

# Math 164: Problem Set 9

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**12.18** The problem is equivalent to minimizing  $\frac{1}{2}\|\mathbf{x} - \mathbf{b}\|^2$ . If  $\mathbf{x} \in \mathcal{R}(\mathbf{A})$ ,  $\exists \mathbf{y} \in \mathbb{R}^n$  s.t  $\mathbf{A}\mathbf{y} = \mathbf{x}$

It follows  $\mathbf{x}^* = \mathbf{A}\mathbf{y}^* = \mathbf{A}(\mathbf{A}^\top \mathbf{A})^{-1} \mathbf{A}^\top \mathbf{b}$  using the least squares method with variable  $\mathbf{y}$ .

**12.20** Let  $\mathbf{y} = \mathbf{x} - \mathbf{x}_0$ , so our problem becomes

$\min_{\mathbf{A}\mathbf{y}=\mathbf{b}-\mathbf{A}\mathbf{x}_0} \|\mathbf{y}\|$ . Using Theorem 12.2,  $\mathbf{y}^* = \mathbf{A}^\top (\mathbf{A}\mathbf{A}^\top)^{-1} (\mathbf{b} - \mathbf{A}\mathbf{x}_0)$  is a unique minimizer to our constrained minimization problem. Since  $\mathbf{x}^* = \mathbf{y}^* + \mathbf{x}_0$ ,

$$\begin{aligned}\mathbf{x}^* &= \mathbf{A}^\top (\mathbf{A}\mathbf{A}^\top)^{-1} (\mathbf{b} - \mathbf{A}\mathbf{x}_0) + \mathbf{x}_0 \\ &= \mathbf{A}^\top (\mathbf{A}\mathbf{A}^\top)^{-1} \mathbf{b} - \mathbf{A}^\top (\mathbf{A}\mathbf{A}^\top)^{-1} \mathbf{A}\mathbf{x}_0 + \mathbf{I}_n \mathbf{x}_0 \\ &= \mathbf{A}^\top (\mathbf{A}\mathbf{A}^\top)^{-1} \mathbf{b} + (\mathbf{I}_n - \mathbf{A}^\top (\mathbf{A}\mathbf{A}^\top)^{-1} \mathbf{A}) \mathbf{x}_0\end{aligned}$$

**12.23** Let  $\mathbf{y} \in \mathcal{R}(\mathbf{A}^\top)$  satisfy  $\mathbf{A}\mathbf{y} = \mathbf{b}$ . It follows  $\exists \mathbf{z} \in \mathbb{R}^m$  s.t  $\mathbf{A}^\top \mathbf{z} = \mathbf{y}$ .

Since  $\mathbf{A}\mathbf{y}$  and  $\mathbf{A}\mathbf{x}^*$  both equal  $\mathbf{b}$

$$\mathbf{A}\mathbf{y} - \mathbf{A}\mathbf{x}^* = \mathbf{A}\mathbf{A}^\top \mathbf{z} - \mathbf{A}(\mathbf{A}^\top (\mathbf{A}\mathbf{A}^\top)^{-1} \mathbf{b}) = \mathbf{0}$$

$$\Rightarrow \mathbf{A}\mathbf{A}^\top (\mathbf{z} - (\mathbf{A}\mathbf{A}^\top)^{-1} \mathbf{b}) = \mathbf{0}$$

$$\Rightarrow \mathbf{z} = (\mathbf{A}\mathbf{A}^\top)^{-1} \mathbf{b} \text{ because } \mathbf{A}\mathbf{A}^\top \text{ is invertible.}$$

$$\text{Thus, } \mathbf{y} = \mathbf{A}^\top \mathbf{z} = \mathbf{A}^\top (\mathbf{A}\mathbf{A}^\top)^{-1} \mathbf{b} = \mathbf{x}^*$$

**20.2** (a) Let  $f(\mathbf{x}) = x_1^2 + 2x_1x_2 + 3x_2^2 + 4x_1 + 5x_2 + 6x_3$ ,

$$h(\mathbf{x}) = [x_1 + 2x_2 - 3, 4x_1 + 5x_3 - 6]^\top,$$

$$\text{and } l(\mathbf{x}, \lambda) = f(\mathbf{x}) + \lambda^\top h(\mathbf{x}).$$

We first want to find an  $(\mathbf{x}^*, \lambda^*)$  that satisfies the Lagrange condition:

$$Dl(\mathbf{x}^*, \lambda^*) = [D_x l(\mathbf{x}^*, \lambda^*), D_\lambda(\mathbf{x}^*, \lambda^*)] = \mathbf{0}^\top$$

