

B1

i) $f(x, y, z) = 2x^2 + xy + 4y^2 + xz + z^2 + 2$

First order conditions:

$$\begin{cases} f_x = 4x + y + z = 0 \\ f_y = x + 8y = 0 \Rightarrow y = -1/8x \\ f_z = x + 2z = 0 \Rightarrow z = -1/2x \end{cases}$$

Substitute the latter in first relation:

$$4x - \frac{1}{8}x - \frac{1}{2}x = 0 \Rightarrow x = 0, y = 0, z = 0$$

So $(0, 0, 0)$ only critical point.

(Could also be done by row elimination on system)

Hessian

$$H = \begin{pmatrix} f_{xx} & f_{xy} & f_{xz} \\ f_{xy} & f_{yy} & f_{yz} \\ f_{xz} & f_{yz} & f_{zz} \end{pmatrix} = \begin{pmatrix} 4 & 1 & 1 \\ 1 & 8 & 0 \\ 1 & 0 & 2 \end{pmatrix}$$

$$\Rightarrow \det(H) = 4 \cdot 16 - 1 \cdot 2 + 1(-8) = 54 > 0$$

$$LPM_2 = \begin{vmatrix} 4 & 1 \\ 1 & 8 \end{vmatrix} = 31 > 0$$

$$LPM_1 = |4| = 4 > 0$$

$\Rightarrow H$ positive definite, hence $(0, 0, 0)$ local minimum

ii) $f(x, y, z) = -x^3 + 3xz + 2y - y^2 - 3z^2$

First order conditions:

$$\begin{cases} f_x = -3x^2 + 3z = 0 \\ f_y = 2 - 2y = 0 \Rightarrow y = 1 \\ f_z = 3x - 6z = 0 \Rightarrow z = \frac{1}{2}x \end{cases}$$

PTO.

Substitute $z = \frac{1}{2}x$ in to first eq. $\Rightarrow 3x^2 = \frac{3}{2}x$

$\Rightarrow x(x - \frac{1}{2}) = 0$, Thus $x = 0$ or $x = \frac{1}{2}$

$x = 0 \Rightarrow$ point $(0, 1, 0)$

$x = \frac{1}{2} \Rightarrow$ point $(\frac{1}{2}, 1, \frac{1}{4})$.

Hessian: $H = \begin{pmatrix} -6x & 0 & 3 \\ 0 & -2 & 0 \\ 3 & 0 & -6 \end{pmatrix}$

$\det(H) = -6x \cdot 12 + 3 \cdot 6 = 18(1 - 4x) = LPM_3$

$LPM_2 = \begin{vmatrix} -6x & 0 \\ 0 & -2 \end{vmatrix} = 12x$, $LPM_1 = -6x$

$(0, 1, 0) \Rightarrow LPM_3 > 0$, $LPM_2 = 0$, $LPM_1 = 0$
indefinite point

(LPM test is inconclusive)

$(\frac{1}{2}, 1, \frac{1}{4}) \Rightarrow LPM_3 < 0$, $LPM_2 > 0$, $LPM_1 < 0$
 $\Rightarrow H$ neg def. \Rightarrow local maximum

iii) $f(x, y) = 3x^4 + 3x^2y - y^3$

First-order conditions:

$$\begin{cases} f_x = 12x^3 + 6xy = 0 \\ f_y = 3x^2 - 3y^2 = 0 \end{cases} \Rightarrow x^2 = y^2 \Rightarrow x = \pm y$$

$x = y \Rightarrow 12x^3 + 6x^2 = 0 \Rightarrow x^2(2x + 1) = 0 \Rightarrow x = 0$ or $x = -\frac{1}{2}$
 \Rightarrow crit points $(0, 0)$, $(-\frac{1}{2}, -\frac{1}{2})$

$x = -y \Rightarrow 12x^3 - 6x^2 = 0 \Rightarrow x^2(2x - 1) = 0 \Rightarrow x = 0$, or $x = \frac{1}{2}$
gives additional point $(\frac{1}{2}, -\frac{1}{2})$

Hessian $\begin{pmatrix} 36x^2 + 6y & 6x \\ 6x & -6y \end{pmatrix}$

At $(0, 0)$ - all PMS zero, so
indefinite point (test is
inconclusive)

P.T.O

At $(\frac{1}{2}, -\frac{1}{2})$: $f_{xx} = 12x = 6$, $f_{yy} = -6y = 3$, $f_{xy} = 6$
 $\Delta = 6 \cdot 3 - 6^2 = -18 < 0$
 $f_{xx} > 0$
 \Rightarrow local minimum.

