

# Lecture 8: Chapter 2 part 3

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Divide-and-Conquer  
CS3310

# Quicksort

**Quicksort** is another divide-and-conquer sorting algorithm. Top-Level Description:

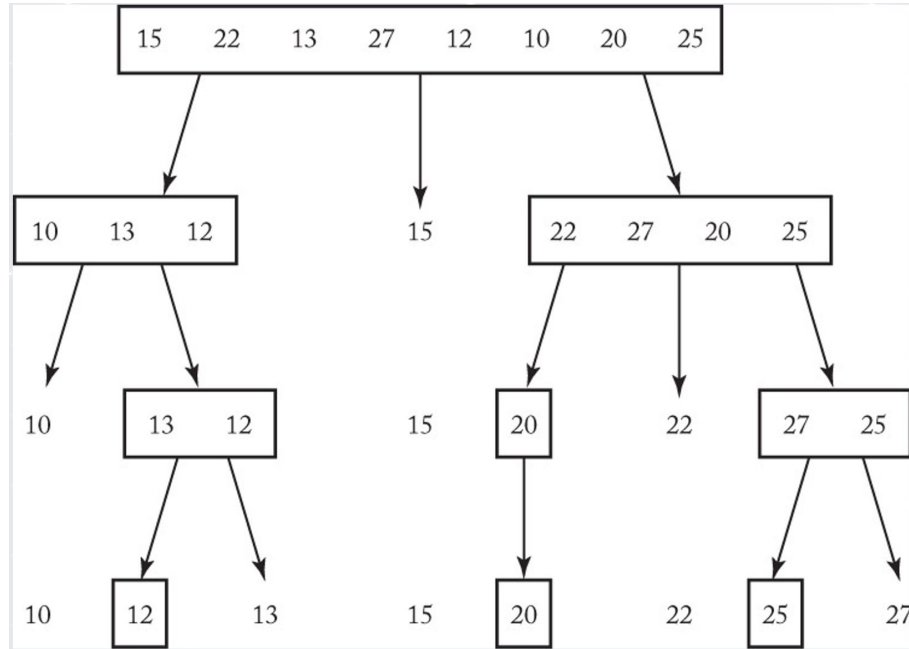
- A **pivot item** is chosen in the array.
  - For simplicity we will choose the first item in the array for now.
- Each item in the array less than the *pivot item* is placed before it and every item greater than the pivot item is placed after it.
- Recursively call Quicksort on the subarray to the left of the pivot and the subarray to its right.

Given this array: [15, 22, 13, 27, 12, 10, 20, 25]

- 15 is our pivot item. Place smaller items before it, larger items after:  
[10, 13, 12, 15, 22, 27, 20, 25]
- Recursively sort the two ‘subarrays’ with Quicksort:  
[10, 12, 13, 15, 20, 22, 25, 27]

# Quicksort

The following diagram shows the recursive tree of Quicksort



# Quicksort

**Problem:** Sort  $n$  keys in nondecreasing order

**Inputs:** Positive integer  $n$ , array of keys  $S$  indexed from 1 to  $n$ , `low` and `high` which indicate the indices of the subarray to sort.

**Outputs:** The array  $S$  containing the keys in nondecreasing order.

```
void quicksort(index low, index high)
{
    index pivotpoint;           // passed by reference and set within partition
    if (high > low)
    {
        partition(low, high, pivotpoint);
        quicksort(low, pivotpoint - 1);
        quicksort(pivotpoint + 1, high);
    }
}
```

# Quicksort

- Following the book's convention,  $n$  and  $S$  are not parameters to `QuickSort`.
- A top-level call to `QuickSort`: `quickSort(1, n);`
- Just as `merge` performs most of the work in `MergeSort`, `partition` performs most of the work in `QuickSort`.
- `partition` accepts `low` and `high` as parameters, indicating which section of the array is currently being sorted.
  - It also accepts `pivotpoint` as a reference parameter.
  - The item at index `low` is chosen as the `pivotitem`.
  - Every item less than `pivotitem` is placed before it in the array.
  - `pivotpoint` is set to `pivotitem`'s new index.

