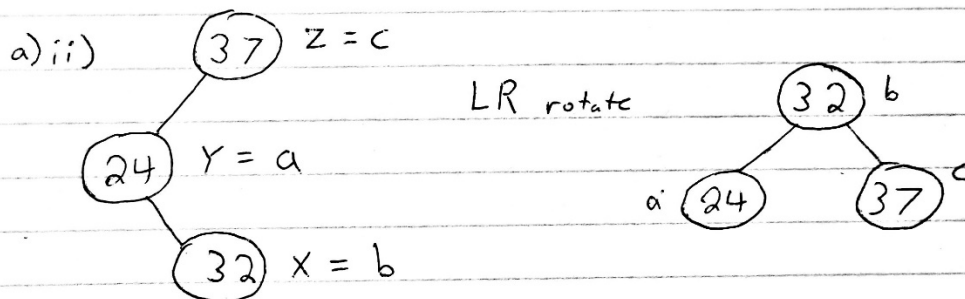
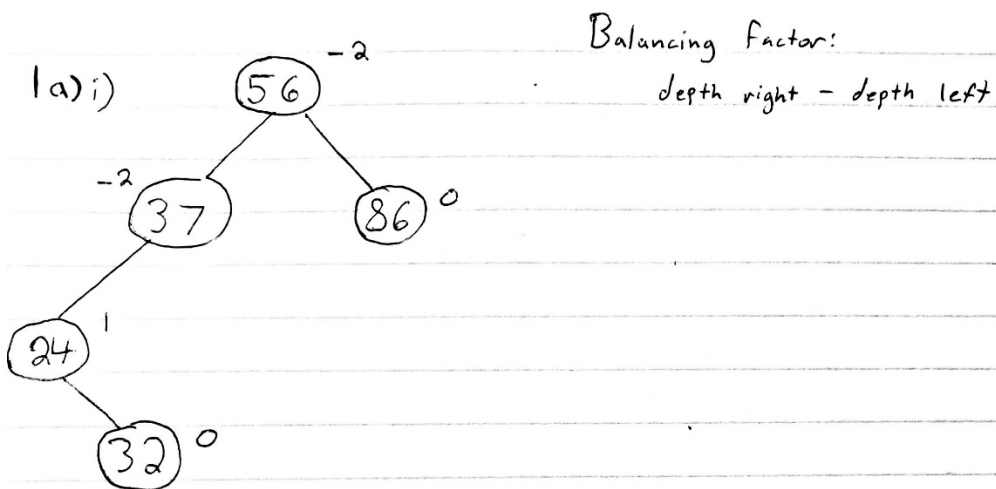
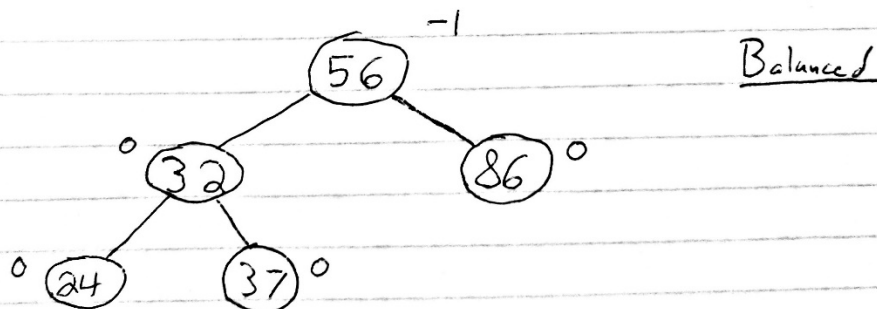


Assignment 5

1. a)

