EECS 3215
Embedded Systems
Lab 8 - Timers
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Problem Statement

The problem statement of this lab is to simulate the seatbelt warning systems of a vehicle. The goal is to create inputs which simulate monitors of the state of the vehicle, with inputs simulating the engine state, whether the seat is occupied, and whether the belt is buckled. The system should respond to these inputs by responding with outputs simulating a buzzer and a warning light. The solution should utilize the systick timer to limit the time in which an output buzzer is active.

Top-Level Design

Our design is straightforward, we initialize the inputs and outputs in the same way we have in previous labs. What is different is the need to initialize the systick timer. We initialize the systick timer using the control register, and we set the reload time for 5 seconds using the reload register. The system moves between states depending on the input values. The state of interest is the one utilizing the systick timer. The system waits for the systick timer to equal zero before resetting the timer by writing to the 16th bit of control register. Inside this area, a flag is set to turn the green LED off while keeping the red LED on. The other states reset this flag so that the green LED will remain on for five seconds when the system returns to the unbuckled state.

Code

```
#include <stdio.h>
#include "board.h"
#include "peripherals.h"
#include "pin mux.h"
#include "clock config.h"
#include "MKL43Z4.h"
#include "fsl debug console.h"
#include <stdlib.h>
int main(void) {
  BOARD InitBootPins();
  BOARD InitBootClocks();
  BOARD InitBootPeripherals();
  BOARD InitDebugConsole();
  SysTick->LOAD |= 0xFF;
  SysTick->CTRL |= 0x05;
  SIM->SCGC5 |= SIM SCGC5 PORTE MASK; // enable clock to port E
  SIM->SCGC5 |= SIM SCGC5 PORTD MASK; // enable clock to port D
  SIM->SCGC5 |= SIM_SCGC5_PORTC_MASK; // enable clock to port C
```

```
SIM->SCGC5 |= SIM_SCGC5_PORTA_MASK; // enable clock to port A
PORTD->PCR[5] |= 0x100; // enable green led
PTD->PDDR |= 1<<5u; // set green led to output
PTD->PSOR |= 1<<5u; // off by default
PORTE->PCR[31] |= 0x100; // enable red led
PTE->PDDR |= 1<<31u; // set green led to output
PTE->PSOR |= 1<<31u; // off by default
PORTC->PCR[3] |= 0x103; // enable pushbutton 1 (belt buckled) left side
PTC->PDDR &= 0<<3u; // set to input
PORTA->PCR[4] |= 0x103; // enable pushbutton 2 (seat occupied)
PTA->PDDR &= 0<<4u; // set to input
PORTA->PCR[1] |= 0x103; // enable pin for third input signal (engine on)
PTA->PDDR &= 0<<1u; // set to input
PORTA->PCR[2] |= 0x103; // enable the second wire
PTA->PDDR &= 0<<2u;
int on = 0:
  while(1) {
    if (PTA->PDIR & 0b10){
       //if engine is off, both LEDs should be off
       printf("engine off\n");
       PTE->PSOR |= 1<<31u;
       PTD->PSOR |= 1<<5u;
       on = 0;
    }
    else if(!(PTA->PDIR & 0b10) && PTA->PDIR & 0b100 && !(PTC->PDIR & 0b1000)){
       // if seat is occupied, and belt is not buckled,
       // turn on warning light and set buzzer for 5 seconds
       printf("unbuckled\n");
       if(on == 0){
         PTE->PCOR |= 1<<31u;
         PTD->PCOR |= 1<<5u;
         while(!(SysTick->VAL == 0)){
         SysTick->CTRL |= 0x10005;
         PTD->PSOR |= 1<<5u;
         on = 1:
         }
```

```
}
       else{
            PTE->PCOR |= 1<<31u;
            PTD->PSOR |= 1<<5u;
         }
       }
       else if (!(PTA->PDIR & 0b10) && !(PTA->PDIR & 0b100) &&
!(PTC->PDIR & 0b1000)){
         // if the seat is occupied and the belt is buckled
         // the warning light and buzzer should be off
         printf("proper\n");
         PTE->PSOR |= 1<<31u;
         PTD->PSOR |= 1<<5u;
         on = 0;
       }
       else {
         // the system is in an illegal state
         // the alarms should be set
         printf("Illegal\n");
         PTE->PCOR |= 1<<31u;
         PTD->PCOR |= 1<<5u;
         on = 0;
       }
    }
}
```