More generally, mediating processes may include multiple mediators. In school-based drug prevention, for example, primary prevention programs target multiple mediators such as resistance skills and social norms to reduce drug use [9]. Reynolds *et al.* [10] explored knowledge, availability of fruits and vegetables, and parental consumption as mediators of a school-based nutrition intervention to increase healthy food consumption in children.

Models with more than one mediator are straightforward extensions of single-mediator models in the linear case, and the product of coefficients approach can be used for the estimation of multiple mediation effects [11, 12]. With multiple-mediator models, additional questions can be raised. For example, one may investigate the total mediation (or indirect) effect, that is, the extent to which a set of intermediate variables collectively mediate the effect of T to Y . Alternatively, one may wish to assess the extent of mediation through each individual mediator. For inference on mediation effects, Preacher and Hayes [12] advocated the bootstrap—especially bias-corrected bootstrap—over the multivariate delta method [13], as the former provides the most powerful and valid method of obtaining confidence intervals (CIs) for specific indirect effect under most conditions.

For a nonlinear response models, a nonstandard, for example, mediation formula, approach may be needed. However, such approaches have so far focused on a single mediator. An extension of the mediation formula approach for multiple, and possibly mixed types of mediators, will require modeling of the joint distribution of discrete and continuous outcomes. Such modeling includes three main approaches. The first approach is based on a conditioning argument that allows the joint distribution to be factorized into a marginal and a conditional density [14, 15]. A drawback of the conditioning approach for mixed outcome models is that it does not directly lead to marginal inferences [16]. Also, conditional models do not easily extend to the settings of three or more outcomes, and the correlations between pairs of outcomes cannot be directly estimated. The second approach attempts to specify the joint density of two outcomes directly. Multivariate methods are well established for the modeling of multivariate normally distributed outcomes [17]. To analyze mixed types of outcomes, bivariate (or multivariate) continuous variables are considered with components being either explicitly observed or latent continuous variables underlying the discrete outcomes [18]. The level of an observed discrete outcome is determined according to whether the corresponding latent variable exceeds some threshold values. A common example is the probit-type model, which assumes an unobservable normally distributed random variable underlying the binary outcome [19]. Instead of using latent variables, the third approach directly specifies the joint distribution via a mixed effects model in which each outcome is modeled conditional on a common random effect or correlated random effects [20]. In this paper, the second approach, which has the advantage of the direct specification of mediator correlation parameters, will be used. This approach is implemented for mixed types of mediators by specifying the joint distribution of the continuous mediators and continuous latent variables underlying binary mediators.

An approach to causal mediation analysis that accommodates multiple mediators is likely to provide a more accurate assessment of mediation effects in many research contexts. A limitation of standard (such as product of coefficients) approaches for multiple-mediator analysis is that they rely on linearity of the regression models, a restriction that may be difficult to justify unless the response and mediator are normally distributed. However, in medical research, the outcome or the mediator is often not normally distributed. The mediation formula approach of Albert and Nelson [21] handles sequential mediators, but not ‘contemporaneous’ mediators, for a discrete (count) outcome. Thus, the problem of causal mediation analysis in nonlinear models for multiple (contemporaneous) mediators does not appear to have been previously addressed in the literature. For estimation of the total indirect effect for a dichotomous outcome with mixed types of mediators, we apply the mediation formula approach under a sequential ignorability assumption. In addition, estimation of the mediation effect through an individual mediator or a subset of mediators is possible with additional identifying assumptions.

The remainder of this work proceeds as follows. In Section 2, we define, for multiple-mediator models with a dichotomous outcome, the natural direct, (total) indirect effects, and decomposed mediation effects through individual or sets of mediators. Section 3 presents a mediation formula approach to estimate the total and decomposed mediation effects under given identification assumptions. We introduce the association models and the maximum likelihood estimation methods for multiple-mediator

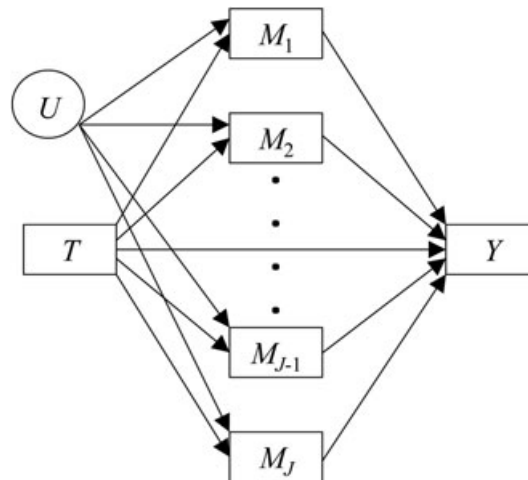


Figure 1. Path diagram for a multiple-mediator model with J mediators. T is exposure or treatment; M_j is mediator j , $j = 1, \dots, J$; Y is outcome; U is set of unobserved confounders of associations among mediators. T may exert indirect effects on Y through M_1, M_2, \dots, M_J , or affect Y directly.

models in Section 4. Section 5 proposes a sensitivity analysis that can be implemented by applied researchers to quantify the robustness of their conclusion to the potential violation of sequential ignorability assumptions. We use simulation studies in Section 6 to examine the statistical properties of the proposed methods. Section 7 describes the application of the proposed method to a dental caries study and presents sensitivity analysis results. We presented discussion and suggestions for further research in Section 8.

2. Defining total and decomposition of mediation effects

Consider the general causal model including a binary exposure or treatment indicator (T with a specific level represented by $t \in \{0, 1\}$), J mediators (M_1, M_2, \dots, M_J) and a dichotomous outcome (Y), where T may affect Y directly and/or T may affect any of the M_j , $j = 1$ to J , which then affect Y . Figure 1 shows the path diagram. We can define the causal mediation effects of interest using nested potential outcomes [7] within this multiple-mediator model. The total mediation effect (through the set $\{M_j, j = 1, \dots, J\}$) under exposure t is defined as

$$IE(t) \equiv E\{Y(t, M_1(1), M_2(1), \dots, M_J(1))\} - E\{Y(t, M_1(0), M_2(0), \dots, M_J(0))\} \quad (1)$$

Here, $Y(t, M_1(t'), M_2(t'), \dots, M_J(t'))$ denotes the potential outcome that Y would attain if T was set to t , and each M_j set to the counterfactual value that would be observed if T was set to t' . $IE(t)$ is called the *natural indirect effect* and represents the difference between two mean potential outcomes that would result under exposure status t , but where all mediators takes values that would result under two different exposure statuses. Similarly, we can define the *natural direct effect* and the *total causal effect* in the potential outcomes framework as

$$DE(t) \equiv E\{Y(1, M_1(t), M_2(t), \dots, M_J(t))\} - E\{Y(0, M_1(t), M_2(t), \dots, M_J(t))\} \quad (2)$$

$$TE \equiv E\{Y(1, M_1(1), M_2(1), \dots, M_J(1))\} - E\{Y(0, M_1(0), M_2(0), \dots, M_J(0))\} \quad (3)$$

Thus, the natural indirect effect under one exposure status and the natural direct effect under the other exposure status sum to the total causal effect. Here, we consider the decomposition involving $IE(1)$ and $DE(0)$ denoted as IE and DE ; for the other decomposition (involving $IE(0)$ and $DE(1)$), the method will be similar.

In multiple-mediator models, we can further consider mediation effects through an individual mediator or sets of mediators. The total natural indirect effect can be broken into J path effects within a J -mediator model; we use ' $IE_j(t_0, t_1, \dots, t_{j-1}, t_{j+1}, \dots, t_J)$ ' to denote the path (or mediation) effect through the j th mediator (Figure 1) with exposure set to t_0 and other mediators except for M_j set to the values attained under exposure levels $t_1, \dots, t_{j-1}, t_{j+1}, \dots, t_J$, respectively.

