

COSC264

Introduction to Computer Networks and the Internet

Introduction to Routing- Link State Routing

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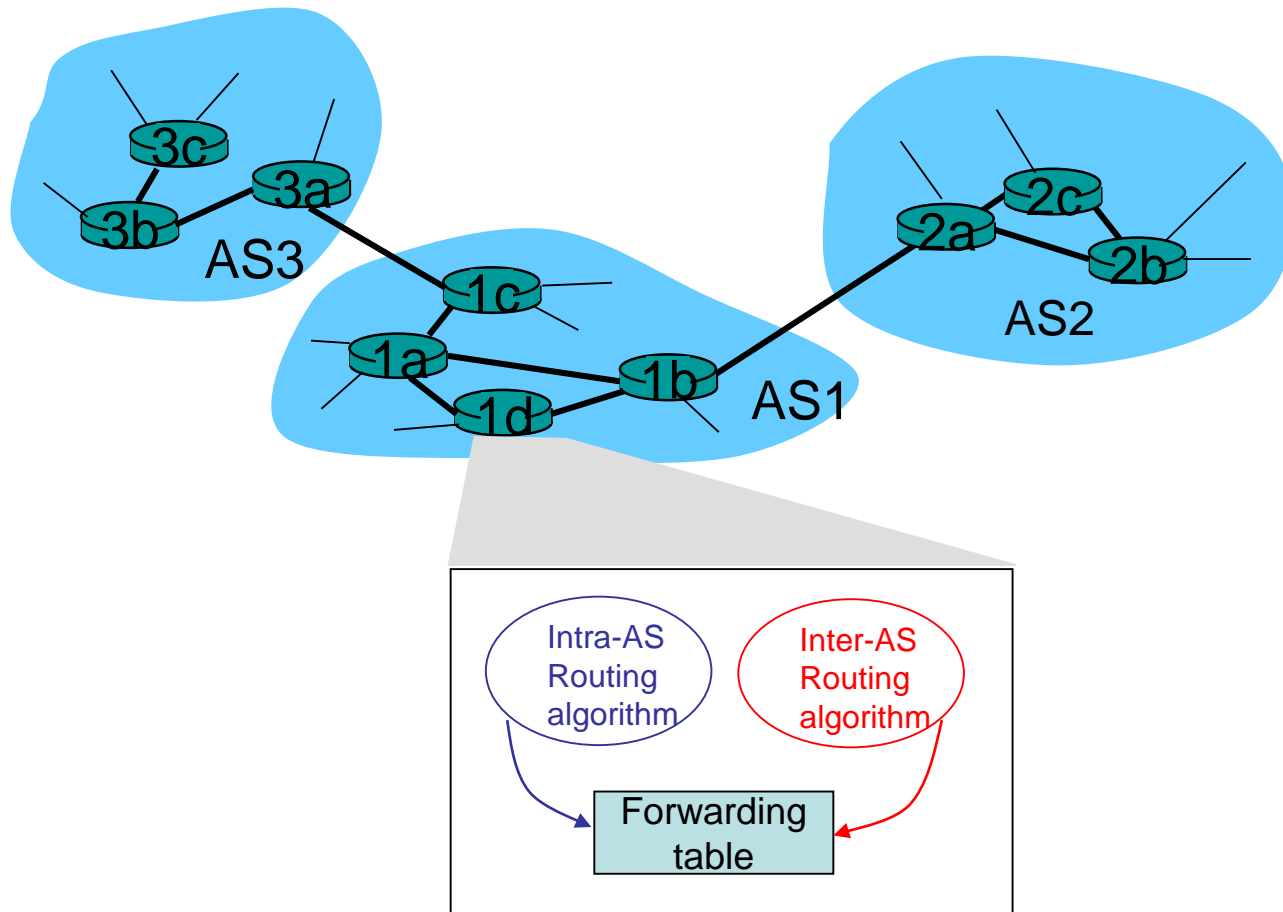
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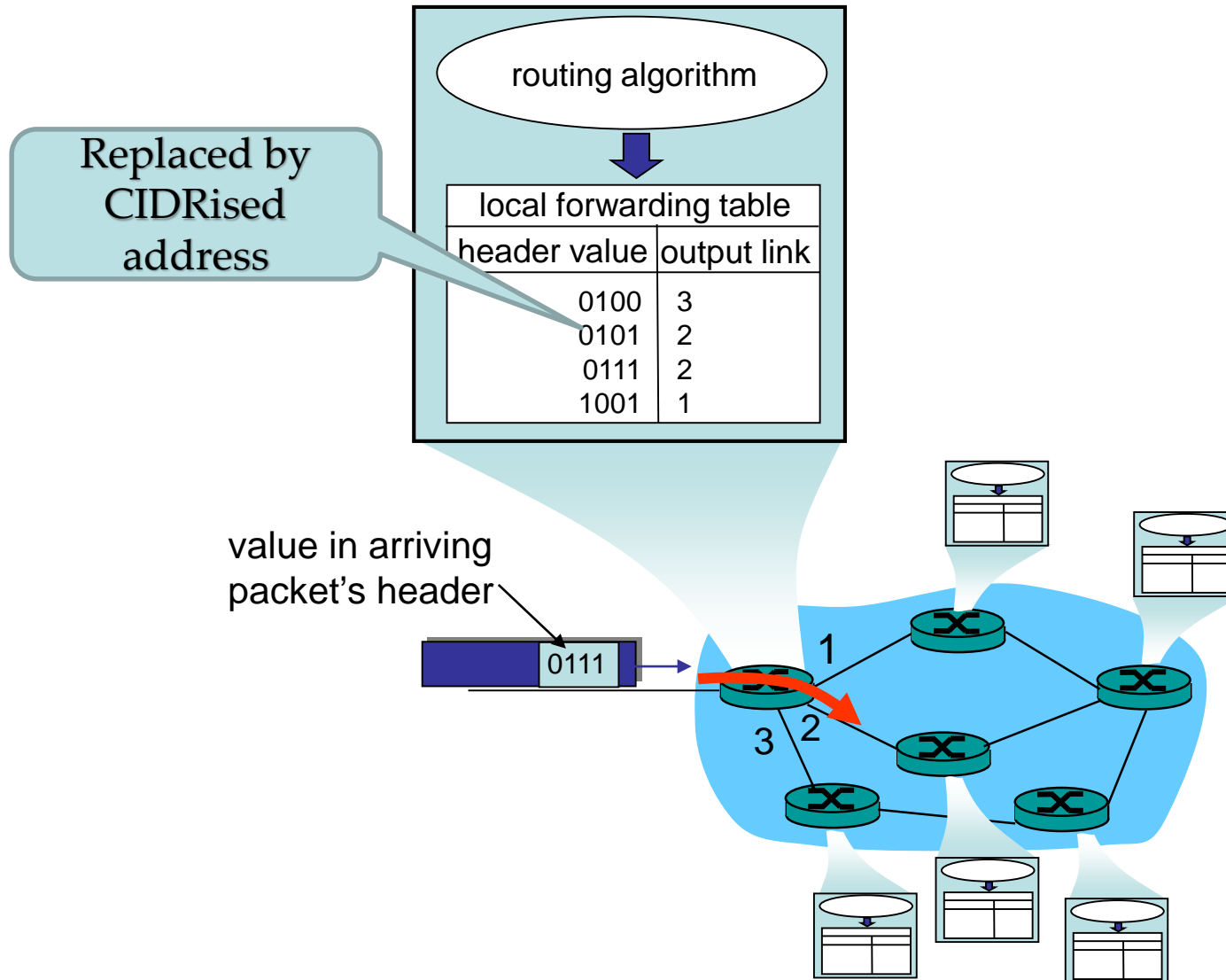
A quick review

- Layer approach and services
- Hierarchical routing and Autonomous System (AS)
- Routing vs forwarding
- Classification of routing algorithms

