

Poisson System:

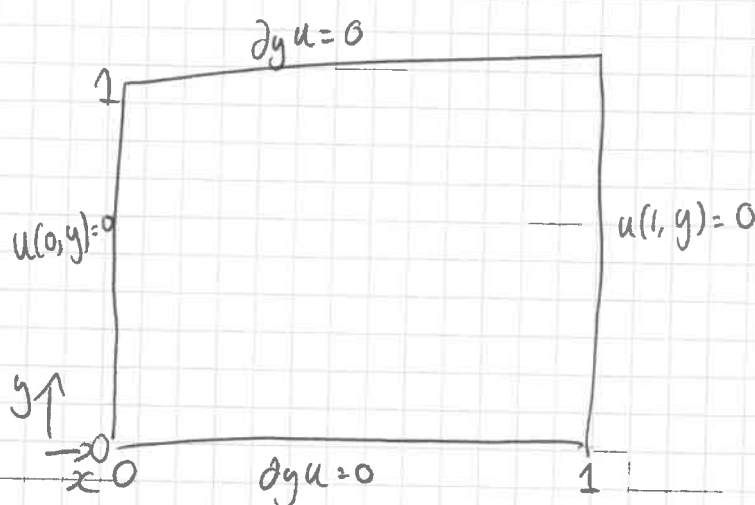
~~$\nabla^2 u$~~

$$-\nabla^2 u = f \quad \text{on } (x, y) \in [0, 1]^2$$

$$f(x, y) = 2\pi^2 \sin(\pi x) \cos(\pi y)$$

$$u(0, y) = u(1, y) = 0 \quad (\text{Dirichlet}) \quad \Gamma_1$$

$$\partial_y u(x, y)|_{y=0} = \partial_y u(x, y)|_{y=1} = 0 \quad (\text{Neumann}) \quad \Gamma_2$$



boundary $\partial\Omega = \Gamma_1 \cup \Gamma_2$ $\Gamma_1 = x=0, 1 (\partial\Omega_D)$ $\Gamma_2 = y=0, 1 (\partial\Omega_N)$

exact solution is $u_e(x, y) = \sin(\pi x) \cos(\pi y)$

$$\frac{\partial}{\partial x} (\sin(\pi x) \cos(\pi y)) = \pi \cos(\pi x) \cos(\pi y)$$

$$\frac{\partial^2}{\partial x^2} (\sin(\pi x) \cos(\pi y)) = -\pi^2 \sin(\pi x) \cos(\pi y)$$

$$\frac{\partial}{\partial y} (\sin(\pi x) \cos(\pi y)) = -\pi \sin(\pi x) \sin(\pi y)$$

$$\frac{\partial^2 u}{\partial y^2} = -\pi^2 \sin(\pi x) \cos(\pi y)$$

$$\nabla^2 u = -\pi^2 (\sin(\pi x) +$$

$$-\nabla^2 u = +\pi^2 (\sin(\pi x) \cos(\pi y) + \sin(\pi x) \cos(\pi y))$$

$$-\nabla^2 u = 2\pi^2 \sin(\pi x) \cos(\pi y)$$

$$\Rightarrow -\nabla^2 u = f$$

exact solution

~~1. Step 1:~~

~~write down the~~

~~Ritz-Galerkin principle and derive the weak~~

~~formulation:~~

~~1. Step 1:~~

To solve poisson system numerically we want to be able to write $u(x,y)$ as a sum of weighted shape functions. $u(x,y) = \sum_{i=0}^n u_i N_i(x,y)$ where N_i is a shape function, 1 at node i and 0 at other nodes. (n is number of nodes). Weights are u_i .

To find the weights, want to put the poisson system in a weak formulation.