It follows

$$\begin{aligned}
Dl(\mathbf{x}, \lambda) &= \begin{bmatrix} 2 & 2 & 0 & 1 & 4 \\ 2 & 6 & 0 & 2 & 0 \\ 0 & 0 & 0 & 0 & 5 \\ 1 & 2 & 0 & 0 & 0 \\ 4 & 0 & 5 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ \lambda_1 \\ \lambda_2 \end{bmatrix} - \begin{bmatrix} -4 \\ -5 \\ -6 \\ 3 \\ 6 \end{bmatrix} = \mathbf{0}^\top \\
\Rightarrow \begin{bmatrix} 2 & 2 & 0 & 1 & 4 \\ 2 & 6 & 0 & 2 & 0 \\ 0 & 0 & 0 & 0 & 5 \\ 1 & 2 & 0 & 0 & 0 \\ 4 & 0 & 5 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ \lambda_1 \\ \lambda_2 \end{bmatrix} &= \begin{bmatrix} -4 \\ -5 \\ -6 \\ 3 \\ 6 \end{bmatrix}
\end{aligned}$$

which reduces to

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ \lambda_1 \\ \lambda_2 \end{bmatrix} = \begin{bmatrix} \frac{16}{5} \\ \frac{1}{10} \\ -\frac{34}{25} \\ -\frac{27}{5} \\ -\frac{6}{5} \end{bmatrix}$$

by Gaussian elimination.

Next, we want to show this point satisfies the SONC

$$L(\mathbf{x}^*, \lambda^*) = \mathbf{F}(\mathbf{x}^*) + \lambda^* \mathbf{H}(\mathbf{x}^*) = \begin{bmatrix} 2 & 2 & 0 \\ 2 & 6 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

because  $H_k(\mathbf{x}^*) = 0, k = 1, 2$

$$T(\mathbf{x}^*) := \{\mathbf{v} \in \mathbb{R}^3 : \begin{bmatrix} 1 & 2 & 0 \\ 4 & 0 & 5 \end{bmatrix} \mathbf{v} = 0\} = \text{span}\left\{\begin{bmatrix} \frac{5}{4} \\ -\frac{5}{8} \\ 1 \end{bmatrix}^\top\right\}$$

$$\forall \mathbf{v} \in T(\mathbf{x}^*), \mathbf{v}^\top L(\mathbf{x}^*, \lambda^*) \mathbf{v} = \alpha^2 \begin{bmatrix} \frac{5}{4} \\ -\frac{5}{8} \\ 1 \end{bmatrix}^\top \begin{bmatrix} 2 & 2 & 0 \\ 2 & 6 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} \frac{5}{4} \\ -\frac{5}{8} \\ 1 \end{bmatrix}$$

$$= \alpha^2 \begin{bmatrix} \frac{5}{4} \\ -\frac{5}{8} \\ 1 \end{bmatrix}^\top \begin{bmatrix} \frac{5}{4} \\ -\frac{5}{4} \\ 0 \end{bmatrix} = \frac{75}{32} \alpha^2 > 0, \forall \alpha \neq 0$$

, so

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ \lambda_1 \\ \lambda_2 \end{bmatrix} = \begin{bmatrix} \frac{16}{5} \\ \frac{1}{10} \\ -\frac{34}{25} \\ -\frac{27}{5} \\ -\frac{6}{5} \end{bmatrix}$$

is a strict local minimizer.

(b) Let

$$\begin{aligned}
f(x) &= 4x_1 + x_2^2 \\
h(x) &= x_1^2 + x_2^2 - 9 \\
l(x, \lambda) &= f(x) + \lambda h(x) \\
\Rightarrow \nabla l(x, \lambda) &= \begin{bmatrix} 4 + 2\lambda x_1 \\ 2x_2 + 2\lambda x_2 \\ x_1^2 + x_2^2 - 9 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}
\end{aligned}$$

We first observe  $\lambda \neq 0$ . If so, we contradict the first innequality. Thus,  $x_1 = -\frac{2}{\lambda}$ .

We have two cases for  $x_2$ .  $x_2 = 0$  or  $x_2 \neq 0$

The first case gives the first two candidates  $[3, 0]^\top \lambda = -\frac{2}{3}$ ,  $[-3, 0]^\top \lambda = \frac{2}{3}$ .

