

# Digital Self-Calibration Technique Based on 14-Bit SAR ADC\*

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**Abstract:** An error correction technique to achieve a 14-bit successive approximation register analog-to-digital converter (SAR ADC) is proposed. A tunable split capacitor is designed to eliminate the mismatches caused by parasitic capacitors. The linearity error of capacitor array caused by process mismatch is calibrated by a novel calibration capacitor array that can improve the sampling rate. The dual-comparator topology ensures both the speed and precision of the ADC. The simulation results show that the SAR ADC after calibration achieves 83.07 dB SNDR and 13.5 bit ENOB at 500 kilosamples/s.

**Keywords:** SAR ADC; capacitor mismatch; error correction technique; split capacitor DAC

The successive approximation register analog-to-digital converter (SAR ADC) with comprehensive advantages of low power consumption and moderate resolution<sup>[1]</sup>, has been widely used in modern very large scale integration (VLSI) and system on chip (SoC)<sup>[2]</sup>. However, at resolutions of 10 bit and beyond, the precision of the SAR ADC is limited by the linearity error caused by parasitic capacitors<sup>[3]</sup> and process mismatch<sup>[4,5]</sup>. Currently, the main method to improve the precision of the SAR ADC is to use digital calibration technique<sup>[6-9]</sup>. This paper presents an error correction method based on a 14-bit SAR ADC to correct the mismatches of the main digital-to-analog converter (DAC). The split capacitor is digitally tuned to eliminate the mismatches caused by parasitic capacitors. A novel calibration capacitor array is used to improve the sampling rate. The dual-comparator topology of ADC ensures the speed and precision.

## 1 Principle

The linearity error of the main DAC is mainly due to two factors, namely parasitic effect caused by split capacitors and capacitor mismatch caused by manufacture process.

Fig.1 shows the structure of the proposed main DAC, which is a 14-bit split capacitor array designed with the high 6-bit, middle 4-bit, and low 4-bit arrays.  $C_{p1}$

is the parasitic capacitor caused by the split capacitor  $C_b$ , while  $C_{p2}$  is the parasitic capacitor in the middle arrays<sup>[10]</sup>. The mismatch caused by  $C_a$  is negligible<sup>[11]</sup>. In the ideal condition with no parasitic capacitors, the equivalent capacitor  $C_H$  from  $V_H$  to ground is 4 080 C/4 081 when the low-bit capacitors are all grounded. Taking  $C_{p1}$  and  $C_{p2}$  into consideration,

$$C_H = (4\,080\,C + 3\,825\,C_{p1} + 240\,C_{p1}\,C_{p2}) / (4\,081 + 240\,C_{p1} + 240\,C_{p2}) \quad (1)$$

From Eq.(1), it is obvious that the existence of parasitic capacitors will cause mismatch when ADC converts from high-bit to low-bit capacitors, which leads to serious error to the final value code.

An  $N$ -bit weighted capacitor DAC is shown in Fig.2. Due to the process variation, the capacitors would not completely match with others. The specific calibration principle of process mismatch of capacitors based on the 14-bit SAR ADC is described below. In the sampling phase, as Fig.3 shows, the top plate of high-bit capacitors is connected to  $V_{CM}$ . In addition, the reference voltage  $V_{ref}$  is sampled on all the capacitors except the MSB capacitor  $C_{14}$ . Assuming that the equivalent value of all capacitors except  $C_{14}$  is  $C_Y$ , the voltage on high-bit capacitor array, which is denoted as  $V_{x_n}$ , will be  $V_{CM}$ . Next, in the conversion phase, the charge is redistributed by reversing the switch configuration.

Accepted date: 2012-12-05.

\*Supported by National Science and Technology Major Project of China (No. 2012ZX03004008).

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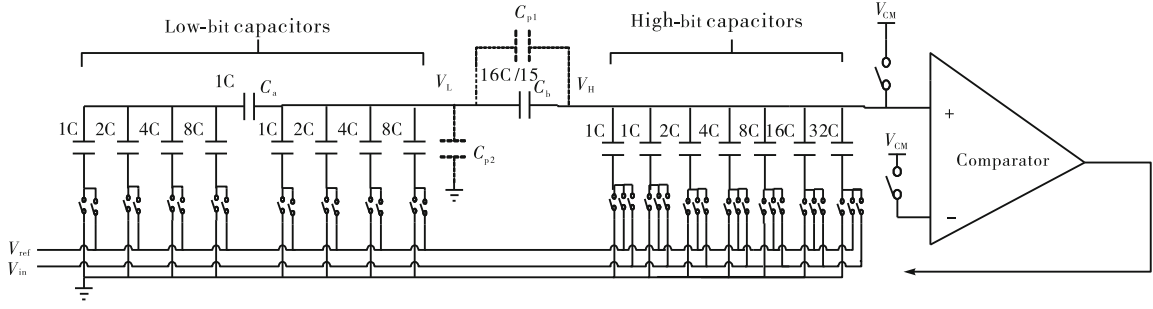


