
X-Ray Data Booklet

4.3 GRATINGS AND MONOCHROMATORS

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A. DIFFRACTION PROPERTIES

A.1 Notation and sign convention

We adopt the notation of Fig. 4.6 in which α and β have opposite signs if they are on opposite sides of the normal.

A.2 Grating equation

The grating equation may be written

$$m\lambda = d_0(\sin \alpha + \sin \beta). \quad (1)$$

The angles α and β are both arbitrary, so it is possible to impose various conditions relating them. If this is done, then for each λ , there will be a unique α and β . The following conditions are used:

(I) *ON-BLAZE CONDITION:*

$$\alpha + \beta = 2\theta_B, \quad (2)$$

where θ_B is the blaze angle (the angle of the sawtooth). The grating equation is then

$$m\lambda = 2d_0 \sin \theta_B \cos(\beta + \theta_B). \quad (3)$$

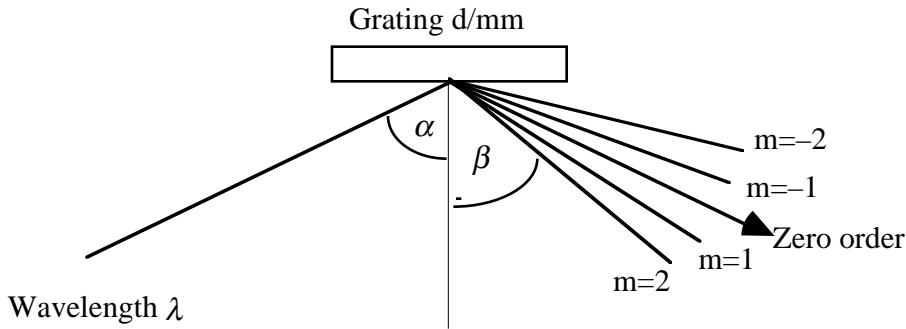


Fig. 4-6. Grating equation notation.

(II) *FIXED IN AND OUT DIRECTIONS:*

$$\alpha - \beta = 2\theta, \quad (4)$$

where 2θ is the (constant) included angle. The grating equation is then

$$m\lambda = 2d_0 \cos\theta \sin(\theta + \beta). \quad (5)$$

In this case, the wavelength scan ends when α or β reaches 90° , which occurs at the horizon wavelength $\lambda_H = 2d_0 \cos^2 \theta$

(III) *CONSTANT INCIDENCE ANGLE: EQUATION (1) GIVES β DIRECTLY.*(IV) *CONSTANT FOCAL DISTANCE (OF A PLANE GRATING):*

$$\frac{\cos\beta}{\cos\alpha} = \text{a constant } c_{ff}, \quad (6)$$

leading to a grating equation

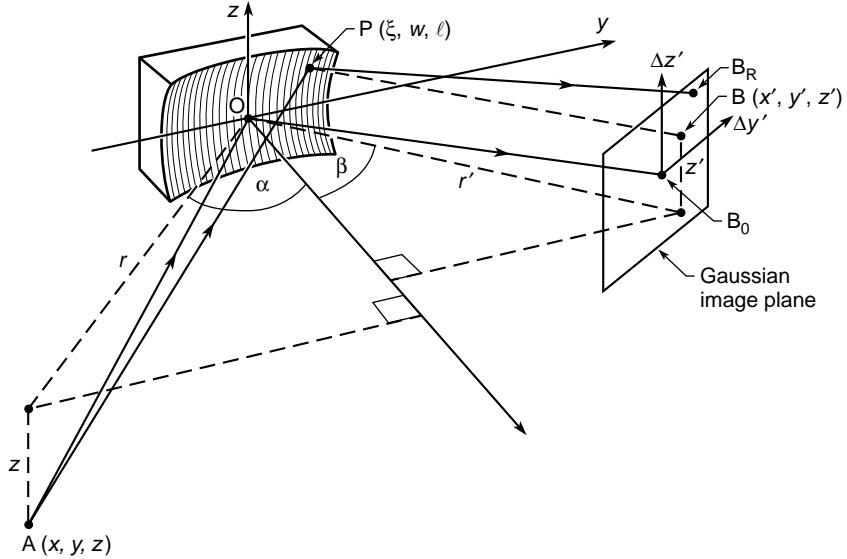
$$1 - \left(\frac{m\lambda}{d_0} - \sin\beta \right)^2 = \frac{\cos^2\beta}{c_{ff}^2} \quad (7)$$