$IE_j(t_0, t_1, \dots, t_{j-1}, t_{j+1}, \dots, t_J)$ can be defined as the difference between two mean potential outcomes as follows:

$$IE_j(t_0, t_1, \dots, t_{j-1}, t_{j+1}, \dots, t_J) \equiv E\{Y(t_0, M_1(t_1), \dots, M_{j-1}(t_{j-1}), M_j(1), M_{j+1}(t_{j+1}), \dots, M_J(t_J))\} \\ - E\{Y(t_0, M_1(t_1), \dots, M_{j-1}(t_{j-1}), M_j(0), M_{j+1}(t_{j+1}), \dots, M_J(t_J))\} \quad (4)$$

Mediation effects through sets of mediators can be defined as the sum of mediation effects through the component individual mediators. Note that 2^J versions of $IE_j(t_0, t_1, \dots, t_{j-1}, t_{j+1}, \dots, t_J = 0 \text{ or } 1)$, the indirect effect of M_j , can be formulated corresponding to 2^J combinations of exposure settings for the outcome and other mediators in a J -mediator model. We use only one of them, $IE_j(t_0 = 1, t_1 = 0, \dots, t_{j-1} = 0, t_{j+1} = 1, \dots, t_J = 1)$, denoted as IE_j for simplicity; the other possible estimands can be handled similarly and thus are not discussed here. Of note, these defined IE_j s provide a proper decomposition of a total (indirect) effect among individual mediators as follows:

$$IE = IE_1 + IE_2 + \dots + IE_{J-1} + IE_J \quad (5)$$

3. Analysis of total and decomposed mediation effects

3.1. Identification assumptions for causal mediation effects in multiple-mediator models

We present identification results for the (total) indirect and direct effects (defined by (1) and (2)) as well as mediation effects through individual mediators (defined by (4)) using the potential outcomes framework described earlier. Under a particular version of the sequential ignorability assumption, the mediation effect estimators are identified nonparametrically in the multiple-mediator causal model. We first define our identifying assumption, which extends the version of Imai *et al.* [22].

Assumption 1 (Sequential ignorability)

$$\{Y(t_0, m_1, \dots, m_J), M_1(t_1), \dots, M_J(t_J)\} \perp\!\!\!\perp T \mid W = w \quad (6)$$

$$Y(t_0, m_1, \dots, m_J) \perp\!\!\!\perp M_j(t_j) \mid W = w, T = t_j, j = 1, \dots, J \quad (7)$$

for $t_0, t_1, \dots, t_J = 0, 1$, and $w \in \Omega$, where Ω denotes the support of the distribution of W .

First, given the observed baseline covariates (W), the exposure or treatment is assumed to be statistically independent of potential outcomes and potential mediators. The second part of Assumption 1 states that all mediators are independent of potential outcomes given the observed exposure or treatment and pre-treatment covariates. In addition, we make the consistency assumption throughout, namely $Y_i(t) = Y_i$ when $T_i = t$; that is, for any individual i , the potential outcome of Y setting $T = t$ is equal to the observed outcome if the individual happened to receive treatment level t . This assumption provides the connection between potential and observed outcomes.

3.2. Estimation of total and decomposed mediation effects for multiple-mediator models

To demonstrate identifiability of total and decomposed mediation effects for multiple-mediator models, we will examine the identification of the relevant potential outcome means (of the general form $E\{Y(t_0, M_1(t_1), \dots, M_J(t_J))\}$) given baseline covariate W under sequential ignorability (Assumption 1), where conditioning on W is left out of the notation for brevity. Under Assumption 1 (along with the consistency assumption), it can be shown that

$$E\{Y(t_0, M_1(t_1), \dots, M_J(t_J))\} = \int \dots \int_{n=J} E\{Y \mid T = t_0, M_1 = m_1, \dots, M_J = m_J\} \times \\ d^J F_{M_1(t_1), \dots, M_J(t_J)}(m_1, \dots, m_J) \quad (8)$$

A proof of formula (8) is given in Appendix A. Integration can be replaced with summation in the case of discrete mediators. Formula (8) shows that under sequential ignorability, the expected potential outcomes (left-hand side of the equation), used in the definition of the causal mediation effects, can be expressed as a function of association parameters (in a model for Y) that are directly estimable from the observed data. Estimability of the expected potential outcomes is then attained so long as the joint distribution of the mediator potential outcomes (last term in the expression on the right-hand side of (8)) can be estimated.

The total natural indirect effect, direct effect, and total causal effect are identifiable from formula (8) with known or estimated values for the joint distribution of $(M_1(0), \dots, M_J(0))$ and of $(M_1(1), \dots, M_J(1))$. However, when assessing mediation effects through individual or sets of mediators, we require joint distributions of $(M_1(t_1), \dots, M_J(t_J))$ in which the t_j 's are not all equal; such a joint distribution is not estimable because this joint potential outcome cannot be observed for the same subject. For identifiability, we need to make additional assumptions regarding the joint distribution of $(M_1(t_1), \dots, M_J(t_J))$. In fact, the marginal distribution of $M_j(t_j)$, $j = 1, \dots, J$, is estimable, and if each correlation coefficient $\rho_{kl}(t_k, t_l)$ between $M_k(t_k)$ and $M_l(t_l)$, $k < l$, $t_k \neq t_l$ is pre-specified, then the mean potential outcome in formula (8) is identifiable, and therefore so is the decomposed natural indirect effect through individual or sets of mediators. We use the simplifying assumption of a common correlation for each pair of mediators, that is, $\rho_{kl}(t_k, t_l) = \rho_{kl}$ for all t_k, t_l . In fact, we may allow more general models, but generally a full specification is not needed; in particular, the identification of any specific individual mediation effect needs only one of the two parameters, $\rho_{kl}(0, 1)$ and $\rho_{kl}(1, 0)$, for example, the former is needed to identify IE_j defined earlier.

To evaluate the joint integrals, we may also use Monte Carlo integration [23], a numerical integration technique that uses pseudo-random numbers generated from a joint distribution of mediator counterfactuals. Suppose (m_{1n}, \dots, m_{Jn}) and $(m_{1n}', \dots, m_{Jn}')$ are drawn from the joint distributions $f_{M_1(0), \dots, M_J(0)}(m_1, \dots, m_J)$ and $f_{M_1(1), \dots, M_J(1)}(m_1', \dots, m_J')$, respectively. Formula (1) can then be approximated by the following (using Monte Carlo approximations for formula (8)):

$$IE(t) \approx \frac{1}{N} \left(\sum_{n=1}^N E\{Y|M_1 = m_{1n}', \dots, M_J = m_{Jn}', T = t\} - \sum_{n=1}^N E\{Y|M_1 = m_{1n}, \dots, M_J = m_{Jn}, T = t\} \right) \quad (9)$$

The indirect effects through individual mediators (the IE_j as defined in formula (4)) can be expressed in a similar way.

4. Association models

Estimation of mediation effects proceeds by estimating the association model parameters in the mediation formula. In this paper, we consider models for the joint distribution of binary and normally distributed continuous mediators.

4.1. Regression models

We assume the following regression models for a dichotomous outcome Y and binary and/or continuous, and possibly correlated, mediators M_j , $j = 1, \dots, J$,

$$\text{logit}(\Pr(Y = 1)) = \beta_0 + \beta_1 M_1 + \dots + \beta_J M_J + \beta_{J+1} T + \beta' W \quad (10)$$

$$M_j^{(*)} = \alpha_{j0} + \alpha_{j1} T + \alpha_j' W + \varepsilon_j, j = 1, \dots, J \quad (11)$$

If M_j is a binary mediator, $M_j^{(*)}$ denotes M_j^* and M_j^* is a latent variable underlying M_j , such that $M_j = I \{M_j^* \geq 0\}$. In this latent variable model, $\text{Var}(\varepsilon_j)$ is not identified, and standard practice assumes that $\text{Var}(\varepsilon_j) = 1$ [24, 25]. Otherwise, if M_j is a continuous mediator, $M_j^{(*)}$ denotes M_j , and $\text{Var}(\varepsilon_j)$ is estimable. In addition, as indicated earlier, we make the potential outcomes model assumption of a constant unstructured correlation matrix for the J continuous (observed and latent) mediators regardless of the set exposure statuses. β_0, β_j s, α_{j0} s, and α_{j1} s are regression parameters, and W is a baseline covariate vector with corresponding coefficient vectors β' and α_j' .

