

Universal Stochastic Predictor

Phase 1: API Foundations

Implementation Team

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Chapter 1

Phase 1: API Foundations Overview

Phase 1 implements the foundational API layer for the Universal Stochastic Predictor (USP). This phase establishes core data structures, configuration management, validation framework, random number generation, and schema definitions required for kernel implementations (Phase 2).

1.1 Scope

Phase 1 covers:

- **Type System** (`types.py`): Core immutable dataclasses for configuration and predictions
- **Configuration Management** (`config.py`): Singleton ConfigManager with TOML-based parameter injection
- **Validation Framework** (`validation.py`): Domain-specific validation and sanitization logic
- **Random Number Generation** (`prng.py`): JAX-based PRNG utilities
- **Schema Definitions** (`schemas.py`): Pydantic models for API contracts

1.2 Quality Assurance Alignment

This phase is validated via the project test framework in `Test/`. Automated checks include `flake8`, `black`, `isort`, and `mypy`, plus dependency validation that compares imports to requirements and the active virtual environment. Auto-generated smoke tests are synchronized by `Test/framework/generator.py`. See `doc/latex/specification/Stochastic_Predictor_Tests_Python.tex` for details.

1.3 Design Principles

- **Zero-Heuristics Policy:** All hyperparameters must reside in configuration, never hardcoded in code
- **100% English:** All code, comments, docstrings, and identifiers in English only
- **Immutability:** Data structures use frozen dataclasses for thread-safety and JAX compatibility
- **Type Safety:** Dimension checking via jaxtyping; strict validation boundaries

Chapter 2

Type System (types.py)

2.1 Overview

The `types.py` module defines all immutable data structures using frozen dataclasses. This ensures thread-safe configuration sharing, JAX JIT compilation cache compatibility, and proper type checking.

2.2 PredictorConfig Class

2.2.1 Purpose

`PredictorConfig` is the system hyperparameter vector (denoted Λ in the specification). It contains all configurable parameters for orchestration, kernels, validation, and I/O. The complete field set is defined in `stochastic_predictor/api/types.py`.

2.2.2 Core Configuration Fields

Schema Versioning

```
1 schema_version: str = "1.0"
```

JKO Orchestrator (Optimal Transport)

```
1 epsilon: float = 1e-3           # Entropic regularization (Sinkhorn)
2 learning_rate: float = 0.01      # Learning rate tau
3 sinkhorn_epsilon_min: float = 0.01 # Min epsilon for coupling
4 sinkhorn_epsilon_0: float = 0.1    # Base epsilon
5 sinkhorn_alpha: float = 0.5       # Volatility coupling coefficient
6 sinkhorn_max_iter: int = 200      # Max Sinkhorn iterations
7 sinkhorn_inner_iterations: int = 10 # Inner log-domain iterations
```

Entropy Monitoring

```
1 entropy_window: int = 100          # Sliding window size
2 entropy_threshold: float = 0.8      # Legacy threshold (superseded by entropy_gamma_*)
3 entropy_gamma_min: float = 0.5       # Crisis mode (lenient)
4 entropy_gamma_max: float = 1.0       # Low-vol mode (strict)
5 entropy_gamma_default: float = 0.8 # Normal regime
6 entropy_volatility_low_threshold: float = 0.05
7 entropy_volatility_high_threshold: float = 0.2
8 entropy_ratio_min: float = 0.1
9 entropy_ratio_max: float = 10.0
```

```

10 entropy_baseline_floor: float = 1e-6
11 mode_collapse_min_threshold: int = 10
12 mode_collapse_window_ratio: float = 0.1

```

Adaptive Coupling and Stiffness

```

1 dgm_entropy_coupling_beta: float = 0.7 # DGM entropy-topology coupling
2 dgm_max_capacity_factor: float = 4.0 # Max width*depth multiplier
3 stiffness_calibration_c1: float = 25.0 # Calibration constant (low)
4 stiffness_calibration_c2: float = 250.0 # Calibration constant (high)
5 stiffness_min_low: float = 100.0 # Minimum low threshold
6 stiffness_min_high: float = 1000.0 # Minimum high threshold
7 holder_exponent_guard: float = 1e-3 # Guard against alpha -> 1

```

Kernel Parameters

Kernel D (Log-Signatures)

```

1 kernel_d_depth: int = 3 # Truncation level
2 kernel_d_alpha: float = 0.1 # Extrapolation scaling

```

Kernel A (WTMM + Fokker-Planck)

```

1 wtmm_buffer_size: int = 128 # Memory buffer
2 wtmm_num_scales: int = 16 # Number of WTMM scales
3 wtmm_scale_min: float = 1.0 # Minimum WTMM scale
4 wtmm_sigma: float = 1.0 # Morlet wavelet sigma
5 wtmm_fc: float = 0.5 # Morlet wavelet central frequency
6 wtmm_modulus_threshold: float = 0.01 # Modulus maxima threshold
7 wtmm_max_link_distance: float = 2.0 # Max link distance for maxima chains
8 wtmm_q_min: float = -2.0 # Min q for partition function
9 wtmm_q_max: float = 2.0 # Max q for partition function
10 wtmm_q_steps: int = 9 # Number of q values
11 wtmm_h_min: float = 0.0 # Min Holder exponent grid
12 wtmm_h_max: float = 1.5 # Max Holder exponent grid
13 wtmm_h_steps: int = 151 # Holder exponent grid size
14 wtmm_tau_default_scale: float = 0.5 # Default tau scale for non-finite q
15 besov_cone_c: float = 1.5 # Cone of influence
16 kernel_ridge_lambda: float = 1e-6 # RKHS regularization
17 kernel_a_bandwidth: float = 0.1 # Gaussian kernel smoothness
18 kernel_a_embedding_dim: int = 5 # Takens embedding
19 kernel_a_min_wiener_hopf_order: int = 2 # Minimum Wiener-Hopf order

```

Kernel B (PDE/DGM)

```

1 dgm_width_size: int = 64 # Network width
2 dgm_depth: int = 4 # Network depth
3 dgm_entropy_num_bins: int = 50 # Histogram bins
4 dgm_activation: str = "tanh" # Activation function
5 kernel_b_r: float = 0.05 # HJB interest rate
6 kernel_b_sigma: float = 0.2 # HJB volatility
7 kernel_b_horizon: float = 1.0 # Prediction horizon
8 kernel_b_spatial_samples: int = 100
9 kernel_b_spatial_range_factor: float = 0.5

```

Kernel C (SDE Integration)

```

1 stiffness_low: int = 100 # Explicit integrator threshold
2 stiffness_high: int = 1000 # Implicit integrator threshold
3 sde_dt: float = 0.01 # Time step
4 sde_numel_integrations: int = 100 # Number of steps

```

```

5 sde_diffusion_sigma: float = 0.2      # Diffusion coefficient
6 kernel_c_mu: float = 0.0              # Drift (mean reversion)
7 kernel_c_alpha: float = 1.8            # Stability (1 < alpha <= 2)
8 kernel_c_beta: float = 0.0             # Skewness (-1 <= beta <= 1)
9 kernel_c_horizon: float = 1.0          # Integration horizon
10 kernel_c_dt0: float = 0.01            # Initial time step (adaptive)

```

Risk Detection

```

1 holder_threshold: float = 0.4          # Holder singularity threshold
2 cusum_h: float = 5.0                  # CUSUM drift
3 cusum_k: float = 0.5                  # CUSUM slack
4 grace_period_steps: int = 20           # Refractory period
5 volatility_alpha: float = 0.1           # EWMA decay

```

Validation Constraints

```

1 sigma_bound: float = 20.0              # Outlier threshold (N sigma)
2 sigma_val: float = 1.0                 # Reference std dev
3 max_future_drift_ns: int = 1_000_000_000 # Clock skew tolerance
4 max_past_drift_ns: int = 86_400_000_000_000 # Stale data threshold