The second case gives the second two candidates  $[2, \sqrt{5}]^\top \lambda = -1$ ,  $[2, -\sqrt{5}]^\top \lambda = -1$ .

All 4 candidates are regular.

$$L(\mathbf{x}, \lambda) = \mathbf{F}(\mathbf{x}) + \lambda \mathbf{H}(\mathbf{x}) = \begin{bmatrix} 2\lambda & 0 \\ 0 & 2 + 2\lambda \end{bmatrix}$$

$$T(\mathbf{x}) = \{\mathbf{v} \in \mathbb{R}^2 : [2x_1, 2x_2] \mathbf{v} = 0\}$$

$$L([3, 0]^\top, -\frac{2}{3}) = \begin{bmatrix} -\frac{4}{3} & 0 \\ 0 & \frac{2}{3} \end{bmatrix}$$

$$T([3, 0]^\top) = \text{span}\{[0, 1]^\top\}$$

$$\forall \mathbf{v} \in T([3, 0]^\top) \neq \mathbf{0}, \mathbf{v}^\top \begin{bmatrix} -\frac{4}{3} & 0 \\ 0 & \frac{2}{3} \end{bmatrix} \mathbf{v} = \alpha^2 \frac{4}{9} > 0$$

$$L([-3, 0]^\top, \frac{2}{3}) = \begin{bmatrix} \frac{4}{3} & 0 \\ 0 & \frac{10}{3} \end{bmatrix} > 0$$

$$L([2, \sqrt{5}]^\top, -1) = \begin{bmatrix} -2 & 0 \\ 0 & 0 \end{bmatrix}$$

$$T([2, \sqrt{5}]^\top) = \text{span}\{[-\sqrt{5}, 2]^\top\}$$

$$\forall \mathbf{v} \in T([2, \sqrt{5}]^\top) \neq \mathbf{0}, \mathbf{v}^\top \begin{bmatrix} -2 & 0 \\ 0 & 0 \end{bmatrix} \mathbf{v} = -\alpha^2 10 < 0$$

$$L([2, \sqrt{5}]^\top, -1) = \begin{bmatrix} -2 & 0 \\ 0 & 0 \end{bmatrix}$$

$$T([2, -\sqrt{5}]^\top) = \text{span}\{[\sqrt{5}, 2]^\top\}$$

$$\forall \mathbf{v} \in T([2, -\sqrt{5}]^\top) \neq \mathbf{0}, \mathbf{v}^\top \begin{bmatrix} -2 & 0 \\ 0 & 0 \end{bmatrix} \mathbf{v} = -\alpha^2 10 < 0$$

Thus,  $[3, 0]^\top \lambda = -\frac{2}{3}, [-3, 0]^\top \lambda = \frac{2}{3}$  are strict local minimizers and  $[2, \sqrt{5}]^\top \lambda = -1, [2, -\sqrt{5}]^\top \lambda = -1$  are strict local maximizers.

(c)

$$f(x) = x_1 x_2$$

$$h(x) = x_1^2 + 4x_2^2 - 1$$

$$l(x, \lambda) = -x_1 x_2 + \lambda x_1^2 + 4\lambda x_2^2$$

$$\nabla l(x, \lambda) = \begin{bmatrix} x_2 + 2\lambda x_1 \\ x_1 + 8\lambda x_2 \\ x_1^2 + 4x_2^2 - 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$x_1 = -8\lambda x_2 \Rightarrow x_2(1 - 16\lambda^2) = 0. \quad x_2 \neq 0 \text{ by inspection.}$$

$$\lambda = \frac{1}{4} \Rightarrow \left[\frac{1}{\sqrt{2}}, -\frac{1}{2\sqrt{2}}\right]^\top, \left[-\frac{1}{\sqrt{2}}, \frac{1}{2\sqrt{2}}\right]^\top \text{ are solutions.}$$

$$\lambda = -\frac{1}{4} \Rightarrow \left[\frac{1}{\sqrt{2}}, \frac{1}{2\sqrt{2}}\right]^\top, \left[-\frac{1}{\sqrt{2}}, -\frac{1}{2\sqrt{2}}\right]^\top \text{ are solutions.}$$

$$L(\mathbf{x}, \frac{1}{4}) = \begin{bmatrix} \frac{1}{2} & 1 \\ 1 & 2 \end{bmatrix}$$

$$L(\mathbf{x}, -\frac{1}{4}) = \begin{bmatrix} -\frac{1}{2} & 1 \\ 1 & -2 \end{bmatrix}$$