4.2. Model of the joint distribution for multiple mediators

We will illustrate our estimation approach by formulating the joint distribution of a single continuous mediator and a single binary mediator, which is easily extended to cases with multiple continuous mediators or multiple binary mediators. Let M_{1i} and M_{2i} be two mediators measured on subject i ($i = 1, 2, \dots, N$), where M_1 denotes the binary mediator and M_2 the continuous mediator. Let M_{1i}^* be a latent variable underlying M_{1i} , such that $M_{1i} = I \{M_{1i}^* \geq 0\}$. For the bivariate response, we assume that

the unobserved latent variable M_{1i}^* and the observed continuous mediator M_{2i} for individual i together follow a bivariate normal model of the form

$$M_{1i}^* = \mathbf{X}_i' \boldsymbol{\alpha}_1 + \varepsilon_{1i} \quad M_{2i} = \mathbf{X}_i' \boldsymbol{\alpha}_2 + \varepsilon_{2i}$$

where $\boldsymbol{\alpha}_1$ and $\boldsymbol{\alpha}_2$ are fixed effect regression coefficient vectors of the covariate vector \mathbf{X}_i for the binary and continuous endpoints, respectively, and \mathbf{X}_i may include treatment T and subsets of baseline covariates W . The variance matrix of the residual (mean zero) error vector is assumed to be

$$\text{Var} \begin{pmatrix} \varepsilon_{1i} \\ \varepsilon_{2i} \end{pmatrix} = \begin{pmatrix} \sigma_1^2 & \rho\sigma_1\sigma_2 \\ \rho\sigma_1\sigma_2 & \sigma_2^2 \end{pmatrix}$$

Thus, this model specifies an unstructured correlation matrix for the two mediators. The parameter σ_1 is not identified as mentioned earlier and is assumed that $\sigma_1 = 1$. The specification of a common design vector \mathbf{X}_i for two mediators is not necessary, although a reasonable assumption in our application.

4.3. Maximum likelihood estimation

As standard linear or logistic regression models are employed for the marginal models, maximum likelihood estimation for the regression parameters is straightforward. For the joint mediator models, continuing our focus on the case of a single continuous and a single binary mediator, we note that the joint likelihood for the two mediators of subject i can be decomposed as

$$\begin{aligned} f(M_{1i}, M_{2i} | \boldsymbol{\alpha}_1, \boldsymbol{\alpha}_2, \sigma_2, \rho) &= f(M_{2i} | \boldsymbol{\alpha}_2, \sigma_2) P(M_{1i} | M_{2i}, \boldsymbol{\alpha}_1, \boldsymbol{\alpha}_2, \sigma_2, \rho) \\ &= f(M_{2i} | \boldsymbol{\alpha}_2, \sigma_2) \{ I(M_{1i} = 1) P(M_{1i}^* \geq 0 | M_{2i}, \boldsymbol{\alpha}_1, \boldsymbol{\alpha}_2, \sigma_2, \rho) \\ &\quad + I(M_{1i} = 0) [1 - P(M_{1i}^* \geq 0 | M_{2i}, \boldsymbol{\alpha}_1, \boldsymbol{\alpha}_2, \sigma_2, \rho)] \} \end{aligned} \quad (12)$$

The preceding first term is the marginal normal distribution given previously. The conditional density function is given by

$$M_{1i}^* | M_{2i} \sim N [\mathbf{X}_i' \boldsymbol{\alpha}_1 + (M_{2i} - \mathbf{X}_i' \boldsymbol{\alpha}_2) \rho / \sigma_2, (1 - \rho^2)]$$

Given this formulation, it is easy to then derive the contribution of M_{1i} to the likelihood. Specifically, we have

$$P(M_{1i}^* \geq 0 | M_{2i}, \boldsymbol{\alpha}_1, \boldsymbol{\alpha}_2, \sigma_2, \rho) = \Phi \left\{ \frac{\mathbf{X}_i' \boldsymbol{\alpha}_1 + (M_{2i} - \mathbf{X}_i' \boldsymbol{\alpha}_2) \rho / \sigma_2}{\sqrt{(1 - \rho^2)}} \right\} \quad (13)$$

Therefore, we can write the subject-specific contribution to the joint likelihood for (M_{1i}, M_{2i}) as the product of the marginal normal likelihood for M_{2i} times either the Bernoulli probability (13) or the probability of the complement, depending on whether M_{1i} is 1 or 0, respectively. The log-likelihood for the data is defined by summing the log of the expression in formula (12) over all subjects. Here, model estimation can be implemented in SAS (Version 9.2, SAS Institute Inc., Cary, NC, USA) using either the NLMIXED procedure to specify the likelihood function manually or the QLIM procedure, which constructs the likelihood automatically from specified regression models.

5. Sensitivity analysis

Sensitivity analysis explores the impact of departures from untestable assumptions and thus is an important component of our approach. Two sensitivity analyses are provided in this section. The first one assesses the effect of the assumed correlation coefficient $\rho_{kl}(t_k, t_l)$ between $M_k^{(*)}(t_k)$ and $M_l^{(*)}(t_l)$, $k < l$, $t_k \neq t_l$ on the estimation of decomposed mediation effects, and the second one evaluates the effect of violation of the no unmeasured mediator-outcome confounder assumption (7) on mediation effect estimation. For ease of presentation, we use a two-mediator model with one binary mediator (M_1) and one continuous mediator (M_2) to illustrate our sensitivity analysis approach in this section. The approach described can be easily extended to models with more than two mediators.

5.1. Effect of assumed correlation coefficient on decomposed mediation effect estimation

As stated in Section 3.2, the correlation coefficient ρ' (indicating $\rho_{12}(0, 1)$) between counterfactuals $M_1^*(0)$ and $M_2(1)$ needs to be pre-specified for the estimation of decomposed mediation effects IE_1 and IE_2 . We may examine the robustness of the IE_1 and IE_2 estimators, thus providing a sensitivity analysis, by varying the specified counterfactual correlation ρ' over the interval -1 to 1 .

5.2. Sensitivity analysis for violation of no unmeasured mediator-outcome confounder assumption

We propose a sensitivity analysis based on the approach of Albert and Nelson [21] and Wang and Albert [26], which applies the Gaussian copula [27], to assess the impact of nonzero correlations between $Y(t_0, m_1, m_2)$ and $M_j(t_j)$ ($j = 1, 2$) on mediation effect estimates, where Y and M_1 are binary and M_2 is continuous (normally distributed). In order to handle binary variables, corresponding continuous latent variables are introduced, such that the observed binary event is realized if the latent variable exceeds some threshold. Specifically, for the probit-type model, the threshold is 0. Then $Y^*(t_0, m_1, m_2)$, $M_1^*(t_1)$, and $M_2(t_2)$ are assumed to have a trivariate normal distribution with covariance matrix Σ and mean μ . The marginal distributions of $Y^*(t_0, m_1, m_2)$, $M_1^*(t_1)$, and $M_2(t_2)$ are estimable, as is the correlation coefficient ρ between $M_1^*(t_1)$ and $M_2(t_2)$ under the assumption that the correlation between $M_1^*(t_1)$ and $M_2(t_2)$ is constant over all t_1 and t_2 . Alternatively, we can use any specified value for ρ as considered in the aforementioned first sensitivity analysis. The correlation between $Y^*(t_0, m_1, m_2)$ and $M_1^*(t_1)$ is denoted as ρ_1 and the correlation between $Y^*(t_0, m_1, m_2)$ and $M_2(t_2)$ as ρ_2 . Similarly, we assume that ρ_1 and ρ_2 are constant over all t_0 , t_1 , and t_2 . Nonzero ρ_1 (or ρ_2) implies that there exists an omitted variable that affects both M_1 (or M_2) and Y . We propose a sensitivity analysis using Monte Carlo approach to estimate the conditional probability $P\{Y(t_0, m_1, m_2) = 1\}$ under the assumed ρ_1 and ρ_2 . This approach involves the following algorithm:

- (1) Sample the pair of mediator values $(m_{1i}^*, m_{2i}) \sim f_{M_1^*(t_1), M_2(t_2)}(m_1^*, m_2)$, $i = 1, 2, \dots, n$. If $m_{1i}^* > 0$, then $m_{1i} = 1$; otherwise, $m_{1i} = 0$.
- (2) The conditional distribution $Y^*(t_0, m_{1i}, m_{2i})$ is obtained on the basis of the trivariate normal distribution of $Y^*(t_0, m_{1i}, m_{2i})$, $M_1^*(t_1)$, and $M_2(t_2)$ with estimated ρ as well as pre-specified ρ_1 and ρ_2 .
- (3) Compute $P\{Y(t_0, m_{1i}, m_{2i}) = 1\}$ as $P\{Y^*(t_0, m_{1i}, m_{2i}) > 0\}$ on the basis of the distribution in (2).
- (4) Repeat steps 1–3 n times and obtain the potential outcome mean $E(Y(t_0, M_1(t_1), M_2(t_2)))$ as $\frac{1}{n} \sum_{i=1}^n P\{Y(t_0, m_{1i}, m_{2i}) = 1\}$.

This algorithm provides an estimation method for the general expected value of potential outcome $Y(t_0, M_1(t_1), M_2(t_2))$ assuming specified correlations (ρ_1 and ρ_2) between each mediators and the outcome adjusted for the mediators. It thus provides a sensitivity analysis of the total and decomposed natural indirect effect for departures from the sequential ignorability assumption (7).

