

# Numerics 1: Alex Carey 2015/09/77

1 We have a system defined by

$$\partial_t b + \partial_2 u b = 0 \text{ and } u = \alpha b^2 - \beta b^2 \partial_2 b \quad (1)$$

for  $z \in [0, H]$ ,  $\alpha, \beta > 0$  and Dirichlet boundary conditions (BCs)

$$b(0, t) = b_\beta \text{ and } b(H, t) = b_\gamma$$

for  $t > 0$ . We have Initial conditions (IC)

$$b(z, 0) = b_i(z).$$

a) We consider the system (1) and substitute the  $u$  value from the second equation to obtain

$$\partial_t b + \partial_2 (\alpha b^3 - \beta b^3 \partial_2 b) = 0. \quad (2)$$

We consider  $b = D_0 + b'$  for some small  $b'$  and constant  $D_0$  such that (2) becomes

$$\begin{aligned} \partial_t b' + 3\alpha(D_0 + b')^2 \partial_2 b' - 3\beta(D_0 + b')(\partial_2 b')^2 \\ - \beta(D_0 + b')^2 \partial_2^2 b' = 0. \end{aligned}$$

As  $b'$  is small (relative to  $D_0$ ) and the scale of  $z$  is much larger than that of  $b$ , giving  $\partial_t b' \ll 1$ , we have further

$$\partial_t b' + 3\alpha D_0^2 \partial_2 b' - \beta(D_0 + b')^2 \partial_2^2 b' = 0. \quad (3)$$

We label (2) & (3) convection-diffusion equations as they have convection term

$$\partial_x b'$$

and diffusive term

$$\partial_x^2 b'$$

- b) We discretise (2) by considering each component.  
 First we define  $\Delta t$  and  $\Delta z$  respectively,  
 the time step and grid spacing such that

$$t_n - t_{n-1} = \Delta t$$

$$z_j - z_{j-1} = \Delta z.$$

defining  $b_j^{\hat{n}} = b(z_j, t_n)$ .

We then consider the discrete approximation

$$\partial_t b \approx \frac{b_j^{n+1} - b_j^n}{\Delta t}.$$

As we are considering a forward Euler scheme  
 the following approximations are explicit  
 (only depending on data from this step  
 $n$  to determine data at time step  $n+1$ ).

For the first order component we consider an upwind scheme with

$$\partial_x \alpha b^3 \approx \alpha \left[ \frac{(b_i^n)^3 - (b_{i-1}^n)^3}{\Delta x} \right]$$

and for the second order component we utilize the explicit method first defining

$$F_{i+\frac{1}{2}}^n = (b_{i+\frac{1}{2}}^n)^3 \frac{b_{i+1}^n - b_i^n}{\Delta x}$$

an approximation of  $b^3 \partial_x b$  where  $b_{i+\frac{1}{2}}^n = \frac{1}{2}(b_{i+1}^n + b_i^n)$ . We further have that

$$\begin{aligned} \partial_x (\beta b^3 \partial_x b) &\approx -\beta \partial_x F \\ &\approx -\beta \left( F_{i+\frac{1}{2}}^n - F_{i-\frac{1}{2}}^n \right). \end{aligned}$$

This leads to full discretization

$$\begin{aligned} & \frac{b_{i+1}^{n+1} - b_i^n}{\Delta t} + \alpha \left[ \frac{(b_i^n)^3 - (b_{i-1}^n)^3}{\Delta x} \right] \\ & - \beta \left[ \frac{(b_{i+1}^n + b_i^n)^3 (b_{i+1}^n - b_i^n) - (b_i^n + b_{i-1}^n)^3 (b_i^n - b_{i-1}^n)}{8(\Delta x)^2} \right] \\ & = 0. \quad (4) \end{aligned}$$

We can similarly describe (3) considering similarly defined time and grid spacing in a field  $b'$  of perturbation such that

$$\partial_t b' \approx \frac{(b')_{j+1}^{n+1} - (b')_j^n}{\Delta t}.$$

The linear component is approximated

$$\beta \alpha D_o^2 \partial_x^2 b' \approx \beta \alpha D_o^2 \frac{((b')_{j+1}^n - (b')_{j-1}^n)}{\Delta x}$$