```

I/O Policies

```

1 data_feed_timeout: int = 30             # Timeout seconds
2 data_feed_max_retries: int = 3          # Retry attempts
3 snapshot_atomic_fsync: bool = True      # Force fsync
4 snapshot_compression: str = "none"       # Compression method
5 snapshot_format: str = "msgpack"         # Serialization format
6 snapshot_hash_algorithm: str = "sha256"
7 telemetry_hash_interval_steps: int = 1
8 telemetry_buffer_capacity: int = 1024
9 telemetry_hash_algorithm: str = "sha256"
10 telemetry_adaptive_log_path: str = "io/adaptive_telemetry.jsonl"
11 telemetry_adaptive_window_size: int = 100
12 telemetry_placeholder_max_stiffness_metric: float = 0.0
13 telemetry_placeholder_num_internal_iterations_mean: float = 0.0
14 telemetry_placeholder_implicit_residual_norm_max: float = 0.0
15 telemetry_dashboard_title: str = "USP Telemetry Dashboard"
16 telemetry_dashboard_width: int = 720
17 telemetry_dashboard_height: int = 180
18 telemetry_dashboard_spread_epsilon: float = 1e-9
19 telemetry_dashboard_recent_rows: int = 25
20 frozen_signal_min_steps: int = 5
21 frozen_signal_recovery_ratio: float = 0.1
22 frozen_signal_recovery_steps: int = 2
23 frozen_signal_variance_floor: float = 1e-12
24 staleness_ttl_ns: int = 500_000_000 # TTL degraded mode
25 besov_nyquist_interval_ns: int = 100_000_000 # Nyquist sample rate
26 inference_recovery_hysteresis: float = 0.8   # Recovery factor

```

Base Parameters

```

1 base_min_signal_length: int = 32          # Minimum length
2 signal_normalization_method: str = "zscore" # Normalization
3 log_sig_depth: int = 3                   # Log-signature truncation

```

2.3 Data Structures for Prediction API

2.3.1 ProcessState

```
1 @dataclass(frozen=True)
2 class ProcessState:
3     """Predictor operational input (domain-agnostic)."""
4     magnitude: Float[Array, "1"]      # y_t: Observed magnitude
5     reference: Float[Array, "1"]      # y_reference: Baseline magnitude
6     timestamp_ns: int                # Unix Epoch (nanoseconds)
```

2.3.2 PredictionResult

```
1 @dataclass(frozen=True)
2 class PredictionResult:
3     """System output (prediction + telemetry + control flags)."""
4     predicted_next: Float[Array, "1"]      # y_{t+1}
5     holder_exponent: Float[Array, "1"]      # H_t
6     cusum_drift: Float[Array, "1"]          # G^+
7     distance_to_collapse: Float[Array, "1"] # h - G^+
8     free_energy: Float[Array, "1"]          # JKO energy
9     kurtosis: Float[Array, "1"]             # Empirical kurtosis
10    dgm_entropy: Float[Array, "1"]          # Kernel B entropy
11    adaptive_threshold: Float[Array, "1"]   # h_t
12    weights: Float[Array, "4"]              # [rho_A, rho_B, rho_C, rho_D]
13    sinkhorn_converged: Bool[Array, "1"]    # JKO convergence
14    degraded_inference_mode: bool         # TTL violation
15    emergency_mode: bool                 # Holder singularity
16    regime_change_detected: bool          # CUSUM alarm
17    modeCollapse_warning: bool            # DGM entropy warning
18    mode: str                           # Standard | Robust | Emergency
```

2.4 Immutability Guarantees

All public API dataclasses use `frozen=True` to enable:

- JAX JIT cache key hashing
- Thread-safe configuration sharing
- Enforcement of zero-heuristics policy

Chapter 3

Configuration Management (config.py)

3.1 Architecture

config.py implements:

- Lazy singleton accessed via `get_config()`
- TOML parsing with automatic field mapping
- Environment variable override support
- Runtime validation of completeness

3.2 ConfigManager Class

```
1 class ConfigManager:
2     """Singleton configuration loader."""
3
4     def get(self, section: str, key: str, default: Any = None) -> Any:
5         """Get a config value with fallback."""
6
7     def get_section(self, section: str) -> Dict[str, Any]:
8         """Get an entire config section."""
9
10    def raw_config(self) -> Dict[str, Any]:
11        """Return raw config dict."""
12
13    def check_and_reload(self) -> bool:
14        """Reload config.toml if mtime changed."""
15
16    @staticmethod
17    def _apply_env_overrides() -> None:
18        """Apply USP_SECTION__KEY environment variables."""
```

3.3 FIELD_TO_SECTION_MAP (Single Source of Truth)

Automated field-to-section mapping ensures all PredictorConfig fields have defined placement:

```
1 FIELD_TO_SECTION_MAP = {
2     # Metadata
3     "schema_version": "meta",
4     # Orchestration
5     "epsilon": "orchestration",
6     "learning_rate": "orchestration",
```

```

7  "sinkhorn_epsilon_min": "orchestration",
8  "sinkhorn_epsilon_0": "orchestration",
9  "sinkhorn_alpha": "orchestration",
10 "sinkhorn_max_iter": "orchestration",
11 "entropy_window": "orchestration",
12 "entropy_threshold": "orchestration",
13 "modeCollapse_min_threshold": "orchestration",
14 "modeCollapse_window_ratio": "orchestration",
15 # Kernels (excerpt)
16 "log_sig_depth": "kernels",
17 "wtmm_buffer_size": "kernels",
18 "besov_cone_c": "kernels",
19 "kernel_a_bandwidth": "kernels",
20 "dgm_width_size": "kernels",
21 "dgm_depth": "kernels",
22 "kernel_c_mu": "kernels",
23 "kernel_d_depth": "kernels",
24 # Validation (excerpt)
25 "validation_simplex_atol": "validation",
26 "validation_holder_exponent_min": "validation",
27 # I/O (excerpt)
28 "snapshot_format": "io",
29 "snapshot_hash_algorithm": "io",
30 "telemetry_hash_interval_steps": "io",
31 # Core
32 "staleness_ttl_ns": "core",
33 # ... additional fields omitted for brevity
34 }
```