(1) Step 1: Weak formulation

(Find weak formulation through a test function)

Method 1

$$-\nabla^2 u = f \quad : \text{strong form}$$

multiply by test function $w(x,y)$, this is an arbitrary function of x and y .

$$-\nabla^2 u(x,y) w(x,y) = f(x,y) w(x,y)$$

integrate over domain Ω

$$-\int_{\Omega} \nabla^2 u(x,y) w(x,y) d\Omega = \int_{\Omega} f(x,y) w(x,y) d\Omega \quad (1)$$

Use partial integration to change form of LHS.
Want to change form of LHS.

$$-\int_{\Omega} \nabla^2 u w d\Omega \Rightarrow \text{LHS.}$$

PRODUCT RULE

$$\nabla \cdot (w \nabla u) = w \nabla^2 u + \nabla u \cdot \nabla w$$

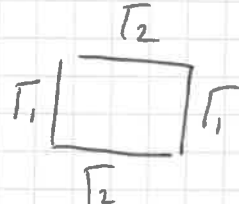
$$\Rightarrow -w \nabla^2 u = \nabla u \cdot \nabla w - \nabla \cdot (w \nabla u)$$

$$\Rightarrow - \int_{\Omega} w \nabla^2 u \, d\Omega = - \int_{\Omega} \nabla \cdot (w \nabla u) \, d\Omega + \int_{\Omega} \nabla u \cdot \nabla w \, d\Omega$$

LHS of ①

Use divergence theorem to rewrite $\int_{\Omega} \nabla \cdot (w \nabla u) \, d\Omega$ as

$$\oint_{\Gamma} \int_{\Gamma_1} w \nabla u \cdot \hat{n} \, d\Gamma + \int_{\Gamma_2} w \nabla u \cdot \hat{n} \, d\Gamma$$

Let Γ_1 den $x=0,1$ Γ_2 den $y=0,1$  so closed surface.

Can eliminate this term as $\nabla u = 0$ on Γ_2 and can choose w so satisfies $u=0$ on Γ_1

Therefore

$$\left| + \int_{\Omega} \nabla u \cdot \nabla w \, d\Omega = \int_{\Omega} f w \, d\Omega \right|$$

$$- \int_{\Omega} \nabla u \cdot \nabla w \, d\Omega + \int_{\Omega} f w \, d\Omega = 0$$

① Finding weak Formulation through variational principle

Method 2

want to minimise the functional \rightarrow type of function that maps vectors to numbers.
Arguments are functions

$$I[u] = \iint_{\Omega} \frac{1}{2} \|\nabla u\|^2 - u f \, d\Omega$$

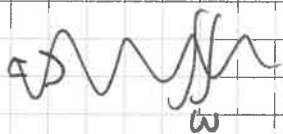
Minimise this function by finding point where $\delta I = 0$
with a variation

$$\delta I \equiv \frac{\delta I}{\delta \epsilon} = \lim_{\epsilon \rightarrow 0} \frac{I[u(x,y) + \epsilon(\delta u)(x,y)] - I[u(x,y)]}{\epsilon}$$

$$\delta I = \delta \left(\iint_{\Omega} \frac{1}{2} \|\nabla u\|^2 - u f \, d\Omega \right)$$

$$= \iint_{\Omega} 2 \times \frac{1}{2} \nabla u \cdot \nabla(\delta u) - f \delta u \, d\Omega$$

$$= \iint_{\Omega} (\nabla u \cdot \nabla(\delta u) - f \delta u) \, d\Omega = 0$$



$$\iint_{\Omega} (\nabla u \cdot \nabla(\delta u) - f \delta u) d\Omega = 0$$

Lin before product rule \Rightarrow

$$\nabla \cdot (\delta u \nabla u) = \delta u \nabla^2 u + \nabla u \cdot \nabla \delta u$$

$$\Rightarrow -\delta u \nabla^2 u = \nabla u \cdot \nabla \delta u - \nabla \cdot (\delta u \nabla u)$$

$$\Rightarrow \nabla u \cdot \nabla(\delta u) = -\delta u \nabla^2 u + \nabla \cdot (\delta u \nabla u)$$

sub this in and use Gauss's divergence theorem.