# Partition

**Problem:** Partition the array  $S$  for Quicksort

**Inputs:** two indices indicating the subarray of  $S$  to be partitioned

**Outputs:** `pivotpoint`, the index of `pivotitem` in the subarray indexed from `low` to `high`

```
void partition(index low, index high, index &pivotpoint)
{
    index i, j;
    keytype pivotitem;

    pivotitem = S[low];           // choose first item as pivotitem
    j = low;                     // j tracks where to place pivotitem
    for (i = low + 1; i <= high; i++)
        if (S[i] < pivotitem)
            j++;
            exchange S[i] and S[j];
    pivotpoint = j;
    exchange S[low] and S[pivotpoint]; // put pivotitem at pivotpoint
}
```

# Partition

A top-level call to `partition`.

```
low = 1, high = 8
```

<i>i</i>	<i>j</i>	S[1]	S[2]	S[3]	S[4]	S[5]	S[6]	S[7]	S[8]
-	-	15	22	13	27	12	10	20	25
2	1	<b>15</b>	<b>22</b>	13	27	12	10	20	25

## Step 1:

```
pivotitem = ??
```

```
j = ??
```

```
i = ??
```

# Partition

A top-level call to `partition`. Items compared each step are in bold.

`low = 1, high = 8`

<i>i</i>	<i>j</i>	S[1]	S[2]	S[3]	S[4]	S[5]	S[6]	S[7]	S[8]
-	-	15	22	13	27	12	10	20	25
2	1	<b>15</b>	<b>22</b>	13	27	12	10	20	25

## Step 1:

`pivotitem = S[1]`

`j = low = 1`

`i = low + 1 = 2`

- We select the first element as `pivotitem` and compare it with `S[i]`
- `S[i]` is bigger, so we make no change.



# Partition

A top-level call to `partition`. Items compared each step are in bold.

`low = 1, high = 8`

<i>i</i>	<i>j</i>	S[1]	S[2]	S[3]	S[4]	S[5]	S[6]	S[7]	S[8]
-	-	15	22	13	27	12	10	20	25
2	1	<b>15</b>	<b>22</b>	13	27	12	10	20	25
3	1 → 2	<b>15</b>	22	<b>13</b>	27	12	10	20	25

## Step 2:

`pivotitem = S[1]`

`j = 1` at beginning of step, `2` at end of step

`i = 3`

Compare `S[1]` with `S[i]`. `S[i]` is smaller: increment `j` and then swap `S[i]` and `S[j]` before step 3.

# Partition

A top-level call to `partition`. Items compared each step are in bold. Red items were swapped at the end of the previous step. At the end, `pivotpoint` is set to `j`

15 < 13. Increment `j`. Swap `S[i]` and `S[j]`.

15 < 12. Increment `j`. Swap `S[i]` and `S[j]`.

15 < 10. Increment `j`. Swap `S[i]` and `S[j]`.

End of list reached. Swap `S[1]` and `S[j]`

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2	1	<b>15</b>	<b>22</b>	13	27	12	10	20	25
3	1 → 2	<b>15</b>	22	<b>13</b>	27	12	10	20	25
4	2	<b>15</b>	13	22	27	12	10	20	25
5	2 → 3	<b>15</b>	13	22	27	12	10	20	25
6	3 → 4	<b>15</b>	13	12	27	10	20	25	22
7	4	<b>15</b>	13	12	10	22	20	25	27
8	4	<b>15</b>	13	12	10	22	27	20	25
-	4	10	13	12	15	22	27	20	25

# Partition Analysis

```
for (i = low + 1; i <= high; i++)  
    if (S[i] < pivotitem)  
        j++;  
        exchange S[i] and S[j];  
pivotpoint = j;  
exchange S[low] and S[pivotpoint]; // put pivot item at pivot point
```

What is the basic operation of partition?