Equations (3), (5), and (7) give β (and thence α) for any λ . Examples of the above α - β relationships are as follows:

- (i) Kunz et al. plane-grating monochromator (PGM) [1], Hunter et al. double PGM[2], collimated-light SX700 [3]
- (ii) Toroidal-grating monochromators (TGMs) [4, 5], spherical-grating monochromators (SGMs, “Dragon” system) [6], Seya-Namioka [7, 8] most aberration-reduced holographic SGMs [9], variable-angle SGM[10], PGMs [11, 12, 13]
- (iii) Spectrographs, “Grasshopper” monochromator [14]
- (iv) SX700 PGM [15] and variants [10, 16, 3]

B. FOCUSING PROPERTIES [17]

The study of diffraction gratings[18, 19] goes back more than a century and has included plane, spherical [20, 21, 22], toroidal [23] and ellipsoidal[24] surfaces and groove patterns made by classical (“Rowland”) ruling [25], holography [26, 27, 28] and variably-spaced ruling [29]. In recent years the optical design possibilities of holographic groove patterns [30, 31, 32] and variably-spaced rulings [13] have been extensively developed. Following normal practice, we provide an analysis of the imaging properties of gratings by means of the path function F [32]. For this purpose we use the notation of Fig. 4.7, in which the zeroth groove (of width d_0) passes through the grating pole O, while the n th groove passes through the variable point P(w, l). The holographic groove pattern is supposed to be made using two coherent point sources C and D with cylindrical polar coordinates (r_C, γ, z_C) , (r_D, δ, z_D) relative to O. The lower (upper) sign in eq. (9) refers



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Fig. 4-7*. Focusing properties notation.

to C and D both real or both virtual (one real and one virtual) for which case the equiphase surfaces are confocal hyperboloids (ellipses) of revolution about CD. The grating with varied line spacing $d(w)$ is assumed to be ruled according to $d(w) = d_0(1 + v_1w + v_2w^2 + \dots)$. We consider all the gratings to be ruled on the general surface $x = \sum_{ij} a_{ij} w l$ and the a_{ij} coefficients[33] are given for the important cases in Tables 1 and 2.

B.1 Calculation of the path function F

F is expressed as

$$F = \sum_{ijk} F_{ijk} w^i l^j \quad (8)$$

where $F_{ijk} = z^k C_{ijk}(\alpha, r) + z'^k C_{ijk}(\beta, r') + \frac{m\lambda}{d_0} f_{ijk}$.

and the f_{ijk} term, originating from the groove pattern, is given by one of the following expressions.

$$f_{ijk} = \begin{cases} \delta_{(i-1)jk} & \text{Rowland} \\ \frac{d_0}{\lambda_0} \left\{ z_C^k C_{ijk}(\gamma, r_C) \pm z_D^k C_{ijk}(\delta, r_D) \right\} & \text{holographic} \\ n_{ijk} & \text{varied line spacing} \end{cases} \quad (9)$$

The coefficient F_{ijk} is related to the strength of the i,j aberration of the wavefront diffracted by the grating. The coefficients C_{ijk} and n_{ijk} are given up to sixth order in Tables 3 and 4 in which the following notation is used:

$$T = T(r, \alpha) = \frac{\cos^2 \alpha}{r} - 2a_{20} \cos \alpha \quad S = S(r, \alpha) = \frac{1}{r} - 2a_{02} \cos \alpha \quad (10)$$

Table 1: Ellipse coefficients Q_{ij} from which the a_{ij} 's are obtained^a[33]

j	0	1	2	3	4	5	6
i							
0	0	0	1	0	$C/4$	0	$C^2/8$
1	0	0	A	0	$3AC/4$	0	*
2	1	0	$(2A^2 + C)/2$	0	$3C(4A^2 + C)/8$	0	*
3	A	0	$A(2A^2 + 3C)/2$	0	*	0	*
4	$(4A^2 + C)/4$	0	$(8A^4 + 24A^2C + 3C^2)/8$	0	*	0	*
5	$A(4A^2 + 3C)/4$	0	*	0	*	0	*
6	$(8A^4 + 12A^2C + C^2)/8$	0	*	0	*	0	*

