

Agenda



- 1) Introduction
- 2) Deliverable 1 - Risk Score Model
- 3) Deliverable 2 - Accident Severity Prediction
- 4) Conclusions and Next Steps

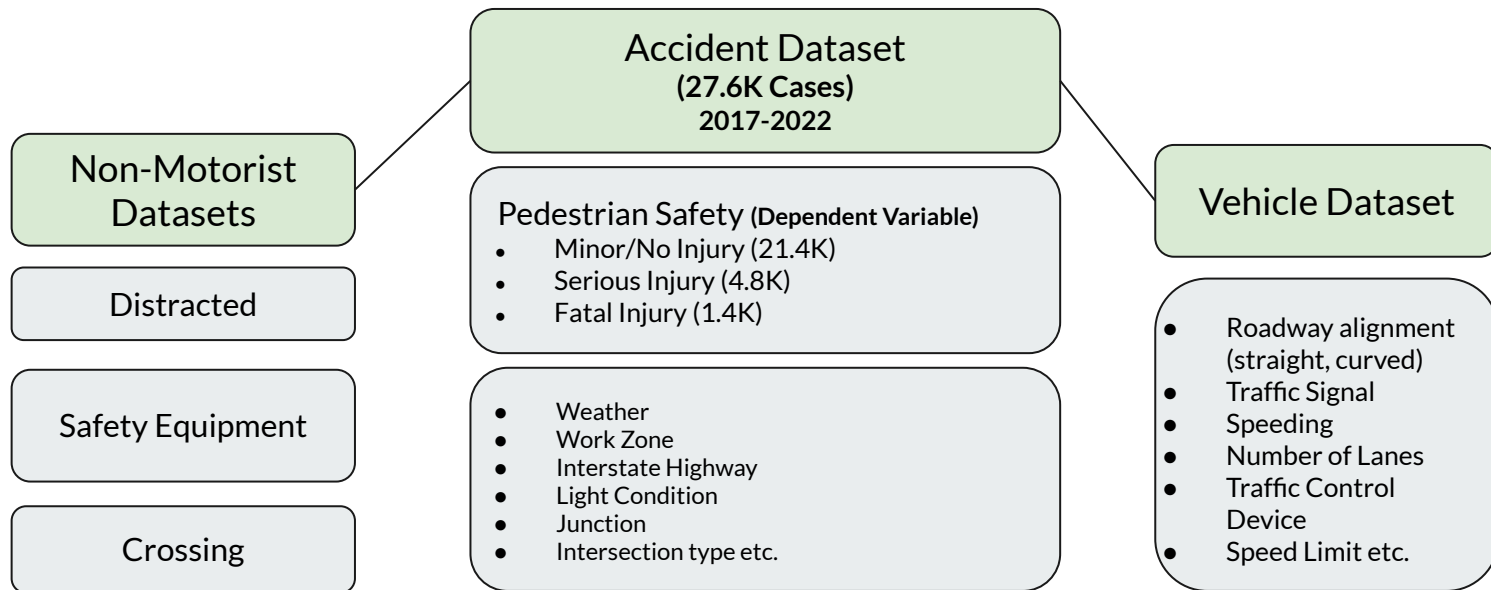
Deliverable 1



CRSS Dataset - Pedestrian Risk Score Model

CRSS - Crash Report Sampling System

“CRSS is a sample of police-reported crashes involving all types of motor vehicles, pedestrians, and cyclists, ranging from property-damage-only crashes to those that result in fatalities.”