Hierarchical routing in the Internet



Routing and Forwarding



Outline – today

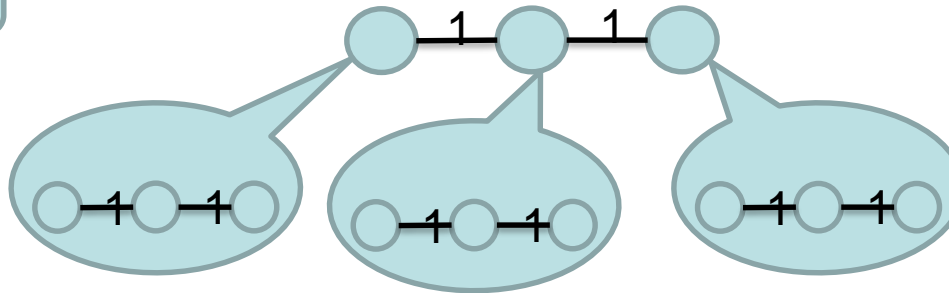
- Network layer overview
- Routing overview
- **Link-state routing (Dijkstra's algorithm)**
- Distance-vector routing (Bellman-Ford)
- Summary

Routing Algorithms and Routing Protocols

Intra-AS Routing

| Routing Protocols | Routing Algorithms |
|-------------------|--|
| RIP | Bellman-Ford (Distance-vector) Algorithm |
| OSFP | Dijkstra's Algorithm |
| BGP | Bellman-Ford (Distance-vector) Algorithm |

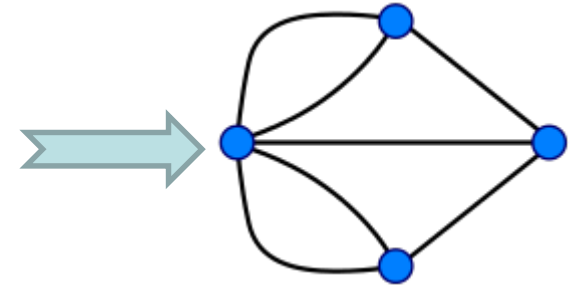
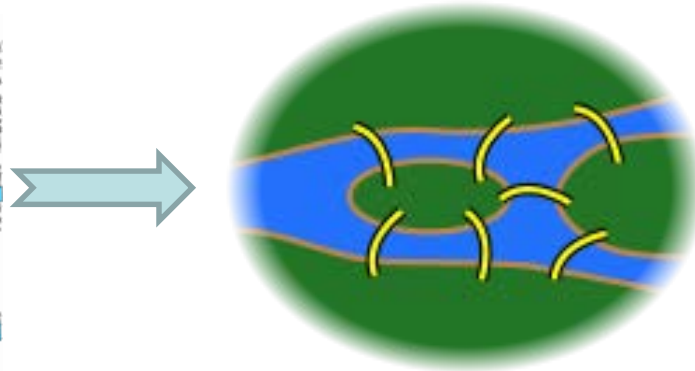
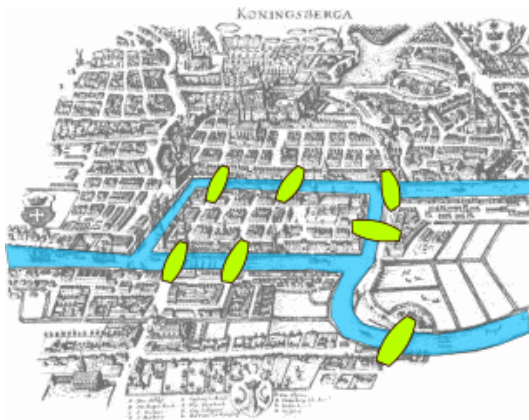
Inter-AS Routing



The Internet routing protocols (RIP, OSPF, and BGP) are *load-insensitive*.

Euler and Graph Theory

- Seven Bridges of Königsberg. 1783
- [Wiki](#)

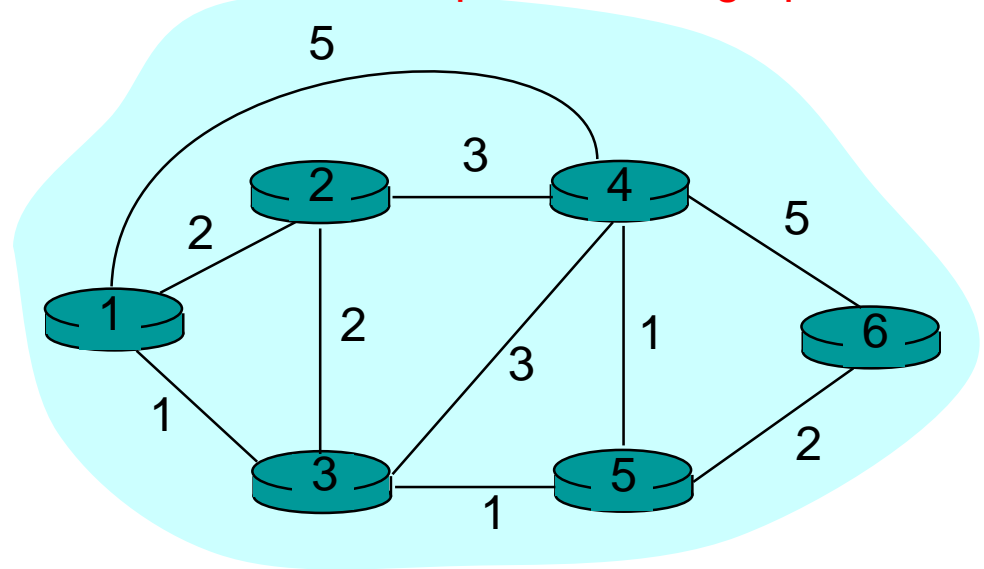


Modeling a network

- Modeled as a graph

- Routers \Rightarrow nodes
- Link \Rightarrow edges

Another example network graph

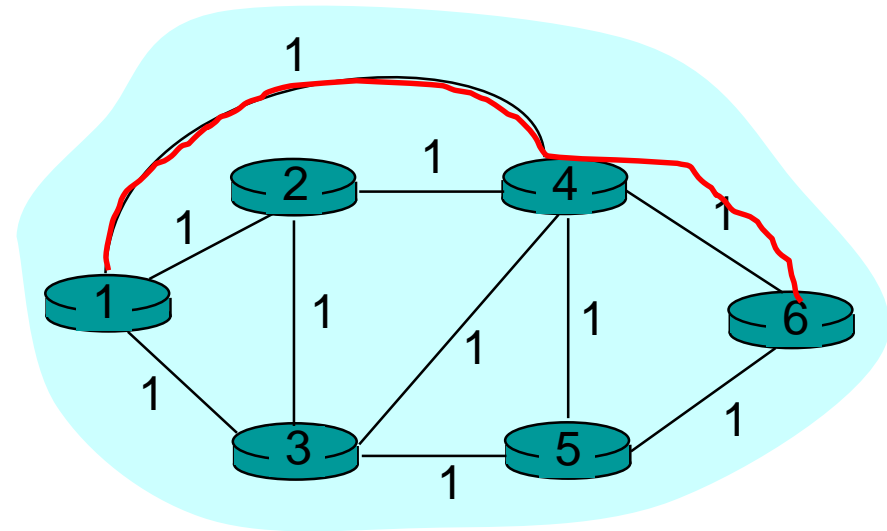
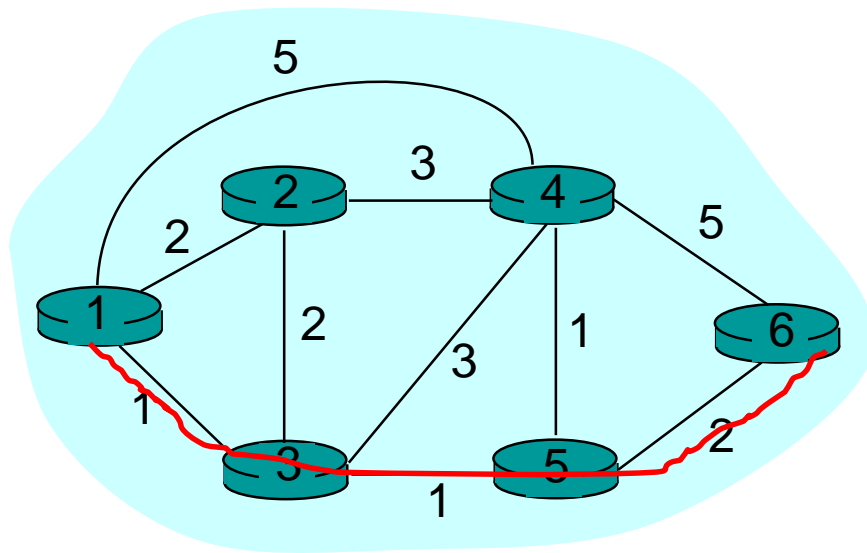