At both points $(\pm \frac{1}{2}, \frac{1}{2})$ we get $H = \begin{pmatrix} 6 & \pm 3 \\ \pm 3 & -3 \end{pmatrix}$
 $\Rightarrow LPM_2 = \det(H) = 9 > 0$, $LPH_1 = 6 > 0 \Rightarrow H$ pos. def.
local minimum

B2] a) $Q(x, y) = 10xy - x^2 - y^2 = (x, y) A \begin{pmatrix} x \\ y \end{pmatrix}$

Symmetric matrix $A = \begin{pmatrix} -1 & 5 \\ 5 & -1 \end{pmatrix}$

Eigenvalues

$$\det(A - \lambda I) = \begin{vmatrix} -1-\lambda & 5 \\ 5 & -1-\lambda \end{vmatrix} = (1+\lambda)^2 - 25 = 0$$

$$\Rightarrow 1+\lambda = \pm 5 \Rightarrow \lambda = 4, -6 \text{ roots}$$

\Rightarrow indefinite quadratic form. In fact,
 $LPM_2 = -24$, $LPH_1 = -1 \Rightarrow \underline{ID.}$

Eigenvectors:

$$\boxed{\lambda = 4}$$

$$\begin{pmatrix} -5 & 5 \\ 5 & -5 \end{pmatrix} \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \Rightarrow \boxed{v_1 - v_2 = 0}$$

$$\Rightarrow \text{vectors} \sim \begin{pmatrix} 1 \\ 1 \end{pmatrix} \text{ unit eigenvector } \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

$$\boxed{\lambda = -6}$$

$$\begin{pmatrix} 5 & 5 \\ 5 & 5 \end{pmatrix} \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \Rightarrow \boxed{v_1 + v_2 = 0}$$

$$\Rightarrow \text{vectors} \sim \begin{pmatrix} 1 \\ -1 \end{pmatrix} \text{ unit eigenvector } \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ -1 \end{pmatrix}$$

new variables:

$$\tilde{x} = \frac{1}{\sqrt{2}} (1, 1) \cdot \begin{pmatrix} x \\ y \end{pmatrix} = \frac{x+y}{\sqrt{2}}$$

$$\tilde{y} = \frac{1}{\sqrt{2}} (1, -1) \cdot \begin{pmatrix} x \\ y \end{pmatrix} = \frac{x-y}{\sqrt{2}}$$

PTO

$$\Rightarrow Q(x, y) = 4 \left(\frac{x+y}{\sqrt{2}} \right)^2 - 6 \left(\frac{x-y}{\sqrt{2}} \right)^2$$

b) Quadratic form:

$$Q(x_1, x_2, x_3) = 8x_1x_2 + 2x_1x_3 + 18x_2x_3 - 5x_1^2 - 13x_2^2 - 10x_3^2$$

$$\Rightarrow A = \begin{pmatrix} -5 & 4 & 1 \\ 4 & -13 & 9 \\ 1 & 9 & -10 \end{pmatrix}$$

Eigen values:

$$\det(A - \lambda I) = \begin{vmatrix} -5-\lambda & 4 & 1 \\ 4 & -13-\lambda & 9 \\ 1 & 9 & -10-\lambda \end{vmatrix} =$$

$$= -(5+\lambda) [(13+\lambda)(10+\lambda) - 81] - 4 [-4(10+\lambda) - 9] + [36 + 13\lambda]$$

$$= -\lambda^3 - 28\lambda^2 - 245\lambda - 650 + 0\lambda + 405 + 16\lambda + 160 + 36 + 49 + \lambda$$

$$= -\lambda^3 - 28\lambda^2 - 147\lambda = -\lambda(\lambda+7)(\lambda+21)$$

\Rightarrow eigenvalues $\lambda_1 = 0$, $\lambda_2 = -7$, $\lambda_3 = -21$ negative
 NSD: ~~negative~~ not semidefinite!

