# Design of Digital Systems Laboratory Exercise 4 Vending Machine

Océane Boulais Performed: 10/9/2017 Submitted: 10/11/2017

Lab Section: 2

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By submitting this report, you attest that you neither have given nor have received any assistance (including writing, collecting data, plotting figures, tables or graphs, or using previous student reports as a reference), and you further acknowledge that giving or receiving such assistance will result in a failing grade for this course.

Your Signature:		
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#### I. Abstract

Although a vending machine is a very complex piece of machinery, the electronic controls are rather simple. FSM control of the vending machine is possible because the physical actions of the machine can be broken down to a small number of distinct states. These states are enumerated within the FSM and control is achieved by encoding the appropriate state transition Table 1 provided in the lab manual.

For this assignment, the model of the vending machine can be broken down into four modes: program (establish states), display (seven segment display), vend, and test (behavorial/post-route simulations and hardware).

The action the vending machine will take in each mode is determined by a sequence of steps, each represented by a state that follows the logic provided in figure 1. There are a few other states which govern the flow of the table as well as some initial start-up states. It is a conglomeration of all these states that the FSM is built.

Code	Price		
0000	\$0.55		
0001	\$0.85		
0010	\$0.95		
0011	\$1.25		
0100	\$1.35		
0101	\$1.50		
0110	\$2.25		
0111	\$2.50		
1000	\$3.00		
1001-1111	Reserved		

**Table 1**: Control codes that correlate to soda prices

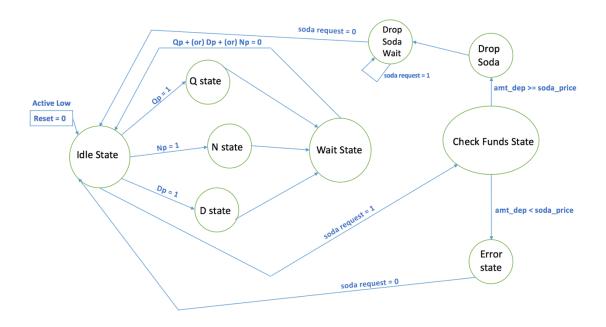


Figure 1: FSM state logic (Prelab work)

#### II. Design Methodology

For this assignment, the challenge was to build a coin controller that would handle the finite state machine and the incoming coins. Provided with the lab manual were the following VHDL modules: Usr interaction.vhd, bin bcd.vhd, coin rx.vhd, seven seg disp.vhd.

I was tasked with designing and implementing the coin controller, which would be the driver for state changes, the seven segment decoder to properly display amount deposited to the seven segment display. We shall now discuss these components and their design/implementation.

#### Vending machine controller

The vending machine controller encompasses the coin controller and seven segment decoder components. The vending machine is rising clock edge triggered and the reset is synchronous/active low.

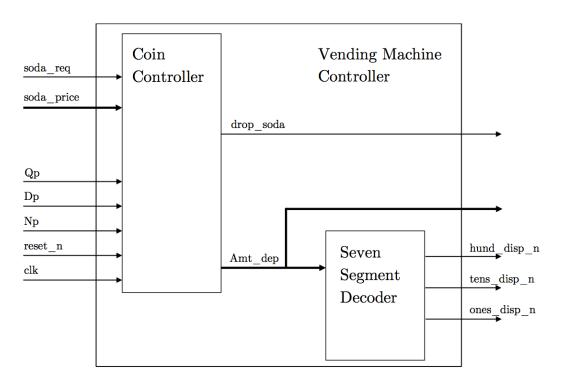


Figure 2: Vending Machine High Level Block Diagram

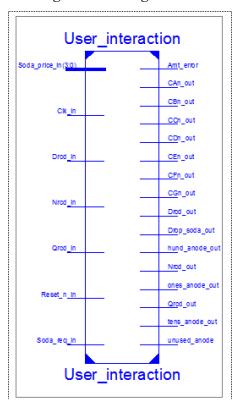


Figure 3: Vending machine RTL Schematic

#### Coin Controller

The coin controller is where the finite state machine lives. By following Figure 1, one can see the abstract concept of changing and holding states. The system's state change is driven by a rising clock edge and active low reset. The user's input drives the internal state changes by the amount of coins put into the machine. The inputs were clock (rising edge sensitive), reset (synchronous, active low), Quarter, Nickel and Dime inputs, a soda request and a four-bit soda price (refer to Table 1).