- Edge labels (called metrics) can be interpreted differently

- as costs, e.g., delay, monetary transmission costs, geographical distance
- as available resources, e.g., number of available phone trunks, current available capacity given the set of flows that already use this link

Routing algorithms

- To find least cost path
 - **Shortest path** if all link costs equal (measures hops)

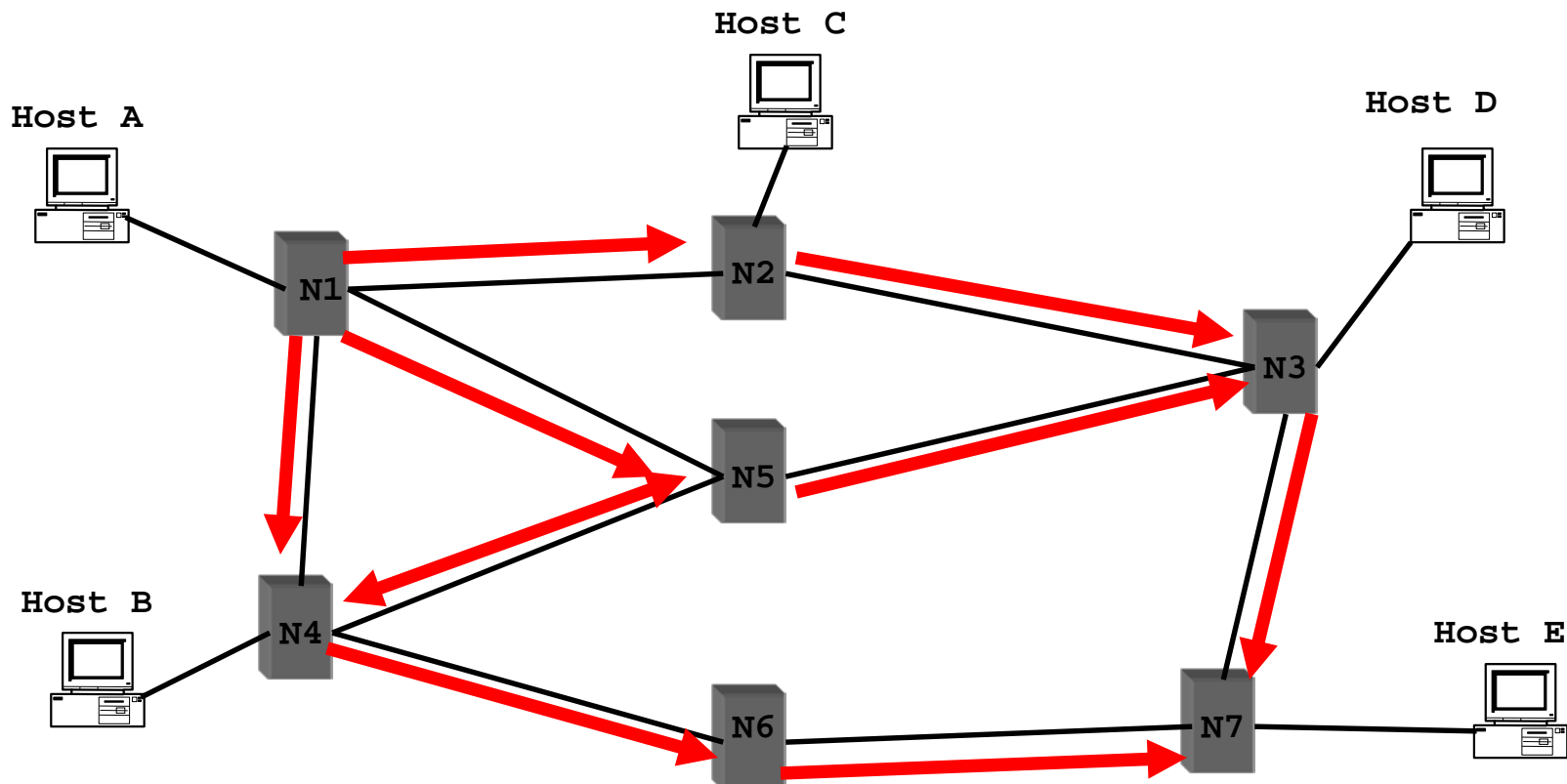


Link State Routing

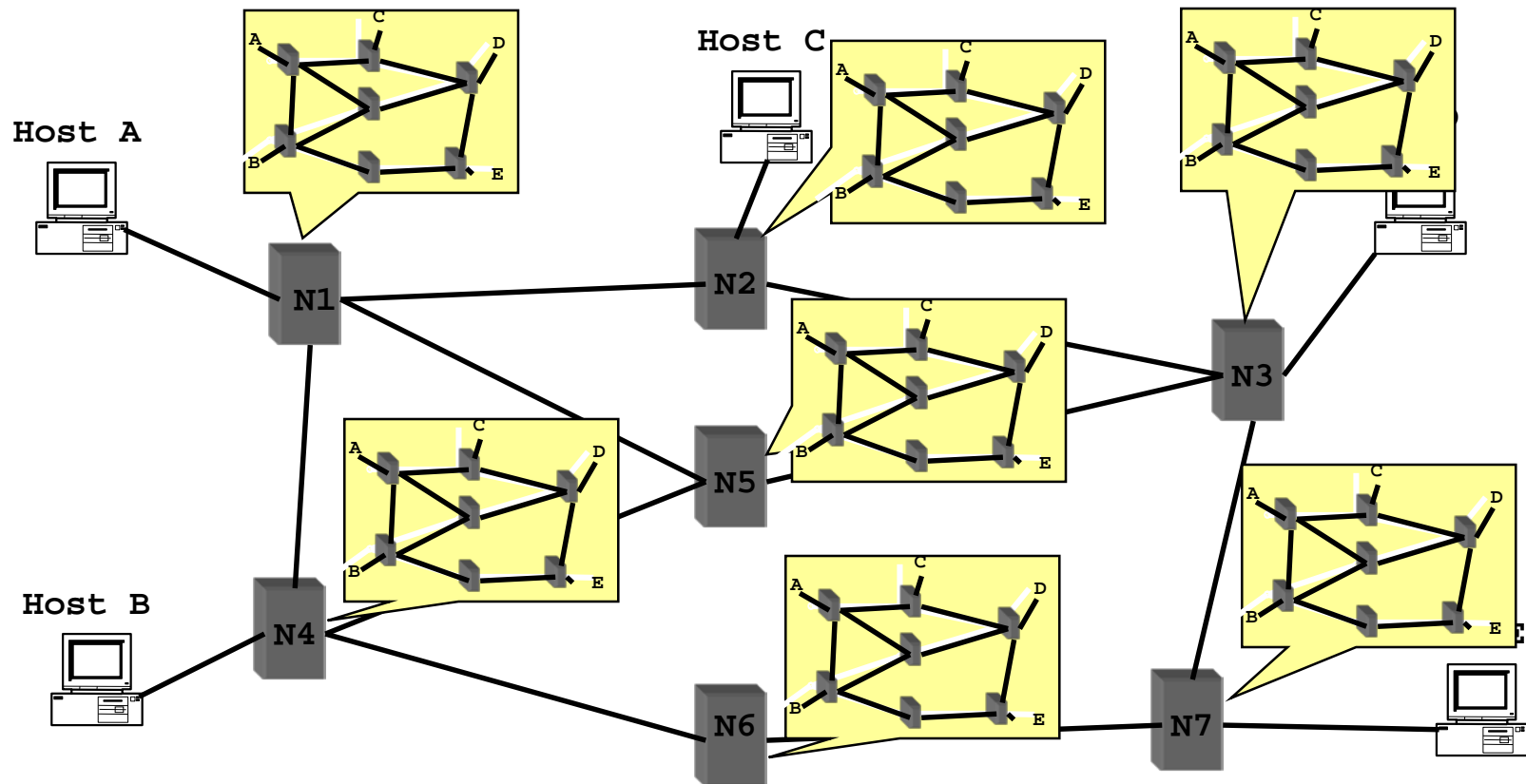
- Each router has **complete network picture**
 - Topology, Link costs
- How does each router get the global state?
 - Each router reliably **floods** information about its neighbors to every other router;
 - All routers have consistent information;

