

Numerics Homework 3 - Finite Element

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Poisson System:

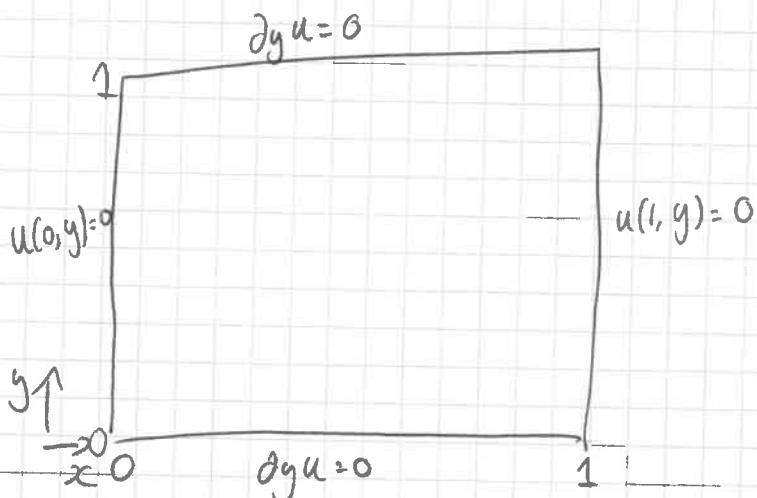
$$-\nabla^2 u = f$$

$$-\nabla^2 u = f \quad \text{on } (x, y) \in [0, 1]^2$$

$$f(x, y) = 2\pi^2 \sin(\pi x) \cos(\pi y)$$

$$u(0, y) = u(1, y) = 0 \quad (\text{Dirichlet})$$

$$\partial_y u(x, y)|_{y=0} = \partial_y u(x, y)|_{y=1} = 0 \quad (\text{Neumann})$$



boundary $\partial\Omega = \Gamma_1 \cup \Gamma_2$ $\Gamma_1 = x = 0, 1 (\partial\Omega_D) \quad \Gamma_2: y = 0, 1 (\partial\Omega_N)$

exact solution is $u_e(x, y) = \sin(\pi x) \cos(\pi y)$

$$\frac{\partial}{\partial x} (\sin(\pi x) \cos(\pi y)) = \pi \sin(\pi x) \cos(\pi y)$$

$$\frac{\partial^2}{\partial x^2} (\sin(\pi x) \cos(\pi y)) = -\pi^2 \sin(\pi x) \cos(\pi y)$$

$$\frac{\partial^2}{\partial y^2} (\sin(\pi x) \cos(\pi y)) = -\pi^2 \sin(\pi x) \cos(\pi y)$$

$$\frac{\partial^2 u}{\partial y^2} = -\pi^2 \sin(\pi x) \cos(\pi y)$$

$$\nabla^2 u = -\pi^2 (\sin(\pi y) +$$

$$-\nabla^2 u = +\pi^2 (\sin(\pi x) \cos(\pi y) + \sin(\pi x) \cos(\pi y))$$

$$-\nabla^2 u = 2\pi^2 \sin(\pi x) \cos(\pi y)$$

$$\Rightarrow -\nabla^2 u = f$$

exact solution

1. Step 1:

~~Ritz-Galerkin principle ad devi the weak
formulation~~

1. Step 1:

To solve poisson system numerically we need to be able to write $u(x,y)$ as a sum of weighted shape functions. $u(x,y) = \sum_{i=0}^n u_i N_i(x,y)$ where N_i is a shape function, 1 at node i and 0 at other nodes. (n is number of nodes). Weights are u_i .

∴

To find the weights, want to put the poisson system in a weak formulation.

