

PSoC® Creator™ Project Datasheet for SystemController

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1 Overview

The Cypress PSoC 5 is a family of 32-bit devices with the following characteristics:

- High-performance 32-bit ARM Cortex-M3 core with a nested vectored interrupt controller (NVIC) and a high-performance DMA controller
- Digital system that includes configurable Universal Digital Blocks (UDBs) and specific function peripherals, such as USB, I2C and SPI
- Analog subsystem that includes 20-bit Delta Sigma converters (ADC), SAR ADCs, 8-bit DACs that can be configured for 12-bit operation, comparators, op amps and configurable switched capacitor (SC) and continuous time (CT) blocks to create PGAs, TIAs, mixers, and more
- Several types of memory elements, including SRAM, flash, and EEPROM
- Programming and debug system through JTAG, serial wire debug (SWD), and single wire viewer (SWV)
- Flexible routing to all pins

Figure 1 shows the major components of a typical <u>CY8C58LP</u> series member PSoC 5LP device. For details on all the systems listed above, please refer to the <u>PSoC 5LP Technical Reference Manual</u>.

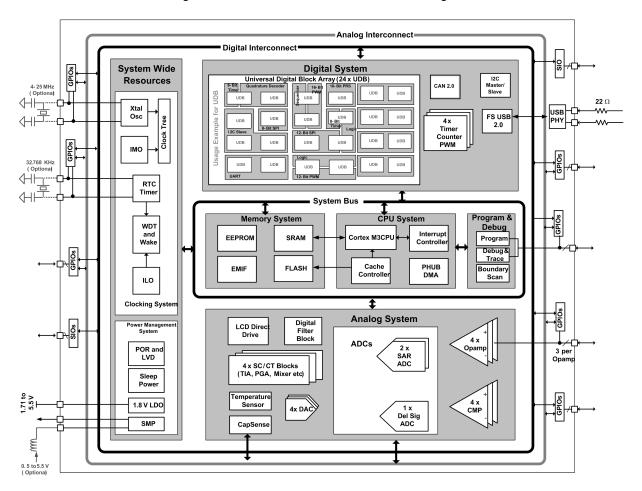


Figure 1. CY8C58LP Device Series Block Diagram



Table 1 lists the key characteristics of this device.

Table 1. Device Characteristics

Name	Value
Part Number	CY8C5888LTI-LP097
Package Name	68-QFN
Family	PSoC 5LP
Series	CY8C58LP
CPU speed (MHz)	80
Flash size (kBytes)	256
SRAM size (kBytes)	64
EEPROM size (Bytes)	2048
Vdd range (V)	1.71 to 5.5
Automotive qualified	No (Industrial Grade Only)
Temp range (Celcius)	-40 to 85
JTAG ID	0x2E161069

NOTE: The CPU speed noted above is the maximum available speed. The CPU is clocked by Bus Clock, listed in the <u>System Clocks</u> section below.

Table 2 lists the device resources that this design uses:

Table 2. Device Resources

Resource Type	Used	Free	Max	% Used
Digital Clocks	3	5	8	37.50 %
Analog Clocks	0	4	4	0.00 %
CapSense Buffers	0	2	2	0.00 %
Digital Filter Block	0	1	1	0.00 %
Interrupts	3	29	32	9.38 %
IO	42	6	48	87.50 %
Segment LCD	0	1	1	0.00 %
CAN 2.0b	0	1	1	0.00 %
I2C	0	1	1	0.00 %
USB	0	1	1	0.00 %
DMA Channels	0	24	24	0.00 %
Timer	0	4	4	0.00 %
UDB				
Macrocells	40	152	192	20.83 %
Unique P-terms	64	320	384	16.67 %
Total P-terms	77			
Datapath Cells	3	21	24	12.50 %
Status Cells	5	19	24	20.83 %
Status Registers	2			
Statusl Registers	2			
Routed Count7 Load/Enable	1			
Control Cells	3	21	24	12.50 %
Control Registers	2			
Count7 Cells	1			
Opamp	0	4	4	0.00 %
Comparator	0	4	4	0.00 %
Delta-Sigma ADC	0	1	1	0.00 %
LPF	0	2	2	0.00 %
SAR ADC	0	2	2	0.00 %
Analog (SC/CT) Blocks	0	4	4	0.00 %



