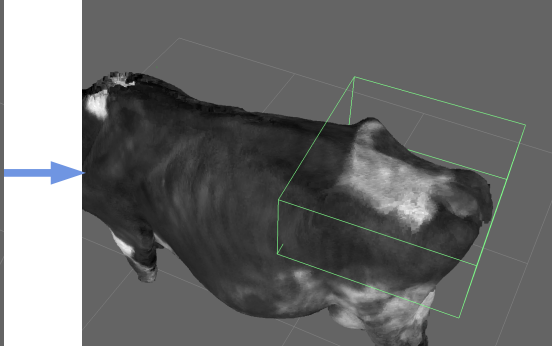
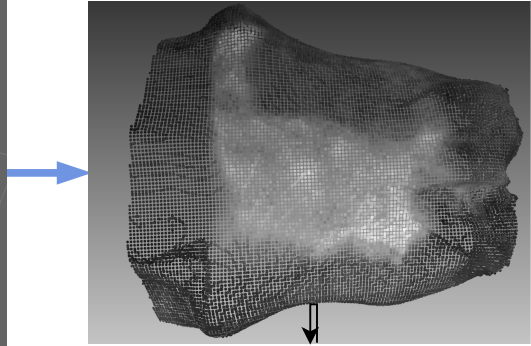


Input cow point cloud



Determine bounding box



Extract rump part point cloud