① Step 1: Weak formulation

Find weak formulation through a test function

Method 1

$$-\nabla^2 u = f \quad : \text{strong form}$$

Multiply by test function $w(x,y)$, this is an arbitrary function of x and y .

$$-\nabla^2 u(x,y) w(x,y) = f(x,y) w(x,y)$$

integrate over domain Ω

$$-\int_{\Omega} \nabla^2 u(x,y) w(x,y) d\Omega = \int_{\Omega} f(x,y) w(x,y) d\Omega \quad ①$$

Use partial integration to change form of LHS.
Want to change form of RHS.

$$-\int_{\Omega} \nabla^2 u w d\Omega \Rightarrow \text{LHS.}$$

PRODUCT RULE

$$\nabla \cdot (w \nabla u) = w \nabla^2 u + \nabla u \cdot \nabla w$$

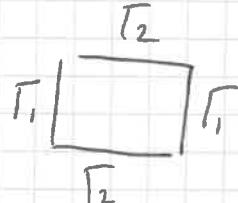
$$\Rightarrow -w \nabla^2 u = \nabla u \cdot \nabla w - \nabla \cdot (w \nabla u)$$

$$\Rightarrow - \int_{\Omega} w \nabla^2 u \, d\Omega = - \int_{\Omega} \nabla \cdot (w \nabla u) \, d\Omega + \int_{\Omega} \nabla u \cdot \nabla w \, d\Omega$$

LHS of ①

Use divergence theorem to rewrite $\int_{\Omega} \nabla \cdot (w \nabla u) \, d\Omega$ as

$$\oint_{\Gamma} w \nabla u \cdot \hat{n} \, d\Gamma + \int_{\Omega} w \nabla u \cdot \hat{n} \, d\Gamma$$

Γ_1 when $x=0, 1$ Γ_2 when $y=0, 1$ Γ_1 
so closed surface.

Can eliminate this term as $\nabla u = \partial u / \partial n$ on Γ_2 and can choose w so satisfies $u=0$ on Γ_1

Therefore

$$\boxed{+ \int_{\Omega} \nabla u \cdot \nabla w \, d\Omega = \int_{\Omega} f w \, d\Omega}$$

$$- \int_{\Omega} \nabla u \cdot \nabla w \, d\Omega + \int_{\Omega} f w \, d\Omega = 0$$

① Finding weak Formulations through variations principle

Method 2

want to minimise the functional \rightarrow type of function
 that maps vectors
 to numbers.
 Argument are functions

$$I[u] = \iint_{\Omega} \frac{1}{2} \|\nabla u\|^2 - uf d\Omega$$

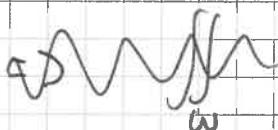
Minimise this function by finding point where $\delta I = 0$
 with a variation

$$\delta I = \frac{\delta I}{\delta \epsilon} = \lim_{\epsilon \rightarrow 0} \frac{I[u(x,y) + \epsilon(\delta u)(x,y)] - I[u(x,y)]}{\epsilon}$$

$$\delta I = \delta \left(\iint_{\Omega} \frac{1}{2} \|\nabla u\|^2 - uf d\Omega \right)$$

$$= \iint_{\Omega} 2 \times \frac{1}{2} \nabla u \cdot \nabla (\delta u) - f \delta u d\Omega$$

$$= \iint_{\Omega} (\nabla u \cdot \nabla (\delta u) - f \delta u) d\Omega = 0$$



$$\iint_{\omega} (\nabla u \cdot \nabla (\delta u) - f \delta u) d\Omega = 0$$

Using before product rule \Rightarrow

$$\nabla \cdot (\delta u \nabla u) = \delta u \nabla^2 u + \nabla u \cdot \nabla \delta u$$

$$\Rightarrow -\delta u \nabla^2 u = \nabla u \cdot \delta u - \nabla \cdot (\delta u \nabla u)$$

$$\Rightarrow \nabla u \cdot \nabla (\delta u) = -\delta u \nabla^2 u + \nabla \cdot (\delta u \nabla u)$$

Sub this in and use Gauss's divergence theorem.

$$-\iint_{\omega} \delta u \nabla^2 u + \delta u f d\Omega + \int_{\Gamma_1} \delta u \nabla u \cdot \hat{n} d\Gamma + \int_{\Gamma_2} \delta u \nabla u \cdot \hat{n} d\Gamma = 0$$