Link State: Control Traffic

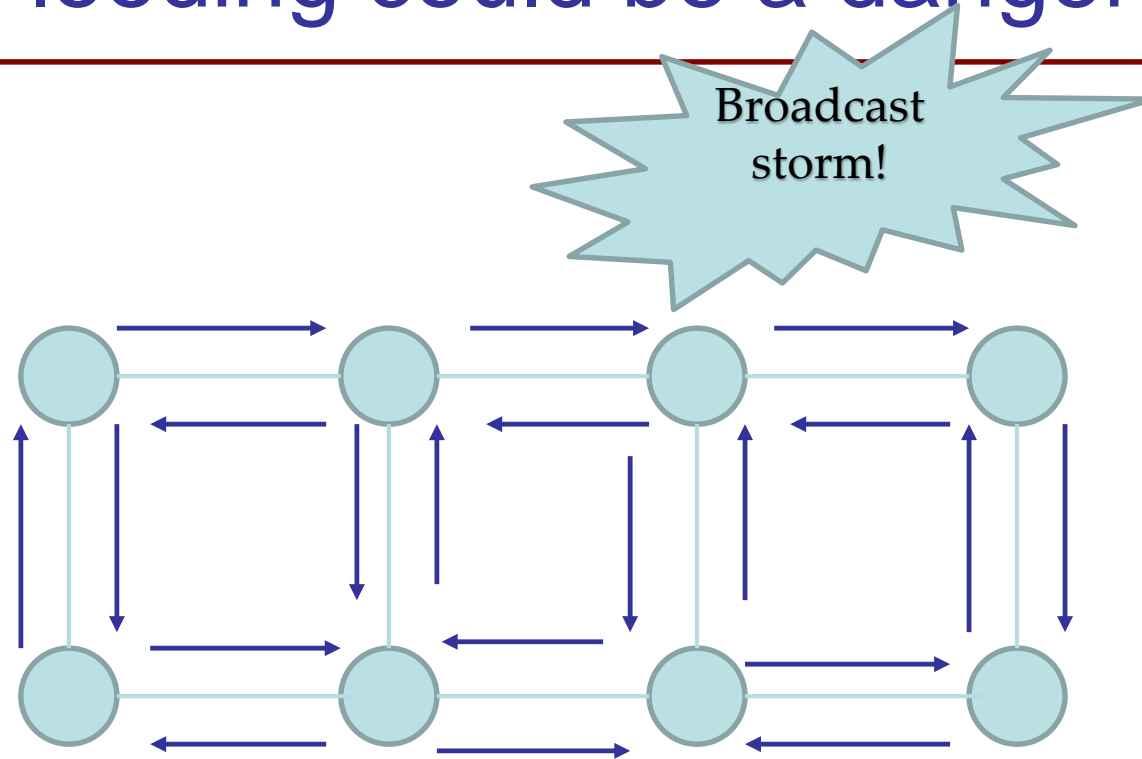
- Each node floods its local information
- Each node ends up knowing the *entire* network topology



Link State: Node State



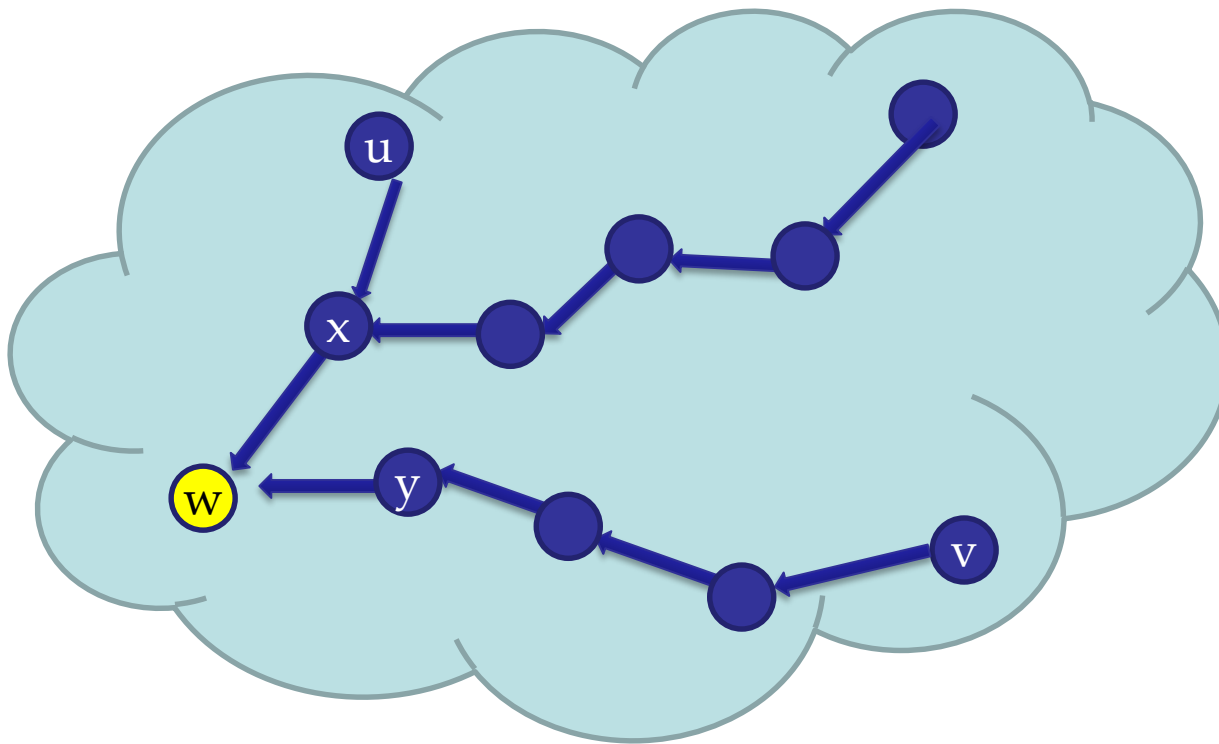
Flooding could be a danger!



There are sophisticated algorithms doing the broadcasting job!
(Controlled flooding, spanning-tree broadcast)

Link State Routing

- Each router independently calculates the least-cost path from itself to every other router;
 - Using Dijkstra's Algorithm;
 - Generates a forwarding table for every destination;



| Dest. | Next-hop |
|-------|----------|
| u | x |
| v | y |
| ... | ... |

Dijkstra's Algorithm

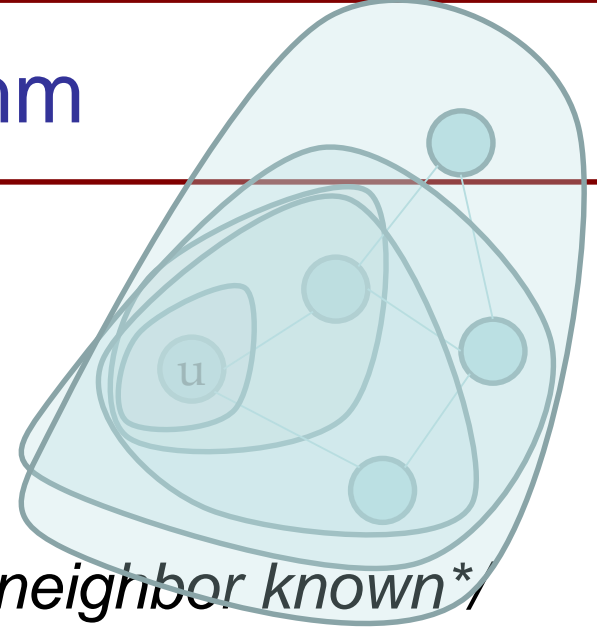
- INPUT:
 - Network topology (graph), with link costs

- OUTPUT:
 - Least cost paths from one node to all other nodes

Dijkstra's Algorithm

- **S**: nodes whose least-cost path already known
 - Initially, $\mathbf{S} = \{u\}$ where u is the source node
 - Add one node to **S** in each iteration
- **D(v)**: current cost of path from source to node v
 - Initially, $\mathbf{D}(v) = \mathbf{c}(u, v)$ for all nodes v adjacent to u
 - ... and $\mathbf{D}(v) = \infty$ for all other nodes v
 - Continually update **D(v)** as shorter paths are learned
- $p(v)$: predecessor node along path from source to v , that is next to v
- $c(i, j)$: link cost from node i to j ; cost infinite if not direct neighbors; ≥ 0