6. Simulation study

In this section, we used a simulation study to assess the empirical bias, coverage probability (CP), and power of total and decomposed natural indirect effect estimators from our mediation formula approach for a binary outcome in a two-mediator model. In addition, we compared CPs for different CI methods. We used SAS/IML for all simulations and statistical analyses.

6.1. Empirical bias

To assess the empirical bias of mediation effect estimators, we conducted simulations using a $3 \times 4 \times 3 \times 3$ factorial design. First of all, we consider two-mediator models with three different combinations of mediator types, two binary, one binary and one continuous, or two continuous mediators. For each two-mediator model, four correlation coefficients values (-0.5 , 0 , 0.5 , and 0.9) between the two mediators (or latent variables underlying any binary mediators) are assumed. The exposure effect is similar for all scenarios (around 0.2). The magnitudes of the total natural indirect effect, IE (involving parameters β_1 , β_2 , α_{11} , and α_{21}) and the natural direct effect, DE (involving β_3), are studied under three cases:

dominant IE , dominant DE , and similar magnitude of IE and DE . The last factor, related to the decomposition of the total natural indirect effect, consists of three scenarios: indirect effect exclusively through one mediator, similar mediation effect through each mediator, and substantial mediation effects through each mediator but with different directions. We used sample sizes of 200 (100 per exposure group) and 500 (250 per exposure group) for each scenario.

We generated the bivariate normal distributed error terms for two mediators (or underlying latent variables corresponding to binary mediators) by using the 'RANDNORMAL' function in SAS/IML. To simplify the calculations, we did not use any baseline covariates in our simulation scenarios. For each given exposure, we generated the mediator variables or corresponding latent variables by using Equation (11) with the aforementioned produced error terms. We then generated the response variates according to the logistic regression model (10) given the individual exposure and observed mediators (possibly from corresponding latent variables). For each dataset, we estimated the total and decomposed natural indirect effects using formulae (1), (4), and (8). The true value is defined by the same function, with true coefficients in place of estimates. In addition, in the calculation of both true and estimated decomposed mediation effects, we assume that the correlation between $M_1^{(*)}(t_1)$ and $M_2^{(*)}(t_2)$ (which is estimable only for $t_1 = t_2$) is constant over all t_1 and t_2 . We performed 1000 independent datasets, and the following statistics for mediation effects estimators (total or individual) were provided: the average estimate, the average percent error (PE, estimate minus true value then divided by true value), and the SD of the estimate.

We focus on results for the two-mediator model with one binary mediator and one continuous mediator; results for two-mediator model with either two binary or continuous mediators are similar and therefore not presented. The simulation results are given in Table I with total sample size 200. We see that the mediation formula approach generally produces a small bias in its estimation of IE , IE_1 , and IE_2 in most scenarios. However, the proposed approach may provide substantial relative biases in some situations (putting aside cases where the true mediation effect is very small and thus, the average relative bias is unreliable). One such scenario is where the two mediators have mediation effects in different directions (the sixth 'mixed direction' scenario in each set); the other scenario has similar mediation effect magnitudes through either mediator but a correlation coefficient between the two mediators of 0.9 (the fifth 'high mediator correlation' scenario). In the 'mixed direction' scenario, our approach tends to produce high relative bias for the IE (overall) estimator, but low relative bias for the IE_1 and IE_2 (individual) estimators (less than 4%); on the other hand, high relative bias for individual and low relative bias (less than 2%) for overall mediation effect estimators can be detected in the 'high mediator correlation' scenario. When the sample size per group is increased to 250, the proposed approach shows low relative bias for all scenarios (less than 8.9%, data not shown).

6.2. Coverage probability and power

In a second simulation study, we compared the CP of 95% CIs constructed by different methods. We evaluated four such methods in this section: jackknife [28], percentile bootstrap, bias-corrected bootstrap, and bootstrap- t [29]. The second goal was to assess the power to detect nonzero mediation effects under different correlation coefficients between two mediators. We chose four correlation coefficients as before: -0.5 , 0 , 0.5 , and 0.9 . For each correlation coefficient, we designed six different simulation scenarios: (i) small indirect effects with different signs for the two mediators; (ii) substantial indirect effects with different signs and magnitudes for the two mediators; (iii) a zero indirect effect through each mediators; (iv) a zero indirect effect through the binary mediator and a small indirect effect through the continuous mediator; (v) a zero indirect effect through the continuous mediator and a small indirect effect through the binary mediator; and (vi) small direct effects with the same sign for both mediators. Of note, for power comparison purpose, we adjusted the corresponding parameter β_1 , β_2 , α_{11} , and α_{21} to make the true mediation estimand almost identical (constant up to the fourth decimal) for different specified correlation coefficient values. The CP is calculated as the percent of simulated datasets for which the 95% CIs covered the true value, and the power is calculated as the proportion of these 1000 replicated CIs that do not include zero. The results are summarized in Table II and Table III, respectively.

Table II shows the CP of four different methods for total and individual indirect effect estimates with sample size 100 per group. The results indicate that the bootstrap percentile CIs, for which the CP is within 3% of the nominal level for all scenarios, perform best. The coverage for bias-corrected bootstrap and jackknife CIs is only around 85% for the second scenario with correlation coefficient -0.5 , and the CP of bootstrap- t CIs for continuous mediator indirect effect, IE_2 , is unstable in most scenarios. We

Table I. Simulation statistics of overall and decomposed mediation effect estimators for a dichotomous outcome model with two mediators (one binary (M_1) and one continuous (M_2)), $n = 100$ per group.

$\rho (M_1, M_2)$	True		True		True		True		Overall IE			IE ₁			IE ₂		
	DE	IE	IE ₁	IE ₂	Est	DE	Ave Est	SD of Est	Ave PE (%)	Ave Est	SD of Est	Ave PE (%)	Ave Est	SD of Est	Ave PE (%)	Ave Est	SD of Est
-0.5	0.185	0.024	0.024	0.000	0.184	0.025	0.025	0.034	3.66	0.025	0.017	1.66	0.000	0.017	—	0.000	0.026
	0.211	0.020	0.010	0.010	0.210	0.022	0.022	0.034	8.70	0.011	0.014	2.53	0.011	0.014	15.21	0.011	0.028
	0.183	0.020	0.198	-0.179	0.173	0.033	0.033	0.100	70.82	0.209	0.082	5.36	-0.176	0.082	-1.78	0.035	0.035
	0.097	0.107	0.107	0.000	0.098	0.107	0.107	0.069	0.63	0.107	0.056	0.44	0.000	0.056	—	0.024	0.024
	0.099	0.113	0.056	0.056	0.097	0.116	0.116	0.095	2.74	0.057	0.054	1.81	0.058	0.054	3.67	0.061	0.061
	0.092	0.101	0.309	-0.208	0.106	0.090	0.090	0.124	-10.89	0.297	0.107	-3.94	-0.207	0.107	-0.57	0.036	0.036
0	0.023	0.179	0.179	0.000	0.022	0.178	0.178	0.087	-0.53	0.177	0.056	-1.58	0.002	0.056	—	0.047	0.047
	0.024	0.182	0.093	0.089	0.025	0.178	0.178	0.078	-2.07	0.090	0.048	-3.24	0.088	0.048	-0.85	0.048	0.048
	0.021	0.188	0.305	-0.117	0.020	0.193	0.193	0.122	2.26	0.308	0.109	0.88	-0.115	0.109	-1.33	0.030	0.030
	0.185	0.024	0.024	0.000	0.184	0.025	0.025	0.031	2.99	0.025	0.017	3.82	-0.000	0.017	—	0.025	0.025
	0.210	0.020	0.010	0.010	0.209	0.021	0.021	0.029	0.74	0.011	0.013	8.27	0.009	0.013	-7.19	0.026	0.026
	0.192	-0.005	0.190	-0.195	0.187	0.001	0.001	0.077	-121.7	0.194	0.060	2.25	-0.193	0.060	-0.64	0.037	0.037
	0.097	0.107	0.107	0.000	0.090	0.111	0.111	0.057	3.93	0.109	0.053	2.10	0.002	0.053	—	0.021	0.021
	0.098	0.112	0.056	0.056	0.097	0.115	0.115	0.075	2.12	0.056	0.049	0.19	0.058	0.049	4.04	0.057	0.057
	0.095	0.083	0.303	-0.220	0.084	0.095	0.095	0.122	14.03	0.312	0.107	3.12	-0.217	0.107	-1.02	0.038	0.038
	0.023	0.179	0.179	0.000	0.022	0.180	0.180	0.071	0.27	0.178	0.053	-0.79	0.002	0.053	—	0.044	0.044
	0.024	0.180	0.093	0.088	0.025	0.177	0.177	0.064	-2.01	0.090	0.048	-2.38	0.086	0.048	-1.61	0.044	0.044
	0.021	0.180	0.302	-0.122	0.020	0.180	0.180	0.114	0.12	0.301	0.107	-0.15	-0.121	0.107	-0.56	0.031	0.031

Table I. Continued.