$\nabla u = 0$ on Γ_2 from boundary conditions

and choose δu such that $(\delta u)_{\Gamma_1} = 0$

$$\Rightarrow \boxed{- \iint_{\omega} (\delta u) (\nabla^2 u + f) d\Omega = 0}$$

Yields the same result as using the test function if $\boxed{\delta u = w}$

$$\boxed{\int_{\omega} \nabla u \cdot \nabla \delta u d\Omega = \int_{\omega} f \delta u d\Omega}$$

Step 2: Discretise WEAK FORMULATION through use of test function

(2)

$$u(x, y) \approx u_h(x, y) = u_j \varphi_j(x, y)$$

$$w(x, y) \approx w_h(x, y) = a_j \varphi_j(x, y)$$

~~u_j = weights~~ u_j = weights
 φ_j = global basis function

a_j = weights for test function, if take $a_j = d_{ij}$ then

$$w_h = \varphi_i(x, y)$$

$$u(x) = \sum_{i=0}^N u_j \varphi_j(x, y)$$

substitute $u_h(x, y)$ and $w_h(x, y)$ into weak formulation:

$$\int_{\Omega} \nabla u \cdot \nabla w \, d\Omega = \int_{\Omega} f w$$

$$\int_{\Omega} \nabla u_h \cdot \nabla w_h \, d\Omega = \int_{\Omega} f w_h \, d\Omega$$

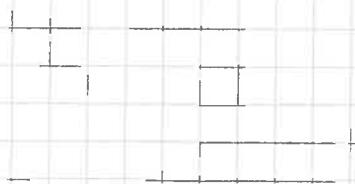
$$\nabla u_h = \nabla(u_j \varphi_j(x, y)) \quad u_j \text{ are constants so can take out of the derivative.}$$

$$\nabla u_h = u_j \nabla \varphi_j(x, y)$$

$$\nabla w_h = \nabla \varphi_i(x, y)$$

$$\Rightarrow \int_{\Omega} u_j \nabla \varphi_j(x, y) \cdot \nabla \varphi_i(x, y) \, d\Omega = \int_{\Omega} f \nabla \varphi_i(x, y) \, d\Omega$$

-2



$$\text{or. } A_{ij} u_j = b_i$$

with

$$A_{ij} = \iint_{\Omega} \nabla \varphi_i(x, y) \cdot \nabla \varphi_j(x, y) d\Omega$$

$$b_i = \iint_{\Omega} \varphi_i(x, y) f(x, y) d\Omega$$

Can Find solution by in rity matrix $\begin{matrix} u_j \\ \vdots \\ u_1 \end{matrix}$

or

~~If use compact support~~

Values are known on Dirichlet boundaries so
can rewrite:

$$A_{ii} u_i = b_i - \sum_{k=N_{\text{nodes}}+1}^{N_n} A_{ik} u_k$$

sum of
 solution over
 known values of boundary
 condition

N_{nodes} = non-dirichlet nodes

N_n = total nodes.

③ Discretise through variational principle

$$u(x, y) \approx u_h(x, y) = u_j \varphi_j(x, y)$$

Sub into function

$$I[u] = \iint_{\Omega} \frac{1}{2} \|\nabla u\|^2 - uf d\Omega$$

$$I = \iint_{\Omega} \left(\frac{1}{2} \|\nabla u_j \varphi_j\|^2 - u_j \varphi_j f \right) d\Omega$$

in set var $\delta I = 0$ and sub in δu_j test function

$$\delta I \equiv \frac{\partial I}{\partial \epsilon} = \lim_{\epsilon \rightarrow 0} \frac{I[u_j \varphi_j(x, y) + \epsilon (\delta u_j)(x, y)] - I[u_j \varphi_j(x, y)]}{\epsilon}$$

$$\partial I = \iint_{\Omega} (\nabla u_j \cdot \nabla (\delta u_j) - f \delta u_j) d\Omega = 0$$

$$\text{sub in } u(x, y) \quad \delta u_j = \varphi_i(x, y)$$

\Rightarrow

$$\iint_{\Omega} u_j \nabla \varphi_j \cdot \nabla \varphi_i d\Omega = \iint_{\Omega} f \varphi_i d\Omega$$

$$\Rightarrow A_{ij} u_j = b_i$$

$$b_i = \iint_{\Omega} \varphi_i(x, y) f(x, y) d\Omega$$

~~where A, b see as~~

$$A_{ij} = \iint_{\Omega} \nabla \varphi_{i,j}(x, y) \cdot \nabla \varphi_j(x, y) d\Omega$$