$$T(\mathbf{x}) = \{\mathbf{v} : [2x_1, 8x_2]\mathbf{v} = 0\}$$

$$T\left(\left[\frac{1}{\sqrt{2}}, -\frac{1}{2\sqrt{2}}\right]^\top\right) = T\left(\left[-\frac{1}{\sqrt{2}}, \frac{1}{2\sqrt{2}}\right]^\top\right) = \text{span}\{[1, 1]^\top\}$$

$$T\left(\left[\frac{1}{\sqrt{2}}, \frac{1}{2\sqrt{2}}\right]^\top\right) = T\left(\left[-\frac{1}{\sqrt{2}}, -\frac{1}{2\sqrt{2}}\right]^\top\right) = \text{span}\{[1, -1]^\top\}$$

$$\text{For } \mathbf{v} \in \text{span}\{[1, -1]^\top\}, \mathbf{v}^\top L(\mathbf{x}, -\frac{1}{4})\mathbf{v} < 0$$

$$\text{For } \mathbf{v} \in \text{span}\{[1, 1]^\top\}, \mathbf{v}^\top L(\mathbf{x}, \frac{1}{4})\mathbf{v} > 0$$

Thus,  $[\frac{1}{\sqrt{2}}, -\frac{1}{2\sqrt{2}}]^\top, [-\frac{1}{\sqrt{2}}, \frac{1}{2\sqrt{2}}]^\top$  are strict local maximizers and  $[\frac{1}{\sqrt{2}}, \frac{1}{2\sqrt{2}}]^\top, [-\frac{1}{\sqrt{2}}, -\frac{1}{2\sqrt{2}}]^\top$  are strict local minimizers.

$$\mathbf{20.3} \quad l(\mathbf{x}, \lambda) = (\mathbf{a}^\top \mathbf{x})(\mathbf{b}^\top \mathbf{x}) + \lambda_1(x_1 + x_2) + \lambda_2(x_2 + x_3) = 0$$

$$\begin{aligned}
\nabla l &= \begin{bmatrix} \nabla_{\mathbf{x}} l \\ h(\mathbf{x}) \end{bmatrix} = \begin{bmatrix} (\mathbf{a}\mathbf{b}^\top + \mathbf{b}\mathbf{a}^\top)\mathbf{x} + [\nabla h_1, \nabla h_2]\lambda \\ h(\mathbf{x}) \end{bmatrix} \\
&= \begin{bmatrix} \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix} \mathbf{x} + \begin{bmatrix} 1 & 0 \\ 1 & 1 \\ 0 & 1 \end{bmatrix} \lambda \\ h(\mathbf{x}) \end{bmatrix} \\
&= \begin{bmatrix} x_2 + \lambda_1 \\ x_1 + x_2 + \lambda_1 + \lambda_2 \\ x_2 + \lambda_2 \\ x_1 + x_2 \\ x_2 + x_3 \end{bmatrix} = \mathbf{0}
\end{aligned}$$

By inspection,  $\mathbf{x}^* = \mathbf{0}, \lambda^* = \mathbf{0}$  solves the system uniquely.

$$L(\mathbf{x}^*, \lambda^*) = \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix},$$

$$T(\mathbf{x}^*) = \text{span}\{[1, -1, 1]^\top\}$$

$\forall \mathbf{v} \in T(\mathbf{x}^*), \mathbf{v}^\top L(\mathbf{x}^*, \lambda^*) \mathbf{v} = -4\alpha^2 < 0$ , so  $\mathbf{0}$  is a strict local maximizer.

$$\begin{aligned}
\mathbf{20.4} \quad \nabla l(\mathbf{x}^\top, \lambda^\top) &= \begin{bmatrix} x_1 + \lambda \\ x_1 + 4 + 4\lambda \\ h(\mathbf{x}^*) \end{bmatrix} = \mathbf{0} \\
\Rightarrow x_1 &= \frac{4}{3} \Rightarrow \nabla f(\mathbf{x}^*) = [\frac{4}{3}, \frac{16}{3}]^\top
\end{aligned}$$

$$\mathbf{20.9} \quad f(\mathbf{x}) = \frac{\mathbf{x}^\top \begin{bmatrix} 18 & -4 \\ -4 & 12 \end{bmatrix} \mathbf{x}}{\mathbf{x}^\top \begin{bmatrix} 2 & 0 \\ 0 & 2 \end{bmatrix} \mathbf{x}}$$