Using an upwind scheme and we have

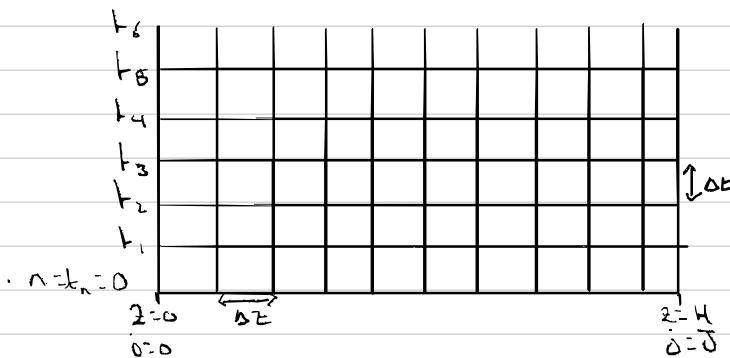
$$-\beta D_o^3 \partial_x^2 b' \approx -\beta D_o^3 \frac{((b')_{j+1}^n - 2(b')_j^n + (b')_{j-1}^n)}{(\Delta x)^2}$$

from the second order central difference. This results in

$$\frac{(b')_{j+1}^{n+1} - (b')_j^n}{\Delta t} + \beta \alpha D_o^2 \frac{((b')_{j+1}^n - (b')_{j-1}^n)}{\Delta x}$$

$$-\frac{\beta D_o^3 ((b')_{j+1}^n - 2(b')_j^n + (b')_{j-1}^n)}{(\Delta x)^2} = 0. \quad (5).$$

The grid is given



If we consider  $(b')_j^n = b_j^n - D_0$  then we can linearize (4) noting that the expansion

$$(b_j^n)^3 - (b_{j+1}^n)^3 \approx D_0^2 ((b')_j^n - b_{j+1}^n)$$

after  $D_0^8$  terms cancel and we assume domination of the higher order  $D_0$  term. We have also that

$$(b_j^n + b_{j+1}^n)^3 \approx (2D_0)^3$$

giving the result of linearization on (4)

$$\frac{(b')_j^{n+1} - (b')_j^n}{\Delta t} + \frac{3\alpha D_0^2 ((b')_j^n - (b')_{j+1}^n)}{\Delta z}$$

$$- \beta D_0^3 ((b')_{j+1}^n - 2(b')_j^n + (b')_{j-1}^n)$$

corresponding with (5).

The collocation form does not require the introduction of an extra term resulting from the chain rule which would also have to be discretized, further complicating the scheme.

The boundary conditions dictate

$$b_i^0 = b_i(z_0)$$

and for  $n > 0$  that

$$\hat{b}_0^n = b_0 \quad \text{and} \quad \hat{b}_{\bar{j}}^n = b_{\bar{j}}$$

where  $z_0 = H$  and  $H(j) = \Delta z$ .

As the scheme is explicit the order of evaluation of spatial points is not relevant and we will only use the scheme to evaluate

$$\hat{b}_i^n \quad \text{for } i = 1, \dots, \bar{j}-1.$$

(c) We assume that the solution  $b'(z, t)$  has some Fourier decomposition of form

$$(b')^n = \sum_{k=-\infty}^{\infty} c_k(k) e^{ik\Delta z}.$$

We consider a single mode and note that it must satisfy the linearized (3) such that

$$\frac{1 - 1}{\Delta t} + 3\alpha D_0^2 \left( 1 - e^{-ik\Delta z} \right)$$

$$- \beta D_0^3 \left( e^{ik\Delta z} - 1 + e^{-ik\Delta z} \right) = 0$$

after division by  $(b')^n$ . As such, we have

$$\lambda(k) = 1 - \Delta t \left[ \frac{3\alpha D_0^2 (1 - e^{-ik\Delta z})}{\Delta z} - \frac{\beta D_0^3}{(\Delta z)^2} \left( e^{\frac{1}{2}ik\Delta z} - e^{-\frac{1}{2}ik\Delta z} \right)^2 \right]$$

$$= 1 - \Delta t \left[ \frac{3\alpha D_0^2 (1 - e^{-ik\Delta z})}{\Delta z} + 4 \frac{\beta D_0^3}{(\Delta z)^2} \sin^2 \frac{1}{2} k \Delta z \right]$$