^aIf r , r' and θ are the object distance, image distance, and incidence angle to the normal, respectively, then

$$a_{ij} = a_{20} \frac{Q_{ij}}{\cos^j \theta} \quad \text{where} \quad a_{20} = \frac{\cos \theta}{4} \left(\frac{1}{r} + \frac{1}{r'} \right), \quad A = \frac{\sin \theta}{2} \left(\frac{1}{r} - \frac{1}{r'} \right), \quad C = A^2 + \frac{1}{rr'}$$

The a_{ij} 's for spheres, circular cylinders, paraboloids and hyperboloids can also be obtained from Tables 1 and 2 by suitable choices of the input parameters r , r' and θ .

Table 2: Toroid^a a_{ij} 's [33]

j	0	1	2	3	4	5	6
i							
0	0	0	$1/(2\rho)$	0	$1/(8R^3)$	0	$1/(16\rho^5)$
1	0	0	0	0	0	0	*
2	$1/(2R)$	0	$1/(4\rho R^2)$	0	$(2\rho + R)/(16\rho^3 R^3)$	0	*
3	0	0	0	0	*	0	*
4	$1/(8R^3)$	0	$3/(16\rho R^4)$	0	*	0	*
5	0	0	*	0	*	0	*
6	$1/(16R^5)$	0	*	0	*	0	*

^a R and ρ are the major and minor radii of the bicycle-tire toroid we are considering.

Table 3: Coefficients C_{ijk} of the expansion of F^a

$C_{011} = -\frac{1}{r}$	$C_{020} = \frac{S}{2}$
$C_{022} = -\frac{S}{4r^2} - \frac{1}{2r^3}$	$C_{031} = \frac{S}{2r^2}$
$C_{040} = \frac{4a_{02}^2 - S^2}{8r} - a_{04} \cos \alpha$	$C_{042} = \frac{a_{04} \cos \alpha}{2r^2} + \frac{3S^2 - 4a_{02}^2}{16r^3} + \frac{3S}{4r^4}$
$C_{100} = -\sin \alpha$	$C_{102} = \frac{\sin \alpha}{2r^2}$
$C_{111} = -\frac{\sin \alpha}{r^2}$	$C_{120} = \frac{S \sin \alpha}{2r} - a_{12} \cos \alpha$
$C_{131} = -\frac{a_{12} \cos \alpha}{r^2} + \frac{3S \sin \alpha}{2r^3}$	$C_{122} = \frac{a_{12} \cos \alpha}{2r^2} - \frac{3S \sin \alpha}{4r^3} - \frac{3 \sin \alpha}{2r^4}$
$C_{200} = \frac{T}{2}$	$C_{140} = -a_{14} \cos \alpha + \frac{1}{2r} (2a_{02}a_{12} + a_{12}S \cos \alpha - a_{04} \sin 2\alpha) + \frac{\sin \alpha}{8r^2} (4a_{02}^2 - 3S^2)$
$C_{202} = -\frac{T}{4r^2} + \frac{\sin^2 \alpha}{2r^3}$	$C_{211} = \frac{T}{2r^2} - \frac{\sin^2 \alpha}{r^3}$
$C_{013} = \frac{1}{2r^3}$	$C_{300} = -a_{30} \cos \alpha + \frac{T \sin \alpha}{2r}$
$C_{220} = -a_{22} \cos \alpha + \frac{1}{4r} (4a_{20}a_{02} - TS - 2a_{12} \sin 2\alpha) + \frac{S \sin^2 \alpha}{2r^2}$	
$C_{222} = \frac{1}{2r^2} a_{22} \cos \alpha + \frac{1}{8r^3} (3ST - 4a_{02}a_{20} + 6a_{12} \sin 2\alpha) + \frac{3}{4r^4} (T - 2S \sin^2 \alpha) - \frac{3 \sin^2 \alpha}{r^5}$	
$C_{231} = -\frac{1}{r^2} a_{22} \cos \alpha + \frac{1}{4r^3} (-3ST + 4a_{02}a_{20} - 6a_{12} \sin 2\alpha) + \frac{3S \sin^2 \alpha}{r^4}$	
$C_{240} = -a_{24} \cos \alpha + \frac{1}{2r} (a_{12}^2 \sin^2 \alpha + 2a_{04}a_{20} + a_{22}S \cos \alpha + a_{04}T \cos \alpha - a_{14} \sin 2\alpha + 2a_{02}a_{22})$ + $\frac{1}{16r^2} (-4a_{02}^2 T - 8a_{02}a_{20}S + 12a_{12}S \sin 2\alpha + 3TS^2 + 16a_{02}a_{12} \sin \alpha - 8a_{04} \sin 2\alpha) + \frac{\sin^2 \alpha}{4r^3} (2a_{02}^2 - 3S^2)$	
$C_{302} = \frac{a_{30} \cos \alpha}{2r^2} - \frac{3T \sin \alpha}{4r^3} + \frac{\sin^3 \alpha}{2r^4}$	
$C_{311} = -\frac{a_{30} \cos \alpha}{r^2} + \frac{3T \sin \alpha}{2r^3} - \frac{\sin^3 \alpha}{r^4}$	

