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% HW Problem 5 template; implement 2nd order Taylor Series (TS) method for IVP:
% y' = f(t,y) \text{ with } y(t 0) = y0
%% Define the ODE
% RHS function of ODE
f = @(t,y) - (5*t)*y^2 + 5/t - 1/t^2;
% Partial derivatives of RHS function (needed for TS)
f_y = @(t,y) -10*y*t;
f_t = @(t,y) -5*y.^2-5/t^2+2/t^3;
%----- End of your edits for this part -----
%% Time-stepping
% Time step
h = 0.2;
% Initial and final time
t0 = 1;
tf = 2;
% Discretization of time
tset = (t0 : h : tf)';
% Number of time steps
numsteps = length(tset);
% Initial value
y0 = 1;
% Initialize time
t = t0;
% Initialization of numerical solution
% Initialize numerical solutions with the initial value
y_FE = y0 ; % Forward Euler method
y_TS = y0 ; % Taylor Series method
% Store the numerical solution
y_FE_set = zeros(numsteps, 1) ; y_FE_set(1) = y0 ;
y_TS_set = zeros(numsteps, 1) ; y_TS_set(1) = y0 ;
%% Actual time stepping
for i = 2:numsteps
   % Update and store FE numerical solution
   y_FE = y_FE + h*f(t,y_FE); % update
   y_FE_set(i) = y_FE ; % store
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% Update TS numerical solution
              ----- Your edits (uncomment below) -----
    y_TS = y_TS + h*f(t,y_TS)+h^2/2*(f_t(t,y_TS)+f(t,y_TS)*f_y(t,y_TS));
    y_TS_set(i) = y_TS;
              ----- End of your edits for this part -----
    % Update time
    t = t + h;
end
%% Plot
figure(1); clf;
% Plot the exact solution on [1,2]
tset_fine = linspace(t0, tf, 1000);
plot(tset_fine, 1./tset_fine, 'k-', 'LineWidth', 2); hold on;
% Plot the Forward Euler numerical solution
plot(tset, y_FE_set, 'b:o', 'LineWidth', 1.8, 'MarkerSize', 10, ...
     'MarkerFaceColor', 'k')
st Plot the Taylor Series method numerical solution (uncomment below once your TS solutionoldsymbol{arkappa}
is ready)
 plot(tset, y_TS_set, 'r:o', 'LineWidth', 1.8, 'MarkerSize', 10, ...
    'MarkerFaceColor', 'r')
% Plot settings for making a nice figure
grid on ;
set(gca, 'FontSize', 20)
set(gcf, 'defaultTexTInterpreter', 'Latex')
set(gcf, 'Position', [223 215 641 449])
leg = legend('Exact sol. y(t) = 1/t', 'FE sol.', 'TS sol.');
set(leg, 'Interpreter', 'Latex')
xlabel('Time $t$')
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