If  $\alpha=0, \beta \neq 0$  then we have

$$\lambda(k) = 1 - \frac{4\Delta t \beta D_0^3}{(\Delta z)^2} \sin^2\left(\frac{1}{2}k\Delta z\right) \leq 1.$$

For stability, we then only require  $|\lambda(k)| \leq 1$  which holds if

$$\frac{4\Delta t \beta D_0^3}{(\Delta z)^2} \leq 2$$

$$\Rightarrow \Delta t \leq \frac{(\Delta z)^2}{2\beta D_0^3}.$$

If  $\alpha \neq 0, \beta=0$  then

$$\lambda(k) = 1 - \frac{3\alpha \Delta t D_0^3}{\Delta z} (1 - e^{-ik\Delta z})$$

Considering the maximum  $|\lambda(k)|$  which is either attained at  $k\Delta z = 0$  or  $\pi$  we have

$$\max |\lambda(k)| = \max \left\{ 1, \left| 1 - \frac{3\alpha \Delta t D_0^3}{\Delta z} (2) \right| \right\}$$

and so we can say  $|\lambda(k)| \leq 1$  if

$$1 - 6\alpha \frac{\Delta t}{(\Delta z)^2} D_0^3 \geq -1$$

$$\Leftrightarrow \Delta t \leq \frac{(\Delta z)^2}{3\alpha D_0^2}$$

That does not make sense should scale with  $dz$  not  $dz^2$ .

- See chap 4 of M&M. You need to square Re and Imaginary parts of lambda and then simplify. -1

Considering  $|A(z)| \leq 1$  we have

$$|\lambda(k)| = |1 - c(1 - e^{-ik\Delta z})|$$

for  $c = 3\alpha \Delta t D_s^2 / \Delta z$ . Further

$$|\lambda(k)| = |[1 - c(1 + \cos(k\Delta z))] - c i \sin(k\Delta z)|.$$

It is sufficient that  $|\lambda(k)|^2 \leq 1$  so we consider

$$|\lambda(k)|^2 = [1 - c(1 + \cos(k\Delta z))]^2 + [c \sin(k\Delta z)]^2.$$

Letting  $\theta = k\Delta z$  we have

$$\partial_\theta |\lambda(k)|^2 = 2(1 - c(1 + \cos(\theta)))c \sin(\theta)$$

$$+ 2c^2 \sin(\theta) \cos(\theta)$$

$$= (2 - 2c) c \sin(\theta)$$

giving maximum/minimum values at  $\theta = 0, \pi$ .

Just keep going, see chap 4:  $a < 1$  st  $dt <$  factor times  $dz$ .

d) We can derive an update scheme from (5)

$$(b')_j^{n+1} = (b')_j^n - \Delta t \left[ 3\alpha D_o^2 [(b')_{j+1}^n - (b')_{j-1}^n] / \Delta z \right. \\ \left. - \beta D_o^3 [(b')_{j+1}^n + (b')_{j-1}^n - 2(b')_j^n] / (\Delta z)^2 \right]$$

We consider the coefficients of each data point with

$$(b')_j^{n+1} = (b')_j^n \left( 1 - \frac{\Delta t}{\Delta z} \left( 3\alpha D_o^2 - \frac{2\beta D_o^3}{\Delta z} \right) \right)$$

$$+ (b')_{j+1}^n \left( \frac{\beta D_o^3}{(\Delta z)^2} \right)$$

$$+ (b')_{j-1}^n \left( \frac{\Delta t}{\Delta z} \left( 3\alpha D_o^2 + \frac{\beta D_o^3}{\Delta z} \right) \right)$$

where the second two coefficients are clearly greater than zero and we have the sum of coefficients equal to 1. To apply the maximum principle we must then only have

$$1 - \frac{\Delta t}{(\Delta z)^2} \left( 3\alpha D_o^2 \Delta z - 2\beta D_o^3 \right) \geq 0$$

$$\Rightarrow \Delta t \leq \frac{(\Delta z)^2}{3\alpha D_o^2 \Delta z - 2\beta D_o^3}$$

e) We aim to derive a variable time step criterion for  $\Delta t_n = t_{n+1} - t_n$  such that  $B_j^{n+1} > 0$  if  $B_j^n > 0$ .