Fig.1 Proposed split main DAC array considering parasitic capacitors

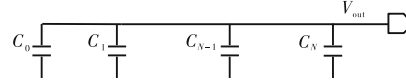
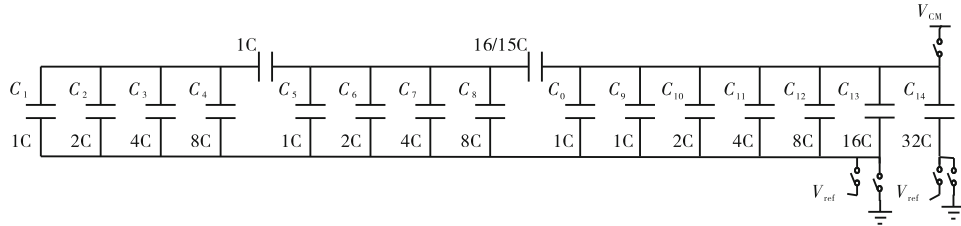


Fig.2 N-bit weighted capacitor DAC


 Fig.3  $C_1$  calibration

In the ideal case with no capacitor mismatch, the charge on the top plate should be unchanged, and the voltage at this moment is still  $V_{CM}$ . However, due to capacitor mismatch, the voltage becomes

$$V'_{X_{14}} = V_{CM} + V_{ref}(C_{14} - C_Y)/(C_{14} + C_Y) \quad (2)$$

The error voltage  $\Delta V_{X_n}$  is the difference between ideal and actual voltage:

$$\Delta V_{X_{14}} = V'_{X_{14}} - V_{X_{14}} = V_{ref}(C_{14} - C_Y)/(C_{14} + C_Y) \quad (3)$$

$$\text{Due to } \sum_{i=0}^{13} 2^{i-1} \sigma_i = -2^{13} \sigma_{14} \quad [12],$$

$$\Delta V_{X_{14}} = \sigma_{14} V_{ref} = 2 V_{\sigma_{14}} \quad (4)$$

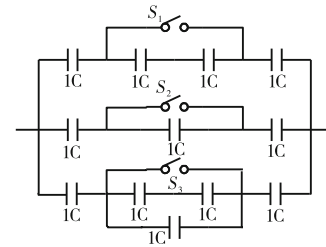
According to the above-mentioned method, the mismatch voltage of the  $i$ th capacitor  $V_{\sigma_i}$  is calculated by

$$V_{\sigma_i} = 1/2(V_{X_i} - \sum_{j=i+1}^{14} V_{\sigma_j}) \quad (5)$$

the mismatch on the split capacitor can greatly affect the precision of ADC. A solution to this problem is to make the split capacitor tunable<sup>[13]</sup>. The schematic of the tunable capacitor  $C_b$  is shown in Fig.4. The value of the split capacitor is given by

$$C_b = [(2 + S_1)^{-1} + (2 + S_2)^{-1} + (2 + S_3)^{-1}]C \quad (6)$$

where the unit capacitor  $C$  is 211 fF; and  $S_1$ ,  $S_2$  and  $S_3$  are 1 or 0.


 Fig.4 Tunable capacitor  $C_b$ 

## 2 Implementation

### 2.1 Calibration of split capacitor

In the ideal condition with no parasitic capacitors, the split capacitor  $C_b$  should be 16C/15 (300 fF) when the unit capacitor of the main DAC is 281 fF. However,

There are 8 combinations of  $S_1$ ,  $S_2$  and  $S_3$  when each of them switches on or off. And for each combination, 300 times Monte Carlo simulations are implemented. Tab.1 presents the simulation results, which indicates that there is always an attenuation capacitor value which is very close to the ideal value (300 fF).

Tab.1 Values of attenuation capacitor after 300 times Monte Carlo simulations

Combination serial No.	1	2	3	4	5	6	7	8
The maximum value / fF	255	284	298	307	320	334	346	375
The minimum value / fF	218	241	249	270	272	298	303	331
The average value / fF	237	263	275	291	299	315	325	353

The calibration principle of the split capacitor  $C_b$  is shown in Fig.5. At the beginning of calibration,  $C_b$  is given a maximum capacitance. All the low-bit capacitors ( $C_1$ — $C_8$ ), all the high-bit capacitors ( $C_9$ — $C_{14}$ ) and the positive terminal of the comparator are connected to  $V_{ref}$ , ground and  $V_{CM}$ , respectively. Then, the positive terminal of the comparator is disconnected from  $V_{CM}$ , and  $C_9$  is switched to  $V_{ref}$ ; besides, all the high-bit ca-

pacitors except  $C_9$  are connected to ground. If  $C_b$  is larger than  $16C/15$ , the weight of the low-bit array will be larger than  $C_9$ , and the output of the comparator is high. So  $C_b$  will be given a smaller value. The above steps are repeated until the comparator output changes. At this time, one tunable capacitance value is selected to offer the best performance.