$\rho (M_1, M_2)$	True	True	True	True	Est	Overall IE				IE ₁			IE ₂				
						Ave Est	Ave PE (%)	SD of Est	Ave Est	Ave PE (%)	SD of Est	Ave Est	Ave PE (%)	SD of Est			
0.5	0.185	0.024	0.024	0.000	0.188	0.024	1.01	0.028	0.024	-0.27	0.017	0.000	—	0.027	0.000	—	0.027
	0.210	0.020	0.010	0.010	0.206	0.021	3.72	0.026	0.011	1.66	0.015	0.010	5.89	0.027	0.010	5.89	0.027
	0.207	-0.019	0.185	-0.204	0.204	-0.012	-35.22	0.063	0.189	2.10	0.056	-0.202	-1.38	0.035	-0.202	-1.38	0.035
	0.097	0.107	0.107	0.000	0.096	0.108	1.28	0.053	0.108	1.07	0.055	0.000	—	0.023	0.000	—	0.023
	0.098	0.112	0.056	0.056	0.102	0.111	-0.75	0.065	0.053	-6.42	0.054	0.059	4.95	0.059	0.059	4.95	0.059
	0.100	0.076	0.305	-0.229	0.096	0.082	8.15	0.102	0.308	1.06	0.093	-0.226	-1.29	0.037	-0.226	-1.29	0.037
	0.023	0.179	0.179	-0.000	0.031	0.174	-2.88	0.062	0.176	-1.85	0.053	-0.002	—	0.047	-0.002	—	0.047
0.9	0.023	0.179	0.093	0.086	0.026	0.176	-1.66	0.058	0.093	-0.21	0.053	0.084	-3.22	0.049	0.084	-3.22	0.049
	0.022	0.177	0.303	-0.126	0.013	0.184	3.85	0.097	0.307	1.53	0.096	-0.124	-1.73	0.031	-0.124	-1.73	0.031
	0.185	0.024	0.024	0.000	0.185	0.024	-0.02	0.029	0.023	-4.46	0.019	0.001	—	0.034	0.001	—	0.034
	0.210	0.020	0.010	0.010	0.210	0.020	-1.26	0.028	0.009	-13.22	0.017	0.011	11.39	0.035	0.011	11.39	0.035
	0.224	-0.025	0.181	-0.206	0.228	-0.025	2.31	0.053	0.176	-2.93	0.054	-0.201	-2.31	0.036	-0.201	-2.31	0.036
	0.097	0.107	0.107	-0.000	0.096	0.108	1.40	0.055	0.107	0.09	0.068	0.001	—	0.028	0.001	—	0.028
	0.097	0.112	0.056	0.056	0.099	0.110	-1.70	0.060	0.051	-10.59	0.064	0.060	7.30	0.073	0.060	7.30	0.073
0.106	0.080	0.313	-0.233	0.111	0.075	-6.04	0.090	0.308	-1.70	0.096	-0.233	-0.20	0.039	-0.233	-0.20	0.039	
	0.023	0.179	0.179	0.000	0.024	0.179	-0.16	0.056	0.177	-1.53	0.067	0.002	—	0.059	0.002	—	0.059
	0.023	0.179	0.094	0.085	0.018	0.181	1.18	0.051	0.092	-1.64	0.060	0.089	4.28	0.059	0.089	4.28	0.059
	0.023	0.180	0.307	-0.128	0.024	0.180	0.18	0.096	0.306	-0.45	0.103	-0.126	-1.33	0.033	-0.126	-1.33	0.033

Table II. Coverage probabilities of four CI methods for overall and decomposed mediation effects in a dichotomous outcome model with two mediators (one binary (M_1) and one continuous (M_2)), $n = 100$ per group.													
$\rho(M_1, M_2)$	True IE	True IE_1	True IE_2	Overall IE			IE_1			IE_2			Bt
				Jackknife	Boot	Bc	Jackknife	Boot	Bc	Jackknife	Boot	Bc	
−0.5	0.000	0.050	−0.050	93.2	94.6	94.5	93.8	94.4	92.9	94.3	93.4	92.7	82.1
	0.200	0.300	−0.100	83.8	97.3	83.1	90.4	97.7	84.4	87.5	94.9	94.3	99.9
	0.000	0.000	0.000	95.2	94.7	93.7	93.5	98.0	95.1	90.8	93.1	90.6	68.0
	0.051	0.000	0.051	96.3	94.8	94.7	94.9	97.3	94.6	92.0	94.3	94.9	64.2
	0.050	0.050	0.000	94.2	95.1	94.9	94.5	95.3	94.6	94.4	95.6	93.0	99.2
0	0.100	0.050	0.050	93.6	94.7	95.1	93.2	95.4	93.4	94.3	94.9	94.0	81.8
	0.000	0.050	−0.050	94.1	94.1	93.5	93.6	96.2	93.6	93.8	94.8	94.1	85.0
	0.200	0.300	−0.100	91.4	94.8	89.7	91.9	94.5	89.0	91.6	94.4	94.6	99.9
	0.000	0.000	0.000	94.7	95.2	93.1	95.0	99.7	95.2	92.3	93.7	91.1	67.5
	0.051	0.000	0.051	95.2	94.8	94.1	94.9	99.7	95.4	93.0	94.0	94.1	61.7
0.5	0.050	0.050	0.000	96.8	96.2	95.6	94.8	96.8	95.5	95.3	94.5	92.9	98.7
	0.100	0.050	0.050	96.1	94.4	94.3	93.9	95.3	92.6	93.9	95.3	95.1	83.9
	0.000	0.050	−0.050	95.2	94.6	94.6	93.9	95.8	93.7	95.0	94.2	93.9	85.8
	0.200	0.300	−0.100	92.6	95.0	94.0	93.5	92.8	93.6	93.3	93.5	94.5	100
	0.000	0.000	0.000	96.7	95.2	93.0	94.3	99.1	94.7	91.2	94.1	91.0	67.5
0.9	0.051	0.000	0.051	95.5	94.7	94.5	93.9	99.4	95.3	92.4	93.1	93.1	62.5
	0.050	0.050	0.000	94.3	95.9	95.0	94.8	95.4	92.2	93.5	94.7	92.7	99.3
	0.100	0.050	0.050	96.2	94.4	94.1	93.6	95.5	93.0	94.7	94.0	93.4	84.2
	0.000	0.050	−0.050	95.9	95.1	94.2	94.5	94.8	93.4	93.5	94.7	94.4	86.5
	0.200	0.300	−0.100	95.4	93.4	93.7	94.0	94.5	93.0	93.1	93.4	94.2	100
	0.000	0.000	0.000	96.4	95.3	94.5	93.9	99.2	94.4	93.6	94.7	93.0	69.2
	0.051	0.000	0.051	95.8	95.3	95.0	94.6	98.8	94.1	91.4	94.7	94.1	66.3
	0.050	0.050	0.000	95.6	95.2	94.8	95.0	95.1	94.3	95.3	94.6	93.8	99.1
	0.100	0.050	0.050	94.6	95.1	94.8	95.4	93.5	94.3	94.1	94.8	94.6	83.4

Jackknife, jackknife CIs; Boot, bootstrap percentile CIs; Bc, bias-corrected bootstrap CIs; Bt, bootstrap- t CIs.

Table III. Power of bootstrap percentile CIs to detect nonzero mediation effect for a dichotomous outcome model with two mediators (one binary (M_1) and one continuous (M_2)), $n = 100$ and 250 per group.