Dijkstra's Algorithm



1 *Initialization:*

2 $S = \{u\}$ /* u is the source */

3 for all nodes v

4 if v is adjacent to u {

5 then $D(v) = c(u, v)$ /* cost of neighbor known */

6 else $D(v) = \infty$ /* cost of others unknown */

7

8 *Loop*

9 find w not in S with the smallest $D(w)$

10 add w to S

11 update $D(v)$ for all v adjacent to w and **not in S** :

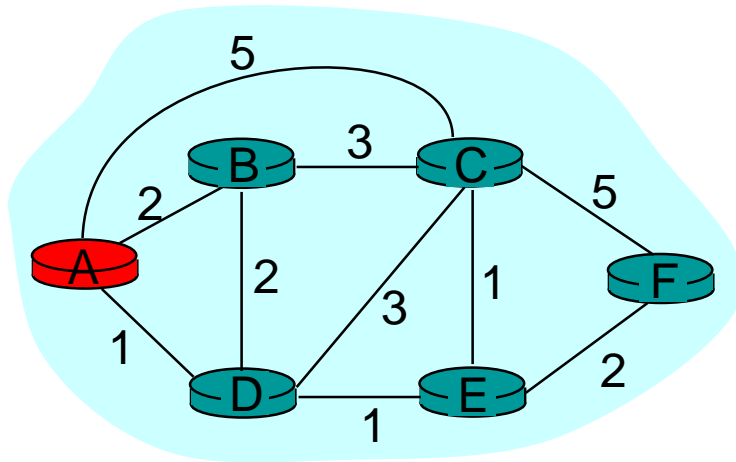
12 $D(v) = \min\{D(v), D(w) + c(w, v)\}$

/* new cost to v is either old cost to v or known
shortest path cost to w plus cost from w to v */

13 until *all nodes in S*

Example: Dijkstra's Algorithm

| Step | start S | D(B),p(B) | D(C),p(C) | D(D),p(D) | D(E),p(E) | D(F),p(F) |
|------|---------|-----------|-----------|-----------|-----------|-----------|
| → 0 | A | 2,A | 5,A | 1,A | ∞ | ∞ |
| 1 | | | | | | |
| 2 | | | | | | |
| 3 | | | | | | |
| 4 | | | | | | |
| 5 | | | | | | |

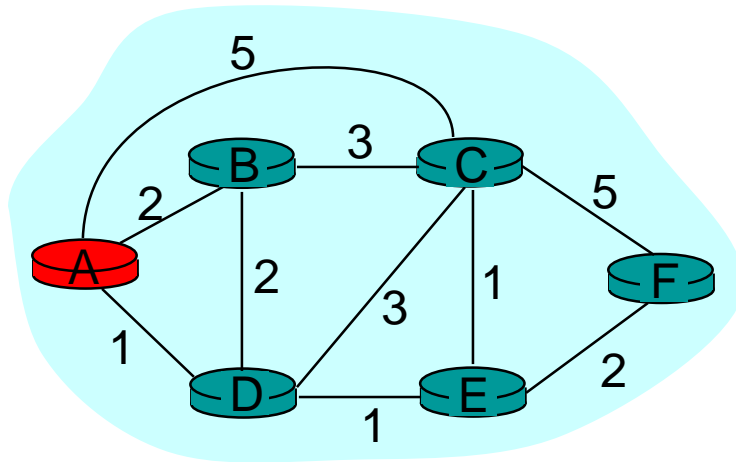


```

1 Initialization:
2 S = {A};
3 for all nodes v
4   if v is adjacent to A
5     then D(v) = c(A,v);
6     else D(v) =  $\infty$ ;
...
  