***Table 3:** Coefficients C_{ijk} of the expansion of F^a (continued)

$$\begin{aligned}
C_{320} = & -a_{32} \cos \alpha + \frac{1}{2r} (2a_{20}a_{12} + 2a_{30}a_{02} + a_{30}S \cos \alpha + a_{12}T \cos \alpha - a_{22} \sin 2\alpha) \\
& + \frac{1}{4r^2} (4a_{20}a_{02} \sin \alpha - 3ST \sin \alpha - 4a_{12} \cos \alpha \sin^2 \alpha) + \frac{S \sin^3 \alpha}{2r^3} \\
C_{400} = & -a_{40} \cos \alpha + \frac{1}{8r} (4a_{20}^2 - T^2 - 4a_{30} \sin 2\alpha) + \frac{T \sin^2 \alpha}{2r^2} \\
C_{402} = & -\frac{1}{16r^3} (4a_{20}^2 + 3T^2 + 12a_{30} \sin 2\alpha) + \frac{a_{40} \cos \alpha}{2r^2} - \frac{3T \sin^2 \alpha}{2r^4} + \frac{\sin^4 \alpha}{2r^5} \\
C_{411} = & -\frac{a_{40} \cos \alpha}{r^2} + \frac{1}{8r^3} (4a_{20}^2 - 3T^2 - 12a_{30} \sin 2\alpha) + \frac{3T \sin^2 \alpha}{r^4} - \frac{\sin^4 \alpha}{r^5} \\
C_{420} = & -a_{42} \cos \alpha + \frac{1}{2r} (2a_{20}a_{22} + 2a_{12}a_{30} \sin^2 \alpha + 2a_{02}a_{40} - a_{32} \sin 2\alpha + a_{40}S \cos \alpha + a_{22}T \cos \alpha) \\
& + \frac{1}{16r^2} (-4a_{20}^2S - 8a_{02}a_{20}T + 3ST^2 + 12 \sin 2\alpha(a_{30}S + a_{12}T) + 8 \sin \alpha(2a_{02}a_{30} - 2a_{22} \sin 2\alpha + 2a_{12}a_{20})) \\
& + \frac{1}{2r^3} (2a_{02}a_{20} \sin^2 \alpha - 3ST \sin^2 \alpha - 2a_{12} \cos \alpha \sin^3 \alpha) + \frac{S \sin^4 \alpha}{2r^4} \\
C_{500} = & -a_{50} \cos \alpha + \frac{1}{2r} (2a_{20}a_{30} + a_{30}T \cos \alpha - a_{40} \sin 2\alpha) + \frac{\sin \alpha}{2r^2} (a_{20}^2 - a_{30} \sin 2\alpha) - \frac{3T^2 \sin \alpha}{8r^2} + \frac{T \sin^3 \alpha}{2r^3} \\
C_{600} = & -a_{60} \cos \alpha + \frac{1}{2r} (a_{30}^2 \sin^2 \alpha + 2a_{20}a_{40} + a_{40}T \cos \alpha - a_{50} \sin 2\alpha) \\
& + \frac{1}{16r^2} (-4a_{20}^2T + T^3 + 16a_{20}a_{30} \sin \alpha + 12a_{30}T \sin 2\alpha - 16a_{40} \cos \alpha \sin^2 \alpha) \\
& + \frac{1}{4r^3} (2a_{20}^2 \sin^2 \alpha - 3T^2 \sin^2 \alpha - 4a_{30} \cos \alpha \sin^3 \alpha) + \frac{T \sin^4 \alpha}{2r^4}
\end{aligned}$$