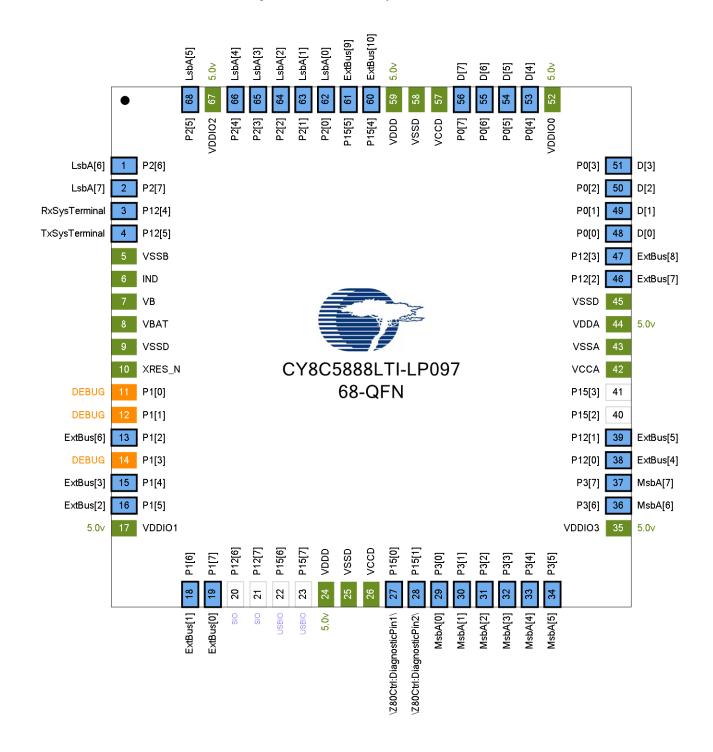
Resource Type	Used	Free	Max	% Used
DAC				
VIDAC	0	4	4	0.00 %



2 Pins

Figure 2 shows the pin layout of this device.

Figure 2. Device Pin Layout





2.1 Hardware Pins

Table 3 contains information about the pins on this device in device pin order. (No connection ["n/c"] pins have been omitted.)

Table 3. Device Pins

Pin	Port	Name	Туре	Drive Mode	Reset State
1	P2[6]	LsbA[6]	Dgtl In	Strong drive	HiZ Analog Unb
2	P2[7]	LsbA[7]	Dgtl In	Strong drive	HiZ Analog Unb
3	P12[4]	RxSysTerminal	Dgtl In	HiZ digital	HiZ Analog Unb
4	P12[5]	TxSysTerminal	Dgtl Out	Strong drive	HiZ Analog Unb
5	VSSB	VSSB	Dedicated		
6	IND	IND	Dedicated		
7	VB	VB	Dedicated		
8	VBAT	VBAT	Dedicated		
9	VSSD	VSSD	Power		
10	XRES_N	XRES_N	Dedicated		
11	P1[0]	Debug:SWD_IO	Reserved		
12	P1[1]	Debug:SWD_CK	Reserved		
13	P1[2]	ExtBus[6]	Software Input	HiZ digital	HiZ Analog Unb
14	P1[3]	Debug:SWV	Reserved		
15	P1[4]	ExtBus[3]	Dgtl In	Strong drive	HiZ Analog Unb
16	P1[5]	ExtBus[2]	Dgtl In	Strong drive	HiZ Analog Unb
17	VDDIO1	VDDIO1	Power		
18	P1[6]	ExtBus[1]	Dgtl In	Strong drive	HiZ Analog Unb
19	P1[7]	ExtBus[0]	Dgtl In	Strong drive	HiZ Analog Unb
20	P12[6]	SIO [unused]			HiZ Analog Unb
21	P12[7]	SIO [unused]			HiZ Analog Unb
22	P15[6]	USB IO [unused]			HiZ Analog Unb
23	P15[7]	USB IO [unused]			HiZ Analog Unb
24	VDDD	VDDD	Power		
25	VSSD	VSSD	Power		
26	VCCD	VCCD	Power		
27	P15[0]	\Z80Ctrl:DiagnosticPin1\	Dgtl Out	Strong drive	HiZ Analog Unb
28	P15[1]	\Z80Ctrl:DiagnosticPin2\	Dgtl Out	Strong drive	HiZ Analog Unb
29	P3[0]	MsbA[0]	Software In/Out	Strong drive	HiZ Analog Unb
30	P3[1]	MsbA[1]	Software In/Out	Strong drive	HiZ Analog Unb
31	P3[2]	MsbA[2]	Software In/Out	Strong drive	HiZ Analog Unb
32	P3[3]	MsbA[3]	Software In/Out	Strong drive	HiZ Analog Unb
33	P3[4]	MsbA[4]	Software In/Out	Strong drive	HiZ Analog Unb
34	P3[5]	MsbA[5]	Software In/Out	Strong drive	HiZ Analog Unb
35	VDDIO3	VDDIO3	Power		
36	P3[6]	MsbA[6]	Software In/Out	Strong drive	HiZ Analog Unb
37	P3[7]	MsbA[7]	Software In/Out	Strong drive	HiZ Analog Unb