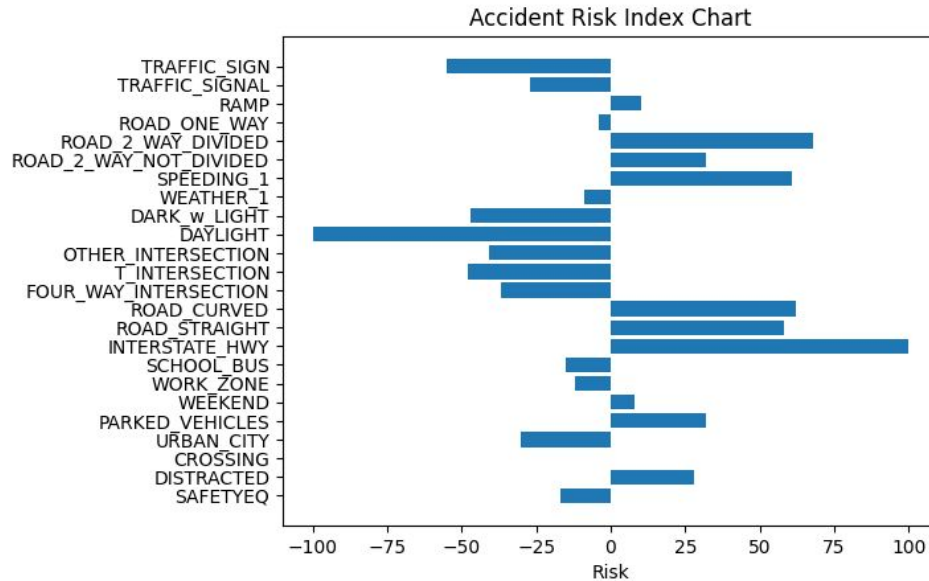
CRSS - Approach 1

- **Binary Dependent Variable** -> 0 for minor/no injury and 1 for fatal/severe injury
- **Removed majority of the missing values** : Size dropped from 27.5K cases to 14.3K
- **One hot encoded all categorical variables**

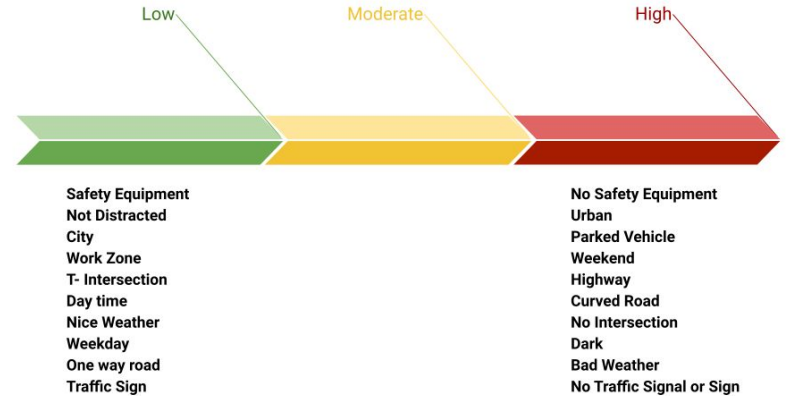
Model Results

Model - Test Dataset	F1 Score	AUC score
★ Logistic Regression - balanced	0.52	0.73
Decision Tree w/ Depth 10	0.3	0.69
Bagging	0.32	0.68
Random Forest	0.32	0.69
Random Forest - balanced_subsamples	0.47	0.68
Random Forest - Upsampling	0.49	0.68
Random Forest - Downsampling	0.48	0.67
Gradientboost-Upsampled	0.52	0.72
Support Vector Machine-Upsampled	0.48	0.71