^aThe coefficients for which $i \leq 6, j \leq 4, k \leq 2, i + j + k \leq 6, j + k = \text{even}$ are included in this table. The only addition to those is C_{013} , which has some interest, because, when the system is specialized to be symmetrical about the x axis, it represents a Seidel aberration, namely distortion.

Table 4: Coefficients n_{ijk} of the expansion of F for a grating with variable line spacing

$n_{ijk} = 0$ for $j, k \neq 0$	
$n_{100} = 1$	$n_{400} = (-v_1^3 + 2v_1v_2 - v_3)/4$
$n_{200} = -v_1/2$	$n_{500} = (v_1^4 - 3v_1^2v_2 + v_2^2 + 2v_1v_3 - v_4)/5$
$n_{300} = (v_1^2 - v_2)/3$	$n_{600} = (-v_1^5 + 4v_1^3v_2 - 3v_1v_2^2 - 3v_1^2v_3 + 2v_2v_3 + 2v_1v_4 - v_5)/6$

B.2 Determination of the Gaussian image point

By definition the principal ray AOB₀ arrives at the Gaussian image point B₀(r'_0, β₀, z'_0) (Fig. 4.7) and its direction is given by Fermat's principle which implies

$$[\partial F/\partial w]_{w=0, l=0} = 0, \quad [\partial F/\partial l]_{w=0, l=0} = 0 \text{ whence}$$

$$\frac{m\lambda}{d_0} = \sin \alpha + \sin \beta_0, \quad \frac{z}{r} + \frac{z'_0}{r'_0} = 0, \quad (11)$$

The tangential focal distance r'_0 is obtained by setting the focusing term F₂₀₀ equal to zero and is given by

$$T(r, \alpha) + T(r'_0, \beta_0) = \begin{cases} 0 & \text{Rowland} \\ -\frac{m\lambda}{\lambda_0} \{T(r_C, \gamma) \pm T(r_D, \delta)\} & \text{holographic} \\ \frac{v_1 m \lambda}{d_0} & \text{varied line spacing} \end{cases} \quad (12)$$

Equations (11) and (12) determine the Gaussian image point B₀, and in combination with the sagittal focusing condition (F₀₂₀=0), describe the focusing properties of grating systems under the paraxial approximation.

For a Rowland spherical grating the focusing condition (Eq. (12)) is

$$\left(\frac{\cos^2 \alpha}{r} - \frac{\cos \alpha}{R} \right) + \left(\frac{\cos^2 \beta}{r'_0} - \frac{\cos \beta}{R} \right) = 0 \quad (13)$$

which has important special cases. (i) plane grating, R = ∞ implying r'_0 = -r cos² α / cos² β, (ii) object and image on the Rowland circle, or r = R cos α, r'_0 = R cos β and M = 1 and (iii) β=90° (Wadsworth condition). The focal distances of TGMs and SGMs are also determined by eq. (13).