```

Example: Dijkstra's Algorithm

| Step | start S | D(B),p(B) | D(C),p(C) | D(D),p(D) | D(E),p(E) | D(F),p(F) |
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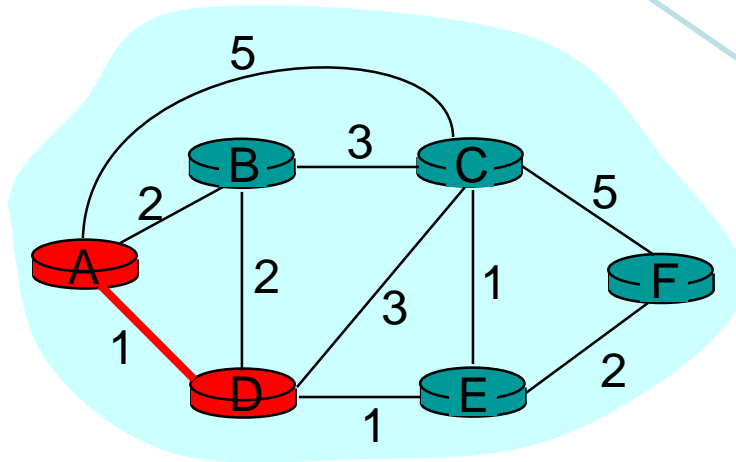


```

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8  Loop
9  find w not in S s.t.  $D(w)$  is a minimum;
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11 update  $D(v)$  for all v adjacent
    to w and not in S:
12 If  $D(w) + c(w,v) < D(v)$  then  $D(v) =$ 
     $D(w) + c(w,v)$ ;  $p(v) = w$ ;
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| 0 | A | 2,A | 5,A | 1,A | ∞ | ∞ |
| 1 | AD | | | | | |
| 2 | | | | | | |
| 3 | | | | | | |
| 4 | | | | | | |
| 5 | | | | | | |

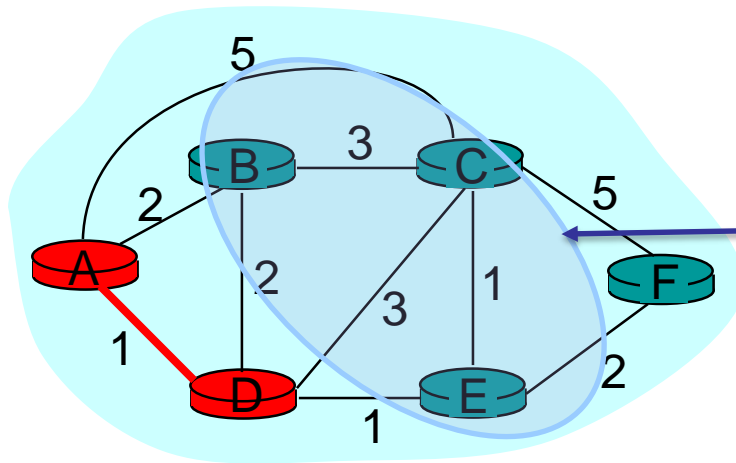


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| 2 | | | | | | |
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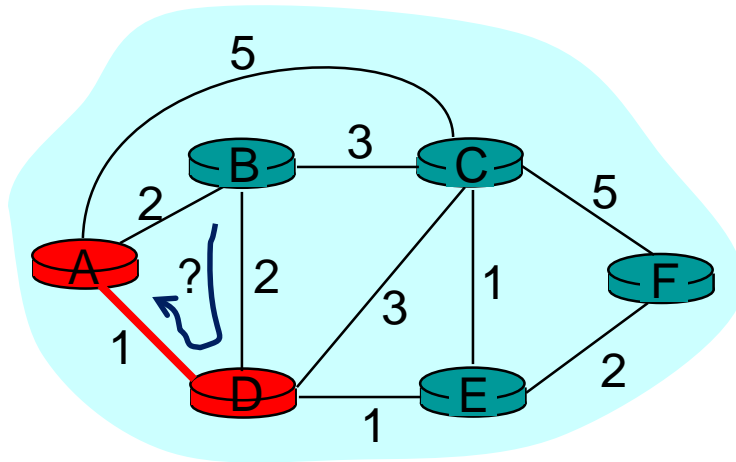


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| 2 | | | | | | |
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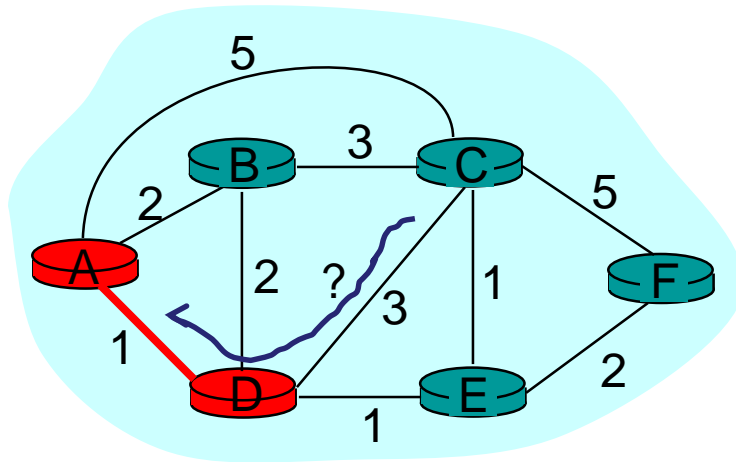


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|------|---------|-----------|-----------|------------------|-----------|-----------|
| 0 | A | 2,A | 5,A | 1,A | ∞ | ∞ |
| 1 | AD | 2,A | 4,D | 1,A | | ∞ |
| 2 | | | | | | |
| 3 | | | | | | |
| 4 | | | | | | |
| 5 | | | | | | |

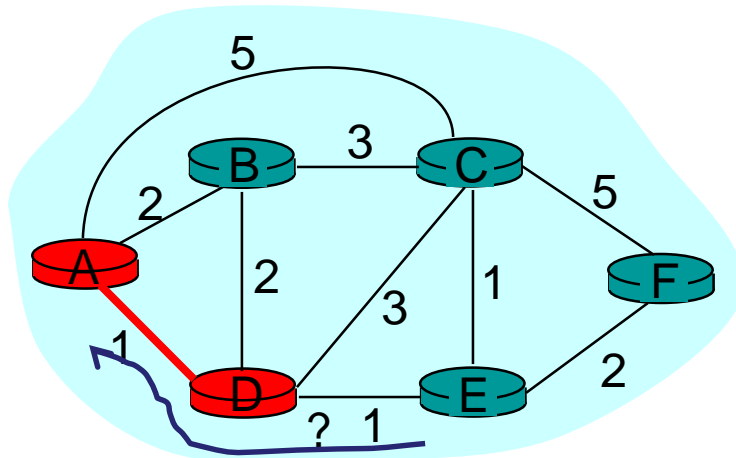


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| 4 | | | | | | |
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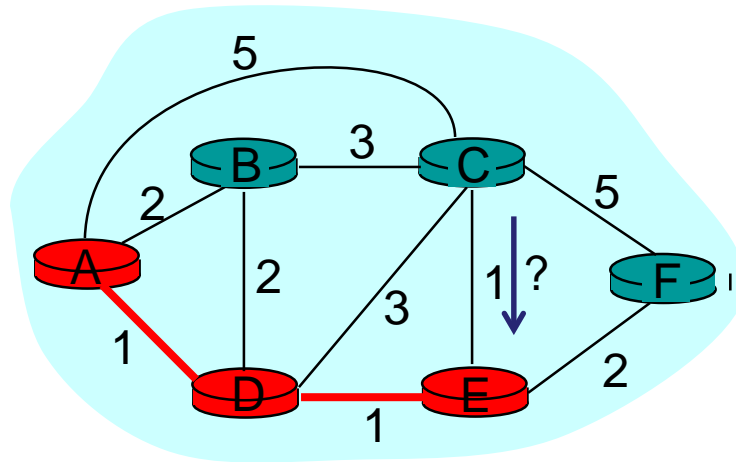


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| 0 | A | 2,A | 5,A | 1,A | ∞ | ∞ |
| 1 | AD | 2,A | 4,D | 1,A | 2,D | ∞ |
| 2 | ADE | 2,A | 3,E | 1,A | 2,D | |
| 3 | | | | | | |
| 4 | | | | | | |
| 5 | | | | | | |

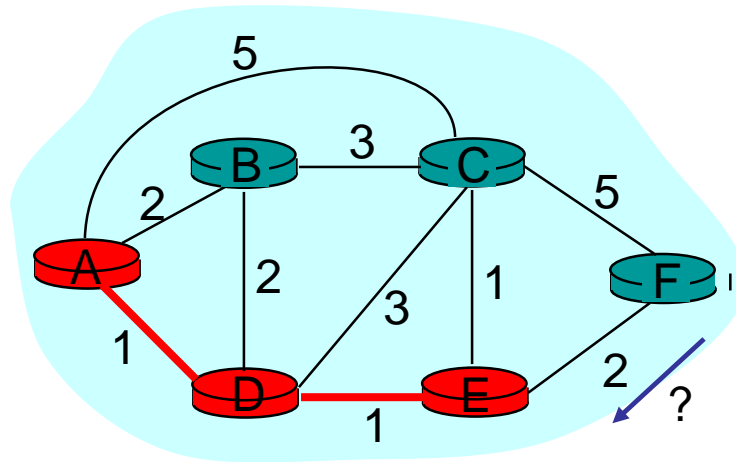


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| 2 | ADE | 2,A | 3,E | 1,A | 2,D | 4,E |
| 3 | | | | | | |
| 4 | | | | | | |
| 5 | | | | | | |

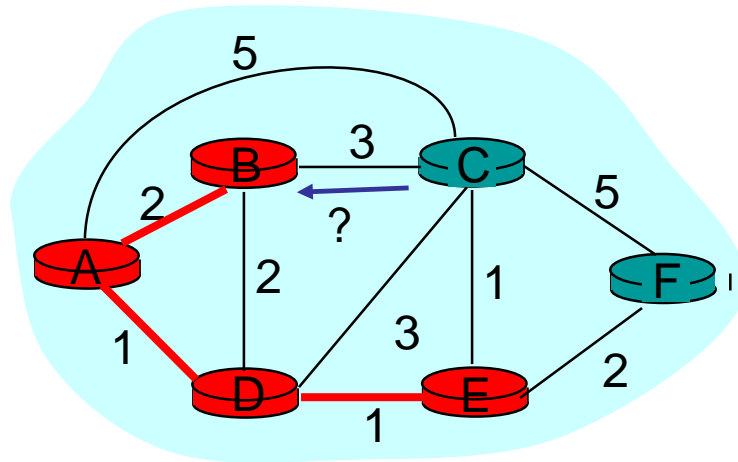


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| 1 | AD | 2,A | 4,D | 1,A | 2,D | ∞ |
| 2 | ADE | 2,A | 3,E | 1,A | 2,D | 4,E |
| → 3 | ADEB | 2,A | 3,E | 1,A | 2,D | 4,E |
| 4 | | | | | | |
| 5 | | | | | | |

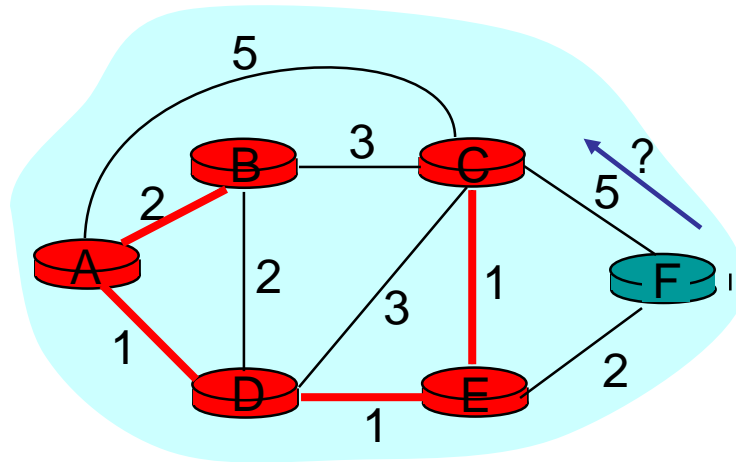


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| 1 | AD | 2,A | 4,D | 1,A | 2,D | ∞ |
| 2 | ADE | 2,A | 3,E | 1,A | 2,D | 4,E |
| 3 | ADEB | 2,A | 3,E | 1,A | 2,D | 4,E |
| 4 | ADEBC | 2,A | 3,E | 1,A | 2,D | 4,E |
| 5 | | | | | | |

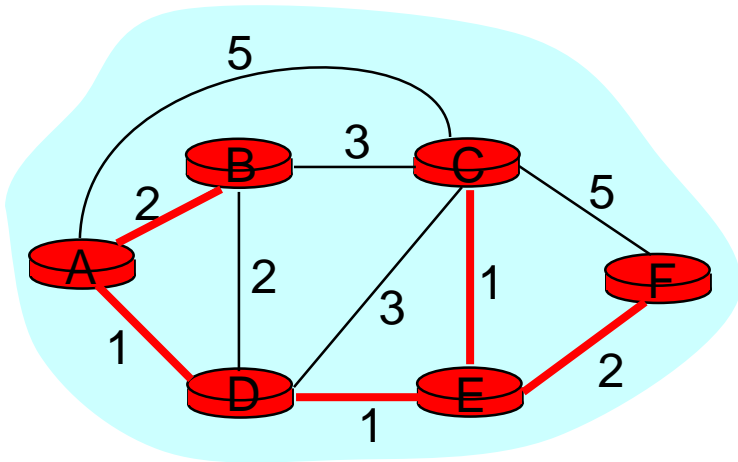


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|------|---------|-----------|-----------|-----------|-----------|-----------|
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| 1 | AD | 2,A | 4,D | 1,A | 2,D | ∞ |
| 2 | ADE | 2,A | 3,E | 1,A | 2,D | 4,E |
| 3 | ADEB | 2,A | 3,E | 1,A | 2,D | 4,E |
| 4 | ADEBC | 2,A | 3,E | 1,A | 2,D | 4,E |
| 5 | ADEBCF | 2,A | 3,E | 1,A | 2,D | 4,E |

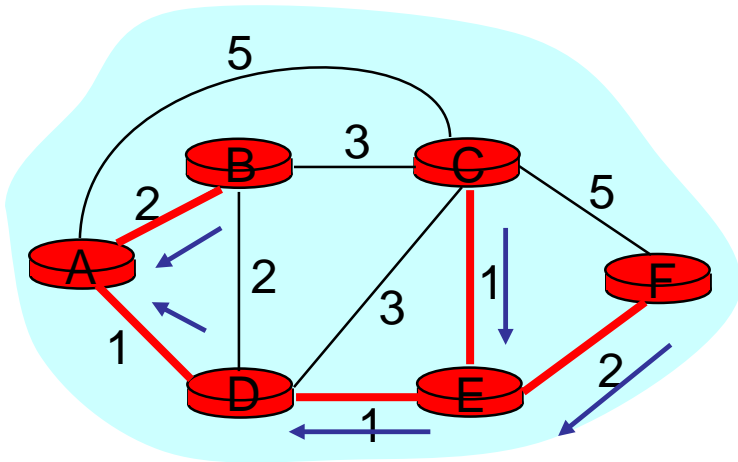


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| 0 | A | 2,A | 5,A | 1,A | ∞ | ∞ |
| 1 | AD | 2,A | 4,D | 1,A | 2,D | ∞ |
| 2 | ADE | 2,A | 3,E | 1,A | 2,D | 4,E |
| 3 | ADEB | 2,A | 3,E | 1,A | 2,D | 4,E |
| 4 | ADEBC | 2,A | 3,E | 1,A | 2,D | 4,E |
| 5 | ADEBCF | 2,A | 3,E | 1,A | 2,D | 4,E |

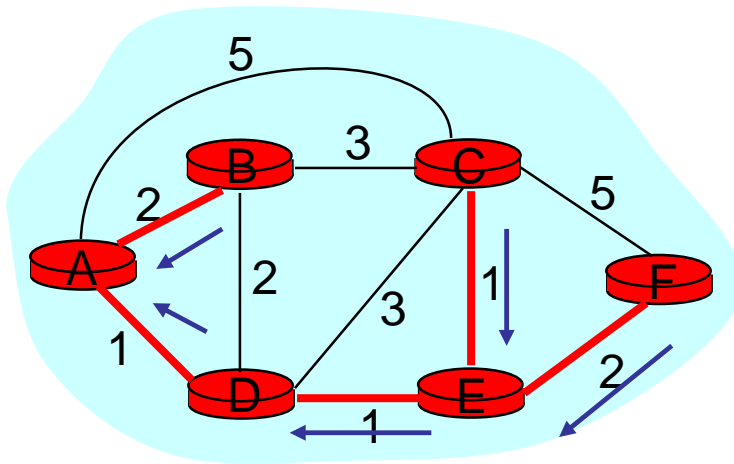


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13  until all nodes in S;
    
```