# Partition Analysis

```
for (i = low + 1; i <= high; i++)  
    if (S[i] < pivotitem)  
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What is the basic operation of partition? The comparison of `S[i]` with `pivotitem`

Does partition have an every-case time complexity?

# Partition Analysis

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What is the basic operation of `partition`? The comparison of `S[i]` with `pivotitem`

Does `partition` have an every-case time complexity? **Yes!** No way to break from loop early.

What is  $T(n)$ ?

# Partition Analysis

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for (i = low + 1; i <= high; i++)  
    if (S[i] < pivotitem)  
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```

What is the basic operation of `partition`? The comparison of `S[i]` with `pivotitem`

Does `partition` have an every-case time complexity? **Yes!** No way to break from loop early.

What is  $T(n)$ ?  $n - 1$ , since the first item is not compared with itself.

# QuickSort Analysis

Now that we have analyzed `partition`, we can analyze Quicksort overall.

```
if (high > low)
    partition(low, high, pivotpoint);
    quicksort(low, pivotpoint - 1);
    quicksort(pivotpoint + 1, high);
```

What is the basic operation?

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What is the basic operation? The comparison of `S[i]` with `pivotitem` in `partition`.

Does Quicksort have an every-case complexity?



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What is the basic operation? The comparison of `S[i]` with `pivotitem` in `partition`.

Does `Quicksort` have an every-case complexity? **No!**

Worst case scenario?

# QuickSort Analysis

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What is the basic operation? The comparison of `S[i]` with `pivotitem` in `partition`.

Does `Quicksort` have an every-case complexity? **No!**

Worst case scenario?

➤ The case in which the list is already sorted.

# QuickSort Analysis

```
if (high > low)
    partition(low, high, pivotpoint);
    quicksort(low, pivotpoint - 1);
    quicksort(pivotpoint + 1, high);
```

- If the list is already sorted:
  - `partition` sets `pivotpoint` to 1 (since nothing is placed before the pivot item). The **first** recursive call to `Quicksort` passes 0 for `high` so it sorts 0 items and performs 0 operations.
  - The **second** recursive call to `Quicksort` sorts  $n - 1$  items.

What is the recurrence relation?

# QuickSort Analysis

```
if (high > low)
    partition(low, high, pivotpoint);
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- If the list is already sorted:
  - partition sets pivotpoint to 1 (since nothing is placed before the pivot item). The first recursive call to Quicksort passes 0 for high so it sorts 0 items and performs 0 operations.
  - The second recursive call to Quicksort sorts  $n - 1$  items.

What is the recurrence relation?

$$w_n = w_0 + w_{n-1} + n - 1$$

time to sort left subarray      time to sort right subarray      time to partition

# QuickSort Analysis

Recurrence Relation:  $w_n = w_0 + w_{n-1} + n - 1$

When the input to `QuickSort` is 0, 0 operations are performed. Therefore:

$$w_0 = 0$$

$$w_n = w_{n-1} + n - 1$$

Solving this recurrence relation gives us:

$$w_n = n(n - 1) / 2 \in \Theta(n^2)$$

# QuickSort Analysis

- Thankfully, `QuickSort` is usually much more efficient than its worst case.
  - In the average case, it is  $\Theta(n \lg n)$
- `QuickSort` can also be improved by choosing the pivot item in a different way if we suspect the array is likely already sorted.
  - We will discuss this strategy in detail in chapter 7.
- Another way to improve `QuickSort` uses the concept of **thresholds**, which we will cover more in the next lecture.
- There is overhead involved each time we divide an array and push new recursive calls to the stack. In recursive calls in which  $n$  is small enough, it is quicker to call an iterative algorithm on the remaining subarray rather than continue with `QuickSort`.

# In-Class Exercise

Consider the following array:

{ 123, 34, 189, 56, 150, 12, 9, 240 }

1. Trace the steps taken in the top-level call to `partition`.
2. Draw the recursive tree that `QuickSort` builds when sorting this array into ascending order. Assume that the first item is chosen as the pivot.
3. Sort  $65, 60_1, 60_2, 60_3$  in nondecreasing order using `Quicksort`. A sorting algorithm is called **stable** if it preserves the relative order of any two equal elements in its input. Is `Quicksort` stable?