$\rho(M_1, M_2)$	True IE	True IE_1	True IE_2	Sample size					
				100			250		
				Overall IE	IE_1	IE_2	Overall IE	IE_1	IE_2
-0.5	0.000	0.050	-0.050	—	24.8	18.6	—	54.8	35.0
	0.200	0.300	-0.100	36.6	91.6	95.6	74.0	100	100
	0.000	0.000	0.000	—	—	—	—	—	—
	0.051	0.000	0.051	33.2	—	53.0	70.2	—	89.1
	0.050	0.050	0.000	14.3	26.0	—	33.6	54.3	—
	0.100	0.050	0.050	26.1	24.4	16.0	55.0	53.0	33.8
0	0.000	0.050	-0.050	—	30.9	20.4	—	59.6	41.6
	0.200	0.300	-0.100	51.7	94.4	97.4	90.5	100	100
	0.000	0.000	0.000	—	—	—	—	—	—
	0.051	0.000	0.051	42.4	—	57.4	86.1	—	93.9
	0.050	0.050	0.000	18.6	27.3	—	46.0	61.8	—
	0.100	0.050	0.050	38.2	30.6	16.7	75.9	63.3	37.5
0.5	0.000	0.050	-0.050	—	25.6	17.3	—	53.5	36.4
	0.200	0.300	-0.100	62.2	94.1	96.2	94.4	100	100
	0.000	0.000	0.000	—	—	—	—	—	—
	0.051	0.000	0.051	53.7	—	53.9	93.0	—	88.1
	0.050	0.050	0.000	25.1	27.2	—	54.8	52.5	—
	0.100	0.050	0.050	45.3	26.7	16.1	85.6	52.0	34.0
0.9	0.000	0.050	-0.050	—	17.5	12.8	—	38.4	24.4
	0.200	0.300	-0.100	54.9	85.7	87.9	93.9	99.9	100
	0.000	0.000	0.000	—	—	—	—	—	—
	0.051	0.000	0.051	48.5	—	33.7	89.9	—	71.7
	0.050	0.050	0.000	30.3	19.3	—	62.3	39.2	—
	0.100	0.050	0.050	56.5	17.8	13.3	91.2	36.8	26.2

repeated the simulations with a sample size of 250 per group (data not shown). With the larger sample size, the CP for bootstrap percentile, bias-corrected bootstrap, and jackknife CIs gets closer to nominal level while problems for bootstrap- t CIs still exist.

We then compared the power of the bootstrap percentile CI to detect nonzero mediation effects under different values of the correlation between the two mediators. The results, given in Table III, show that the power to detect nonzero IE increases as the correlation coefficient between two mediators increases, and the power to detect nonzero IE_1 and IE_2 increases as the absolute value of the correlation coefficient between two mediators gets close to zero for most simulation scenarios. When the sample size per group is increased to 250, the power is larger than that in small sample size scenarios, and similar results can be observed.

7. Study example

The illustrative example considered here comes from a dental caries study measuring the number of decayed, filled, or missing teeth (#DMFT) at around age of 14 years for a cohort of very low birth weight (VLBW) and a matched group of normal birth weight (NBW) children. The exposure variable of interest is the binary variable, socioeconomic status (SES), coded as $SES = 1$ for low SES ('exposed') and $SES = 0$ for high SES ('unexposed'). The outcome considered in this example is the dichotomous DMFT variable, $DMFT = 0$ (#DMFT = 0) versus $DMFT = 1$ (#DMFT > 0). Baseline covariates adjusted for in the model include birth group (VLBW vs. NBW), sex, and race. We also considered the following potential mediators: 'Sealant' (a binary variable indicating use of sealants), 'AvgOHI' (the average oral hygiene index score with higher values indicating worse oral hygiene status), and 'Visit' (a binary variable indicating whether the child received regular (at least once a year) checkups from the

Table IV. Estimated causal effects (and 95% bootstrap percentile CIs) based on the mediation formula approach with ‘exact’ integration and Monte Carlo integration in the two-mediator model using dental data.

		Mediation formula	
		‘Exact’ integration	Monte Carlo integration*
Sealant (binary) and AvgOHI (continuous)	Total <i>TE</i>	0.19 (0.04, 0.34)	0.19 (0.04, 0.33)
	Direct <i>DE</i>	0.15 (0.00 [†] , 0.30)	0.15 (0.00, 0.30)
	Indirect <i>IE</i>	0.04 (−0.00 [†] , 0.09)	0.04 (−0.00, 0.09)
	Through Sealant (<i>IE</i> ₁) [‡]	−0.00 (−0.02, 0.02)	−0.00 (−0.02, 0.02)
	Through AvgOHI (<i>IE</i> ₂) [‡]	0.04 (0.01, 0.09)	0.04 (0.01, 0.09)

*Monte Carlo integration with 10 000 samples was used for estimation of causal effects.

[†]‘0.00’ indicates a positive value and ‘−0.00’ a negative value, less than 0.005 in absolute value.

[‡]Assumes correlation coefficient (ρ') between unobserved counterfactual values $M_1^*(0)$ and $M_2(1)$ the same as that between $M_1^*(0)$ and $M_2(0)$, and $M_1^*(1)$ and $M_2(1)$.

dentist or not). We wanted to assess the direct effect of SES on DMFT and its indirect effect through Sealant, AvgOHI, and Visit.

The dental dataset we used for the analysis included 129 subjects in the exposed group ($SES = 1$) and 74 subjects in the unexposed group ($SES = 0$). 79 of 129 (61.2%) subjects in the exposed group and 28 of 74 (37.8%) subjects in the unexposed group had at least one DMFT, indicating that children from families with low SES may have a higher risk of developing dental caries compared with those from families with high SES. The system of models (including the outcome model (10) and the mediator model (11) for the selected mediators, each of which incorporated the three baseline covariates, birth group, sex, and race) were fitted using maximum likelihood estimation. First, we considered the two-mediator model including Sealant and AvgOHI. Estimates of *TE*, *DE*, *IE*, *IE*₁, and *IE*₂ using the mediation formula approach with ‘exact’ integration (SAS, ‘QUAD’ function) and the Monte Carlo approximate integration approach (using 10 000 bivariate samples of $M_1^*(t_1)$ and $M_2(t_2)$) are provided in Table IV; 95% CIs for these estimators were computed using bootstrap percentile methodology. The ‘exact’ and Monte Carlo approaches provided almost identical mediation effect estimates as well as CIs. The results indicate that the total natural indirect effect accounts for approximately 25% of the total exposure effect, and the mediation effect through AvgOHI predominates among the individual mediation effects. The effect estimates are interpreted as follows. Low (vs. high) SES increases the probability of $DMFT = 1$ by 0.19 (95% CI: 0.04, 0.34), by an estimated 0.04 (−0.00, 0.09) attributable to the two mediators (Sealant and AvgOHI) and an estimated 0.15 (0.00, 0.30) because of the direct effect (or other unknown pathways); we let ‘0.00’ indicate a positive value and ‘−0.00’ a negative value, less than 0.005 in absolute value. The overall indirect effect (attributable to the two mediators together) can be decomposed into mediation effects through Sealant (−0.00 (−0.02, 0.02)) and through AvgOHI (0.04 (0.01, 0.09)). In summary, we found, using the two-mediator model for the dental data, a significant total exposure effect (*TE*), direct effect (*DE*), and indirect effect through AvgOHI (*IE*₂), a marginally significant total indirect effect estimate (*IE*), and a nonsignificant indirect effect through Sealant (*IE*₁) (at the 0.05 level based on the CIs). We next included one additional potential mediator, Visit, in the model; the analysis results of this model are shown in Table V. Similar conclusions were drawn as earlier. Low (vs. high) SES increases the probability of $DMFT = 1$ by an estimated 0.18 (0.03, 0.34) with an estimated increase of 0.05 (0.00, 0.11) attributable to the set of mediators (with the following individual mediation effects: Sealant 0.00 (−0.02, 0.02), AvgOHI 0.04 (0.00, 0.08), and Visit 0.02 (−0.01, 0.05)) and an estimated increase of 0.13 (−0.03, 0.29) due to the direct effect (that is, any other pathways). Comparing the results from Table IV, we may conclude that part of the direct effect in the two-mediator model was explained by an indirect effect through the added mediator Visit, although the indirect effect through Visit is not statistically significant.

We conducted two sensitivity analyses in the two-mediator model for our dental data. In the first sensitivity analysis, we examined the effect on the individual mediation effects, *IE*₁ and *IE*₂, of varying the correlation coefficient ρ' between $M_1^*(0)$ and $M_2(1)$ from −1 to 1 in increments of 0.01. The change in *IE*₁ and *IE*₂ estimates over ρ' is shown in Figure 2. The plots indicate that the *IE*₁ estimate increases (Figure 2(A)) and the *IE*₂ estimate decreases (Figure 2(B)) as ρ' increases; the sum of *IE*₁ and *IE*₂ is constant, as ρ' does not affect the total indirect effect estimate. On the basis of repeated computations of

Table V. Estimated causal effects (and 95% bootstrap percentile CIs) based on the mediation formula approach with ‘exact’ integration and Monte Carlo integration in a three-mediator model using dental data.