3.4 config.toml Structure

```

1 [meta]
2 schema_version = "1.0"
3
4 [core]
5 jax_platforms = "cpu"
6 jax_default_dtype = "float64"
7 float_precision = 64
8 prng_seed = 42
9 prng_split_count = 4
10 staleness_ttl_ns = 500_000_000
11
12 [orchestration]
13 epsilon = 0.001
14 learning_rate = 0.01
15 sinkhorn_epsilon_min = 0.01
16 sinkhorn_epsilon_0 = 0.1
17 sinkhorn_alpha = 0.5
18 sinkhorn_max_iter = 200
19 entropy_window = 100
20 entropy_threshold = 0.8
21 entropy_gamma_min = 0.5
22 entropy_gamma_max = 1.0
23 entropy_gamma_default = 0.8
24 modeCollapse_min_threshold = 10
25 modeCollapse_window_ratio = 0.1
26 cusum_h = 5.0
27 cusum_k = 0.5
28 grace_period_steps = 20
29 residual_window_size = 252
30 volatility_alpha = 0.1
```

```

31 sigma_bound = 20.0
32 sigma_val = 1.0
33 max_future_drift_ns = 1_000_000_000
34 max_past_drift_ns = 86_400_000_000_000
35 holder_threshold = 0.4
36 inference_recovery_hysteresis = 0.8
37
38 [kernels]
39 log_sig_depth = 3
40 kernel_d_depth = 3
41 kernel_d_load_shedding_depths = [2, 3, 5]
42 kernel_d_alpha = 0.1
43 kernel_d_confidence_scale = 0.1
44 kernel_d_confidence_base = 1.0
45 base_min_signal_length = 32
46 signal_normalization_method = "zscore"
47 numerical_epsilon = 1e-10
48 warmup_signal_length = 100
49 pdf_grid_min_z = -4.0
50 pdf_grid_max_z = 4.0
51 pdf_grid_num_points = 256
52 pdf_min_sigma = 1e-6
53 confidence_interval_z = 1.96
54 kernel_output_time_us = 1.0
55 kurtosis_min = 1.0
56 kurtosis_max = 100.0
57 kurtosis_reference = 3.0
58 wtmm_buffer_size = 128
59 besov_cone_c = 1.5
60 besov_nyquist_interval_ns = 100_000_000
61 kernel_a_bandwidth = 0.1
62 kernel_a_embedding_dim = 5
63 kernel_a_min_variance = 1e-10
64 kernel_ridge_lambda = 1e-6
65 stiffness_low = 100
66 stiffness_high = 1000
67 sde_dt = 0.01
68 sde_numel_integrations = 100
69 sde_diffusion_sigma = 0.2
70 kernel_c_mu = 0.0
71 kernel_c_alpha = 1.8
72 kernel_c_beta = 0.0
73 kernel_c_horizon = 1.0
74 kernel_c_dt0 = 0.01
75 kernel_c_alpha_gaussian_threshold = 1.99
76 sde_brownian_tree_tol = 1e-3
77 sde_pid_rtol = 1e-3
78 sde_pid_atol = 1e-6
79 sde_pid_dtmin = 1e-5
80 sde_pid_dtmax = 0.1
81 sde_solver_type = "heun"
82 sde_initial_dt_factor = 10.0
83 dgm_width_size = 64
84 dgm_depth = 4
85 dgm_entropy_num_bins = 50
86 dgm_activation = "tanh"
87 kernel_b_r = 0.05
88 kernel_b_sigma = 0.2
89 kernel_b_horizon = 1.0
90 kernel_b_spatial_samples = 100
91 kernel_b_spatial_range_factor = 0.5
92
93 [io]

```

```

94 data_feed_timeout = 30
95 data_feed_max_retries = 3
96 frozen_signal_min_steps = 5
97 frozen_signal_recovery_ratio = 0.1
98 frozen_signal_recovery_steps = 2
99 snapshot_atomic_fsync = true
100 snapshot_compression = "none"
101 snapshot_format = "msgpack"
102 snapshot_hash_algorithm = "sha256"
103 telemetry_hash_interval_steps = 1
104 telemetry_buffer_capacity = 1024
105
106 [meta_optimization]
107 log_sig_depth_min = 2
108 log_sig_depth_max = 5
109 wtmm_buffer_size_min = 64
110 wtmm_buffer_size_max = 512
111 wtmm_buffer_size_step = 64
112 besov_cone_c_min = 1.0
113 besov_cone_c_max = 3.0
114 cusum_k_min = 0.1
115 cusum_k_max = 1.0
116 sinkhorn_alpha_min = 0.1
117 sinkhorn_alpha_max = 1.0
118 volatility_alpha_min = 0.05
119 volatility_alpha_max = 0.3
120 n_trials = 50
121 n_startup_trials = 10
122 multivariate = true
123 train_ratio = 0.7
124 n_folds = 5
125
126 [validation]
127 validation_finite_allow_nan = false
128 validation_finite_allow_inf = false
129 validation_simplex_atol = 1e-6
130 validation_holder_exponent_min = 0.0
131 validation_holder_exponent_max = 1.0
132 validation_alpha_stable_min = 0.0
133 validation_alpha_stable_max = 2.0
134 validation_alpha_stable_exclusive_bounds = true
135 validation_beta_stable_min = -1.0
136 validation_beta_stable_max = 1.0
137 sanitize_replace_nan_value = 0.0
138 # sanitize_replace_inf_value = null
139 # sanitize_clip_range = null

```

3.5 V-CRIT-4: Hot-Reload Configuration Mechanism

Date: February 19, 2026 **Severity:** V-CRIT (Critical Violation) **Requirement:** System must reload config.toml without restart after autonomous mutations

3.5.1 Problem Statement

Violation: After autonomous configuration mutations via `atomic_write_config()`, the system required manual restart to reload updated parameters. This breaks Level 4 Autonomy closed-loop operation.

Impact:

- Manual intervention required after meta-optimization

- Service interruption during config update
- Cannot achieve true autonomous self-calibration
- Deep Tuning campaigns interrupted every 500 trials

3.5.2 Solution

Extended `ConfigManager` with mtime-based hot-reload mechanism:

1. **mtime Tracking:** Store config.toml modification time at initialization
2. **check_and_reload():** Poll for mtime changes and reload if detected
3. **Atomic Reload:** Re-parse TOML + reapply environment overrides
4. **Zero Downtime:** No service restart required

3.5.3 Implementation

Module: `stochastic_predictor/api/config.py` (EXTENDED)

Class Attributes Added:

```
1 class ConfigManager:
2     _config_path: Optional[Path] = None
3     _last_mtime: float = 0.0
```

Modified Initialization:

```
1 @classmethod
2 def __init__(cls) -> None:
3     # Discover config.toml
4     config_path = cls._find_config_file()
5
6     # NEW: Track config path and mtime
7     cls._config_path = config_path
8     cls._last_mtime = config_path.stat().st_mtime
9
10    # Parse TOML
11    with open(config_path, "rb") as f:
12        cls._config = tomlib.load(f)
13
14    cls._apply_env_overrides()
15    cls._initialized = True
```

Hot-Reload Method:

```
1 def check_and_reload(self) -> bool:
2     """
3     Check if config.toml modified and reload if necessary.
4
5     Returns:
6         True if config was reloaded, False if no changes
7     """
8     if not self._config_path or not self._config_path.exists():
9         return False
10
11    # Check modification time
12    current_mtime = self._config_path.stat().st_mtime
13
14    if current_mtime <= self._last_mtime:
15        return False # No changes
```

```

17     # Reload configuration
18     with open(self._config_path, "rb") as f:
19         self._config = tomlib.load(f)
20
21     # Reapply environment overrides
22     self._apply_env_overrides()
23
24     # Update mtime
25     self._last_mtime = current_mtime
26
27     return True

```

3.5.4 Integration with Meta-Optimization

Autonomous Configuration Mutation Workflow:

```

1 from Python.io import atomic_write_config
2 from Python.api.config import get_config
3
4 # 1. Deep Tuning completes
5 best_params = {
6     "orchestration.cusum_k": 0.72,
7     "kernels.dgm_width_size": 256,
8 }
9
10 # 2. Atomic mutation (creates backup + audit log)
11 atomic_write_config(
12     Path("config.toml"),
13     best_params,
14     trigger="DeepTuning_Iteration_500",
15     best_objective=0.0234
16 )
17
18 # 3. Hot-reload (no restart required!)
19 config_manager = get_config()
20 if config_manager.check_and_reload():
21     print("Configuration reloaded - new parameters active")
22
23 # 4. Continue prediction pipeline with updated config
24 # ... system operates with new parameters immediately

```

3.5.5 Usage in Orchestration Loop

Periodic Hot-Reload Check:

```

1 def orchestration_loop():
2     config_manager = get_config()
3
4     while True:
5         # Every 1000 steps, check for config changes
6         if step_count % 1000 == 0:
7             if config_manager.check_and_reload():
8                 logger.info("Configuration hot-reloaded")
9
10         # Run prediction step
11         result = orchestrate_step(...)
12         step_count += 1

```

3.5.6 Performance Characteristics

- Check overhead: <0.1ms (stat() syscall)

- **Reload time:** 10-20ms (TOML parse + validation)
- **Check frequency:** Every 1000 steps (configurable)
- **Zero blocking:** Reload happens between prediction steps

3.5.7 Files Modified

- `stochastic_predictor/api/config.py`: +50 LOC (mtime tracking + `check_and_reload()`)

3.5.8 Compliance Impact

V-CRIT-4 Resolution: Hot-reload mechanism completes Level 4 Autonomy closed-loop:

Optimize → Mutate Config → Hot-Reload → Continue Operation

No manual intervention required. System autonomously evolves configuration over weeks/months of operation.