$$-\iint_{\Omega} \delta u \nabla^2 u + \delta u f d\Omega + \int_{\Gamma_1} \delta u \nabla u \cdot \hat{n} d\Gamma + \int_{\Gamma_2} \delta u \nabla u \cdot \hat{n} d\Gamma = 0$$

$\nabla u = 0$ on Γ_2 from boundary conditions
and choose δu such that $(\delta u)_{\Gamma_1} = 0$

$$\Rightarrow \left| -\iint_{\Omega} (\delta u) (\nabla^2 u + f) d\Omega = 0 \right|$$

Yields the same result as using the
test function if $\boxed{\delta u = w}$

$$\boxed{\int_{\Omega} \nabla u \cdot \nabla \delta u d\Omega = \int_{\Omega} f \delta u d\Omega}$$

2. Step 2: Discretise WEAK FORMULATION through use of test function

(2)

$$u(x, y) \approx u_h(x, y) = u_j \varphi_j(x, y)$$

$$w(x, y) \approx w_h(x, y) = a_j \varphi_j(x, y)$$

~~$u_j = \text{weights}$~~ $u_j = \text{weights}$
 $\varphi_j = \text{global basis function}$

$a_j = \text{weights for test function}$, if take $a_j = \delta_{ij}$ then

$$w_h = \varphi_i(x, y)$$

$$u(x) = \sum_{j=0}^N u_j \varphi_j(x, y)$$

substitute $u_h(x, y)$ and $w_h(x, y)$ into weak formulation:

$$\int_{\Omega} \nabla u \cdot \nabla w \, d\Omega = \int_{\Omega} f w \, d\Omega$$

$$\int_{\Omega} \nabla u_h \cdot \nabla w_h \, d\Omega = \int_{\Omega} f w_h \, d\Omega$$

$$\nabla u_h = \nabla (u_j \varphi_j(x, y))$$

u_j are constants so can take out of the derivative.

$$\nabla u_h = u_j \nabla \varphi_j(x, y)$$

$$\nabla w_h = \nabla \varphi_i(x, y)$$

$$\Rightarrow \int_{\Omega} u_j \nabla \varphi_j(x, y) \cdot \nabla \varphi_i(x, y) \, d\Omega = \int_{\Omega} f \nabla \varphi_i(x, y) \, d\Omega$$

or. $A_{ij} u_j = b_i$

with

$$A_{ij} = \iint_{\Omega} \nabla \phi_i(x, y) \cdot \nabla \phi_j(x, y) d\Omega$$

$$b_i = \iint_{\Omega} \phi_i(x, y) f(x, y) d\Omega$$

Can Find ^{u_j} solution by inverting matrix

or

~~Use compact support~~

Values are known on Dirichlet boundaries so

can rewrite:

$$A_{i'j'} u_{j'} = b_{i'} - \sum_{k=N_{\text{nodes}}+1}^{N_n} A_{i'k} u_k$$

↙ sum of
 solution over
 known values of boundary
 condition

N_{nodes} = non-dirichlet nodes

N_n = total nodes.

② Discretise through variational principle

• substitute finite element expansion for u_h into the minimax principle

• introduce integrals

• taking variation with respect to u_j
 $\delta u_j = \eta_j$

$$|u(x, y) \approx u_h(x, y) = u_j \varphi_j(x, y)|$$

sub into functional

$$I[u] = \iint_{\Omega} \frac{1}{2} \|\nabla u\|^2 - u f \, d\Omega$$

$$I = \iint_{\Omega} \left(\frac{1}{2} |u_j \varphi_j|^2 - u_j \varphi_j f \right) d\Omega$$

in set ~~var~~ $\delta I = 0$ and sub in δu_j test function

$$\delta I \equiv \frac{\partial I}{\partial \epsilon} = \lim_{\epsilon \rightarrow 0} \frac{I[u_j \varphi_j(x, y) + \epsilon (\delta u_j)(x, y)] - I[u_j \varphi_j(x, y)]}{\epsilon}$$