		Mediation formula	
		‘Exact’ integration	Monte Carlo integration*
Sealant (binary), AvgOHI (continuous), and Visit (binary)	Total TE	0.18 (0.03, 0.34)	0.18 (0.03, 0.34)
	Direct DE	0.13 (−0.03, 0.29)	0.13 (−0.03, 0.29)
	Indirect IE	0.05 (0.00 [†] , 0.11)	0.05 (0.00, 0.11)
	Through Sealant (IE_1) [‡]	0.00 (−0.02, 0.02)	0.00 (−0.02, 0.02)
	Through AvgOHI and Visit (IE_{23}) [‡]	0.05 (0.01, 0.11)	0.05 (0.01, 0.11)
	Through AvgOHI (IE_2) [‡]	0.04 (0.00, 0.08)	0.04 (0.00, 0.08)
	Through Sealant and Visit (IE_{13}) [‡]	0.02 (−0.02, 0.05)	0.02 (−0.02, 0.05)
	Through Visit (IE_3) [‡]	0.02 (−0.01, 0.05)	0.02 (−0.01, 0.05)
	Through Sealant and AvgOHI (IE_{12}) [‡]	0.04 (−0.00, 0.08)	0.04 (−0.00 [†] , 0.08)

*Monte Carlo integration with 1 000 000 samples was used for estimation of causal effects.

[†]‘0.00’ indicates a positive value and ‘−0.00’ a negative value, less than 0.005 in absolute value.

[‡]Assumes correlation between $M_i^{(*)}(t_i)$, $M_j^{(*)}(t_j)$ ($i, j = 1, 2, 3$ and $i \neq j$) is constant over all t_i and t_j .

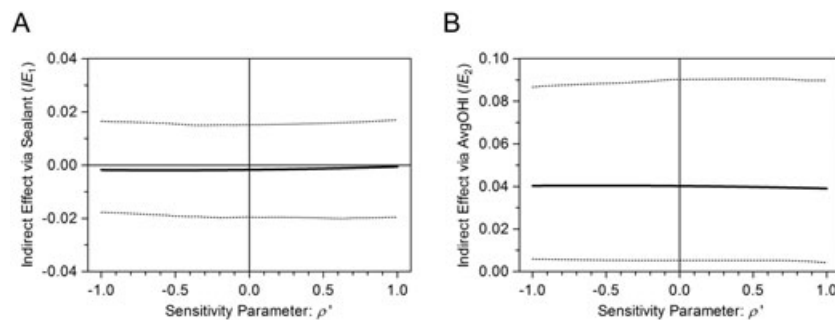


Figure 2. Sensitivity analysis for overall indirect effect decomposition of dental data involving binary ‘Sealant’ and continuous ‘AvgOHI’ mediators. A and B show the estimated indirect effect through ‘Sealant’ and ‘AvgOHI’, respectively, for varying correlation ρ' between $M_1^*(0)$ and $M_2(1)$. The areas between dotted lines represent the 95% CIs for the decomposed natural indirect effect estimator at each value of ρ' .

the CIs, we found a nonsignificant indirect effect through Sealant and a significant indirect effect through AvgOHI over the whole range of ρ' , indicating robustness of the decomposed mediation effect estimates to the correlation between counterfactuals $M_1^*(0)$ and $M_2(1)$.

In the second sensitivity analysis, we assessed the effect on mediation effect estimates (IE , IE_1 , and IE_2) of possible violation of the no unmeasured mediator-outcome confounding assumption. As there are two correlation parameters of interest, 3-D graphs (Figure 3) were plotted describing the change of mediation effect estimates over the ranges of the two correlations. Namely the correlations are those between each of the two mediators (or underlying latent variables) and the latent variable underlying the outcome variable adjusting for the mediators. Of note, when assuming no mediator-outcome confounders ($\rho_1, \rho_2 = 0$), a significant positive indirect effect through AvgOHI (IE_2 , 0.04 (0.01, 0.09)), a positive marginally significant total indirect effect (IE , 0.04 (−0.00, 0.09)), and no significant indirect effect through Sealant (IE_1 , −0.00 (−0.02, 0.02)) were detected. We find that ρ_1 (the correlation between $Y^*(t_0, m_1, m_2)$ and $M_1^*(t_1)$) does not substantially affect estimates of the overall indirect effect (IE), and as ρ_2 (the correlation between $Y^*(t_0, m_1, m_2)$ and $M_2(t_2)$) increases, the IE estimate significantly decreases (Figure 3(A)). Furthermore, the IE estimate is held in the bounded interval [−0.14, 0.16], and when ρ_2 is greater than 0.56, we find a significant negative IE estimate. For the IE_1 estimate, it is stable and trivial (bounded by [−0.01, 0.00]) over the range of ρ_1 and ρ_2 (Figure 3(B)). The fact that the 95% CIs recalculated over the full bivariate range for the two correlation coefficients always contain zero indicates the robustness of the original conclusion (that there is no evidence for a mediation effect through Sealant). The pattern of the change in the IE_2 estimate (over the ranges of ρ_1 and ρ_2) is similar with that of IE estimate (Figure 3(C)); IE_2 is close to IE in this example as the estimate of IE_1 is approximately zero. This result indicates that our original conclusion regarding the significant positive indirect effect

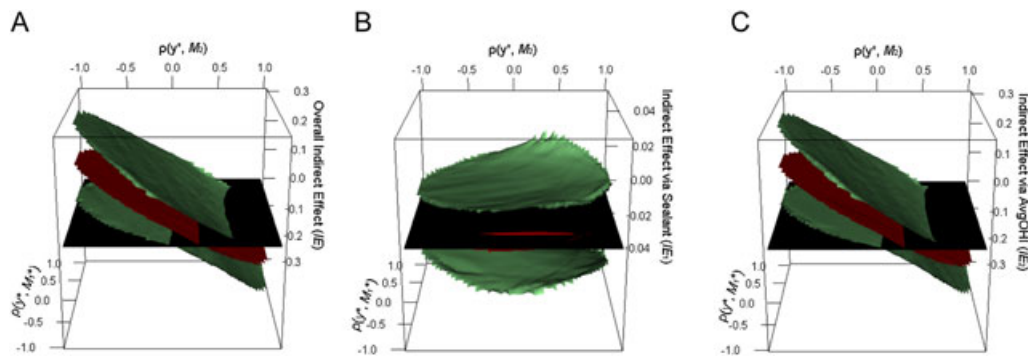


Figure 3. Sensitivity analysis for overall indirect effect estimation and indirect effect decomposition of dental data involving binary ‘Sealant’ (M_1) and continuous ‘AvgOHI’ (M_2) mediators. A shows the estimated overall indirect effect for varying correlations ρ_1 (between $Y^*(t_0, m_1, m_2)$ and $M_1^*(t_1)$) and ρ_2 (between $Y^*(t_0, m_1, m_2)$ and $M_2(t_2)$). B shows indirect effect estimation through ‘Sealant’, and C shows indirect effect estimation through ‘AvgOHI’. Red surface shows the mediation effect estimate, the space between the two green surfaces represents the 95% CIs, and the black surface indicates zero mediation effect reference.

through AvgOHI may not hold if unmeasured confounders (explaining a correlation of greater than 0.5) between the mediator and outcome exist.

8. Discussion

In this article, we consider multiple-mediator models with binary or continuous mediators and a binary outcome. We model the joint distribution assuming multivariate normality among the latent (if binary) and observed (if continuous) mediators, with marginal probit models for binary mediators and linear models for continuous mediators. Our approach thus accommodates correlations among multiple contemporaneous mediators of different types. The total and individual mediation effects are estimated with a mediation formula approach, and proposed sensitivity analyses allow an assessment of the robustness of the results. Mediation effects estimation for two-mediator and three-mediator models described in this paper has been encoded in a SAS macro, which is available for downloading from the webpage <http://epbiwww.case.edu/index.php/people/faculty/53-albert>.

Our simulation study showed good properties (low bias and close-to-nominal CI coverage rates) for the proposed estimators under most scenarios. For the estimation of individual natural indirect effects, there appears to be some bias when there are substantial mediation effects through each mediator and the correlation coefficient between the two mediators is high. This bias, which occurs for $n = 200$, suggests that our method may have difficulty dissecting the total natural indirect effect accurately in some scenarios when the two mediators are highly correlated and the sample size is relatively small. However, in most scenarios, low bias for individual mediator indirect effect was obtained even in this case. In addition, we found that our estimators of the total natural indirect effect had low bias in most scenarios, and high mediator correlation appears to be a favorable condition for this estimand.