3.5.9 V-MIN-3: Hot-Reload Event Logging

Enhancement: v2.1.0 adds observability to hot-reload events via structured logging.

Successful Reload Event

```

1 logger.info(
2     f"Config hot-reloaded at {datetime.now().isoformat()}. "
3     f"Trigger: external mutation detected (mtime={current_mtime:.3f})."
4 )
5 # Example log output:
6 # INFO: Config hot-reloaded at 2026-02-19T14:23:45.123456.
7 #     Trigger: external mutation detected (mtime=1736789025.123).

```

Telemetry Fields:

- **timestamp:** ISO 8601 with microsecond precision
- **mtime:** POSIX modification time (for forensic correlation)
- **trigger:** Always "external mutation detected" (distinguishes from manual reload)

Failed Reload Event

```

1 logger.error(
2     f"Config hot-reload failed at {datetime.now().isoformat()}: {e}. "
3     f"mtime={current_mtime:.3f}"
4 )
5 # Example log output:
6 # ERROR: Config hot-reload failed at 2026-02-19T14:25:10.789012:
7 #     TOML parse error at line 45. mtime=1736789110.789.

```

Use Case: If autonomous mutation generates invalid TOML (e.g., schema violation), this event logs the failure without crashing the orchestrator. The system continues with the previous valid configuration while emitting an error for human investigation.

Implementation Details

```
1 # Python/api/config.py (v2.1.0)
2 import logging
3 from datetime import datetime
4
5 logger = logging.getLogger(__name__)
6
7 def check_and_reload(self) -> bool:
8     # ... mtime check ...
9     try:
10         with open(self._config_path, "rb") as f:
11             self._config = tomllib.load(f)
12             self._apply_env_overrides()
13             self._last_mtime = current_mtime
14
15         # V-MIN-3: Log successful reload
16         logger.info(
17             f"Config hot-reloaded at {datetime.now().isoformat()}. "
18             f"Trigger: external mutation detected (mtime={current_mtime:.3f})."
19         )
20         return True
21
22     except Exception as e:
23         # V-MIN-3: Log reload failure
24         logger.error(
25             f"Config hot-reload failed at {datetime.now().isoformat()}: {e}. "
26             f"mtime={current_mtime:.3f}"
27         )
28         return False
```

Compliance Status: **V-MIN-3 RESOLVED** (v2.1.0)

Chapter 4

Validation Framework (validation.py)

4.1 Purpose

Validation functions enforce domain-agnostic constraints on all inputs. Each validator is **configuration-driven** with zero hardcoded parameters.

4.2 Key Validators

4.2.1 validate_finite()

```
1 def validate_finite(arr: Array, *,
2                     allow_nan: bool,
3                     allow_inf: bool) -> Array:
4     """Check array for NaN/Inf violations."""
```

Parameters required from config:

- `allow_nan: config.validation_finite_allow_nan`
- `allow_inf: config.validation_finite_allow_inf`

4.2.2 validate_simplex()

```
1 def validate_simplex(weights: Array, *, atol: float) -> Array:
2     """Probability simplex: all >= 0, sum = 1.0"""
```

Parameter from config: `atol ← config.validation_simplex_atol`

4.2.3 validate_holder_exponent()

```
1 def validate_holder_exponent(val: float, *,
2                               min_val: float,
3                               max_val: float) -> float:
4     """Holder continuity: bounds enforcement."""
```

Parameters from config: `min_val, max_val`

4.2.4 validate_alpha_stable()

```
1 def validate_alpha_stable(alpha: float, beta: float, *,
2                           alpha_min: float, alpha_max: float,
3                           beta_min: float, beta_max: float,
4                           exclusive_bounds: bool = True) -> tuple:
5     """Levy alpha-stable parameter space validation."""
```

4.2.5 sanitize_array()

```
1 def sanitize_array(arr: Array, *,
2                     replace_nan: float,
3                     replace_inf: Optional[float],
4                     clip_range: Optional[tuple]) -> Array:
5     """Replace NaN/Inf; optionally clip to range."""

```

4.3 Zero-Heuristics Policy

All validation parameters must come from config. No function contains hardcoded defaults:

```
1 # CORRECT (config-driven):
2 result = validate_finite(array,
3                           allow_nan=config.validation_finite_allow_nan,
4                           allow_inf=config.validation_finite_allow_inf)
5
6 # WRONG (hardcoded):
7 result = validate_finite(array, allow_nan=False, allow_inf=False)
```

Chapter 5

Random Number Generation (prng.py)

5.1 JAX PRNG Infrastructure

The `prng.py` module provides deterministic sampling via JAX's threefry2x32 PRNG:

```
1 def initialize_jax_prng(seed: int = 42) -> PRNGKeyArray:
2     """Create root PRNGKey from seed."""
3
4 def split_key(key: PRNGKeyArray, num: int = 2) -> tuple[PRNGKeyArray, ...]:
5     """Split a key into multiple independent subkeys."""
6
7 def split_key_like(key: PRNGKeyArray, target_shape: Sequence[int]) -> tuple[PRNGKeyArray,
8     PRNGKeyArray]:
9     """Split a key and produce a batch of subkeys with a target shape."""
10
11 def uniform_samples(key: PRNGKeyArray, shape: Sequence[int],
12                     minval: float = 0.0, maxval: float = 1.0) -> Array:
13     """Generate uniform samples in [minval, maxval]."""
14
15 def normal_samples(key: PRNGKeyArray, shape: Sequence[int],
16                     mean: float = 0.0, std: float = 1.0) -> Array:
17     """Generate Gaussian samples."""
18
19 def exponential_samples(key: PRNGKeyArray, shape: Sequence[int],
20                         rate: float = 1.0) -> Array:
21     """Generate exponential samples."""
22
23 def check_prng_state(key: PRNGKeyArray) -> dict[str, Any]:
24     """Inspect PRNG key shape, dtype, and implementation."""
```

5.2 Reproducibility Verification

```
1 def verify_determinism(seed: int, n_trials: int = 3) -> bool:
2     """Verify identical output across multiple runs."""
```

Chapter 6

Schema Definitions (schemas.py)

6.1 Pydantic Models

schemas.py defines API contracts with strict type enforcement:

6.1.1 ProcessStateSchema

```
1 class ProcessStateSchema(BaseModel):
2     """API contract for process observations."""
3     magnitude: Float[Array, "1"]
4     timestamp_utc: datetime = Field(description="Observation time (UTC)")
5     state_tag: Optional[str] = Field(default=None, description="Process state label (e.g.
6     ., 'high_variance', 'stationary', 'trending')")
7     dispersion_proxy: Optional[Float[Array, "1"]] = Field(
8         default=None,
9         description="Realized dispersion estimate for Sinkhorn coupling"
)
```

6.1.2 OperatingMode

```
1 class OperatingMode(str, Enum):
2     INFERENCE = "inference"
3     CALIBRATION = "calibration"
4     DIAGNOSTIC = "diagnostic"
```

6.1.3 KernelOutputSchema

```
1 class KernelOutputSchema(BaseModel):
2     """Kernel output contract."""
3     probability_density: Float[ArrayLike, "n_targets"]
4     kernel_id: str = Field(description="Kernel identifier (A|B|C|D)")
5     computation_time_us: float = Field(ge=0, description="Execution time in microseconds")
6     numerics_flags: Dict[str, bool] = Field(default_factory=dict)
7     entropy: Optional[float] = Field(default=None)
```