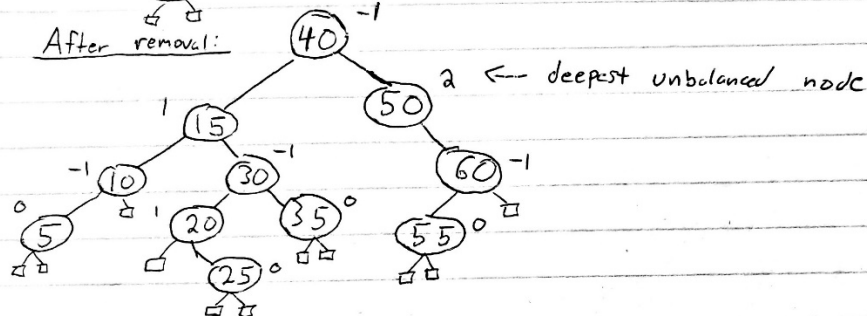
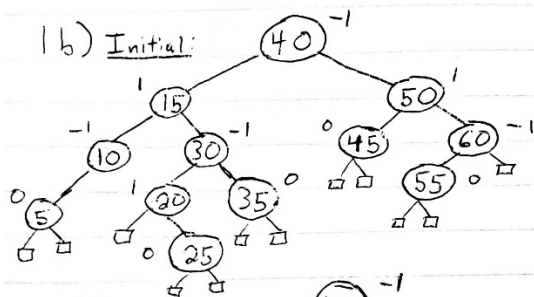


Resulting tree with balancing factors:

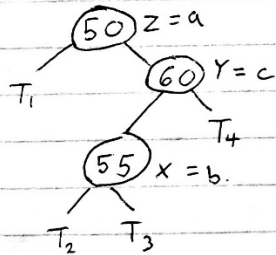


1 b)

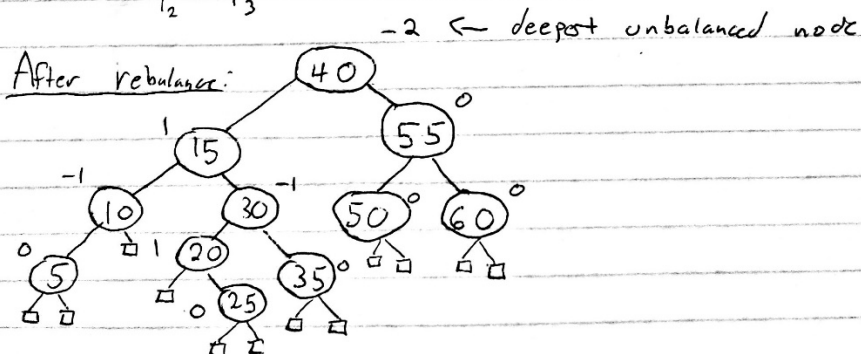
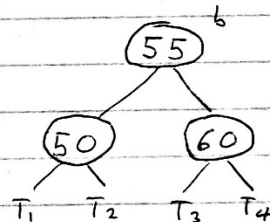
Balancing factor: depth right - depth left



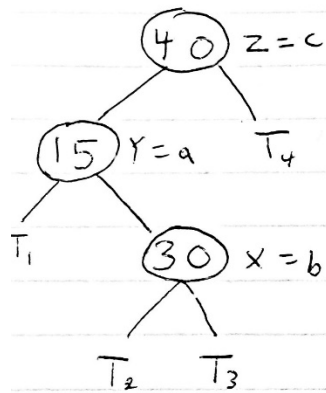
Rebalance



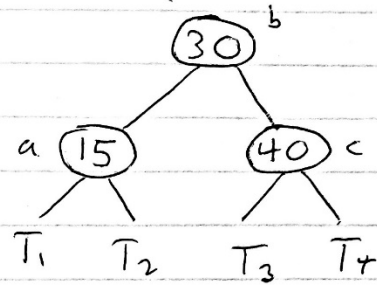
RL rotate:



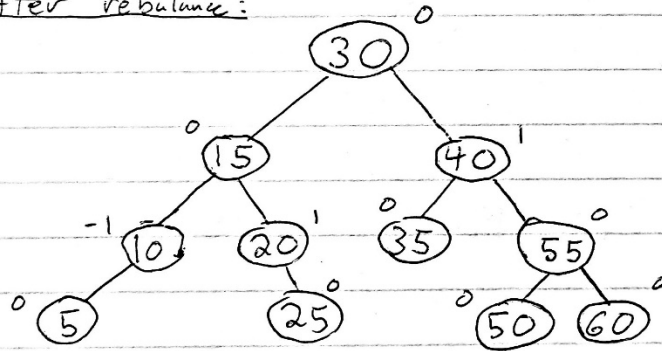
1b) continue Rebalance



LR rotate:



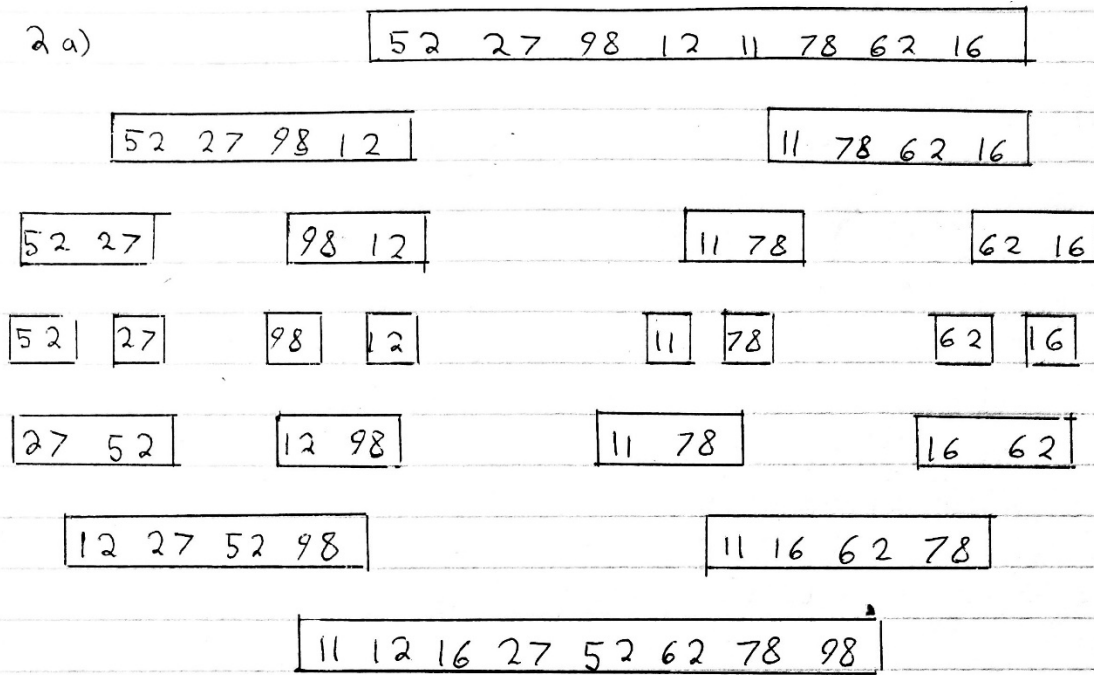
After rebalance:



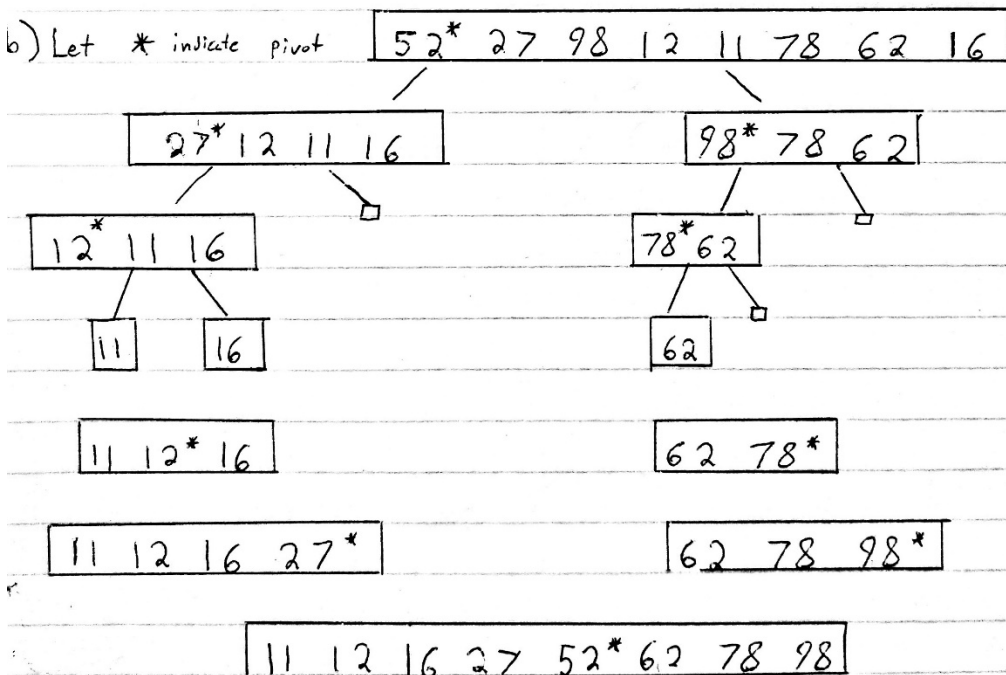
Balanced

2)