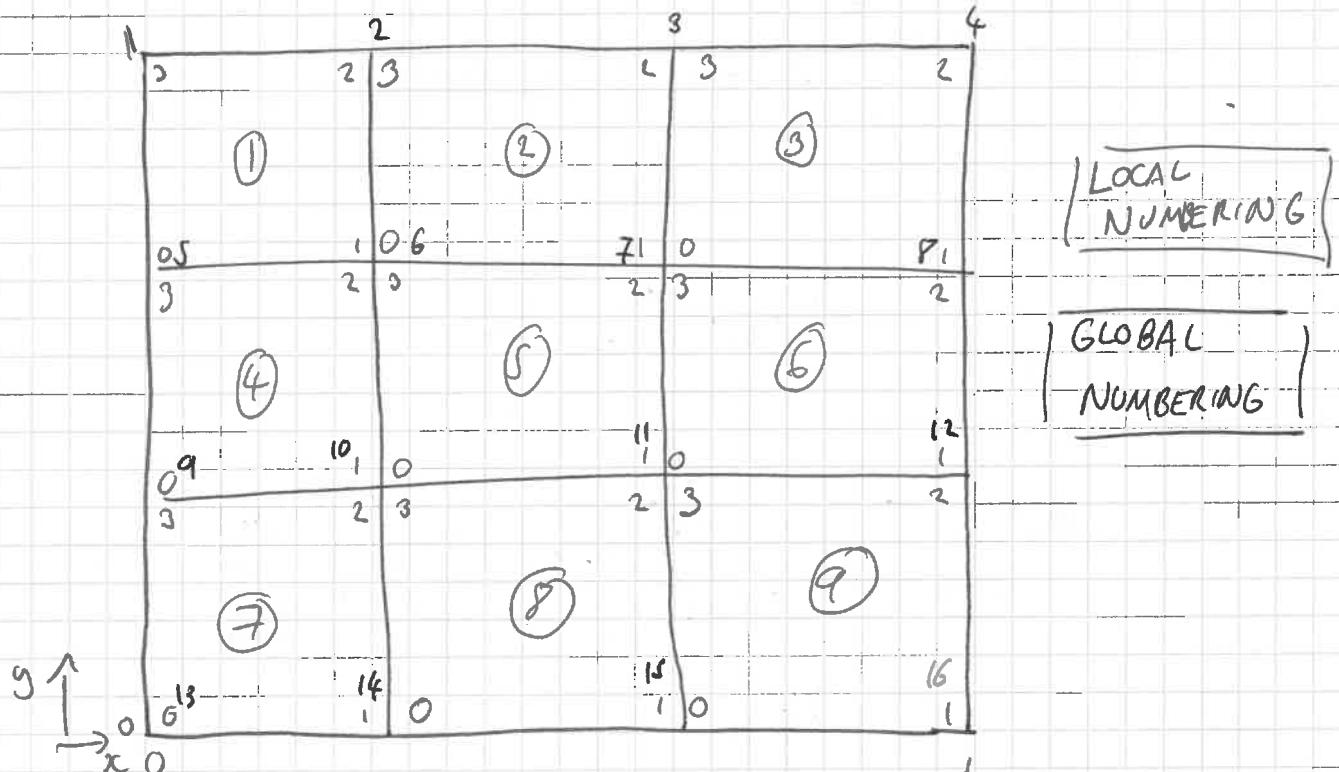
- substitute finite element expansion for u_h into the minimum principle
- introduce integrals taking variation with respect to u_j'
- $\delta u_j' = \eta_j'$

③

Introduce local coordinate system and reference coordinates

Quadrilateral elements

e.g. 3×3 Mesh.



Element ⑨

LOCAL(α) GLOBAL

0	15
1	16
2	12
3	11

etc.