$$\partial I = \iint_{\Omega} (\nabla u_j \cdot \nabla (\delta u_j) - f \delta u) \, d\Omega = 0$$

sub in ~~$u(x, y)$~~ $\delta u_j = \varphi_j(x, y)$

\Rightarrow

$$\iint_{\Omega} u_j \nabla \varphi_j(x, y) \cdot \nabla \varphi_i(x, y) \, d\Omega = \iint_{\Omega} f \varphi_i(x, y) \, d\Omega$$

$$\Rightarrow A_{ij} u_j = b_i$$

$$b_i = \iint_{\Omega} \varphi_i(x, y) f(x, y) \, d\Omega$$

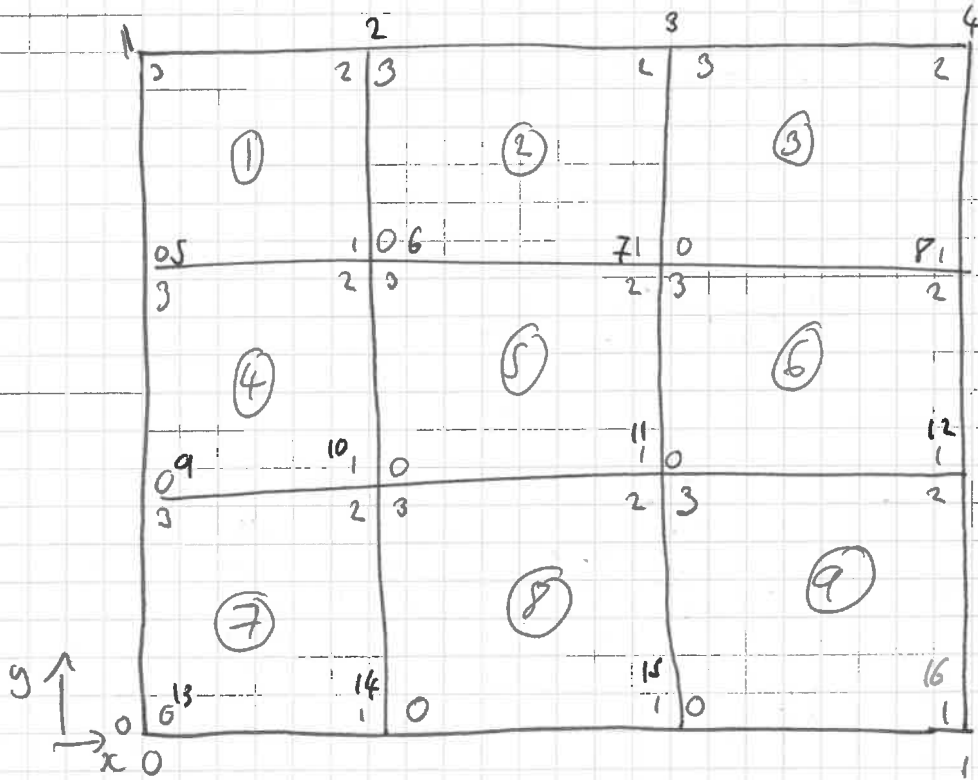
~~where A, b are as~~

$$A_{ij} = \iint_{\Omega} \nabla \varphi_i(x, y) \cdot \nabla \varphi_j(x, y) \, d\Omega$$

③ Introduce local coordinate system and reference coordinates

Quadrilateral element

eg. 3×3 Mesh.



LOCAL NUMBERING

GLOBAL NUMBERING

Element (i)	LOCAL (i)	GLOBAL
	0	15
	1	16
	2	12
	3	11

etc.