The Forwarding Table


- Running Dijkstra at node *A* gives the shortest path from *A* to all destinations
- We then construct the *forwarding* table



| Destination | Next hop |
|-------------|----------|
| B | B |
| C | D |
| D | D |
| E | D |
| F | D |

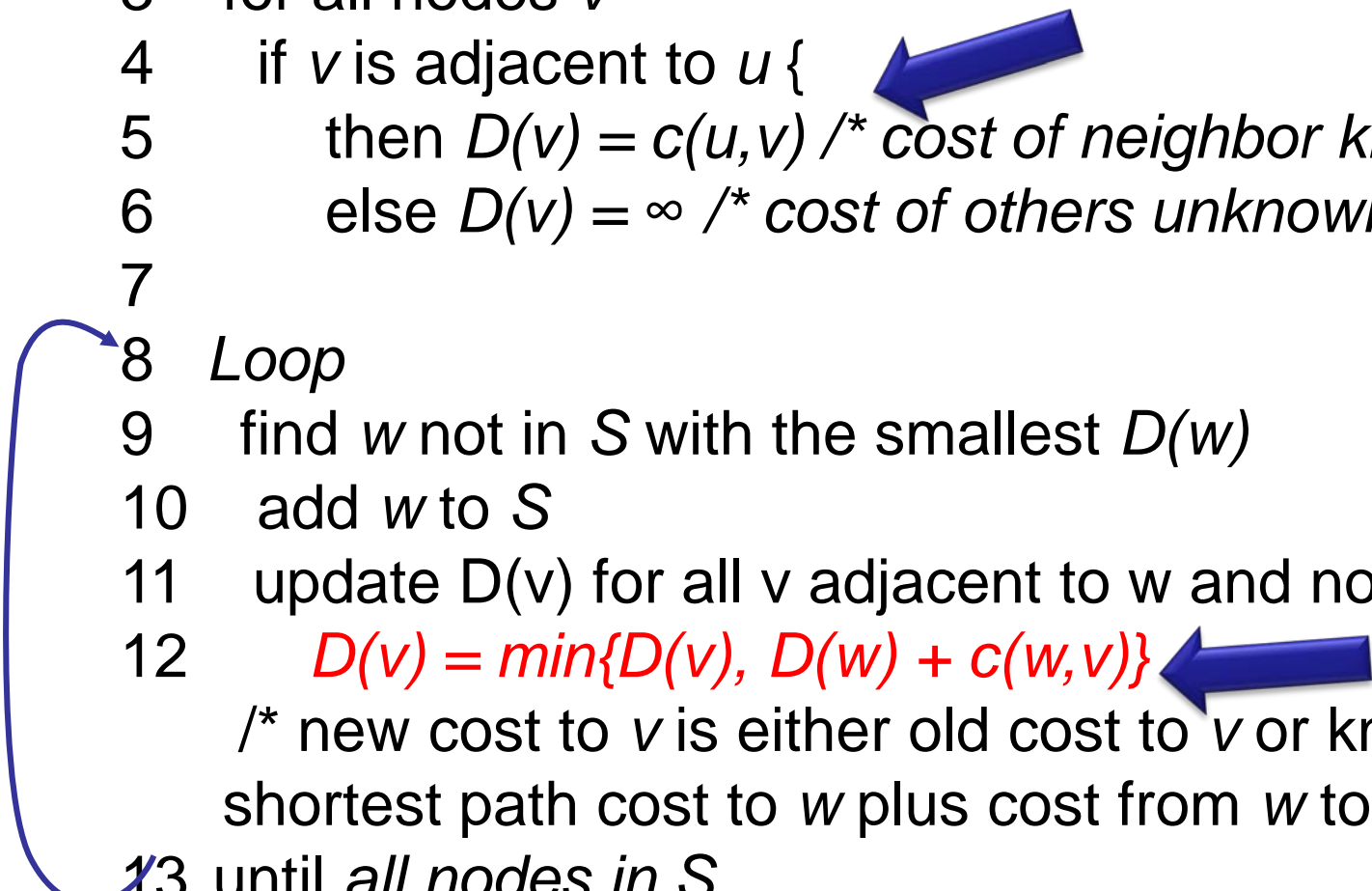
Dijkstra's Algorithm – set $p(v)$

```
1  Initialization:
2   $S = \{u\}$  /*  $u$  is the source */
3  for all nodes  $v$ 
4    if  $v$  is adjacent to  $u$  {
5      then  $D(v) = c(u, v)$  /* cost of neighbor known */
6      else  $D(v) = \infty$  /* cost of others unknown */
7
8  Loop
9    find  $w$  not in  $S$  with the smallest  $D(w)$ 
10   add  $w$  to  $S$ 
11   update  $D(v)$  for all  $v$  adjacent to  $w$  and not in  $S$ :
12      $D(v) = \min\{D(v), D(w) + c(w, v)\}$ 
13     /* new cost to  $v$  is either old cost to  $v$  or known
        shortest path cost to  $w$  plus cost from  $w$  to  $v$  */
14 until all nodes in  $S$ 
```