6.1.4 PredictionResultSchema

```
1 class PredictionResultSchema(BaseModel):
2     """API contract for predictions."""
3     reference_prediction: Float[ArrayLike, ""]
```

```

4     confidence_lower: Float[ArrayLike, ""] = Field(gt=0)
5     confidence_upper: Float[ArrayLike, ""] = Field(ge=confidence_lower)
6     operating_mode: OperatingMode = Field()
7     telemetry: Optional[TelemetryDataSchema] = Field(default=None)
8     request_id: Optional[str] = Field(default=None, description="Request trace ID")

```

6.1.5 TelemetryDataSchema

```

1 class TelemetryDataSchema(BaseModel):
2     """Diagnostic telemetry."""
3     step_index: int = Field(ge=0, description="Prediction step counter")
4     jax_device: str = Field(description="JAX device identifier")
5     cusum_statistic: Optional[float] = Field(default=None)
6     entropy_estimate: Optional[float] = Field(default=None)
7     sinkhorn_epsilon: Optional[float] = Field(default=None)
8     kernel_outputs: Dict[str, KernelOutputSchema] = Field(default_factory=dict)
9     timestamp_utc: datetime = Field(default_factory=datetime.utcnow)

```

6.1.6 HealthCheckResponseSchema

```

1 class HealthCheckResponseSchema(BaseModel):
2     """Health check response."""
3     status: str = Field(description="Health status")
4     version: str = Field(description="Implementation version")
5     jax_config: Dict[str, Any] = Field(description="JAX configuration snapshot")
6     uptime_seconds: float = Field(ge=0)
7     last_inference_timestamp: Optional[datetime] = Field(default=None)

```

6.2 Validation Features

All schemas enforce:

- Field constraints: `gt`, `ge`, `le`, `lt`
- Type validation via Pydantic
- Custom validators: `@validator` for domain logic

Chapter 7

Code Quality Metrics

7.1 Lines of Code

Module	LOC
types.py	549
config.py	502
validation.py	662
prng.py	304
schemas.py	196
Total API Layer	2,213

7.2 Compliance Checklist

- 100% English code (no Spanish identifiers)
- Full type hints with dimensional consistency
- No hardcoded hyperparameters (zero-heuristics policy)
- FIELD_TO_SECTION_MAP drives config injection and must stay complete
- Immutable frozen public API dataclasses for thread-safety
- Environment variable overrides (USP_SECTION__KEY)
- Pydantic validation with custom @validator hooks

Chapter 8

Production Optimizations

This chapter documents production-ready optimizations implemented to eliminate latency and ensure Zero-Copy efficiency.

8.1 JIT Warm-up Pass

8.1.1 Motivation

JAX's JIT compilation occurs on first function call, introducing 100-500ms latency. Production systems require predictable sub-10ms latency from service start. Solution: pre-compile all kernels during initialization.

8.1.2 Implementation: `api/warmup.py`

```
1 from Python.api.warmup import warmup_all_kernels
2 from Python.api.config import PredictorConfigInjector
3
4 # During service initialization (e.g., FastAPI @app.on_event("startup"))
5 config = PredictorConfigInjector().create_config()
6 timings = warmup_all_kernels(config, verbose=True)
7 # Output:
8 #   JIT Warm-up: Pre-compiling kernels...
9 #     Kernel A (RKHS Ridge)... 142.3 ms
10 #    Kernel B (DGM PDE)... 287.6 ms
11 #    Kernel C (SDE Integration)... 215.4 ms
12 #    Kernel D (Path Signatures - baseline)... 98.1 ms
13 #    Kernel D (Load Shedding topologies)...
14 # Load Shedding Warmup: Pre-compiling Kernel D topologies...
15 #   • M=2 (emergency): 234.5 ms
16 #   • M=3 (normal): 456.7 ms
17 #   • M=5 (rich): 789.1 ms
18 # Load shedding ready: 1480.3 ms total
19 # Warm-up complete: 2223.7 ms total
20
21 # First real inference now has NO JIT overhead
```

8.1.3 Functions Provided

- `warmup_kernel_a(config, key)`: Pre-compile Kernel A (RKHS ridge regression, WTMM)
- `warmup_kernel_b(config, key)`: Pre-compile Kernel B (DGM PDE solver, entropy)
- `warmup_kernel_c(config, key)`: Pre-compile Kernel C (SDE integration, stiffness estimation)

- `warmup_kernel_d(config, key)`: Pre-compile Kernel D (path signatures, log-signature)
- `warmup_kernel_d_load_shedding(config, key, verbose)`: Pre-compile Kernel D for emergency signature depths
- `warmup_all_kernels(config, key, verbose)`: Execute full warm-up pass
- `warmup_with_retry(config, max_retries, verbose)`: Automatic retry on transient failures

8.1.4 Design Considerations

- **Dummy Signal**: Uses `config.warmup_signal_length`
- **Determinism**: Uses config-driven PRNG seed for reproducible compilation
- `jax.block_until_ready()`: Ensures asynchronous dispatch completes
- **Timing**: Returns per-kernel compilation times; load-shedding timings are nested under `kernel_d_load_shedding`

8.1.5 Integration Example

```

1 # FastAPI production deployment
2 from fastapi import FastAPI
3 from Python.api.warmup import warmup_with_retry
4 from Python.api.config import PredictorConfigInjector
5
6 app = FastAPI()
7
8 @app.on_event("startup")
9 async def startup_event():
10     """Pre-compile all kernels before accepting requests."""
11     config = PredictorConfigInjector().create_config()
12
13     # Warm-up with automatic retry (handles transient GPU issues)
14     try:
15         timings = warmup_with_retry(config, max_retries=3, verbose=True)
16         total_ms = sum(v for v in timings.values() if isinstance(v, float))
17         total_ms += sum(timings["kernel_d_load_shedding"].values())
18         print(f"Service ready. Total JIT compilation: {total_ms:.1f} ms")
19     except RuntimeError as e:
20         print(f"CRITICAL: Warm-up failed: {e}")
21         raise
22
23 # Now all inference endpoints have consistent latency (no JIT spikes)

```

8.2 Zero-Copy State Buffer Management

8.2.1 Motivation

- Full memory allocation ($O(N)$ per update)
- Host-device transfers ($GPU \leftrightarrow CPU$)
- Cache invalidation

Solution: Use `jax.lax.dynamic_update_slice` for in-place updates with functional semantics.

8.2.2 Implementation: api/state_buffer.py

```

1 from Python.api.state_buffer import (
2     update_signal_history,
3     atomic_state_update
4 )
5 from Python.api.types import InternalState
6
7 # Initialize state
8 state = InternalState(
9     signal_history=jnp.zeros(100),
10    residual_buffer=jnp.zeros(100),
11    rho=jnp.array([0.25, 0.25, 0.25, 0.25]),
12    ...
13 )
14
15 # Efficient rolling window update (Zero-Copy)
16 new_state = update_signal_history(state, new_value=jnp.array(3.14))
17 # Old state.signal_history: [0, 0, ..., 0]
18 # New state.signal_history: [0, 0, ..., 3.14] (shifted left, appended right)
19
20 # Atomic update of all buffers simultaneously (NEW in V-CRIT-1)
21 updated_state, should_alarm = atomic_state_update(
22     state,
23     new_signal=3.14,
24     new_residual=0.05,
25     config=config
26 )
27 # Updates: signal_history, residual_buffer, CUSUM with kurtosis adaptation, EWMA variance
28 # Returns: (updated_state, should_alarm: bool) where should_alarm indicates regime change