Pin	Port	Name	Type	Drive Mode	Reset State
38	P12[0]	ExtBus[4]	Software	Strong drive	HiZ Analog Unb
			Output		
39	P12[1]	ExtBus[5]	Dgtl In	HiZ digital	HiZ Analog Unb
40	P15[2]	GPIO [unused]			HiZ Analog Unb
41	P15[3]	GPIO [unused]			HiZ Analog Unb
42	VCCA	VCCA	Power		
43	VSSA	VSSA	Power		
44	VDDA	VDDA	Power		
45	VSSD	VSSD	Power		
46	P12[2]	ExtBus[7]	Software	Strong drive	HiZ Analog Unb
			Output		
47	P12[3]	ExtBus[8]	Dgtl Out	Strong drive	HiZ Analog Unb
48	P0[0]	D[0]	Dgtl In	Strong drive	HiZ Analog Unb
49	P0[1]	D[1]	Dgtl In	Strong drive	HiZ Analog Unb
50	P0[2]	D[2]	Dgtl In	Strong drive	HiZ Analog Unb
51	P0[3]	D[3]	Dgtl In	Strong drive	HiZ Analog Unb
52	VDDIO0	VDDIO0	Power		
53	P0[4]	D[4]	Dgtl In	Strong drive	HiZ Analog Unb
54	P0[5]	D[5]	Dgtl In	Strong drive	HiZ Analog Unb
55	P0[6]	D[6]	Dgtl In	Strong drive	HiZ Analog Unb
56	P0[7]	D[7]	Dgtl In	Strong drive	HiZ Analog Unb
57	VCCD	VCCD	Power		
58	VSSD	VSSD	Power		
59	VDDD	VDDD	Power		
60	P15[4]	ExtBus[10]	Dgtl In	HiZ digital	HiZ Analog Unb
61	P15[5]	ExtBus[9]	Dgtl Out	Strong drive	HiZ Analog Unb
62	P2[0]	LsbA[0]	Dgtl In	Strong drive	HiZ Analog Unb
63	P2[1]	LsbA[1]	Dgtl In	Strong drive	HiZ Analog Unb
64	P2[2]	LsbA[2]	Dgtl In	Strong drive	HiZ Analog Unb
65	P2[3]	LsbA[3]	Dgtl In	Strong drive	HiZ Analog Unb
66	P2[4]	LsbA[4]	Dgtl In	Strong drive	HiZ Analog Unb
67	VDDIO2	VDDIO2	Power		
68	P2[5]	LsbA[5]	Dgtl In	Strong drive	HiZ Analog Unb

Abbreviations used in Table 3 have the following meanings:

- Dgtl In = Digital Input
- HiZ Analog Unb = Hi-Z Analog Unbuffered
- HiZ digital = High impedance digital
- Dgtl Out = Digital Output



2.2 Hardware Ports

Table 4 contains information about the pins on this device in device port order. (No connection ["n/c"], power and dedicated pins have been omitted.)