Mapping between global ord local.

$$\bar{x} = F_K(\bar{\beta}) = \sum_{\alpha=0}^{n_{\text{el}}-1} \bar{x}_{\alpha} \varphi_{\alpha}(\bar{\beta})$$

Define basis functions with global node number i on

Element K_K

$$\varphi_{\alpha}(x, y) = \hat{\varphi}_{\alpha}(F_K^{-1}(x, y)) = \chi_{\alpha}(\bar{\beta})$$

α = local elem index, for local support w.r.t = 1 on
global node i and 0 on other nodes.

Apply this to :

$$\boxed{\begin{aligned} A_{ij} u_j &= b_i \\ A_{ij} &= \iint \nabla \varphi_i(x,y) \cdot \nabla \varphi_j(x,y) d\Omega \\ b_i &= \iint \varphi_i(x,y) f(x,y) d\Omega \end{aligned}}$$

$$\Rightarrow \hat{A}_{\alpha\beta} = \int_K \nabla \chi_\alpha \cdot \nabla \chi_\beta d\Omega$$

$$= \int_K \left((J^T)^{-1} \begin{pmatrix} \frac{\partial \chi_\alpha}{\partial \xi_1} \\ \frac{\partial \chi_\alpha}{\partial \xi_2} \end{pmatrix} \right) \cdot \left((J^T)^{-1} \begin{pmatrix} \frac{\partial \chi_\beta}{\partial \xi_1} \\ \frac{\partial \chi_\beta}{\partial \xi_2} \end{pmatrix} \right) |\det J| d\bar{\xi}$$

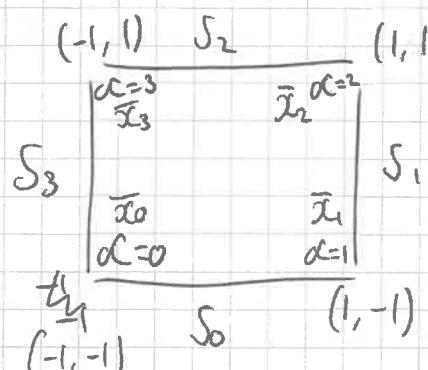
$$\hat{b}_\alpha = \int_K f \chi_\alpha d\Omega$$

$$= \int_{\bar{\Sigma}} f(\boldsymbol{x}(\xi_1, \xi_2), \boldsymbol{y}(\xi_1, \xi_2)) \chi_\alpha(\xi_1, \xi_2) |\det J(\xi)| d\xi$$

for $\alpha, \beta = 0, \dots, N_n^K - 1$ or each reference cell \bar{K}

For quadrilateral $\alpha, \beta = 0, 1, 2, 3$

For reference element $\bar{\gamma} \in (-1, 1)^2$



To assemble matrix loop through α and β

for the total number of nodes N_n^k

where k is the number of elements and n the
number of nodes per element. Assign $\hat{b}_{\alpha\beta}$ and
 $\hat{A}_{\alpha\beta}$ through.

$$\hat{A}_{\alpha\beta} = \int_K \nabla \chi_\alpha \cdot \chi_\beta \, d\Omega$$

$$\hat{b}_{\alpha\beta} = \int_K f \varphi_\alpha \, d\Omega$$

for each element into a global matrix

$$A=0 \quad b=0 \quad A_{ij} = b_i = 0$$

for all elements K_k , $k=1, N_e$ elmts:

for $\alpha = 1$ to N_n^k :

$i = \text{Index}(k, \alpha)$ ← set i to relevant value for
 k th element and $\alpha = 0, 1, 2, 3$
for that element

for $\beta = 1, N_n^k$:

$j = \text{Index}(k, \beta)$ ← set j to relevant value
for value β element

$A_{ij} = A_{ij} + \hat{A}_{\alpha\beta}$ ← and $\beta = 0, 1, 2, 3$

$b_i = b_i + \hat{b}_{\alpha\beta}$

calculate
 $\hat{A}_{\alpha\beta}$ and assign
to matrix

Assign to b matrix
for all values of α