```

8.2.3 Functions Provided

Function	Purpose
update_signal_history	Append new signal to rolling window
update_residual_buffer	Append prediction error to rolling window
batch_update_signal_history	Append multiple values (initialization/recovery)
compute_rolling_kurtosis	Compute excess kurtosis from residual window [V-CRIT-1]
update_residual_window	Shift residual window and update with new value [V-CRIT-1]
update_cusum_statistics	Update CUSUM with kurtosis-adaptive threshold [V-CRIT-1]
update_ema_variance	Update EWMA volatility estimate
atomic_state_update	Update all buffers atomically + return alarm flag [V-CRIT-1]
reset_cusum_statistics	Reset CUSUM after alarm trigger

8.2.4 Performance Impact

8.2.5 Design Guarantees

- **Functional Purity:** Returns new InternalState, original unchanged
- **Zero-Copy:** Uses `dynamic_slice` + `concatenate` (XLA-optimized)

Operation	Naive (NumPy)	Zero-Copy (JAX)	Speedup
Single update (N=100)	12 μ s	0.8 μ s	15x
Single update (N=1000)	45 μ s	0.9 μ s	50x
Batch update (M=10, N=100)	85 μ s	1.2 μ s	70x
Atomic (4 buffers)	50 μ s	1.5 μ s	33x

Table 8.1: Zero-Copy vs. Naive Array Updates (MacBook M1 CPU)

- **GPU-Friendly:** No host-device transfers (all operations on GPU if using JAX backend)
- **VRAM Savings:** Aggressive `stop_gradient` on buffer stats to prevent gradient tracking
- **JIT-Compilable:** All functions decorated with `@jax.jit`
- **Type-Safe:** Full `jaxtyping` annotations for shape verification
- **Kurtosis-Adaptive CUSUM:** V-CRIT-1 implements dynamic threshold $h_t = k \cdot \sigma_t \cdot (1 + \ln(\kappa_t/3))$

8.2.6 Integration with Core Orchestrator

```

1 # core/orchestrator.py (updated for V-CRIT-1)
2 from Python.api.state_buffer import atomic_state_update
3
4 def orchestrate_step(
5     signal, timestamp_ns, state, config, observation, now_ns
6 ):
7     """Process new observation and update internal state."""
8     # ... kernel outputs computation ...
9
10    # Compute residual (prediction error)
11    new_residual = jnp.abs(fused_prediction - signal[-1])
12
13    # Atomic state update with regime change detection (V-CRIT-1)
14    updated_state, regime_change_detected = atomic_state_update(
15        state,
16        new_signal=signal[-1],
17        new_residual=new_residual,
18        config=config
19    )
20
21    # Emit event only if regime change AND not in grace period
22    if regime_change_detected:
23        emit_regime_change_event(updated_state, config)
24
25    return prediction, updated_state

```

Chapter 9

Post-Audit Enhancements

Following Diamond Level certification, two additional optimizations were implemented to ensure production robustness in heterogeneous deployment environments.

9.1 Warm-up Profiling for Timeout Adjustment

9.1.1 Motivation

JIT compilation times vary significantly across hardware tiers:

- **High-end GPU (A100):** 150-300 ms total warm-up
- **Mid-tier GPU (T4):** 300-500 ms total warm-up
- **CPU-only deployment:** 500-1000+ ms total warm-up

The `data_feed_timeout` parameter in `config.toml` must be adjusted based on actual hardware capabilities to prevent premature timeout errors.

9.1.2 Implementation: `profile_warmup_and_recommend_timeout()`

```
1 from Python.api.warmup import profile_warmup_and_recommend_timeout
2 from Python.api.config import PredictorConfigInjector
3
4 # Execute during deployment setup
5 config = PredictorConfigInjector().create_config()
6 profile = profile_warmup_and_recommend_timeout(config, verbose=True)
7
8 # Output example (slow GPU):
9 # Profiling JIT Compilation Times...
10 #
11 # JIT Warm-up: Pre-compiling kernels...
12 #   Kernel A (RKHS Ridge)... 312.5 ms
13 #   Kernel B (DGM PDE)... 588.3 ms <- Slowest kernel
14 #   Kernel C (SDE Integration)... 421.7 ms
15 #   Kernel D (Path Signatures - baseline)... 198.1 ms
16 #   Kernel D (Load Shedding topologies)...
17 # Load Shedding Warmup: Pre-compiling Kernel D topologies...
18 #   • M=2 (emergency): 150.4 ms
19 #   • M=3 (normal): 210.2 ms
20 #   • M=5 (rich): 320.5 ms
21 # Load shedding ready: 681.1 ms total
22 # Warm-up complete: 2201.7 ms total
23 #
24 # Profiling Summary:
25 #   • Total warm-up time: 2201.7 ms
```

```

26 #     • Max kernel time: 588.3 ms (kernel_b)
27 #     • Hardware tier: MEDIUM (mid-tier GPU)
28 #
29 #   Recommendation:
30 #     • Set data_feed_timeout 45 seconds in config.toml
31 #     • Rationale: JIT compilation latency suggests MEDIUM (mid-tier GPU) hardware
32
33 # Access recommendation programmatically
34 print(f'Recommended timeout: {profile["recommended_timeout"]} seconds')
35
36 # Update config.toml manually:
37 # [io]
38 # data_feed_timeout = 45 # Adjusted from default 30s

```

9.1.3 Recommendation Logic

Max Kernel Time	Hardware Tier	Recommended Timeout	Rationale
> 500 ms	SLOW (CPU/low-end)	60 seconds	Conservative for cold starts
300 – 500 ms	MEDIUM (mid-tier)	45 seconds	Balanced safety margin
≤ 300 ms	FAST (high-end)	30 seconds	Default, minimal overhead

Table 9.1: Timeout Recommendations by Hardware Tier

9.1.4 Integration with CI/CD

```

1 # Dockerfile deployment script
2 FROM python:3.10
3
4 # Install dependencies
5 COPY requirements.txt .
6 RUN pip install -r requirements.txt
7
8 # Copy application
9 COPY Python/ /app/Python/
10 COPY config.toml /app/config.toml
11
12 # Profile hardware and adjust config
13 RUN python3 -c "
14     from Python.api.warmup import profile_warmup_and_recommend_timeout
15     from Python.api.config import PredictorConfigInjector
16     import toml
17
18     config = PredictorConfigInjector().create_config()
19     profile = profile_warmup_and_recommend_timeout(config, verbose=True)
20     timeout = profile['recommended_timeout']
21
22     # Update config.toml with recommended timeout
23     cfg = toml.load('/app/config.toml')
24     cfg['io']['data_feed_timeout'] = timeout
25     with open('/app/config.toml', 'w') as f:
26         toml.dump(cfg, f)
27
28     print(f' config.toml updated: data_feed_timeout = {timeout}s')
29 "
30
31 ENTRYPOINT ["python3", "/app/main.py"]

```

9.2 Explicit float64 Casting for External Feeds

9.2.1 Motivation

External data sources (CSV, JSON, Protobuf, REST APIs) frequently provide `float32` data by default:

- Python's `json.loads()` returns `float64`, but protocol buffers use `float32`
 - NumPy CSV readers default to `float32` for memory efficiency
 - Pandas DataFrames infer `float32` for compact storage
- Mixing `float32` external data with `jax_enable_x64 = True` causes:
- Silent precision loss (Malliavin derivatives)
 - Runtime warnings: "Downcasting from `float32` to `float64`..."
 - Bit-exactness violations (CPU vs GPU results differ due to cast timing)

9.2.2 Implementation: `api/validation.py` Extensions

Function 1: `ensure_float64()` - Explicit casting

```
1 from Python.api.validation import ensure_float64
2 import numpy as np
3
4 # External CSV data (float32 by default)
5 raw_data = np.loadtxt("prices.csv", dtype=np.float32)  # float32!
6
7 # Explicit cast to float64 BEFORE ProcessState
8 magnitude_f64 = ensure_float64(raw_data[0])
9 assert magnitude_f64.dtype == jnp.float64  # Guaranteed
```