We consider (4) and find the update scheme

$$b_j^{n+1} = b_j^n - \Delta t_n \left[ \frac{a_n}{\Delta z} - \frac{d_n}{(\Delta z)^2} \right]$$

where

$$a_n = \alpha \left[ (b_j^n)^3 - (b_{j-1}^n)^3 \right]$$

$$d_n = \frac{\beta}{8} \left[ (b_{j+1}^n + b_j^n)^3 (b_{j+1}^n - b_j^n) - (b_j^n + b_{j-1}^n)^3 (b_j^n - b_{j-1}^n) \right]$$

We require

$$b_j^n - \Delta t_n [a_n/\Delta z - d_n/(\Delta z)^2] > 0$$

$$\Rightarrow \Delta t_n < \frac{(\Delta z)^2 b_j^n}{c_n \Delta z - d_n}$$

f) We consider an explicit central approximation of

$$\partial_2 b_i^n \approx \frac{\hat{b}_{i+1}^n - \hat{b}_{i-1}^n}{2\Delta z}$$

using this to discretize (2) and finding update scheme

$$b_i^{n+1} = b_i^n - \Delta t_n \left( \frac{c_n}{\Delta z} - \frac{d_n}{(\Delta z)^2} \right)$$

where  $d_n$  is e.g previous end

$$c_n = \frac{\hat{b}_{i+1}^n - \hat{b}_{i-1}^n}{2}$$

with variable time step criterion

$$\Delta t_n < \frac{(\Delta z)^2 \hat{b}_i^n}{c_n \Delta z - d_n}$$

That needs more analysis. -0.5 since scheme with  $d_n=0$  is linearly unstable.

2c) Given that we are at some steady state

$$\partial_t = 0$$

then we have, from (2), that

$$\partial_x (\alpha b^3 - \beta b^3 \partial_z b) = 0$$

$$\Rightarrow \alpha b^3 - \beta b^3 \partial_z b = Q$$

for some  $Q \in \mathbb{R}$ .

d) We consider the derivatives of the given exact first with respect to time giving

$$-\alpha^2 = \partial_1 b \left( 1 - \frac{1}{1-b^2} \right)$$

where  $\alpha=c$  and  $\beta=1$ . We then have

$$\partial_1 b = -\alpha^2 (1-b^{-2}).$$

We then consider the derivative w.r.t. 2 finding

$$\alpha = \partial_2 b \left( 1 - \frac{1}{1-b^2} \right)$$

$$\Rightarrow \partial_2 b = \alpha (1-b^{-2}).$$

We have

$$u = \alpha b^2 - b^2 \alpha (1-b^{-2})$$

$$= \alpha$$

and that the full eq<sup>s</sup> (1) gives

$$-\alpha^2 (1-b^{-2}) + \alpha (\alpha (1-b^{-2})) = 0$$

and the sol<sup>n</sup> satisfies the equations.

We note that

$$\operatorname{erctanh} x \approx x + \frac{x^3}{3} + \frac{x^5}{5}$$

and that the initial condition gives, after scaling such that  $H=1$ ,

$$b(0, 3, 0) = 0$$

$$\Rightarrow z_{r_0} = 0.3.$$

We can then consider values such that  $b=0$  noting the travelling wave nature results in

$$z = 0.3 + \alpha t.$$

This being the height above which the data is dead.

Further, we can use the erctanh approximation above to find

$$z - 0.3 - \alpha t \approx \frac{1}{\alpha} \left( -\frac{b^3}{3} \right)$$

$$\Rightarrow b \approx \left[ 3\alpha(\alpha t + 0.3 - z) \right]^{\frac{1}{3}}$$

which we use to define the initial condition with

$$b(z, 0) = \left[ 3\alpha(0.3 - z) \right]^2.$$

We define boundary conditions using these same approximations such that

$$b(0,t) \approx [3\alpha^2(t + \frac{0.3}{\alpha})]^{1/3}$$

$$b(1,t) \approx [3\alpha^2(t - \frac{0.7}{\alpha})]^{1/3}$$

where  $b(1,t)$  is valid for  $t \geq 0.7/\alpha$   
and is 0 for  $t \in [0, 0.7/\alpha]$ .

Note that in the end we did not use this approximation instead using the exact solution to create a map

$$z(b,t)$$

that could be searched for a range of values of  $t$  and then "inverted" at high enough resolution.

2e)