CRSS - Approach 1



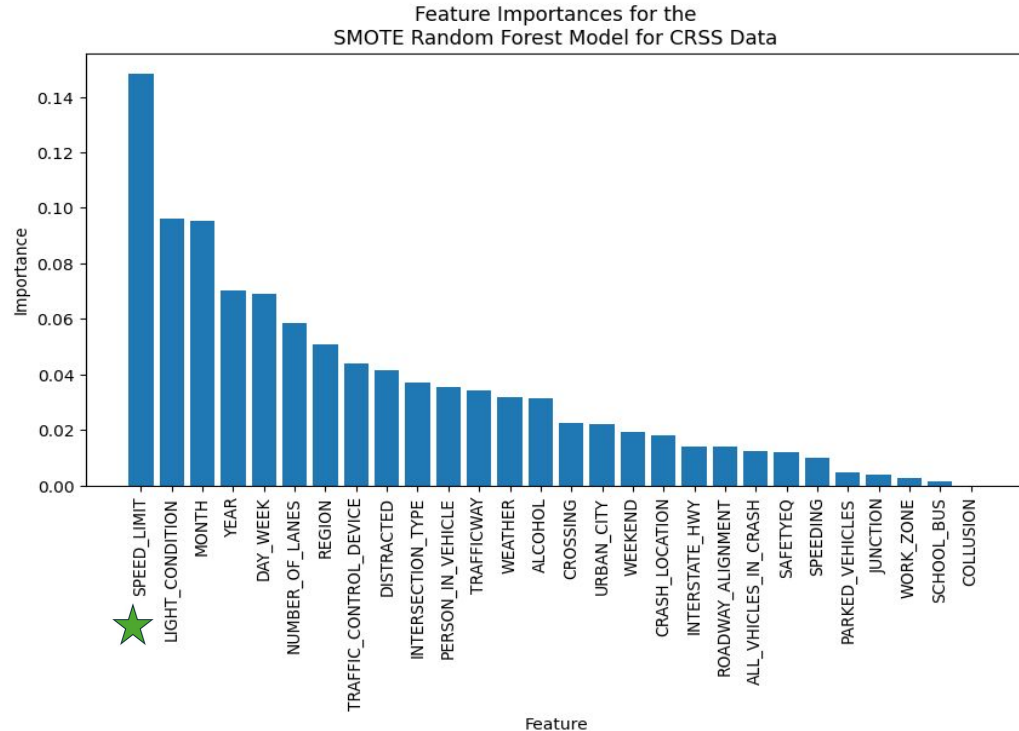
Risk Categorization



CRSS - Approach 2

- **Ternary Dependent Variable:**
 - 0 for minor or no injury
 - 1 for severe injury
 - 2 for fatal
- Instead of removing missing values in approach 1, they were imputed

Model	Test Accuracy
Random Forest Non-SMOTE	77.63% ★
Random Forest SMOTE	75.42%
Neural Network Non-SMOTE	77.18%
Neural Network SMOTE	62.36%



Approach 2: Neural Network Models

- Configuration:
 - 2 dense layers
 - 1 batch normalization layer in between
- Non-SMOTE Model:
 - Predicted classes 1 & 2 poorly
- SMOTE Model:
 - Better at predicting classes 1 & 2
- Both versions predicted class 0 better than classes 1 & 2

Model: "sequential"		
Layer (type)	Output Shape	Param #
dense (Dense)	(None, 32)	928
batch_normalization (Batch Normalization)	(None, 32)	128
dense_1 (Dense)	(None, 3)	99
Total params: 1,155		
Trainable params: 1,091		
Non-trainable params: 64		

