Math 151b: Problem Set 3

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- **Problem 1.** (a) Using the Trapezoidal rule, we can approximate the area of the curve $\int_{t_n}^{t_{n+1}} y'(t)dt \approx (t_{n+1}-t_n) \frac{y'(t_{n+1})+y'(t_n)}{2}.$ We are given f(t,y(t))=y'(t) and $h=t_{n+1}-t_n$, so we substitute the expressions into our approximation to obtain $\frac{h}{2}(f(t_{n+1},y(t_{n+1}))+f(t_n,y(t_n))).$ Assume $y_n=y(t_n)$ and let y_{n+1} be our approximation for $y(t_{n+1})$. From (1), solving for $y(t_{n+1})$, we obtain $y_{n+1}=y_n+\frac{h}{2}(f(t_{n+1},y_{n+1})+f(t_n,y_n)).$
 - (b) Using the one-step Forward Euler's method to approximate y_{n+1} in $f(t_{n+1},y_{n+1})$ we obtain $f(t_{n+1},y_{n+1})=f(t_{n+1},y_n+hf(t_n,y_n))$. Substituting into (2) we get $y_{n+1}=y_n+\frac{h}{2}(f(t_{n+1},y_n+hf(t_n,y_n))+f(t_n,y_n))$. Moreover, if we substitute (3a) and (3b) into our expression, we obtain

$$y_{n+1} = y_n + \frac{h}{2}(k_2 + k_1).$$

(c) i. $f(t_{n+1}, y_n + hf(t_n, y_n)) = f(t_n + h, y_n + hf(t_n, y_n))$ Applying the chain rule: $\frac{\partial f}{\partial h} = \frac{\partial f}{\partial t} \frac{\partial t}{\partial h} + \frac{\partial f}{\partial y} \frac{\partial y}{\partial h} = f_t + ff_y$ $\frac{\partial^2 f}{\partial h^2} = \frac{\partial^2 f}{\partial t^2} \left(\frac{\partial t}{\partial h}\right)^2 + \frac{\partial^2 f}{\partial y^2} \left(\frac{\partial y}{\partial h}\right)^2 + 2 \frac{\partial^2 f}{\partial t \partial y} \frac{\partial t}{\partial h} \frac{\partial y}{\partial h} = f_{tt} + f^2 f_{yy} + 2 f f_{ty}$ Second order Taylor expanding around the point (t_n, y_n) , we obtain

$$f(t_n + h, y_n + hf(t_n, y_n))$$

= $f + h(f_t + ff_y) + \frac{h^2}{2}(f_{tt}(\xi, \eta) + 2ff_{ty}(\xi, \eta) + f^2f_{ty}(\xi, \eta))$

ii. Assume $y(t_n) = y_n$. $\tau_{n+1} = y(t_{n+1}) - y_{n+1}$. Taylor expand $y(t_{n+1}) = y(t_n) + hy'(t_n) + \frac{h^2}{2}y''(t_n) + \frac{h^3}{6}y'''(\xi')$ Using (i), $y_{n+1} = y_n + \frac{h}{2}(2f + h(f_t + ff_y) + \frac{h^2}{2}(f_{tt}(\xi, \eta) + 2ff_{ty}(\xi, \eta) + f^2f_{ty}(\xi, \eta)))$ $= y_n + hf + \frac{h^2}{2}(f_t + ff_y) + \frac{h^3}{4}(f_{tt}(\xi, \eta) + 2ff_{ty}(\xi, \eta) + f^2f_{ty}(\xi, \eta))$ Thus, $y(t_{n+1}) - y_{n+1} = [y(t_n) - t_n] + h[y'(t_n) - f] + \frac{h^2}{2}[y''(t_n) - f_t + ff_y]$

+ $\left[\frac{h^3}{6}y'''(\xi') - \frac{h^3}{4}(f_{tt}(\xi,\eta) + 2ff_{ty}(\xi,\eta) + f^2f_{ty}(\xi,\eta))\right]$ We know y'(t) = f(t,y(t)) and $y''(t) = f_t + ff_y$ and assume Hence, $y(t_{n+1}) - y_{n+1} = \left[\frac{h^3}{6}y'''(\xi') - \frac{h^3}{4}(f_{tt}(\xi, \eta) + 2ff_{ty}(\xi, \eta) + f^2f_{ty}(\xi, \eta))\right] = O(h^3)$, so τ_{n+1} is second order accurate.