The amount deposited does not clear any extra change after vending, instead, the change is kept and added to future purchases.

#### Seven Segment Decoder

The seven segment decoder was responsible for producing pulses that displayed the amount deposited on the seven segment display. The inputs are a 12-bit binary converted decimal, making a three-digit number capable of dynamic display on the seven segment display. The outputs of the decoder were the ones, tens and hundreds place digit.

#### User Interaction

The user interaction is the top-level of the vending machine. All created and given components are mapped and ported here. The following results shall clearly explain the current behavior of the user interaction.

#### III. Results

#### Vending Machine Controller

The first two sodas are requested here by their price code (0000) for simple demonstration of functionality. An amount error is triggered by a request for a soda with too little funds, and then the soda is vended once the funds have accumulated as show below in Figure 4. The amount deposit is given in binary representation for the segment display. At 235 ns, there is a \$0.55 soda dropped. Binary to decimal conversions are provided for ease of analysis.

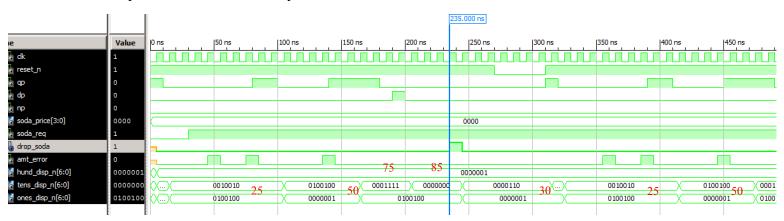


Figure 4a: Vending machine behavioral simulation at drop soda

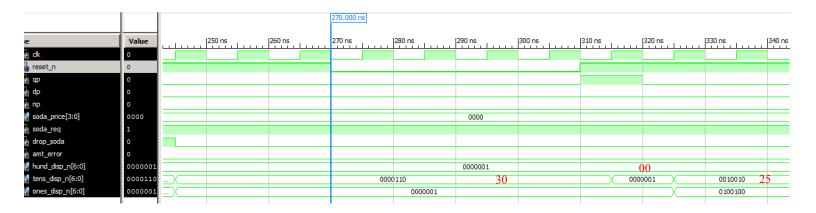


Figure 4b: Vending machine behavioral simulation at reset

#### Coin Controller

The heart of the vending machine controller, the coin controller shows the correlated amount deposited in decimal for easier viewing. One can also observe the "change" that is rolled over once a purchase is made. At 1.17 us, the \$0.55 soda is dropped and the remaining change (\$0.30) rolls over to next purchase. At approximately 1.35 us, reset is set to zero, therefore clearing whatever values were previously held in the amount deposited.

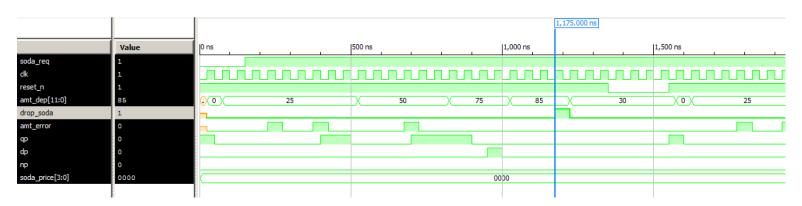


Figure 5: Coin controller behavioral simulation

#### User Interaction

User interaction is provided as a top level of the vending machine. It connects the various components described above vis signal wires that later allow for behavioral simulation and post-route implementation. Table 2 gives an overview summary of the characteristics in the FSM.

```
States
                    | 7
| Transitions
                    | 16
                    | 4
Inputs
| Outputs
                    | 6
| Clock
                    | Clk (rising edge)
                    | Reset n INV 36 o (positive)
Reset
                    synchronous
| Reset type
                    | idle
| Reset State
| Power Up State
                    | idle
| Encoding
                    | auto
| Implementation
                    | LUT
```

Table 2: Summary of FSM qualities

The user interaction was comprised of several components that were not built by the student. Although the user interaction should theoretically only be a giant port map, the components that were built and tested against respective test benches for this lab were unable to replicate the results from the vending machine and coin controller. Instead, the behavioral and post-route simulations match, and I implemented a successful run of the vending machine on the Artix 7. Potential solutions to continue debugging the error in the user interaction simulations include extensively following signal wire traces, re-wiring the input/outputs of the user interaction or simply build a new one from scratch.