Deliverable 2

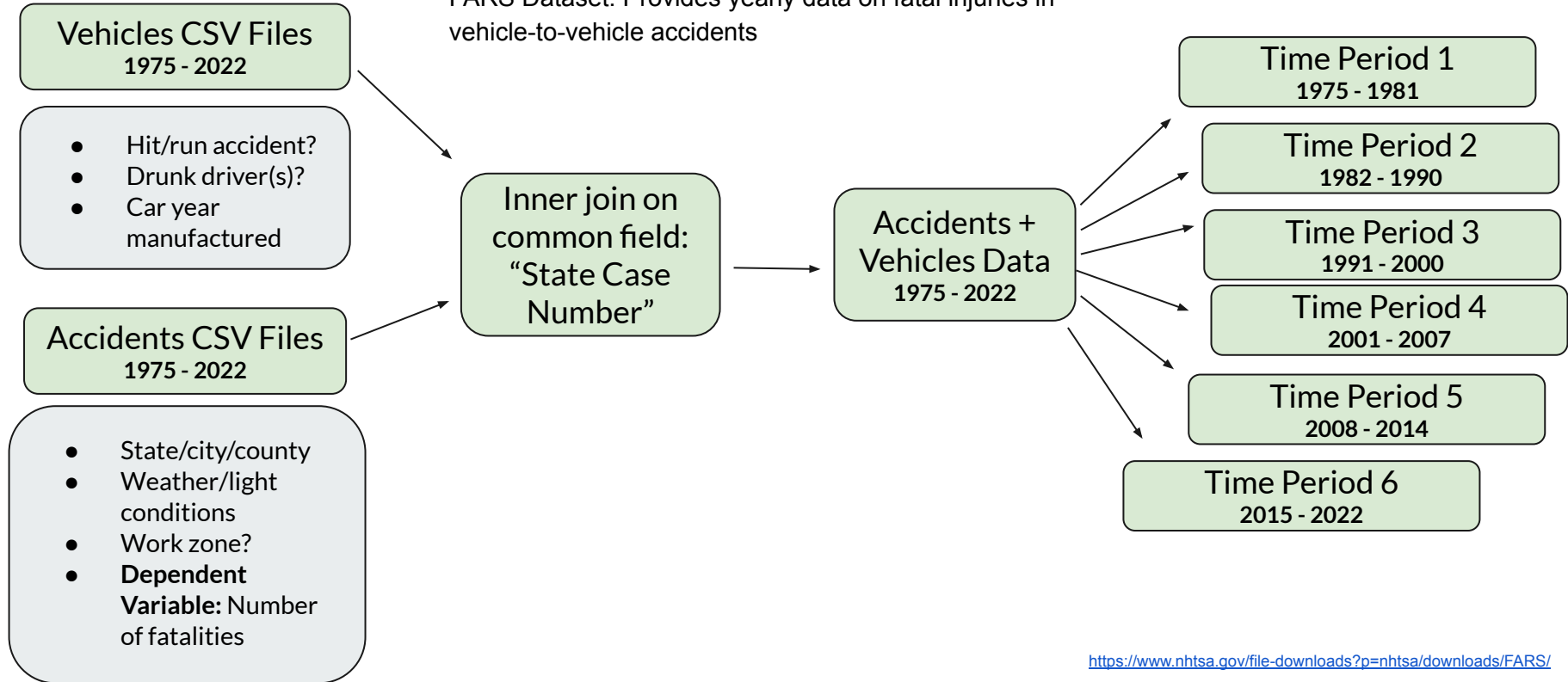


Accident Severity Prediction:

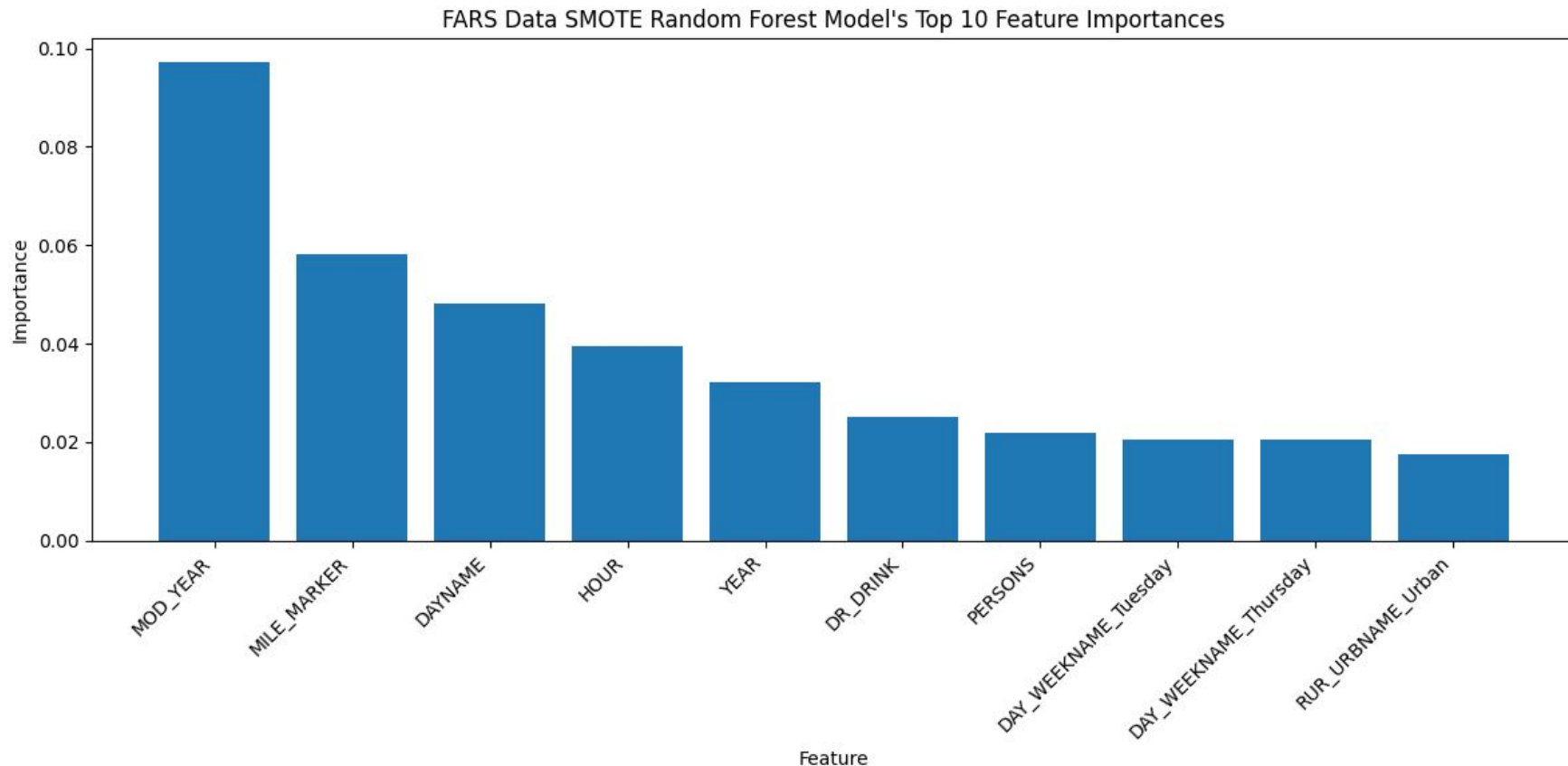
- Part 1: FARS Dataset - Pedestrian Injury Prediction

FARS - Fatality Analysis Reporting System

FARS Dataset: Provides yearly data on fatal injuries in vehicle-to-vehicle accidents



FARS Variable Importance Chart: 2015 - 2022



Part 2 - Vehicle-to-Vehicle Traffic Severity Modeling



- **Dependent Variable “Severity”** -> classes 1 - 4
- **Datetime Breakdown** -> Datetime becomes year, month, day, hour, minute columns
- **Encode categorical variables**
- **Removed redundant columns**
 - Windchill, when we already have temperature
 - End Latitude
- **Scaled numerical values**

Model	Accuracy	Precision	Recall	F1
LightGBM	0.75	0.75	0.75	0.75
XGB	0.76	0.76	0.76	0.76
MLP	0.72	0.7152	0.7204	0.716
KNN	0.48	0.47	0.48	0.47
LSTM	0.62	0.62	0.63	0.62
GRU	0.63	0.64	0.64	0.64



Model Results for Downsampled Data



Conclusions and Next Steps

Conclusions



1. Overall Impact - Deliverable 1:

- CRSS models identified key factors that impact accident severity using variable importance plots
- Models can predict accident risks, urging organizations to improve road safety
- **Recommendations:**
 - Decrease speed limit for high risk roads
 - Increase lighting on rural highways. The lighting condition was ranked 2nd most important

Conclusions



1. Overall Impact - Deliverable 2A:

- a. Like CRSS models, FARS models' variable importance plots are crucial to predicting the number of fatalities, so organizations can prioritize certain factors
- b. **Recommendations:** Keep US fleet up to date, year of manufacture and mile marker (specific section) on the road were important factors.

2. Overall Impact - Deliverable 2B:

- a. Advanced models like XGBoost revealed critical predictive road features such as 'Amenities', Traffic Signal', and 'Station'
- b. **Recommendations:** Improve traffic signals and infrastructure near high-traffic amenities to reduce severe accidents.