Maps between global and local.

$$\bar{x} = f_{kk}(\bar{\beta}) = \sum_{a=0}^{N_k-1} \bar{x}_{ka} \chi_a(\bar{\beta})$$

Define basis functions with global node number i on Element K_K

$$\varphi_\alpha(x, y) = \hat{\varphi}_\alpha(F_K^{-1}(x, y)) = \chi_\alpha(\bar{t})$$

$\alpha =$ local element index, for local support $w_\alpha = 1$ on global node i and 0 on other nodes.

Apply this to:

$$\begin{aligned} A_{ij} u_j &= b_i \\ A_{ij} &= \iint_{\Omega} \nabla \varphi_i(x, y) \cdot \nabla \varphi_j(x, y) \, d\Omega \\ b_i &= \iint_{\Omega} \varphi_i(x, y) f(x, y) \, d\Omega \end{aligned}$$

$$\Rightarrow \hat{A}_{\alpha\beta} = \int_K \nabla \chi_\alpha \cdot \nabla \chi_\beta \, d\Omega$$

$$= \int_{\hat{K}} \left((J^T)^{-1} \begin{pmatrix} \frac{\partial \chi_\alpha}{\partial \xi_1} \\ \frac{\partial \chi_\alpha}{\partial \xi_2} \end{pmatrix} \right) \cdot \left((J^T)^{-1} \begin{pmatrix} \frac{\partial \chi_\beta}{\partial \xi_1} \\ \frac{\partial \chi_\beta}{\partial \xi_2} \end{pmatrix} \right) | \det J | \, d\bar{\xi}$$

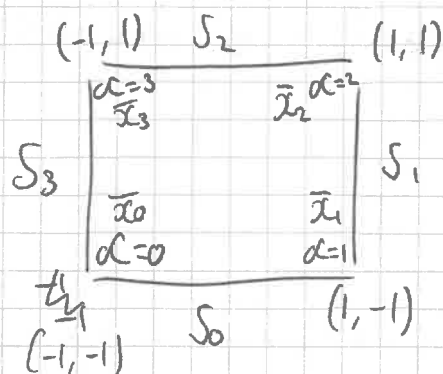
$$\hat{b}_\alpha = \int_K f \chi_\alpha \, d\Omega$$

$$= \int_{\hat{K}} f(x(\xi_1, \xi_2), y(\xi_1, \xi_2)) \chi_\alpha(\xi_1, \xi_2) | \det J(\bar{\xi}) | \, d\bar{\xi}$$

for $\alpha, \beta = 0, \dots, N_h^K - 1$ on each reference element \hat{K}

For quadrilateral $\alpha, \beta = 0, 1, 2, 3$

For reference element $\bar{\xi} \in (-1, 1)^2$



To assemble matrix loop through α and β
 for the total number of nodes N_n^k
 where k is the number of elements and n the
 number of nodes per element. Assign \hat{b}_α and
 $\hat{A}_{\alpha\beta}$ through

$$\hat{A}_{\alpha\beta} = \int_K \nabla \chi_\alpha \cdot \chi_\beta \, d\Omega$$

$$\hat{b}_\alpha = \int_K f \, \chi_\alpha \, d\Omega$$

for each element into a global matrix

$$A = 0 \quad b = 0 \quad A_{ij} = b_i = 0$$

for all elements K_k , $k=1, \dots, N_k$ elements:

for $\alpha = 1$ to N_n^k :

$i = \text{Index}(k, \alpha) \leftarrow$ set i to relevant value for
 k^{th} element and $\alpha = 0, 1, 2, 3$
 for $\beta = 1$ to N_n^k :
 for that element

$j = \text{Index}(k, \beta) \leftarrow$ set j to relevant value
 for β^{th} element
 $A_{ij} = A_{ij} + \hat{A}_{\alpha\beta}$
 R and $\beta = 0, 1, 2, 3$

$$b_i = b_i + \hat{b}_\alpha$$

calculate
 $\hat{A}_{\alpha\beta}$ and assign
 to matrix

Assign to b matrix
 for all values of α