Table 4. Device Ports

Port	Pin	Name	Type	Drive Mode	Reset State
P0[0]	48	D[0]	Dgtl In	Strong drive	HiZ Analog Unb
P0[1]	49	D[1]	Dgtl In	Strong drive	HiZ Analog Unb
P0[2]	50	D[2]	Dgtl In	Strong drive	HiZ Analog Unb
P0[3]	51	D[3]	Dgtl In	Strong drive	HiZ Analog Unb
P0[4]	53	D[4]	Dgtl In	Strong drive	HiZ Analog Unb
P0[5]	54	D[5]	Dgtl In	Strong drive	HiZ Analog Unb
P0[6]	55	D[6]	Dgtl In	Strong drive	HiZ Analog Unb
P0[7]	56	D[7]	Dgtl In	Strong drive	HiZ Analog Unb
P1[0]	11	Debug:SWD_IO	Reserved		
P1[1]	12	Debug:SWD_CK	Reserved		
P1[2]	13	ExtBus[6]	Software Input	HiZ digital	HiZ Analog Unb
P1[3]	14	Debug:SWV	Reserved		
P1[4]	15	ExtBus[3]	Dgtl In	Strong drive	HiZ Analog Unb
P1[5]	16	ExtBus[2]	Dgtl In	Strong drive	HiZ Analog Unb
P1[6]	18	ExtBus[1]	Dgtl In	Strong drive	HiZ Analog Unb
P1[7]	19	ExtBus[0]	Dgtl In	Strong drive	HiZ Analog Unb
P12[0]	38	ExtBus[4]	Software Output	Strong drive	HiZ Analog Unb
P12[1]	39	ExtBus[5]	Dgtl In	HiZ digital	HiZ Analog Unb
P12[2]	46	ExtBus[7]	Software Output	Strong drive	HiZ Analog Unb
P12[3]	47	ExtBus[8]	Dgtl Out	Strong drive	HiZ Analog Unb
P12[4]	3	RxSysTerminal	Dgtl In	HiZ digital	HiZ Analog Unb
P12[5]	4	TxSysTerminal	Dgtl Out	Strong drive	HiZ Analog Unb
P12[6]	20	SIO [unused]			HiZ Analog Unb
P12[7]	21	SIO [unused]			HiZ Analog Unb
P15[0]	27	\Z80Ctrl:DiagnosticPin1\	Dgtl Out	Strong drive	HiZ Analog Unb
P15[1]	28	\Z80Ctrl:DiagnosticPin2\	Dgtl Out	Strong drive	HiZ Analog Unb
P15[2]	40	GPIO [unused]			HiZ Analog Unb
P15[3]	41	GPIO [unused]			HiZ Analog Unb
P15[4]	60	ExtBus[10]	Dgtl In	HiZ digital	HiZ Analog Unb
P15[5]	61	ExtBus[9]	Dgtl Out	Strong drive	HiZ Analog Unb
P15[6]	22	USB IO [unused]			HiZ Analog Unb
P15[7]	23	USB IO [unused]			HiZ Analog Unb
P2[0]	62	LsbA[0]	Dgtl In	Strong drive	HiZ Analog Unb
P2[1]	63	LsbA[1]	Dgtl In	Strong drive	HiZ Analog Unb
P2[2]	64	LsbA[2]	Dgtl In	Strong drive	HiZ Analog Unb
P2[3]	65	LsbA[3]	Dgtl In	Strong drive	HiZ Analog Unb
P2[4]	66	LsbA[4]	Dgtl In	Strong drive	HiZ Analog Unb
P2[5]	68	LsbA[5]	Dgtl In	Strong drive	HiZ Analog Unb
P2[6]	1	LsbA[6]	Dgtl In	Strong drive	HiZ Analog Unb
P2[7]	2	LsbA[7]	Dgtl In	Strong drive	HiZ Analog Unb
P3[0]	29	MsbA[0]	Software In/Out	Strong drive	HiZ Analog Unb



Port	Pin	Name	Type	Drive Mode	Reset State
P3[1]	30	MsbA[1]	Software In/Out	Strong drive	HiZ Analog Unb
P3[2]	31	MsbA[2]	Software In/Out	Strong drive	HiZ Analog Unb
P3[3]	32	MsbA[3]	Software In/Out	Strong drive	HiZ Analog Unb
P3[4]	33	MsbA[4]	Software In/Out	Strong drive	HiZ Analog Unb
P3[5]	34	MsbA[5]	Software In/Out	Strong drive	HiZ Analog Unb
P3[6]	36	MsbA[6]	Software In/Out	Strong drive	HiZ Analog Unb
P3[7]	37	MsbA[7]	Software In/Out	Strong drive	HiZ Analog Unb

Abbreviations used in Table 4 have the following meanings:

- Dgtl In = Digital Input
- HiZ Analog Unb = Hi-Z Analog Unbuffered
 HiZ digital = High impedance digital
- Dgtl Out = Digital Output



2.3 Software Pins

Table 5 contains information about the software pins on this device in alphabetical order. (Only software-accessible pins are shown.)