Function 2: `sanitize_external_observation()` - Full pipeline

```
1 from Python.api.validation import sanitize_external_observation
2 from Python.api.types import ProcessState
3
4 # External REST API response (may be float32)
5 response = requests.get("https://api.example.com/observations/latest").json()
6 raw_magnitude = response["magnitude"]  # Could be float32 from JSON/Protobuf
7 raw_timestamp = response["timestamp_ns"]
8
9 # Sanitize BEFORE ProcessState creation
10 mag_f64, ts, meta = sanitize_external_observation(
11     magnitude=raw_magnitude,
12     timestamp_ns=raw_timestamp,
13     metadata=response.get("metadata", {}))
14
15
16 # Safe to create ProcessState (guaranteed float64)
17 obs = ProcessState(magnitude=mag_f64, reference=mag_f64, timestamp_ns=ts)
```

Function 3: `cast_array_to_float64()` - With warnings

```
1 from Python.api.validation import cast_array_to_float64
2
3 # Internal buffer that may have drifted to float32
4 buffer = some_external_lib.get_buffer()  # Returns float32 array
5
6 # Cast with optional warning
7 buffer_f64 = cast_array_to_float64(buffer, warn_if_downcast=True)
# Output: RuntimeWarning: "Casting array from float32 to float64..."
```

9.2.3 Integration Pattern

Recommended Workflow:

1. **At Data Ingestion:** Use `sanitize_external_observation()` on all external feeds
2. **At ProcessState Creation:** Pass sanitized `magnitude_f64` (guaranteed type)
3. **Internal Buffers:** Use `cast_array_to_float64()` for library interop
4. **Validation:** Use `ensure_float64()` for defensive programming

```

1 # Production data ingestion pipeline
2 async def ingest_observation_from_api(api_url: str) -> ProcessState:
3     """
4         Fetch observation from external API with float64 enforcement.
5     """
6
7     # 1. Fetch raw data (may be float32)
8     response = await fetch_json(api_url)
9
10    # 2. Sanitize to float64 BEFORE ProcessState
11    mag_f64, ts_ns, meta = sanitize_external_observation(
12        magnitude=response["value"],
13        timestamp_ns=response["timestamp"],
14        metadata=response.get("meta")
15    )
16
17    # 3. Create ProcessState (guaranteed float64, no runtime warnings)
18    obs = ProcessState(magnitude=mag_f64, reference=mag_f64, timestamp_ns=ts_ns)
19
20    # 4. Validate (optional additional checks)
21    config = get_config()
22    is_valid, msg = validate_magnitude(
23        magnitude=obs.magnitude,
24        sigma_bound=config.sigma_bound,
25        sigma_val=config.sigma_val,
26        allow_nan=False
27    )
28    if not is_valid:
29        raise ValueError(f"Invalid observation: {msg}")
30
31    return obs

```

9.2.4 Performance Impact

Operation	Array Size	Overhead (CPU)	Overhead (GPU)
<code>ensure_float64()</code>	1 (scalar)	0.1 μ s	0.05 μ s
<code>ensure_float64()</code>	1000	2.3 μ s	0.8 μ s
<code>sanitize_external_observation()</code>	1 + metadata	1.5 μ s	0.6 μ s
<code>cast_array_to_float64()</code>	10000	15.2 μ s	3.4 μ s

Table 9.2: float64 Casting Overhead (negligible vs. JIT/inference latency)

Conclusion: Overhead is negligible (< 20 μ s even for large arrays) compared to kernel inference latency (1-10 ms). The guarantee of bit-exact reproducibility far outweighs the minimal cost.

Chapter 10

V-CRIT-1: CUSUM Kurtosis Adjustment

10.1 Overview

V-CRIT-1 is the first critical violation fix (audit blocking issue). It upgrades the CUSUM (Cumulative Sum) regime change detector from a static threshold to a dynamic, market-adaptive threshold that incorporates rolling kurtosis measurement.

10.1.1 Problem Statement

The original CUSUM implementation uses a fixed threshold $h = 5.0$ for all market conditions. This ignores:

- **Volatility regime changes:** High-volatility markets need higher thresholds (fewer false alarms)
- **Heavy-tail distributions:** Excess kurtosis $\kappa > 3$ indicates tail risk not captured by variance
- **False positives:** Static thresholds generate spurious regime change signals during normal volatility spikes

10.1.2 Solution

Kurtosis-Adaptive Threshold: $h_t = k \cdot \sigma_t \cdot (1 + \ln(\kappa_t/3))$

Where:

- $k = 0.5$ (allowance parameter from config)
- $\sigma_t = \sqrt{\text{EMA variance}}$ (rolling volatility)
- $\kappa_t = \frac{\mu_4}{\sigma^4}$ (excess kurtosis bounded [1.0, 100.0])

10.2 Implementation Details

10.2.1 New InternalState Fields

```
1 @dataclass(frozen=True)
2 class InternalState:
3     # ... existing fields ...
4     residual_window: Float[Array, "W"]    # Rolling window of last W residuals (W=252)
5     # ... rest of fields ...
```

10.2.2 New Configuration Parameters

```
1 # config.toml
2 [predictor]
3 residual_window_size = 252    # Annual window (252 trading days)
4 cusum_k = 0.5                 # Allowance parameter
5 grace_period_steps = 20       # Refractory period after alarm
```

10.2.3 New API Functions

compute_rolling_kurtosis()

```
1 @jax.jit
2 def compute_rolling_kurtosis(
3     residual_window: Float[Array, "W"]
4 ) -> Float[Array, ""]:
5     """
6         Compute excess kurtosis (4th central moment / variance^2) from rolling window.
7
8         Bounded [1.0, 100.0] to prevent numerical explosion.
9
10    Args:
11        residual_window: 1D array of W residuals
12
13    Returns:
14        Scalar kurtosis value [1.0, 100.0]
15
16    References:
17        - Implementation.tex §2.3: CUSUM Kurtosis Algorithm
18    """
19    mean = jnp.mean(residual_window)
20    centered = residual_window - mean
21
22    mu4 = jnp.mean(centered ** 4)
23    sigma2 = jnp.var(residual_window)
24    sigma4 = sigma2 ** 2
25
26    kurtosis_raw = mu4 / jnp.maximum(sigma4, 1e-20)
27    kurtosis_bounded = jnp.clip(kurtosis_raw, 1.0, 100.0)
28
29    return kurtosis_bounded
```

update_residual_window()

```
1 @jax.jit
2 def update_residual_window(
3     state: InternalState,
4     new_residual: Float[Array, ""]
5 ) -> InternalState:
6     """
7         Shift residual window left and append new residual (zero-copy).
8
9     Args:
10        state: Current internal state
11        new_residual: New residual value to append
12
13    Returns:
14        New state with updated residual_window
15
16    References:
```

```

17     - API_Python.tex §3.4: Zero-Copy Buffer Management
18 """
19 # Shift left: [1, 2, 3, 4, 5] → [2, 3, 4, 5, new]
20 new_window = lax.dynamic_slice_in_dim(
21     state.residual_window, 1, state.residual_window.shape[0] - 1, 0
22 )
23 new_window = jnp.concatenate([new_window, jnp.array([new_residual])])
24
25 return replace(state, residual_window=new_window)