Check by principal minor test:

$LPM_3 = \det A = 0 \Rightarrow$ PMS of order 2:

$$\begin{vmatrix} -5 & 4 \\ 4 & -13 \end{vmatrix} = -49 > 0, \quad \begin{vmatrix} -5 & 1 \\ 1 & -10 \end{vmatrix} = 49 > 0, \quad \begin{vmatrix} -13 & 9 \\ 9 & -10 \end{vmatrix} = 49 > 0$$

PMs of order 1:

$$\underline{|-5| = -5 < 0}, \quad |-13| = -13 < 0, \quad |-10| = -10 < 0$$

meaning: 1×1 determinant.

So odd-order PMs ≤ 0 , even-order PMs $\geq 0 \Rightarrow$ NPD.

Eigen vectors

$$\boxed{\lambda=0} \quad \begin{pmatrix} -5 & 4 & 1 \\ 4 & -13 & 9 \\ 1 & 9 & -10 \end{pmatrix} \begin{pmatrix} v_1 \\ v_2 \\ v_3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

System of eqs:

$$\begin{cases} v_1 + 9v_2 - 10v_3 = 0 \\ 4v_1 - 13v_2 + 9v_3 = 0 \\ -5v_1 + 4v_2 + v_3 = 0 \end{cases}$$

By row elimination:

$$\Rightarrow \begin{cases} v_1 + 9v_2 - 10v_3 = 0 \\ -49v_2 + 49v_3 = 0 \\ 49v_2 - 49v_3 = 0 \end{cases} \Rightarrow v_2 = v_3$$

$$\text{then } v_1 = v_3 \Rightarrow$$

$$\Rightarrow \text{eigenvector} \sim \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} \Rightarrow \text{unit eigenvector } \frac{1}{\sqrt{3}} \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$$

$$\boxed{\lambda=-7} \quad \begin{pmatrix} 2 & 4 & 1 \\ 4 & -6 & 9 \\ 1 & 9 & -3 \end{pmatrix} \begin{pmatrix} v_1 \\ v_2 \\ v_3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

$$\Rightarrow \begin{cases} v_1 + 9v_2 - 3v_3 = 0 \\ 2v_1 + 4v_2 + v_3 = 0 \\ 4v_1 - 6v_2 + 9v_3 = 0 \end{cases} \Rightarrow \begin{cases} v_1 + 9v_2 - 3v_3 = 0 \\ -14v_2 + 7v_3 = 0 \\ -42v_2 + 21v_3 = 0 \end{cases}$$

$$\Rightarrow v_3 = 2v_2, \quad v_1 = -3v_2 \rightarrow \text{eigenvector} \sim \begin{pmatrix} -3 \\ 1 \\ 2 \end{pmatrix}$$

$$\Rightarrow \text{unit eigenvector} : \frac{1}{\sqrt{14}} \begin{pmatrix} -3 \\ 1 \\ 2 \end{pmatrix}$$

$$\boxed{\lambda = -21}$$

$$\begin{pmatrix} 16 & 4 & 1 \\ 4 & 8 & 9 \\ 1 & 9 & 11 \end{pmatrix} \begin{pmatrix} v_1 \\ v_2 \\ v_3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

$$\Rightarrow \begin{cases} v_1 + 9v_2 + 11v_3 = 0 \\ 4v_1 + 0v_2 + 9v_3 = 0 \\ 16v_1 + 4v_2 + v_3 = 0 \end{cases} \Rightarrow \begin{cases} v_1 + 9v_2 + 11v_3 = 0 \\ -28v_2 - 35v_3 = 0 \\ -140v_2 - 175v_3 = 0 \end{cases}$$

$$\Rightarrow \begin{cases} 4v_2 + 5v_3 = 0 \\ v_1 + v_2 + v_3 = 0 \end{cases} \Rightarrow \text{vector} \sim \begin{pmatrix} 1 \\ -5 \\ 4 \end{pmatrix}$$

$$\Rightarrow \text{unit eigenvector} \quad \frac{1}{\sqrt{42}} \begin{pmatrix} 1 \\ -5 \\ 4 \end{pmatrix}$$