Table 5. Software Pins

Name	Port	Type	Reset State
\Z80Ctrl:DiagnosticPin1\	P15[0]	Dgtl Out	HiZ Analog Unb
\Z80Ctrl:DiagnosticPin2\	P15[1]	Dgtl Out	HiZ Analog Unb
D[0]	P0[0]	Dgtl In	HiZ Analog Unb
D[1]	P0[1]	Dgtl In	HiZ Analog Unb
D[2]	P0[2]	Dgtl In	HiZ Analog Unb
D[3]	P0[3]	Dgtl In	HiZ Analog Unb
D[4]	P0[4]	Dgtl In	HiZ Analog Unb
D[5]	P0[5]	Dgtl In	HiZ Analog Unb
D[6]	P0[6]	Dgtl In	HiZ Analog Unb
D[7]	P0[7]	Dgtl In	HiZ Analog Unb
Debug:SWD_CK	P1[1]	Reserved	
Debug:SWD IO	P1[0]	Reserved	
Debug:SWV	P1[3]	Reserved	
ExtBus[0]	P1[7]	Dgtl In	HiZ Analog Unb
ExtBus[1]	P1[6]	Dgtl In	HiZ Analog Unb
ExtBus[10]	P15[4]	Dgtl In	HiZ Analog Unb
ExtBus[2]	P1[5]	Dgtl In	HiZ Analog Unb
ExtBus[3]	P1[4]	Dgtl In	HiZ Analog Unb
ExtBus[4]	P12[0]	Software	HiZ Analog Unb
		Output	-
ExtBus[5]	P12[1]	Dgtl In	HiZ Analog Unb
ExtBus[6]	P1[2]	Software	HiZ Analog Unb
		Input	
ExtBus[7]	P12[2]	Software	HiZ Analog Unb
		Output	
ExtBus[8]	P12[3]	Dgtl Out	HiZ Analog Unb
ExtBus[9]	P15[5]	Dgtl Out	HiZ Analog Unb
GPIO [unused]	P15[2]		HiZ Analog Unb
GPIO [unused]	P15[3]		HiZ Analog Unb
LsbA[0]	P2[0]	Dgtl In	HiZ Analog Unb
LsbA[1]	P2[1]	Dgtl In	HiZ Analog Unb
LsbA[2]	P2[2]	Dgtl In	HiZ Analog Unb
LsbA[3]	P2[3]	Dgtl In	HiZ Analog Unb
LsbA[4]	P2[4]	Dgtl In	HiZ Analog Unb
LsbA[5]	P2[5]	Dgtl In	HiZ Analog Unb
LsbA[6]	P2[6]	Dgtl In	HiZ Analog Unb
LsbA[7]	P2[7]	Dgtl In	HiZ Analog Unb
MsbA[0]	P3[0]	Software In/Out	HiZ Analog Unb
MsbA[1]	P3[1]	Software In/Out	HiZ Analog Unb
MsbA[2]	P3[2]	Software In/Out	HiZ Analog Unb
MsbA[3]	P3[3]	Software In/Out	HiZ Analog Unb



Name	Port	Type	Reset State
MsbA[4]	P3[4]	Software	HiZ Analog Unb
		In/Out	
MsbA[5]	P3[5]	Software	HiZ Analog Unb
		In/Out	
MsbA[6]	P3[6]	Software	HiZ Analog Unb
		In/Out	
MsbA[7]	P3[7]	Software	HiZ Analog Unb
		In/Out	
RxSysTerminal	P12[4]	Dgtl In	HiZ Analog Unb
SIO [unused]	P12[7]		HiZ Analog Unb
SIO [unused]	P12[6]		HiZ Analog Unb
TxSysTerminal	P12[5]	Dgtl Out	HiZ Analog Unb
USB IO [unused]	P15[6]		HiZ Analog Unb
USB IO [unused]	P15[7]		HiZ Analog Unb

Abbreviations used in Table 5 have the following meanings:

- Dgtl Out = Digital Output
- HiZ Analog Unb = Hi-Z Analog Unbuffered
- Dgtl In = Digital Input

For more information on reading, writing and configuring pins, please refer to:

- Pins chapter in the <u>System Reference Guide</u>
 CyPins API routines
- Programming Application Interface section in the cy_pins component datasheet



3 System Settings

3.1 System Configuration

Table 6. System Configuration Settings

Name	Value
Device Configuration Mode	Compressed
Enable Error Correcting Code (ECC)	False
Store Configuration Data in ECC Memory	True
Instruction Cache Enabled	True
Enable Fast IMO During Startup	True
Unused Bonded IO	Allow but warn
Heap Size (bytes)	0x80
Stack Size (bytes)	0x0800
Include CMSIS Core Peripheral Library Files	True

3.2 System Debug Settings

Table 7. System Debug Settings

Name	Value
Debug Select	SWD+SWV (serial
	wire debug and
	viewer)
Enable Device Protection	False
Embedded Trace (ETM)	False
Use Optional XRES	False

3.3 System Operating Conditions

Table 8. System Operating Conditions

Name	Value
VDDA (V)	5.0
VDDD (V)	5.0
VDDIO0 (V)	5.0
VDDIO1 (V)	5.0
VDDIO2 (V)	5.0
VDDIO3 (V)	5.0
Variable VDDA	False
Temperature Range	0C - 85/125C



4 Clocks

The clock system includes these clock resources:

- Four internal clock sources increase system integration:
 - o 3 to 74.7 MHz Internal Main Oscillator (IMO) ±1% at 3 MHz
 - o 1 kHz, 33 kHz, and 100 kHz Internal Low Speed Oscillator (ILO) outputs
 - 12 to 80 MHz clock doubler output, sourced from IMO, MHz External Crystal Oscillator (MHzECO), and Digital System Interconnect (DSI)
 - 24 to 80 MHz fractional Phase-Locked Loop (PLL) sourced from IMO, MHzECO, and DSI
- Clock generated using a DSI signal from an external I/O pin or other logic
- Two external clock sources provide high precision clocks:
 - o 4 to 25 MHz External Crystal Oscillator (MHzECO)
 - o 32.768 kHz External Crystal Oscillator (kHzECO) for Real Time Clock (RTC)
- Dedicated 16-bit divider for bus clock
- Eight individually sourced 16-bit clock dividers for the digital system peripherals
- Four individually sourced 16-bit clock dividers with skew for the analog system peripherals
- IMO has a USB mode that synchronizes to USB host traffic, requiring no external crystal for USB. (USB equipped parts only)

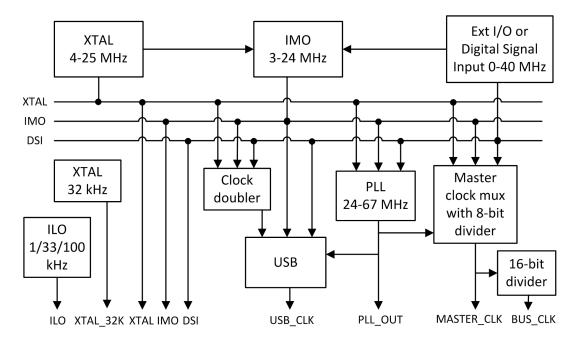


Figure 3. System Clock Configuration



4.1 System Clocks

Table 9 lists the system clocks used in this design.

Table 9. System Clocks

Name	Domain	Source	Desired		Accuracy	Start	Enabled
			Freq	Freq	(%)	at	
						Reset	
PLL_OUT	DIGITAL	IMO	48 MHz	48 MHz	±1	True	True
MASTER_CLK	DIGITAL	PLL_OUT	? MHz	48 MHz	±1	True	True
BUS_CLK	DIGITAL	MASTER_CLK	? MHz	24 MHz	±1	True	True
IMO	DIGITAL		3 MHz	3 MHz	±1	True	True
ILO	DIGITAL		? MHz	1 kHz	-50,+100	True	True
USB_CLK	DIGITAL	PLL_OUT	48 MHz	? MHz	±0	False	False
XTAL	DIGITAL		20 MHz	? MHz	±0.1	False	False
XTAL 32kHz	DIGITAL		32.768	? MHz	±0	False	False
			kHz				
Digital Signal	DIGITAL		? MHz	? MHz	±0	False	False

4.2 Local and Design Wide Clocks

Local clocks drive individual analog and digital blocks. Design wide clocks are a user-defined optimization, where two or more analog or digital blocks that share a common clock profile (frequency, etc) can be driven from the same clock divider output source.

Figure 4. Local and Design Wide Clock Configuration

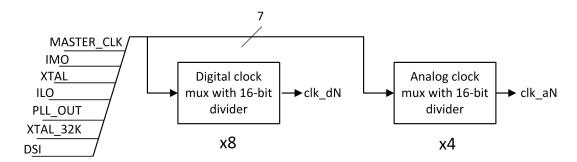


Table 10 lists the local clocks used in this design.

Table 10. Local Clocks

Name	Domain	Source	Desired Freq	Nominal Freq	Accuracy (%)	at	Enabled
						Reset	
CPUCLK_FAST	DIGITAL	MASTER_CLK	? MHz	24 MHz	±1	True	True
Z80Ctrl_BusClk	DIGITAL	BUS_CLK	? MHz	24 MHz	±1	True	True
SysTerminal IntClock	DIGITAL	MASTER_CLK	921.6 kHz	923.077 kHz	±1	True	True
CPU_CLK	DIGITAL	ILO	1 kHz	1 kHz	-50,+100	True	True

For more information on clocking resources, please refer to:

- Clocking System chapter in the PSoC 5LP Technical Reference Manual
- Clocking chapter in the <u>System Reference Guide</u>
 - CyPLL API routines
 - CylMO API routines

4 Clocks



- CylLO API routinesCyMaster API routinesCyXTAL API routines



5 Interrupts and DMAs

5.1 Interrupts

This design contains the following interrupt components: (0 is the highest priority)

Table 11. Interrupts

Name	Priority	Vector
Z80Ctrl_ISR_IO	1	2
SysTerminal RXInternalInterrupt	2	0
SysTerminal TXInternalInterrupt	3	1

For more information on interrupts, please refer to:

- Interrupt Controller chapter in the PSoC 5LP Technical Reference Manual
- Interrupts chapter in the System Reference Guide

 O Cylnt API routines and related registers
- Datasheet for cy_isr component

5.2 DMAs

This design contains no DMA components.



