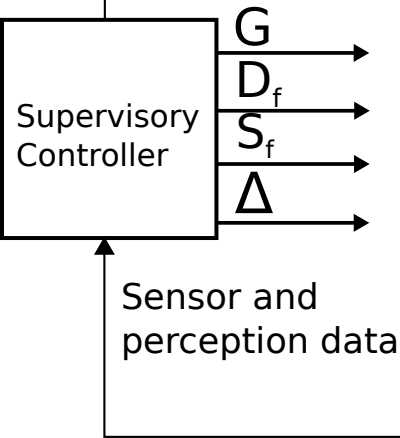


Trajectory data (e.g., step length, step height, shape, etc.)



Robot
+
Environment