Observe that if  $\mathbf{x}^*$  is a maximizer,  $\alpha \mathbf{x}^*$  for some scalar  $\alpha$  is also a maximizer because

$$\begin{aligned}
f(\alpha \mathbf{x}^*) &= \frac{(\alpha \mathbf{x}^*)^\top \begin{bmatrix} 18 & -4 \\ -4 & 12 \end{bmatrix} (\alpha \mathbf{x}^*)}{(\alpha \mathbf{x}^*)^\top \begin{bmatrix} 2 & 0 \\ 0 & 2 \end{bmatrix} (\alpha \mathbf{x}^*)} \\
&= \frac{\alpha^2 \mathbf{x}^{*\top} \begin{bmatrix} 18 & -4 \\ -4 & 12 \end{bmatrix} \mathbf{x}^*}{\alpha^2 \mathbf{x}^{*\top} \begin{bmatrix} 2 & 0 \\ 0 & 2 \end{bmatrix} \mathbf{x}^*} = f(\mathbf{x}^*)
\end{aligned}$$

It follows we can solve an equivalent problem to maximize  $\mathbf{x}^\top \begin{bmatrix} 18 & -4 \\ -4 & 12 \end{bmatrix} \mathbf{x}$

constrained to  $\mathbf{x}^\top \begin{bmatrix} 2 & 0 \\ 0 & 2 \end{bmatrix} \mathbf{x} = 1$

$$l(\mathbf{x}, \lambda) = \mathbf{x}^\top \begin{bmatrix} 18 & -4 \\ -4 & 12 \end{bmatrix} \mathbf{x} + \lambda(1 - \mathbf{x}^\top \begin{bmatrix} 2 & 0 \\ 0 & 2 \end{bmatrix} \mathbf{x})$$

$$\nabla l_x = 2\left(\begin{bmatrix} 18 & -4 \\ -4 & 12 \end{bmatrix} - \lambda \begin{bmatrix} 2 & 0 \\ 0 & 2 \end{bmatrix}\right)\mathbf{x} = \mathbf{0}$$

$$\Leftrightarrow (\lambda \mathbf{I}_2 - \begin{bmatrix} 9 & -2 \\ -2 & 6 \end{bmatrix})\mathbf{x} = \mathbf{0}$$

which is equivalent to solving an eigenvalue eigenvector problem.

$\det(\lambda \mathbf{I}_2 - \begin{bmatrix} 9 & -2 \\ -2 & 6 \end{bmatrix}) = (\lambda - 10)(\lambda - 5)$   $\lambda = 10$  will give us a much larger value.

$\mathbf{x}^* = \frac{1}{\sqrt{10}} \begin{bmatrix} 2 \\ -1 \end{bmatrix}$  gives us a solution that satisfies  $h(\mathbf{x}^*) = 0$ .

Thus, any scalar multiple of  $\mathbf{x}^*$  will give us a maximizer.

**20.10** Let  $\mathbf{Q}_0 = \frac{1}{2}(\begin{bmatrix} 3 & 4 \\ 0 & 3 \end{bmatrix} + \begin{bmatrix} 3 & 0 \\ 4 & 3 \end{bmatrix})$

$$\nabla l(\mathbf{x}^*, \lambda^*) = 2\mathbf{Q}_0\mathbf{x}^* - 2\lambda^*\mathbf{x} = \mathbf{0}$$

which is equivalent to solving for  $\mathbf{Q}_0$  eigenvalues and corresponding eigenvectors.

$$\det \begin{bmatrix} \lambda - 3 & -2 \\ -2 & \lambda - 3 \end{bmatrix} = \lambda^2 - 6\lambda + 5 = (\lambda - 1)(\lambda - 5)$$

Thus, the maximizers are the eigenvectors for  $\lambda = 5$  constrained to  $\|\mathbf{x}\| = 1$   
 $[\frac{1}{\sqrt{2}}, \frac{1}{\sqrt{2}}], [-\frac{1}{\sqrt{2}}, -\frac{1}{\sqrt{2}}]$

**20.14** Suppose  $\mathbf{x}^* = [1, 1]$  is a solution to  $\nabla l(\mathbf{x}, \lambda) = \begin{bmatrix} a + 2\lambda x_1 \\ b + 2\lambda x_2 \\ x_1^2 + x_2^2 - 2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$ .

It follows  $a = -2\lambda$  and  $b = -2\lambda$ , so  $a = b$ .