6 Flash Memory

PSoC 5LP devices offer a host of Flash protection options and device security features that you can leverage to meet the security and protection requirements of an application. These requirements range from protecting configuration settings or Flash data to locking the entire device from external access.

Table 12 lists the Flash protection settings for your design.

Table 12. Flash Protection Settings

Start Address	End Address	Protection Level
0x0	0x3FFFF	U - Unprotected

Flash memory is organized as rows with each row of flash having 256 bytes. Each flash row can be assigned one of four protection levels:

- U Unprotected
- F Factory Upgrade
- R Field Upgrade
- W Full Protection

For more information on Flash memory and protection, please refer to:

- Flash Protection chapter in the PSoC 5LP Technical Reference Manual
- Flash and EEPROM chapter in the System Reference Guide
 - o CyWrite API routines
 - CyFlash API routines

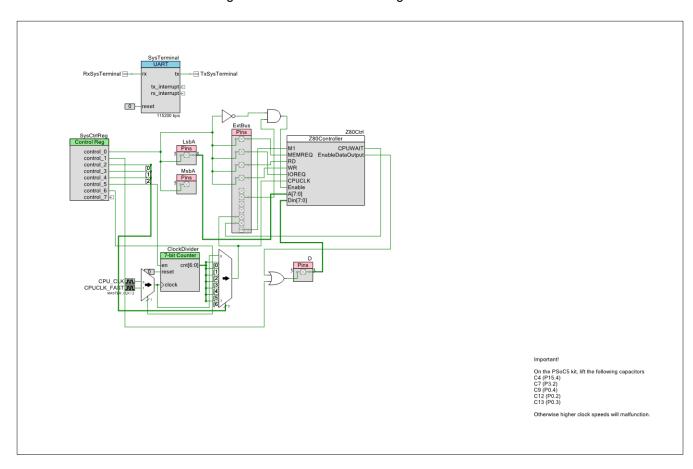


7 Design Contents

This design's schematic content consists of the following schematic sheet:

7.1 Schematic Sheet: Page 1

Figure 5. Schematic Sheet: Page 1



This schematic sheet contains the following component instances:

- Instance ClockDivider (type: BasicCounter_v1_0)
- Instance <u>SysCtrlReg</u> (type: CyControlReg_v1_80)
- Instance <u>SysTerminal</u> (type: UART_v2_50)
- Instance <u>Z80Ctrl</u> (type: Z80Controller)



8 Components

8.1 Component type: BasicCounter [v1.0]

8.1.1 Instance ClockDivider

Description: Basic Counter

Instance type: BasicCounter [v1.0]

Datasheet: online component datasheet for BasicCounter

Table 13. Component Parameters for ClockDivider

Parameter Name	Value	Description
Width	7	Width of the counter. Must be
		between 2 and 32.

8.2 Component type: CyControlReg [v1.80]

8.2.1 Instance SysCtrlReg

Description: The Control Register allows the firmware to set values for to use for digital

signals.

Instance type: CyControlReg [v1.80]

Datasheet: online component datasheet for CyControlReg

Table 14. Component Parameters for SysCtrlReg

Parameter Name	Value	Description
Bit0Mode	DirectMode	Defines bit 0 mode
Bit1Mode	DirectMode	Defines bit 1 mode
Bit2Mode	DirectMode	Defines bit 2 mode
Bit3Mode	DirectMode	Defines bit 3 mode
Bit4Mode	DirectMode	Defines bit 4 mode
Bit5Mode	DirectMode	Defines bit 5 mode
Bit6Mode	DirectMode	Defines bit 6 mode
Bit7Mode	DirectMode	Defines bit 7 mode
BitValue	0	Defines bit value
BusDisplay	false	Displays the output terminals as
		bus
ExternalReset	false	Shows the reset terminal
NumOutputs	8	Defines the number of outputs
		needed (1-8)

8.3 Component type: UART [v2.50]

8.3.1 Instance SysTerminal

Description: Universal Asynchronous Receiver Transmitter

Instance type: UART [v2.50]

Datasheet: online component datasheet for UART

Table 15. Component Parameters for SysTerminal

Parameter Name	Value	Description
Address1	0	This parameter specifies the RX
		Hardware Address #1.