Figure 6: User interaction behavioral simulation



Figure 7: User interaction post-route simulation

Constraint	 	Check	I		Best Case   Achievable		Timing Score
Autotimespec constraint for clock net Cl _in_BUFGP		SETUP HOLD	I	N/A  0.030ns	6.105ns  	N/A  0	0

**Table 3:** Best case achievable

### Area Used

## Device Utilization Summary: Slice Logic Utilization:

Tice Logic Othization.			
Number of Slice Registers:	102 out of	126,800	1%
Number used as Flip Flops:	93		
Number used as Latches:	9		
Number used as Latch-thrus:	0		
Number used as AND/OR logics:	0		
Number of Slice LUTs:	246 out of	63,400	1%
Number used as logic:	245 out of	63,400	1%
Number using O6 output only:	193		
Number using O5 output only:	17		
Number using 05 and 06:	35		
Number used as ROM:	0		
Number used as Memory:	0 out of	19,000	0%
Number used exclusively as route-thrus:	1		
Number with same-slice register load:	0		
Number with same-slice carry load:	1		
Number with other load:	0		

#### Slice Logic Distribution: 92 out of 15,850 1% Number of occupied Slices: Number of LUT Flip Flop pairs used: 262 164 out of 262 16 out of 262 Number with an unused Flip Flop: **62**% Number with an unused LUT: 6ક 82 out of 262 Number of fully used LUT-FF pairs: 31% Number of slice register sites lost to control set restrictions: 0 out of 126,800 0%

#### IV. Appendix Page

#### Source Code Description

```
______
-- File: usr interaction.vhd
-- Entity: User_interaction
-- Architecture: Behavioral
-- Author: Océane Boulais
-- Create Date: 11/10/2017
-- Modified Date: 11/20/2017
-- Description: Top level wrapper of vending machine that provides port
mapping. Contains all following components.
-- File: vending machine controller.vhd
-- Entity: vending machine controller
-- Architecture: Structural
-- Author: Océane Boulais
-- Create Date: 11/10/2017
-- Modified Date: 11/20/2017
-- Description: Contains coin controller and seven segment decoder.
Accepts quarters, nickels, dimes, soda requests and soda prices.
Outputs the seven segment display nodes that display amount deposit.
-- File: coin controller.vhd
-- Entity: coin controller
-- Architecture: Structural
-- Author: Océane Boulais
-- Create Date: 11/10/2017
-- Modified Date: 11/20/2017
-- Description: The coin controller is where a FSM resides along with a
series of prices that are used for soda selection.
_____
-- File: bin bcd.vhd
-- Entity: binary vector
-- Architecture: Structural
-- Author: Océane Boulais
-- Create Date: 11/10/2017
-- Modified Date: 11/20/2017
-- Description: A function library that provides a function the will
```

```
convert a binary vector to a BCD vector
______
-- File: coin_rx.vhd
-- Entity: coin rx
-- Architecture: Behavioral
-- Author: Océane Boulais
-- Create Date: 11/10/2017
-- Modified Date: 11/20/2017
-- Description: This component handles the debouncing of the buttons to
ensure that two coins are not counted when only one was inserted. As a
part of this, it outputs a signal for each received coin (via Qp, Dp,
______
______
-- File: seven seg disp.vhd
-- Entity: Seven segment display
-- Architecture: Behavioral
-- Author: Océane Boulais
-- Create Date: 11/10/2017
-- Modified Date: 11/20/2017
-- Description: This module simplifies away those issues by taking in
the vectors from the seven segment decoder and outputting the necessary
signals for the display. Displays amount deposit.
_____
_____
-- File: seven segment decoder.vhd
-- Entity: seven segment decoder
-- Architecture: Behavioral
-- Author: Océane Boulais
-- Create Date: 11/10/2017
-- Modified Date: 11/20/2017
-- Description:
The seven segment decoder is responsible for producing the pulses
necessary to display the amt dep on the seven segment display.
Inputs include the 12 bit BCD (three digit number in BCD) and the
Outputs:
- hund disp n (7 bits): Binary representing the segments that should be
on or off for the hundreds digit. Since the display has a common anode,
segments are active low.
- tens disp n (7 bits): Same as the hund disp n, but for the tens
place.
- ones disp n (7 bits): Same as the hund disp n, but for the ones
place.
```