Dijkstra's Algorithm – set $p(v)$

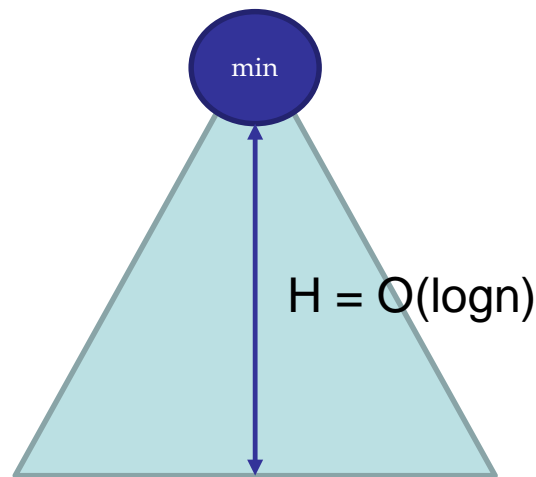
```
1  Initialization:
2   $S = \{u\}$  /*  $u$  is the source */
3  for all nodes  $v$ 
4    if  $v$  is adjacent to  $u$  {
5      then  $D(v) = c(u, v)$  /* cost of neighbor known */
6      else  $D(v) = \infty$  /* cost of others unknown */
7
8  Loop
9    find  $w$  not in  $S$  with the smallest  $D(w)$ 
10   add  $w$  to  $S$ 
11   update  $D(v)$  for all  $v$  adjacent to  $w$  and not in  $S$ :
12      $D(v) = \min\{D(v), D(w) + c(w, v)\}$ 
13   /* new cost to  $v$  is either old cost to  $v$  or known
    shortest path cost to  $w$  plus cost from  $w$  to  $v$  */
14 until all nodes in  $S$ 
```



Dijkstra's algorithm, discussion

Algorithm complexity: n nodes

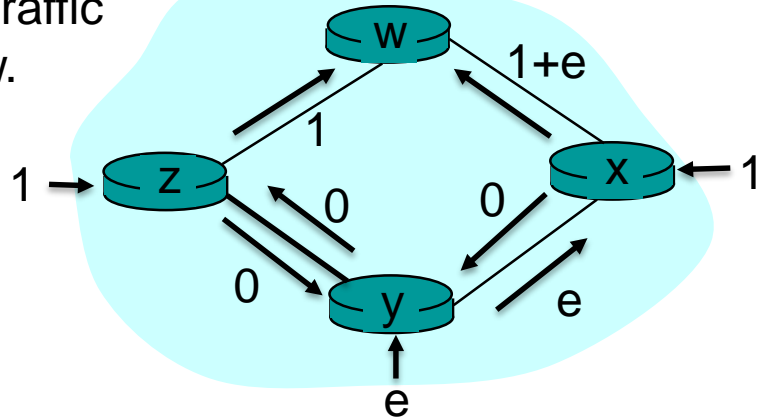
- each iteration: need to check every node, w , not in N
- $n(n-1)/2$ comparisons: $O(n^2)$
- more efficient implementations possible: $O(n \log n)$
 - Using a min-heap;
 - we can find out the node with min cost in $O(\log n)$;
 - Total cost = $O(\log(n-1) + \log(n-2) + \dots + \log 1)$
 - $= O(n \log n)$.



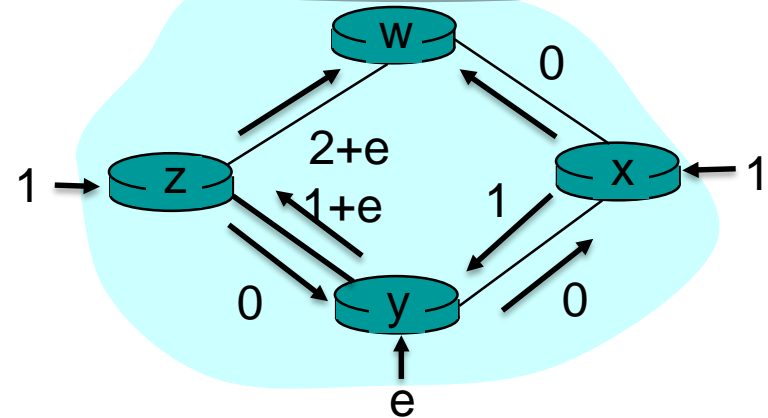
Oscillation with link-state routing

Today's Internet routing algorithms are load-*insensitive*!

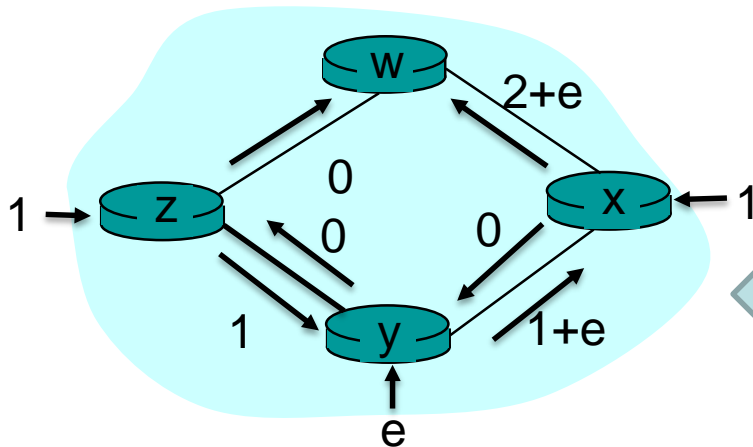
Dest. of
all traffic
is w.



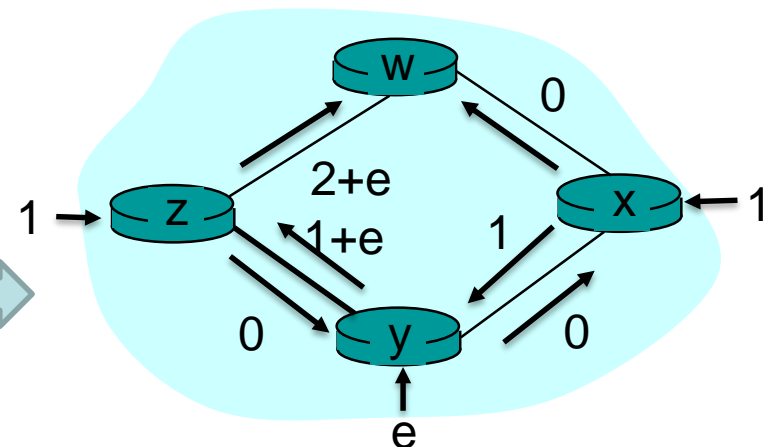
a. Initial routing



b. x,y detect better path to w, clockwise



c. x, y, z detect better path to w,
counterclockwise



d. x,y,z detect better path to w, clockwise

Summary: Link-State Routing

- Each router broadcasts the link state
 - To give every router a complete view of the graph
- Each router runs Dijkstra's algorithm
 - Compute least-cost paths, then construct forwarding table

References

- [KR3] James F. Kurose, Keith W. Ross, *Computer networking: a top-down approach featuring the Internet*, 3rd edition.

Acknowledgements

- Slides are developed mainly based on slides from the following two sources:
 - Prof Aleksandar Kuzmanovic's lecture notes for CS340, Northwestern University,
https://users.cs.northwestern.edu/~akuzma/classes/CS340-w05/lecture_notes.htm