

## ICMU Mini-course on Gaussian Processes

### Homework 2: Inference for Multivariate Normal Models; Gaussian Processes

Please upload your completed homework using [this link](#) by the end of the day on Thursday, February 11. Please [email me](#) if you have questions or would like to request an extension. The document name should include your last name. Scans or clear photographs of hand-written answers are acceptable if they are uploaded as a single document. If you upload multiple documents with the same name (e.g., if you wish to update a previously submitted document), we will grade the latest version.

1. Let  $Y_1, \dots, Y_n$  be a random sample of size  $n$  from the univariate normal distribution

$$Y_1, \dots, Y_n \sim_{ind} N(\mu, \sigma^2),$$

where the population mean  $\mu \in \mathbb{R}$  is unknown and the variance  $\sigma^2 > 0$  is known. Next, assume that an appropriate prior probability model for the unknown mean  $\mu$  is

$$\mu \sim N(m_0, \nu_0^2)$$

where  $m_0$  and  $\nu_0^2$  are the prior mean and prior variance, respectively (these are chosen by the data analyst to model information about  $\mu$  before the data is observed).

- Show that the posterior distribution of  $\mu | Y_1 = y_1, \dots, Y_n = y_n$  is univariate normal.  
*Hint: Recall that the posterior distribution describes our uncertainty about  $\mu$  after the data is observed. Its probability density function (pdf) is,*

$$f(\mu | y_1, \dots, y_n) \propto f(y_1, \dots, y_n | \mu) f(\mu), \quad (1)$$

where  $f(y_1, \dots, y_n | \mu)$  is the likelihood (joint density of the data) and  $f(\mu)$  is the prior pdf. Consider rearranging the right-hand-side to obtain the pdf of another normal distribution.

- (b) Write down the expressions for the posterior mean  $m_n$  and the posterior variance  $\nu_n^2$  from part (a). Express the posterior mean  $m_n$  as a weighted average of the prior mean  $m_0$  and the sample mean  $\bar{y} = \frac{1}{n} \sum_{i=1}^n y_i$ . If we take the posterior mean as an estimator of the unknown parameter  $\mu$ , what does its form imply when the sample size  $n$  is small versus when it is large?
2. A random sample of  $n$  students is drawn from a large population, and their weights are measured. The average weight of the  $n$  sampled students is  $\bar{y} = 150$  pounds. Assume the weights in the population are normally distributed with unknown mean  $\mu$  and known variance of 400. Suppose your prior distribution for  $\mu$  is normal with mean 180 and a variance of 1600.
  - (a) Write down the posterior distribution for  $\mu$  as a function of  $n$ .
  - (b) For  $n = 10$ , give a 95% posterior credible interval for  $\mu$ . *Hint: The endpoints of this interval are the 0.025 and the 0.975 quantiles of the posterior distribution. Numerical quantiles of the normal distribution may be obtained in R using the function qnorm().*
  - (c) For  $n = 100$ , give a 95% posterior credible interval for  $\mu$ .
  - (d) Briefly describe how your answers in parts (b) and (c) differ.
3. Define the Gaussian process  $X \sim \mathcal{GP}(m(t), C(t, s))$ ,  $t \in [0, 1]$  where  $m(t) = 0$  and  $C(t, s)$  is the squared exponential covariance with length-scale  $\ell = 0.2$ .

- (a) What is the distribution of the random vector  $\mathbf{X} = (X(0.1), X(0.5), X(0.9))^\top$ ? Calculate the numerical values of the mean vector and covariance matrix.
- (b) Generate and plot 5 sample paths of the Gaussian process  $X$  over the domain  $t \in [0, 1]$  over an equally-spaced discrete grid with  $n = 200$  knots. Please include the R script and figures in your answer. *Hint: One way to sample such a realization is to compute  $\mathbf{x} = \mathbf{L}\mathbf{g}$ , where  $\mathbf{g}$  is a random sample from the standard multivariate normal distribution  $N_n(\mathbf{0}_n, \mathbf{I}_{n \times n})$  and  $\mathbf{L}$  is the Cholesky factor of the covariance matrix  $\mathbf{C}$  (where  $\mathbf{C} = \mathbf{L}\mathbf{L}^T$ ). Adding a small jitter  $\epsilon\mathbf{I}_{n \times n}$  (e.g.,  $\epsilon = 10^{-8}$ ) to the diagonal of  $\mathbf{C}$  is recommended for numerical stability.*
- (c) Repeat part (b) with  $\ell = 0.1$ .
- (d) Briefly describe the difference between the plot in part (b) and (c).
4. Modify the R script `gaussian_process_realizations.R` from the course GitHub directory to sample realizations from a Gaussian process on the domain  $D = [0, 1] \times [0, 1]$  with zero mean function and Matérn covariance with smoothness  $\nu$  and length-scale  $\ell$  defined as follows. Please include the R script and figures in your answer.
- (a) Set  $\nu = 0.5$  and  $\ell = 1$ .
- (b) Set  $\nu = 1.5$  and  $\ell = 1$ .
- (c) Briefly describe the difference between the samples in part (a) and part (b).