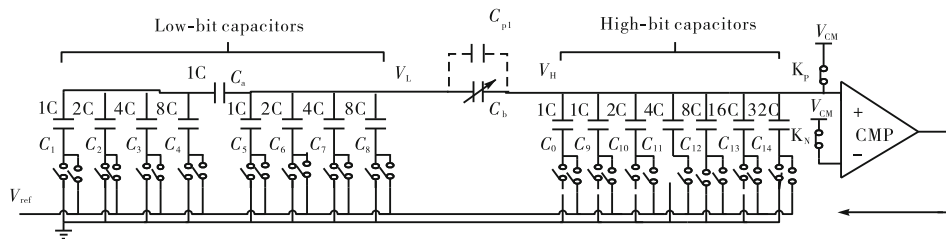


Fig.5 Calibration principle of split capacitor

## 2.2 Calibration of process mismatch of capacitors

The calibration capacitor array consists of multiple capacitor arrays which are shown in Fig.6. The top plate of the calibration capacitor array is connected to the negative terminal of the comparator. Each calibration sub-DAC array corresponds to a capacitor in the main DAC that needs to be calibrated. After all the error voltages are calculated, the compensation phase begins. The calibration sub-DAC is connected to ground when the error voltage of the corresponding capacitor is positive. Otherwise, it is connected to  $V_{ref}$ . Then the negative terminal of the comparator will be disconnected from  $V_{CM}$ . If the comparator judges the result as “H”, the switching status of the sub-DAC remains unchanged. However, if the comparator output is “L”, the switches need revert to the initial state.

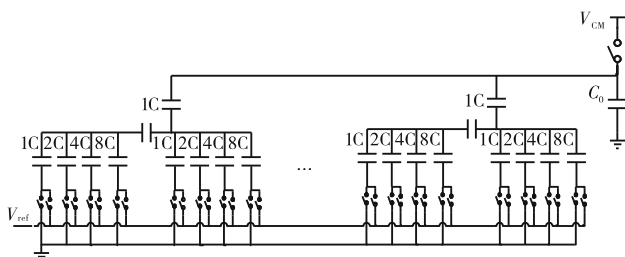


Fig.6 Calibration capacitor array

## 2.3 Implementation of digital calibration technique based on 14-bit SAR ADC

Fig.7 shows the block diagram of the SAR ADC. The main DAC employs segmented architecture with three parts, which reduces the number of unit capacitors<sup>[14]</sup>. The calibration DAC arrays consist of six sub-

DAC arrays with the same structure. The dual-comparator topology ensures the speed and precision. A comparator with high precision is used in the calibration phase. The other comparator, the precision of which is a little lower, is used in the converting phase to ensure the speed of the ADC. At the beginning of the working process, the switch that controls the negative terminal of the comparator is connected to  $V_{CM}$ . Other switches are all connected to ground. Then when the six high bits are being converted, the error-correction voltages should be compensated to the negative terminal of the comparator. The above steps are repeated until the six high bits are all calibrated. Fig.8 shows the timing waveform of the calibration process. The six thick line rectangles show the phase of obtaining the calibration code of the six high bits. The output result of the SAR ADC after calibration is in the oval region.