Problem 2. If $y' = f(t, y) = 1 \Rightarrow k_i = 1$, for $i = 1, 2, \dots s$ Assume $y(t_n) = y_n$. Thus, $h[1 - \sum_{i=1}^{s} b_i k_i] = 0 \Rightarrow 1 - \sum_{i=1}^{s} b_i k_i = 0$. Because $k_i = 1$, for $i = 1, 2, \dots, s = 1$.

Because k_i = $\sum_{i=1}^{s} b_i = 1$. If $\sum_{i=1}^{s} b_i = 1$, then $1 - \sum_{i=1}^{s} b_i k_i = 0$, Thus, $h[y'(t_n) = f(t, y_n)] = 0$, so the numerical method is at least first order accurate.

- Problem 3. (a) $\mathbf{f}(t, \mathbf{y}) = \begin{bmatrix} x' \\ 2y' + x \frac{\mu_0(x+\mu)}{r_1^3} \frac{\mu(x-\mu_0)}{r_2^3} \\ y' \\ -2x + y \frac{\mu_0 y}{r_1^3} \frac{\mu y}{r_2^3} \end{bmatrix}$
 - (c) I used about 20000 steps in my function.
 - (d) I chose an error tolerance of 10^{-7} as my absolute error tolerance. I used a max step size of 0.01, so RK45 used 1725 steps.

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In [1]:
         import numpy as np
         import math as m
         from matplotlib import pyplot as plt
         from scipy import integrate
In [2]:
         y_0=np.array([0.994,0,0,-2.00158510637908252240537862224])
         points = 20000
         t = np.linspace(0,17.1,points)
In [3]:
         def f(t,y):
             mu=0.012277471
             mu_0=1-mu
             r_1=m.sqrt((y[0]+mu)**2+y[1]**2)
             r_2=m.sqrt((y[0]-mu_0)**2+y[1]**2)
             dx=2*y[3]+y[0]-mu_0*(y[0]+mu)/(r_1**3)-mu*(y[0]-mu_0)/(r_2**3)
             dy=-2*y[2]+y[1]-mu_0*y[1]/(r_1**3)-mu*y[1]/(r_2**3)
             return np.array([y[2],y[3],dx,dy])
In [4]:
         def RK_method(f,y_0,t):
             y = np.zeros([len(t),4])
             y[0] = y_0
             for i in range(0,len(t)-1):
                 h = t[i+1]-t[i]
                 F1 = f(t[i],y[i])
                 F2 = f((t[i]+h/2),(y[i]+F1*h/2))
                 F3 = f((t[i]+h/2),(y[i]+F2*h/2))
                 F4 = f((t[i]+h),(y[i]+F3*h))
                 y[i+1] = y[i] + h/6*(F1 + 2*F2 + 2*F3 + F4)
             return y.transpose()
In [5]:
         y_RK = RK_method(f, y_0, t)
In [6]:
         mu=0.012277471
         plt.plot(y_RK[0],y_RK[1],'k-', label = "Orbit")
         plt.plot(mu,0,'ro',label="Planet A")
         plt.plot(1-mu,0,'bo',label="Planet B")
         plt.legend()
Out[6]: <matplotlib.legend.Legend at 0x7f90f8406940>
                                                  Orbit
         1.0
                                                  Planet A
                                                  Planet B
         0.5
          0.0
         -0.5
         -1.0
                  -1.0
                           -0.5
                                    0.0
                                             0.5
                                                      1.0
In [7]:
         solution=integrate.solve_ivp(f,[0,17.1],y_0,max_step=0.01,atol=10e-7)
         plt.plot(solution.y[0], solution.y[1], 'k-', label = "Orbit")
         plt.plot(mu,0,'ro',label="Planet A")
         plt.plot(1-mu,0,'bo',label="Planet B")
         plt.legend()
```

Out[7]: <matplotlib.legend.Legend at 0x7f90f840e0d0>