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#### **Waveforms**

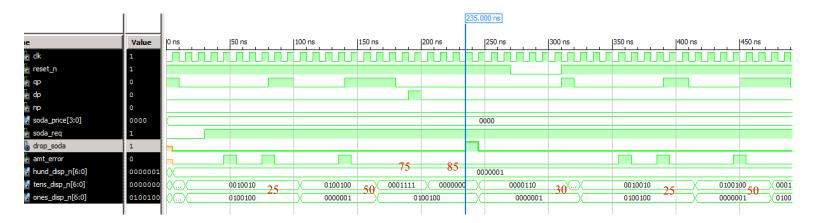


Figure 4a: Vending machine behavioral simulation at drop soda

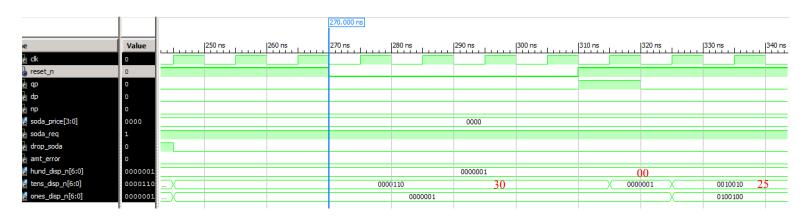


Figure 4b: Vending machine behavioral simulation at reset

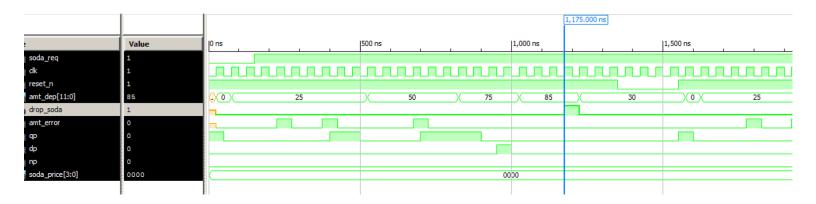


Figure 5: Coin controller behavioral simulation

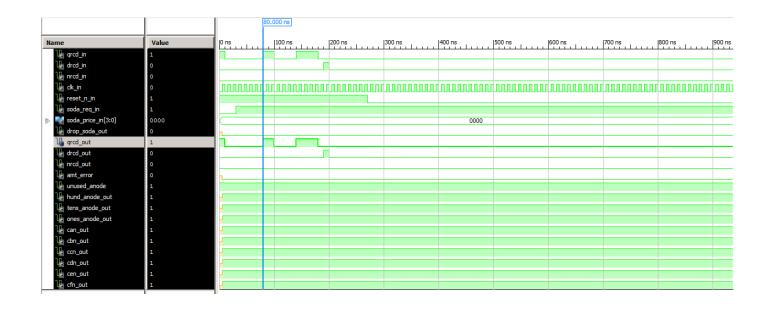


Figure 6: User interaction behavioral simulation

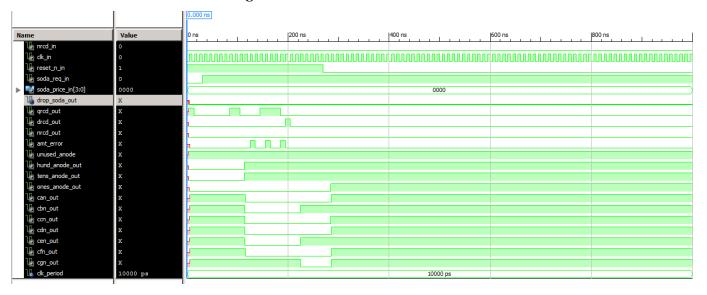


Figure 7: User interaction post-route simulation