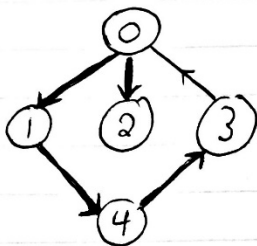
2 a)



b) Let \* indicate pivot

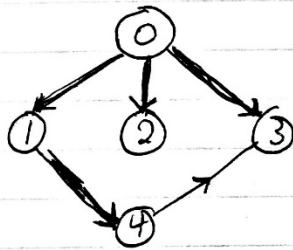


3 a)



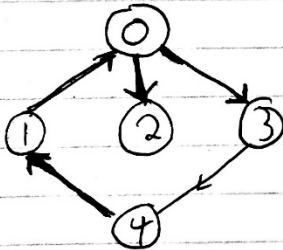
<u>Node</u>	<u>Discovery edge</u>	<u>Back edge</u>
0	—	—
1	(0, 1)	—
4	(1, 4)	—
3	(4, 3)	(3, 0)
<del>2</del>	<del>(0, 2)</del>	<del>(2, 4)</del>
2	(0, 2)	—

b)



<u>Node</u>	<u>Discovery edge</u>	<u>Cross edge</u>
0	—	—
1	(0, 1)	—
2	(0, 2)	—
3	(0, 3)	—
4	(1, 4)	(4, 3)

c)



<u>Node</u>	<u>Discovery Edge</u>	<u>Back edge</u>
4	—	—
1	(4, 1)	—
0	(1, 0)	—
2	(0, 2)	—
3	(0, 3)	(3, 4)

4. I will execute Dijkstra's algorithm in the form of a table. Each row will represent the new analysis of a vertex with minimums listed, star represents the next vertex to analyze and dash means infinity.

Vertex	Jean	Paul	Sam	Kim	Emma	Joe	Jack	Jane	Ali	Bob	Luce	Wen	Edge
Jean	0	1*	-	-	-	1	-	2	-	2	2	-	
Paul	0	1	2	-	-	1*	-	2	-	2	2	-	(Jean, Paul)
Joe	0	1	2*	-	-	1	3	2	-	2	2	-	(Jean, Joe)
Sam	0	1	2	5	-	1	3	2*	-	2	2	-	(Paul, Sam)
Jane	0	1	2	5	-	1	3	2	5	2*	2	-	(Jean, Jane)
Bob	0	1	2	5	-	1	3	2	5	2	2*	-	(Jean, Bob)
Luce	0	1	2	5	-	1	3*	2	4	2	2	-	(Jean, Luce)
Jack	0	1	2	5	-	1	3	2	4*	2	2	-	(Joe, Jack)
Ali	0	1	2	5*	5	1	3	2	4	2	2	6	(Luce, Ali)
Kim	0	1	2	5	5*	1	3	2	4	2	2	6	(Sam, Kim)
Emma	0	1	2	5	5	1	3	2	4	2	2	6*	(Ali, Emma)
Wen	0	1	2	5	5	1	3	2	4	2	2	6	(Ali, Wen)

From this table we see immediately the total degree of separation separating Emma from Jean is 5. We follow the discovery edges in reverse which forming the path back to Jean. We then deduce the shortest path from Jean to Emma as [Jean, Luce, Ali, Emma] with a total degree of separation of 5.

5.

First we calculate  $h(k)$  for each value and insert it into the array. In the event of a collision we increment the value within the mod 17 field until an empty cell is reached.

Calculation and insertion:

k	h(k)	Inc	(h(k)+inc) mod 17
66	15	0	15
20	3	0	3
50	16	0	16
75	7	0	7
104	2	0	2
100	15	2	0
17	0	1	1
24	7	1	8
70	2	2	4
25	8	1	9

Compression map domain [0, 16]

0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16
100	17	104	20	70			75	24	25						66	50