Parameter Name	Value	Description
Address2	0	This parameter specifies the RX
		Hardware Address #2.
BaudRate	115200	Sets the target baud rate.
BreakBitsRX	13	Specifies the break signal
		length for the RX (detection)
D. I.D.Y. T.Y.	40	channel.
BreakBitsTX	13	Specifies the break signal
BreakDetect	false	length for the TX channel. Enables the break detect
DieakDetect	laise	hardware.
CRCoutputsEn	false	Enables the CRC outputs.
EnIntRXInterrupt	true	Enables the internal RX
		interrupt configuration and the
		ı ığr.
EnIntTXInterrupt	true	Enables the internal TX interrupt
		configuration and the ISR.
FlowControl	None	Enable the flow control signals.
HalfDuplexEn	false	Enables half duplex mode on
		the RX Half of the UART
LluTVEnSignal	false	module. Enables the external TX enable
HwTXEnSignal	laise	signal output.
InternalClock	true	Enables the internal clock. This
Internal older	1 40	parameter removes the clock
		input pin.
InterruptOnTXComplete	false	This is an Interrupt mask used
		to enable/disable the interrupt
		on 'TX complete' event.
InterruptOnTXFifoEmpty	true	This is an Interrupt mask used
		to enable/disable the interrupt on 'TX FIFO empty' event.
InterruptOnTXFifoFull	false	This is an Interrupt mask used
interrupter in the direction of the contract o	laiss	to enable/disable the interrupt
		on 'TX FIFO full' event.
InterruptOnTXFifoNotFull	false	This is an Interrupt mask used
		to enable/disable the interrupt
		on 'TX FIFO not full' event.
IntOnAddressDetect	false	Enables the interrupt on hardware address detected
		event by default
IntOnAddressMatch	false	Enables the interrupt on
interia tadi cociviatori	laiss	hardware address match
		detected event by default
IntOnBreak	false	Enables the interrupt on break
		signal detected event by default
IntOnByteRcvd	true	Enables the interrupt on RX
110.0		byte received event by default
IntOnOverrunError	false	Enables the interrupt on overrun
IntOnParityError	false	error event by default Enables the interrupt on parity
Intoni antychol	laise	error event by default
IntOnStopError	false	Enables the interrupt on stop
		error event by default
NumDataBits	8	Defines the number of data bits.
		Values can be 5, 6, 7 or 8 bits.
NumStopBits	1	Defines the number of stop bits.
		Values can be 1 or 2 bits.



Parameter Name	Value	Description
OverSamplingRate	8	This parameter defines the over sampling rate.
ParityType	None	Sets the parity type as Odd, Even or Mark/Space
ParityTypeSw	false	This parameter allows the parity type to be changed through software by using the WriteControlRegister API
RXAddressMode	None	Configures the RX hardware address detection mode
RXBufferSize	4096	The size of the RAM space allocated for the RX input buffer.
RXEnable	true	Enables the RX in the UART
TXBitClkGenDP	true	When enabled, this parameter enables the TX clock generation on DataPath resource. When disabled, TX clock is generated from Clock7.
TXBufferSize	128	The size of the RAM space allocated for the TX output buffer.
TXEnable	true	Enables the TX in the UART
Use23Polling	false	Allows the use of 2 out of 3 polling resources on the RX UART sampler.

8.4 Component type: Z80Controller [v0.0]

8.4.1 Instance Z80Ctrl

Description: (custom component) Instance type: Z80Controller [v0.0] Datasheet: (not available)



9 Other Resources

The following documents contain important information on Cypress software APIs that might be relevant to this design:

- Standard Types and Defines chapter in the <u>System Reference Guide</u>
 - Software base types
 - o Hardware register types
 - Compiler defines
 - Cypress API return codes
 - Interrupt types and macros
- Registers
 - The full PSoC 5LP register map is covered in the PSoC 5LP Registers Technical Reference
 - o Register Access chapter in the System Reference Guide

 - § CY_GET API routines § CY_SET API routines
- System Functions chapter in the **System Reference Guide**
 - o General API routines
 - o CyDelay API routines
 - o CyVd Voltage Detect API routines
- Power Management
 - o Power Supply and Monitoring chapter in the PSoC 5LP Technical Reference Manual
 - o Low Power Modes chapter in the PSoC 5LP Technical Reference Manual
 - o Power Management chapter in the System Reference Guide
 - § CyPm API routines
- Watchdog Timer chapter in the System Reference Guide
 - CyWdt API routines
- Cache Management
 - o Cache Controller chapter in the PSoC 5LP Technical Reference Manual
 - o Cache chapter in the System Reference Guide
 - § CyFlushCache() API routine