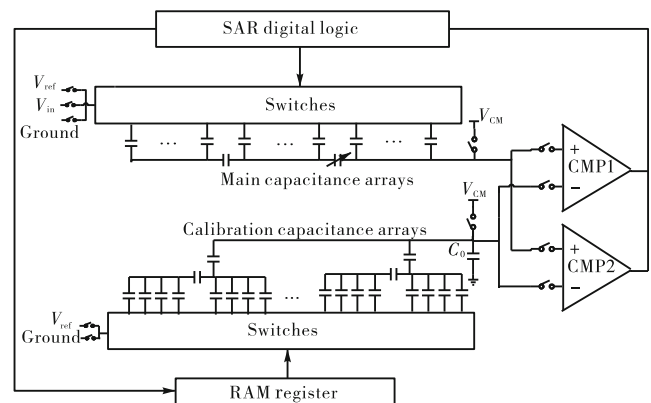


Fig.7 Block diagram of SAR ADC with calibration

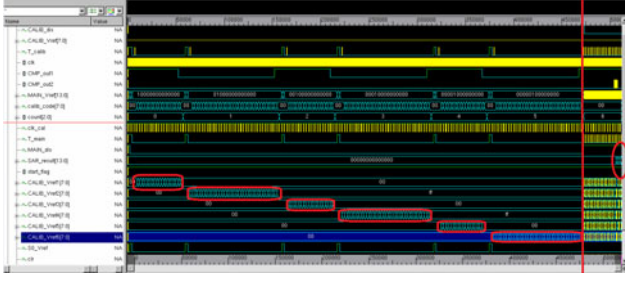
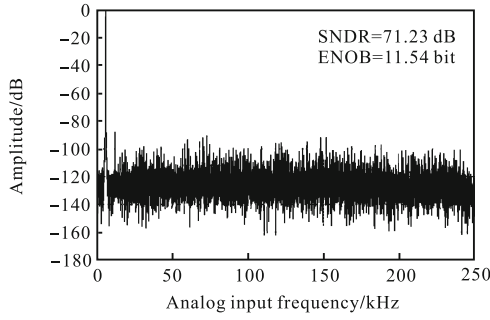


Fig.8 Timing waveform of calibration

### 3 Simulation result

A 14-bit 500 ksamples/s prototype SAR ADC with 0–2.5 V input signal swing was simulated and calibrated in Simulink to demonstrate the effectiveness of the proposed calibration technique. The capacitor mismatch rate  $\sigma$  was set to be 0.5%. Firstly, a 6.17 kHz sine wave was



(a) Before calibration

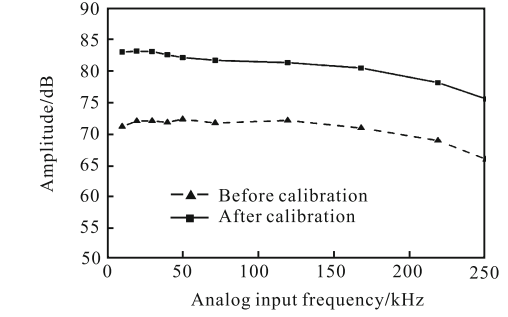
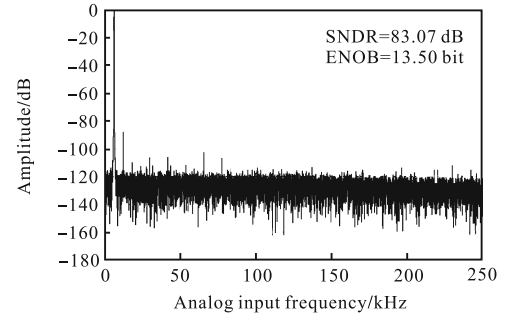


Fig.9 SNDR for various input frequencies at 500 ksamples/s



(b) After calibration

Fig.10 Simulated ADC output spectra at 6.17 kHz input

### 4 Conclusions

The main DAC of the SAR ADC adopts a three-stage discrete structure for reducing the area of capacitor array<sup>[15]</sup>. The calibration DAC arrays consist of six sub-DAC arrays with the same structure, which can increase the speed of calibration at the expense of area relative to the single calibration DAC array. The existing method for calibrating the split capacitor adds an adjustable capacitor in parallel with the lower weight side of the DAC to compensate for mismatches. However, it will bring mismatches to the lower weight side. The method proposed in this paper makes the split capacitor tunable and chooses the value that can offer the best performance, which avoids the defect of the existing method.

A digital calibration technique is proposed based on

a 14-bit SAR ADC. The technique not only eliminates the impact of parasitic capacitor of split capacitor, but also calculates and compensates the mismatch voltage of capacitor array. The ADC was fabricated in Global Foundry 0.35  $\mu\text{m}$  CMOS process (Fig.11). The active area of the ADC was 3.23  $\text{mm}^2$ . All the digital calibration circuits were implemented on a chip measuring 0.68  $\text{mm}^2$ , which was 21% of the ADC area. When the supply volt-

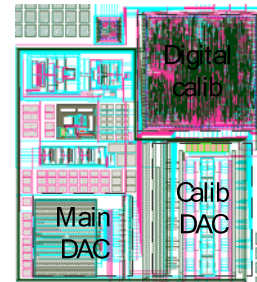


Fig.11 Chip layout

age was 5 V and the reference voltage was 2.5 V, the power consumption of the ADC was 15 mW. The simulation results show that the SAR ADC with calibration achieved ENOB of 13.5 bit at 500 ksamples/s.

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(Editor: Liu Wenge)