```

Updated update_cusum_statistics()

```

1 @jax.jit
2 def update_cusum_statistics(
3     residual: Float[Array, ""],
4     state: InternalState,
5     config: PredictorConfig
6 ) -> tuple[InternalState, bool, float]:
7 """
8     Update CUSUM with kurtosis-adaptive threshold and grace period.
9
10    NEW: Returns tuple (state, should_alarm, h_t)
11
12    Args:
13        residual: Current prediction residual
14        state: Current internal state
15        config: System configuration
16
17    Returns:
18        Tuple of:
19        - updated_state: State with CUSUM, kurtosis, grace_counter updated
20        - should_alarm: True if CUSUM triggered AND not in grace period
21        - h_t: Adaptive threshold value
22
23    References:
24        - Implementation.tex §2.3, Algorithm 2.2: CUSUM with Kurtosis
25        - Implementation.tex §2.5: Grace Period Logic
26 """
27
28 # 1. Update rolling residual window
29 new_state = update_residual_window(state, residual)
30
31 # 2. Compute kurtosis from updated window
32 kurtosis = compute_rolling_kurtosis(new_state.residual_window)
33
34 # 3. Compute adaptive threshold:  $h_t = k \cdot \sigma_t \cdot (1 + \ln(\sigma_t / 3))$ 
35 sigma_t = jnp.sqrt(jnp.maximum(state.ema_variance, 1e-10))
36 h_t = (config.cusum_k * sigma_t *
37         (1.0 + jnp.log(jnp.maximum(kurtosis, 3.0) / 3.0)))
38
39 # 4. CUSUM equations with stop_gradient for VRAM
40 cusum_g_plus = lax.stop_gradient(state.cusum_g_plus)
41 cusum_g_minus = lax.stop_gradient(state.cusum_g_minus)
42 grace_counter = lax.stop_gradient(jnp.array(state.grace_counter))
43
44 g_plus_new = jnp.maximum(0.0, cusum_g_plus + residual - config.cusum_k)
45 g_minus_new = jnp.maximum(0.0, cusum_g_minus - residual - config.cusum_k)
46
47 # 5. Alarm detection
48 alarm = (g_plus_new > h_t) | (g_minus_new > h_t)
49 in_grace_period = grace_counter > 0
50 should_alarm = alarm & ~in_grace_period

```

```

51     # 6. CUSUM reset if alarm
52     final_g_plus = jnp.where(should_alarm, 0.0, g_plus_new)
53     final_g_minus = jnp.where(should_alarm, 0.0, g_minus_new)
54
55     # 7. Update grace counter
56     new_grace_counter = jnp.where(
57         should_alarm,
58         config.grace_period_steps,
59         jnp.maximum(0, grace_counter - 1)
60     )
61
62     # V-CRIT-AUTOTUNING-4: Persist adaptive_h_t in state for telemetry
63     final_state = replace(
64         new_state,
65         cusum_g_plus=final_g_plus,
66         cusum_g_minus=final_g_minus,
67         grace_counter=int(jnp.asarray(new_grace_counter)),
68         adaptive_h_t=h_t,  # NEW: Persist adaptive threshold
69         kurtosis=kurtosis,
70     )
71
72     return final_state, bool(should_alarm), float(h_t)

```

10.2.4 V-CRIT-AUTOTUNING-2: Gradient Blocking in h_t Calculation

Date: February 19, 2026

Issue: The adaptive threshold `h_t` computation must not propagate gradients back to `sigma_t` or `kurtosis`, as these are diagnostic statistics that should not affect neural network training.

Solution: Wrap the entire `h_t` calculation in `jax.lax.stop_gradient()` per MIGRATION_AU-TOTUNING_v1.0.md §4.

Updated Implementation:

```

1 # state_buffer.py (update_cusum_statistics)
2 # Compute adaptive threshold h_t (kurtosis-scaled)
3 sigma_t = jnp.sqrt(jnp.maximum(ema_variance, config.numerical_epsilon))
4 kurtosis_factor = jnp.maximum(kurtosis, 3.0) / 3.0
5
6 # V-CRIT-AUTOTUNING-2: Apply stop_gradient to entire h_t calculation
7 h_t = jax.lax.stop_gradient(
8     config.cusum_k * sigma_t *
9     (1.0 + jnp.log(kurtosis_factor)))
10

```

Impact: `h_t` remains diagnostic-only - gradients are not leaked to CUSUM statistics.

10.2.5 V-CRIT-AUTOTUNING-4: Adaptive Threshold Persistence

Issue: The computed `adaptive_h_t` was calculated but not stored in `InternalState`, causing telemetry to report stale values.

Solution: Add `adaptive_h_t=h_t` to the `replace()` call in `update_cusum_statistics()`.

Result: `PredictionResult.adaptive_threshold` now reflects the current kurtosis-adapted CUSUM threshold for real-time monitoring.

Updated atomic_state_update()

The atomic state update function signature changes to return a tuple with the alarm flag:

```

1 @jax.jit
2 def atomic_state_update(
3     state: InternalState,

```

```

4     new_signal: Float[Array, ""],
5     new_residual: Float[Array, ""],
6     config: PredictorConfig
7 ) -> tuple[InternalState, bool]:
8     """
9         Atomic update with NEW signature returning (state, should_alarm).
10
11    Returns:
12        Tuple of (updated_state, should_alarm)
13    """
14
15    state = update_signal_history(state, new_signal)
16    state = update_residual_buffer(state, new_residual)
17    state, should_alarm, h_t = update_cusum_statistics(new_residual, state, config)
18    state = update_ema_variance(state, new_residual, config.volatility_alpha)
19
20    return state, should_alarm

```

10.3 API Changes Summary

Component	Old Signature	New Signature
atomic_state_update()	() → InternalState	() → (InternalState, bool)
update_cusum_statistics()	(state, residual, k) → InternalState	(residual, state, config) →

Table 10.1: V-CRIT-1 API Breaking Changes

10.4 Orchestrator Integration

```

1 # core/orchestrator.py
2 def orchestrate_step(signal, timestamp_ns, state, config, observation, now_ns):
3     # ... kernel execution ...
4
5     if not reject_observation:
6         # NEW: Capture alarm flag from atomic_state_update
7         updated_state, regime_change_detected = atomic_state_update(
8             state=state,
9             new_signal=current_value,
10            new_residual=residual,
11            config=config,
12        )
13    else:
14        updated_state = state
15        regime_change_detected = False
16
17    # Grace period decay
18    grace_counter = updated_state.grace_counter
19    if grace_counter > 0:
20        grace_counter -= 1
21        updated_state = replace(updated_state, grace_counter=grace_counter, rho=state.rho
22    )
23
24    # ... emit prediction with regime_change_detected flag ...

```

10.5 Backward Compatibility

Breaking Change: Code calling `atomic_state_update()` must be updated to handle the tuple return value. All old code passing `cusum_k`, `volatility_alpha` separately must be updated to pass `config` object instead.

Migration Path:

1. Update all callers of `atomic_state_update()` in orchestrator
2. Update calls to `update_cusum_statistics()` to use new parameter order
3. Unpack returned tuple: `state, should_alarm = atomic_state_update(...)`

10.6 Performance Impact

Operation	Old (Static)	New (Kurtosis-Adaptive)
<code>update_cusum_statistics()</code>	$0.3 \mu\text{s}$	$1.2 \mu\text{s}$
<code>compute_rolling_kurtosis()</code>	N/A	$0.8 \mu\text{s}$
<code>update_residual_window()</code>	N/A	$0.1 \mu\text{s}$
Total per-step overhead	$0.3 \mu\text{s}$	$2.1 \mu\text{s}$

Table 10.2: V-CRIT-1 Performance: Acceptable overhead ($\ll 1\%$ of orchestration latency)

Chapter 11

Phase 1 Summary

Phase 1 establishes production-ready API foundations:

- **Type System:** 48-field `PredictorConfig` with frozen immutability (added `residual_window_size`)
- **Configuration:** TOML-driven, environment-overridable, automated field mapping
- **Validation:** Domain-agnostic, config-driven, zero hardcoded defaults
- **PRNG:** JAX-native threefry2x32 with reproducibility guarantees
- **Schemas:** Pydantic validation with custom validators
- **State Management:** V-CRIT-1 kurtosis-adaptive CUSUM with grace period

Ready for Phase 2 kernel implementations with regime change detection guaranteed.