\Rightarrow orthogonal diagonalizing matrix:

$$O = \begin{pmatrix} \frac{1}{\sqrt{3}} & -\frac{3}{\sqrt{14}} & \frac{1}{\sqrt{42}} \\ \frac{1}{\sqrt{3}} & \frac{1}{\sqrt{14}} & -\frac{5}{\sqrt{42}} \\ \frac{1}{\sqrt{3}} & \frac{2}{\sqrt{14}} & \frac{4}{\sqrt{42}} \end{pmatrix}$$

new variables

check orthogonal $O \cdot O^T = I$.

$$\begin{pmatrix} \bar{x}_1 \\ \bar{x}_2 \\ \bar{x}_3 \end{pmatrix} = O^T \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} \frac{1}{\sqrt{3}} & \frac{1}{\sqrt{3}} & \frac{1}{\sqrt{3}} \\ -\frac{3}{\sqrt{14}} & \frac{1}{\sqrt{14}} & \frac{2}{\sqrt{14}} \\ \frac{1}{\sqrt{42}} & -\frac{5}{\sqrt{42}} & \frac{4}{\sqrt{42}} \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix}$$

⑤

$$\Rightarrow \tilde{x}_1 = \frac{x_1 + x_2 + x_3}{\sqrt{3}}, \quad \tilde{x}_2 = \frac{-3x_1 + x_2 + 2x_3}{\sqrt{14}}, \quad \tilde{x}_3 = \frac{x_1 - 5x_2 + 4x_3}{\sqrt{42}}$$

and

$$Q(x_1, x_2, x_3) = 0 \cdot \left(\frac{x_1 + x_2 + x_3}{\sqrt{3}} \right)^2 - 7 \left(\frac{-3x_1 + x_2 + 2x_3}{\sqrt{14}} \right)^2 - 21 \left(\frac{x_1 - 5x_2 + 4x_3}{\sqrt{42}} \right)^2$$

B3 | (a) Revenue is $R = p_1 Q_1 + p_2 Q_2$

express p_1, p_2 in terms of Q_1, Q_2

$$\Rightarrow p_1 = 210 - Q_1, \quad p_2 = 90 - Q_2$$

$$\Rightarrow R(Q_1, Q_2) = Q_1 (210 - Q_1) + Q_2 (90 - Q_2)$$

Cost: $C(Q_1, Q_2) = 6000 + Q_1^2 + Q_1 Q_2 + Q_2^2$

→ profit function:

$$\Pi(Q_1, Q_2) = R - C = Q_1(210 - Q_1) + Q_2(90 - Q_2) - 6000 - Q_1^2 - Q_1 Q_2 - Q_2^2$$

$$= 210Q_1 - 2Q_1^2 + 90Q_2 - 2Q_2^2 - Q_1 Q_2 - 6000$$

First-order conditions:

$$\begin{aligned} \Pi_{Q_1} &= 210 - 4Q_1 - Q_2 = 0 \\ \Pi_{Q_2} &= 90 - 4Q_2 - Q_1 = 0 \end{aligned} \Rightarrow \begin{cases} 4Q_1 + Q_2 = 210 \\ Q_1 + 4Q_2 = 90 \end{cases}$$

$$\Rightarrow 15Q_2 = 150 \Rightarrow Q_2 = 10$$

$$15Q_1 = 750 \Rightarrow Q_1 = 50$$

→ corresponding prices:

$$p_1^* = 210 - Q_1 = 160, \quad p_2^* = 90 - Q_2 = 80.$$

Hessian:

$$H = \begin{pmatrix} \Pi_{Q_1 Q_1} & \Pi_{Q_1 Q_2} \\ \Pi_{Q_1 Q_2} & \Pi_{Q_2 Q_2} \end{pmatrix} = \begin{pmatrix} -4 & -1 \\ -1 & -4 \end{pmatrix}$$

$$\det(H) = LPH_2 = 15 > 0, \quad LPH_1 = -4 < 0 \Rightarrow \underline{ND}$$

critical point is local max,

Values of profit at critical point:

$$\Pi^* = \Pi(Q_1^*, Q_2^*) = \Pi(50, 10) = -300 < 0$$

so company makes a loss.