B.3 Calculation of ray aberrations

In an aberrated system, the outgoing ray will arrive at the Gaussian image plane at a point B_R displaced from the Gaussian image point B_0 by the ray aberrations $\Delta y'$ and $\Delta z'$ (Fig. 4.7). The latter are given by [34, 35, 36]

$$\Delta y' = \frac{r'_0}{\cos \beta_0} \frac{\partial F}{\partial w}, \quad \Delta z' = r'_0 \frac{\partial F}{\partial l}, \quad (14)$$

where F is to be evaluated for $A = (r, \alpha, z)$, $B = (r'_0, \beta_0, z'_0)$. By means of the expansion of F , these equations allow the ray aberrations to be calculated separately for each aberration type.

$$\Delta y'_{ijk} = \frac{r'_0}{\cos \beta_0} F_{ijk} i w^{i-1} l^j, \quad \Delta z'_{ijk} = r'_0 F_{ijk} w^i j l^{j-1} \quad . \quad (15)$$

Moreover, provided the aberrations are not too large, they are additive, so that they may either reinforce or cancel.

C. DISPERSION PROPERTIES

C.1 Angular dispersion

$$\left(\frac{\partial \lambda}{\partial \beta} \right)_\alpha = \frac{d \cos \beta}{m} \quad (16)$$

C.2 Reciprocal linear dispersion

$$\left(\frac{\partial \lambda}{\partial (\Delta y')} \right)_\alpha = \frac{d \cos \beta}{mr'} \equiv \frac{10^{-3} d [\text{\AA}] \cos \beta}{mr' [\text{m}]} \text{\AA/mm}, \quad (17)$$

C.3 Magnification (M)

$$M(\lambda) = \frac{\cos \alpha}{\cos \beta} \frac{r'}{r}. \quad (18)$$

C.4 Phase-space acceptance (ε)

$$\varepsilon = N \Delta \lambda_{S_1} = N \Delta \lambda_{S_2} \quad (\text{assuming } S_2 = M S_1) \quad (19)$$

where N is the number of participating grooves.

D. RESOLUTION PROPERTIES

The following are the main contributions to the width of the instrumental line spread function. The actual width is the vector sum.

(I) *ENTRANCE SLIT (WIDTH S_1):*

$$\Delta\lambda_{S_1} = \frac{S_1 d \cos \alpha}{mr}. \quad (20)$$

(II) *EXIT SLIT (WIDTH S_2):*

$$\Delta\lambda_{S_2} = \frac{S_2 d \cos \beta}{mr'}. \quad (21)$$

(III) *ABERRATIONS (OF PERFECTLY MADE GRATING):*

$$\Delta\lambda_A = \frac{\Delta y' d \cos \beta}{mr'} = \frac{d}{m} \left(\frac{\partial F}{\partial w} \right). \quad (22)$$

(IV) *SLOPE ERROR $\Delta\phi$ (OF IMPERFECTLY MADE GRATING):*

$$\Delta\lambda_{SE} = \frac{d(\cos \alpha + \cos \beta)\Delta\phi}{m}, \quad (23)$$

Note that, provided the grating is large enough, diffraction at the entrance slit always guarantees a coherent illumination of enough grooves to achieve the slit-width limited resolution and a diffraction contribution to the width need not be added to the above.

1. EFFICIENCY

The most accurate way to calculate grating efficiencies is by the full electromagnetic theory [37, 38] for which a code is available from Neviere. However, approximate scalar-theory calculations are often useful and, in particular, provide a way to choose the groove depth (h) of a laminar grating. According to Bennett [39], the best value of the groove-width-to-period ratio (r) is the one for which the usefully illuminated groove area is equal to the land area. The scalar theory efficiency of a laminar grating with $r=0.5$ is given by [40]

$$E_0 = \frac{R}{4} \left\{ 1 + 2(1-P) \cos \left(\frac{4\pi h \cos \alpha}{\lambda} \right) + (1-P)^2 \right\}$$

$$E_m = \begin{cases} \frac{R}{m^2 \pi^2} \left\{ 1 - 2 \cos Q^+ \cos(Q^- + \delta) + \cos^2 Q^+ \right\} & m = \text{odd} \\ \frac{R}{m^2 \pi^2} \cos^2 Q^+ & m = \text{even} \end{cases}$$

where

$$P = \frac{4h \tan \alpha}{d_0}, \quad Q^\pm = \frac{m\pi h}{d_0} (\tan \alpha \pm \tan \beta), \quad \delta = \frac{2\pi h}{\lambda} (\cos \alpha + \cos \beta) \quad (24)$$

and R is the reflectance at angle $\sqrt{\alpha\beta}$.

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