On the basis of our simulation study of CPs from four methods of constructing CIs, we recommend that CIs for mediation effects in our multiple-mediator model context be obtained using the bootstrap percentile method. Preacher and Hayes [12] advocated the bias-corrected bootstrap for CIs of mediation effects estimated with the product of coefficients approach in linear multiple-mediator models. However, we found that CIs from the bias-corrected bootstrap may be biased when there are substantial unbalanced indirect effects through both mediators with different signs, and the sample size is 200. An interesting finding is that the power for detecting a total indirect effect increases as the correlation between two mediators increases, and the power for individual-mediator indirect effects is maximized when the two mediators are uncorrelated. Therefore, it is relatively easy to detect a total mediation effect when the two mediators are highly correlated, whereas individual mediation effects are most easily detected with uncorrelated mediators.

Multiple-mediator models allow us to dissect the total mediation effect and estimate mediation effects through individual or sets of mediators under additional assumptions. Estimation of the decomposed mediation effects involves the joint distribution of counterfactuals that cannot be observed at the same

time (namely $M_1^*(0)$ and $M_2(1)$ in our data example). This problem, which may occur when there are more than two stages of mediation, was recognized previously in the literature [21, 26, 30]. The simple identifying assumption of a constant correlation coefficient between counterfactuals $M_1^*(t_1)$ and $M_2(t_2)$ for all t_1 and t_2 may not always be plausible. Therefore, it may be sensible to make use of bounds for the decomposed mediation effect estimate by considering ρ' over a plausible range or even over the entire interval $[-1, 1]$.

To assess the effect on mediation effect estimates of violations of the no unmeasured mediator-outcome confounders assumption, we use the correlation coefficients between each mediator (or underlying latent variables) and the latent variable underlying the outcome variable (adjusting for the mediators), denoted as ρ_1 and ρ_2 , as our sensitivity analysis parameters. Alternatively, Imai *et al.* [22] expressed the correlation coefficient between the mediator and the outcome as a function of the coefficients of determination (i.e., R^2 , which represent the proportion of previously unexplained variance either in the mediator or outcome that is explained by the unobserved confounders), allowing for the sensitivity analysis to be based on the magnitudes of an effect of the omitted confounder. Imai *et al.* [31] also extended this approach to the case of a binary mediator and/or binary outcome using the pseudo- R^2 of McKelvey and Zavoina [32]. This approach may possibly be applied to our model. Although R^2 as a sensitivity parameter has an advantage of interpretability, a disadvantage of this approach is that it requires two such R^2 s instead of a single parameter (ρ). One consequence is that the graphical presentation of the sensitivity analysis results is more difficult, especially for our multiple-mediator models. Imai and Yamamoto [33] (a paper to which an anonymous referee called our attention) also addressed a multiple-mediator problem, but where a causal direction between the mediators is specified. They provide an alternative set of identifying assumptions developed for the situation where there is a single mediator of interest that may be causally affected by other mediators.

In conclusion, we have proposed a mediation formula approach for mediation analysis of multiple-mediator models with a dichotomous outcome that allows estimation of the total indirect effect, as well as further decomposition of the total indirect effect through individual mediators. This approach can be easily extended to other types of discrete outcomes (such as a count response). One limitation of the proposed mediation analysis approach is that unbiased mediation effect estimation requires correct specifications of the parametric models for both the mediators and the outcome. This assumption may be violated, for example, if nonzero quadratic terms or treatment-mediator interactions are excluded from the model. However, standard model assessment techniques may be used to test and formulate reasonably correct association models. In addition, the use of the mediation formula (8) involves integration for continuous mediators. Because of the extensive computations required for multivariate integration, the proposed approach may not be feasible with more than three continuous mediators. In such cases, some sort of dimensionality reduction (for example, reducing the number of mediators or using linear combinations) may still allow use of this approach. Future research is needed to find more efficient computational techniques that will allow a larger number of mediators.

Appendix A: Proof of formula (8)

In this proof, we assume sequential ignorability (6) and (7) and consistency. Note that the potential outcomes for J mediators in $Y(t_0, M_1(t_1), \dots, M_J(t_J))$ are random variables; therefore, to obtain the marginal expected value of $Y(t_0, M_1(t_1), \dots, M_J(t_J))$ requires that we integrate over these variables, comprising the endogenous (random) explanatory variables in the model of Y [21], as follows:

$$\begin{aligned} E\{Y(t_0, M_1(t_1), \dots, M_J(t_J))\} &= \\ &= \int_{n=J}^{\dots} \int E\{Y(t_0, m_1, \dots, m_J) | M_1(t_1) = m_1, \dots, M_J(t_J) = m_J\} d^J F_{M_1(t_1), \dots, M_J(t_J)}(m_1, \dots, m_J) \quad \text{Definition} \\ &= \int_{n=J}^{\dots} \int E\{Y(t_0, m_1, \dots, m_J) | T = t_1, M_1(t_1) = m_1, \dots, M_J(t_J) = m_J\} d^J F_{M_1(t_1), \dots, M_J(t_J)}(m_1, \dots, m_J) \\ &\quad \text{by (6)} \\ &= \int_{n=J}^{\dots} \int E\{Y(t_0, m_1, \dots, m_J) | T = t_1, M_2(t_2) = m_2, \dots, M_J(t_J) = m_J\} d^J F_{M_1(t_1), \dots, M_J(t_J)}(m_1, \dots, m_J) \\ &\quad \text{by (7)} \\ &= \int_{n=J}^{\dots} \int E\{Y(t_0, m_1, \dots, m_J) | T = t_2, M_2(t_2) = m_2, \dots, M_J(t_J) = m_J\} d^J F_{M_1(t_1), \dots, M_J(t_J)}(m_1, \dots, m_J) \\ &\quad \text{by (6)} \end{aligned}$$

$$\begin{aligned}
 &= \int_{n=J}^{\dots} \int E\{Y(t_0, m_1, \dots, m_J) | T = t_2, M_3(t_3) = m_3, \dots, M_J(t_J) = m_J\} d^J F_{M_1(t_1), \dots, M_J(t_J)}(m_1, \dots, m_J) \\
 &\quad \text{by (7)} \\
 &= \dots \\
 &= \int_{n=J}^{\dots} \int E\{Y(t_0, m_1, \dots, m_J) | T = t_J\} d^J F_{M_1(t_1), \dots, M_J(t_J)}(m_1, \dots, m_J) \\
 &\quad \text{by (7)} \\
 &= \int_{n=J}^{\dots} \int E\{Y(t_0, m_1, \dots, m_J) | T = t_0\} d^J F_{M_1(t_1), \dots, M_J(t_J)}(m_1, \dots, m_J) \\
 &\quad \text{by (6)} \\
 &= \int_{n=J}^{\dots} \int E\{Y(t_0, m_1, \dots, m_J) | T = t_0, M_1(t_0) = m_1\} d^J F_{M_1(t_1), \dots, M_J(t_J)}(m_1, \dots, m_J) \\
 &\quad \text{by (7)} \\
 &= \int_{n=J}^{\dots} \int E\{Y(t_0, m_1, \dots, m_J) | T = t_0, M_1(t_0) = m_1, M_2(t_0) = m_2\} d^J F_{M_1(t_1), \dots, M_J(t_J)}(m_1, \dots, m_J) \\
 &\quad \text{by (7)} \\
 &= \dots \\
 &= \int_{n=J}^{\dots} \int E\{Y(t_0, m_1, \dots, m_J) | T = t_0, M_1(t_0) = m_1, \dots, M_J(t_0) = m_J\} d^J F_{M_1(t_1), \dots, M_J(t_J)}(m_1, \dots, m_J) \\
 &\quad \text{by (7)} \\
 &= \int_{n=J}^{\dots} \int E\{Y | T = t_0, M_1 = m_1, \dots, M_J = m_J\} d^J F_{M_1(t_1), \dots, M_J(t_J)}(m_1, \dots, m_J) \quad \text{Consistency}
 \end{aligned}$$

So formula (8) holds.

Acknowledgements

The authors would like to thank Dr. Lynn Singer for providing access to the longitudinal cohort of VLBW and NBW adolescents, supported by the Maternal and Child Health Program, Health Resources and Services Administration, Department of Health and Human Services (grant numbers MC-390592, MC-00127, and MC-00334). Support for this research was provided in part by the National Institute of Dental and Craniofacial Research, National Institutes of Health Research (grant numbers R01DE022674 (J. Albert) and R21-DE16469 (S. Nelson)).

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