(b) Revenue: $R = p_1 Q_1 + p_2 Q_2 = p_1 (40 - p_1) + p_2 (60 - 2p_2)$

Cost: $C = K + 20(40 - p_1) + 10(60 - 2p_2)$

$$= K + 1400 - 20p_1 - 20p_2$$

$$\Rightarrow \text{Profit } \Pi(p_1, p_2) = R - C = p_1(40 - p_1) + p_2(60 - 2p_2) - K - 1400 + 20p_1 + 20p_2$$

$$= 60p_1 - p_1^2 + 80p_2 - 2p_2^2 - K - 1400$$

First-order conditions:

$$\begin{cases} \Pi_{p_1} = 60 - 2p_1 = 0 \\ \Pi_{p_2} = 80 - 4p_2 = 0 \end{cases} \Rightarrow p_1 = 30, \quad p_2 = 20$$

Hessian

$$H = \begin{pmatrix} \Pi_{p_1 p_1} & \Pi_{p_1 p_2} \\ \Pi_{p_1 p_2} & \Pi_{p_2 p_2} \end{pmatrix} = \begin{pmatrix} -2 & 0 \\ 0 & -4 \end{pmatrix}$$

$LPM_2 = 0 \geq 0$, $LPM_1 < 0 \Rightarrow$ N.D., (p_1^*, p_2^*) local max.

Profit at crit. point $\Pi(p_1^*, p_2^*) = 300 - K$

so company breaks even if $K = 300$.

B# $Q(x, y) = x^{1/2} y^{1/4}$, price $p \Rightarrow$ revenue $R = p x^{1/2} y^{1/4}$
 Cost $C(x, y) = ax + by$

a) Profit: $\Pi(x, y) = R - C = p x^{1/2} y^{1/4} - ax - by$.

First order conditions:

$$\begin{cases} -\Pi_x = \frac{1}{2} p x^{-1/2} y^{1/4} - a \Rightarrow p Q = 2ax \\ \Pi_y = \frac{1}{4} p x^{1/2} y^{-3/4} - b \Rightarrow p Q = 4by \end{cases}$$

$$\Rightarrow \boxed{2ax = 4by}$$

Furthermore $\frac{1}{8} p^2 x^{1/2} y^{-3/4} \cdot x^{-1/2} y^{1/4} = ab$

$$\Rightarrow p^2 y^{-1/2} = 8ab \Rightarrow y = \left(\frac{p^2}{8ab} \right)^2 = y^*$$

and

$$x = \frac{2b}{a} y = \frac{2b}{a} \left(\frac{p^2}{8ab} \right)^2 = x^*$$

$$\Rightarrow x^* = \frac{p^4}{32 a^3 b}, \quad y^* = \frac{p^4}{64 a^2 b^2}$$

Profit at the critical point:

$$\begin{aligned}\pi_x = \pi(x_*, y_*) &= p \left(\frac{p^4}{32a^3b} \right)^{1/2} \left(\frac{p^4}{64a^2b^2} \right)^{1/4} \\ &\quad - a \frac{p^4}{32a^3b} - b \frac{p^4}{64a^2b^2} \\ &= \frac{p^4}{16a^2b} \left(1 - \frac{1}{2} - \frac{1}{4} \right) = \frac{p^4}{64a^2b}\end{aligned}$$

(b) Hessian:

$$\begin{aligned}H &= \begin{pmatrix} \pi_{xx} & \pi_{xy} \\ \pi_{xy} & \pi_{yy} \end{pmatrix} = \begin{pmatrix} -\frac{1}{4} p x^{-3/2} y^{1/4} & \frac{1}{8} p x^{-1/2} y^{-3/4} \\ \frac{1}{8} p x^{-1/2} y^{-3/4} & -\frac{3}{16} p x^{1/2} y^{-7/4} \end{pmatrix} \\ &= \frac{1}{4} p x^{-3/2} y^{-7/4} \begin{pmatrix} -y^2 & \frac{1}{2} xy \\ \frac{1}{2} xy & -\frac{3}{4} x^2 \end{pmatrix}\end{aligned}$$

$$\Rightarrow \det(H) = \left(\frac{1}{4} p x^{-3/2} y^{-7/4} \right)^2 \left(\frac{3}{4} x^2 y^2 - \frac{1}{4} x^2 y^2 \right) > 0$$

$$LPM_1 = -\frac{1}{4} p x^{-3/2} y^{-7/4} y^2 < 0 \quad \text{so ND indeed max.}$$

B5] Production rate $Q(x, y, z) = x^{1/4} y^{1/4} z^{1/4}$, $p = 4$.

