

Linear Algebra

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1 Preface

Self study Linear Algebra notes. Source is *Vector Calculus, Linear Algebra, and Differential Geometry* by John and Barbara Hubbard. These notes will start from Section 1.3. Notes for Sections 1.1 and 1.2 will be added later.

2 Matrix Multiplication as Linear Transformation

Definition 2.1 (Linear transformation from \mathbb{R}^n to \mathbb{R}^m): A *linear transformation* $T : \mathbb{R}^n \rightarrow \mathbb{R}^m$ is a mapping such that for all scalars a and for all $\vec{v}, \vec{w} \in \mathbb{R}^n$,

$$T(\vec{v} + \vec{w}) = T(\vec{v}) + T(\vec{w}) \text{ and } T(a\vec{v}) = aT(\vec{v}) \quad (2.1)$$

This above was the definition of a linear transformation. The following theorem will relate matrices to linear transformation.

Theorem 2.1 (Matrices and linear transformation)

1. Any $m \times n$ matrix A defines a linear transformation $T : \mathbb{R}^n \rightarrow \mathbb{R}^m$ is given by matrix multiplication:

$$T(\vec{v}) = A\vec{v}. \quad (2.2)$$

2. Every linear transformation $T : \mathbb{R}^n \rightarrow \mathbb{R}^m$ is given by multiplication by the $m \times n$ matrix $[T]$:

$$T(\vec{v}) = [T]\vec{v}, \quad (2.3)$$

where the i^{th} column of $[T]$ is $T(\vec{e}_i)$.

Proof to part 2 of Theorem 2.1. Given that our domain is \mathbb{R}^n we can write any vector $\vec{v} \in \mathbb{R}^n$ as

$$\vec{v} = u_1\vec{e}_1 + u_2\vec{e}_2 + \dots + u_n\vec{e}_n = \sum_{i=1}^n u_i\vec{e}_i$$

Thus,

$$\begin{aligned} T(\vec{v}) &= T\left(\sum_{i=1}^n u_i\vec{e}_i\right) \\ &= \sum_{i=1}^n u_i T(\vec{e}_i) \end{aligned}$$

Also note that since every i^{th} column of $[T]$ is $T(\vec{\mathbf{e}}_i)$. When $[T]$ is multiplied by $\vec{\mathbf{v}}$, the i^{th} of the resultant column vector can be denoted as $u_1T(\vec{\mathbf{e}}_1) + \dots + u_nT(\vec{\mathbf{e}}_n)$ which is just $T(\vec{\mathbf{v}})$. \square