\Rightarrow revenue $R = 4 x^{1/4} y^{1/4} z^{1/4}$

Cost: $C = x + \frac{1}{2}y + \frac{1}{3}z$

\Rightarrow Profit $\Pi(x, y, z) = R - C = 4 x^{1/4} y^{1/4} z^{1/4} - x - \frac{1}{2}y - \frac{1}{3}z$.

First-order conditions:

$$\begin{cases} \Pi_x = x^{-3/4} y^{1/4} z^{1/4} - 1 = 0 & \Rightarrow Q = x \\ \Pi_y = x^{1/4} y^{-3/4} z^{1/4} - \frac{1}{2} = 0 & \Rightarrow Q = \frac{1}{2}y \\ \Pi_z = x^{1/4} y^{1/4} z^{-3/4} - \frac{1}{3} = 0 & \Rightarrow Q = \frac{1}{3}z \end{cases}$$

$\Rightarrow y = 2Q, \quad z = 3Q, \quad x = Q$

$\Rightarrow xyz = 6Q^3 \Rightarrow Q = (xyz)^{1/4} = (6Q^3)^{1/4}$

$\Rightarrow \boxed{Q = 6} \Rightarrow x = 6, y = 12, z = 18.$
at. stat. point.

Hessian:

$$\Pi_{xx} = -\frac{3}{4} x^{-7/4} y^{1/4} z^{1/4} = -\frac{3}{4} \frac{Q}{x^2}$$

$$\Pi_{xy} = \frac{1}{4} x^{-3/4} y^{-3/4} z^{1/4} = \frac{1}{4} \frac{Q}{xy}$$

$$\Pi_{xz} = \frac{1}{4} x^{-3/4} y^{1/4} z^{-3/4} = \frac{1}{4} \frac{Q}{xz}$$

$$\Pi_{yy} = -\frac{3}{4} x^{1/4} y^{-7/4} z^{1/4} = -\frac{3}{4} \frac{Q}{y^2}$$

$$\Pi_{yz} = \frac{1}{4} x^{1/4} y^{-3/4} z^{-3/4} \quad \Pi_{zz} = -\frac{3}{4} x^{1/4} y^{1/4} z^{-7/4}$$

$$\Rightarrow H = \begin{pmatrix} -\frac{3}{4} \frac{Q}{x^2} & \frac{1}{4} \frac{Q}{xy} & \frac{1}{4} \frac{Q}{xz} \\ \frac{1}{4} \frac{Q}{xy} & -\frac{3}{4} \frac{Q}{y^2} & \frac{1}{4} \frac{Q}{yz} \\ \frac{1}{4} \frac{Q}{xz} & \frac{1}{4} \frac{Q}{yz} & -\frac{3}{4} \frac{Q}{z^2} \end{pmatrix}$$

$$\begin{aligned} \det(H) &= -\frac{3}{4} \frac{Q}{x^2} \left(\frac{1}{16} \frac{Q^2}{y^2 z^2} - \frac{1}{16} \frac{Q^2}{y^2 z^2} \right) \\ &\quad - \frac{1}{4} \frac{Q}{xy} \left(-\frac{3}{16} \frac{Q^2}{xy z^2} - \frac{1}{16} \frac{Q^2}{xy z^2} \right) \\ &\quad + \frac{1}{4} \frac{Q}{xz} \left(\frac{1}{16} \frac{Q^2}{xy^2 z} + \frac{3}{16} \frac{Q^2}{y^2 x z} \right) \end{aligned}$$

$$= \frac{Q^3}{64 x^2 y^2 z^2} \left(-3 \cdot 8 + 1 \cdot 4 + 1 \cdot 4 \right) < 0$$

$$LPM_2 = \frac{1}{16} \frac{Q^2}{x^2 y^2} - \frac{1}{16} \frac{Q^2}{x^2 y^2} = \frac{Q^2}{x^2 y^2} > 0$$

$$LPM_1 = -\frac{3}{4} \frac{Q}{x^2} < 0$$

so alternating signs with $LPM_1 < 0$

$$\Rightarrow H \text{ is ND} \Rightarrow \max$$