

- 7.12** Write the following function that searches the  $n$  bytes beginning with `s` for the character `c`, where  $n$  is the number of bytes that `s` has to be incremented before it points to the null character `'\0'`. If the character is found, a pointer to it is returned; otherwise return `NULL`:
- ```
char* chr(char* s, char c)
```
- 7.13** Write the following function that returns the sum of the `floats` pointed to by the first  $n$  pointers in the array `p`:
- ```
float sum(float* p[], int n)
```
- 7.14** Write the following function that changes the sign of each of the negative `floats` pointed to by the first  $n$  pointers in the array `p`:
- ```
void abs(float* p[], int n)
```
- 7.15** Write the following function that indirectly sorts the `floats` pointed to by the first  $n$  pointers in the array `p` by rearranging the pointers:
- ```
void sort(float* p[], int n)
```
- 7.16** Implement the *Indirect Selection Sort* using an array of pointers. (See Problem 6.19 on page 144 and Example 7.17 on page 170.)
- 7.17** Implement the *Indirect Insertion Sort*. (See Problem 6.18 on page 144 and Example 7.17 on page 170.)
- 7.18** Implement the *Indirect Perfect Shuffle*. (See Problem 6.29 on page 145.)
- 7.19** Rewrite the `sum()` function (Example 7.18 on page 171) so that it applies to functions with return type `double` instead of `int`. Then test it on the `sqrt()` function (defined in `<math.h>`) and the reciprocal function.
- 7.20** Apply the `riemann()` function (Problem 7.4 on page 173) to the following functions defined in `<math.h>`:
- `sqrt()`, on the interval  $[1, 4]$ ;
  - `cos()`, on the interval  $[0, \pi/2]$ ;
  - `exp()`, on the interval  $[0, 1]$ ;
  - `log()`, on the interval  $[1, e]$ .
- 7.21** Apply the `derivative()` function (Problem 7.5 on page 175) to the following functions defined in `<math.h>`:
- `sqrt()`, at the point  $x = 4$ ;
  - `cos()`, at the point  $x = \pi/6$ ;
  - `exp()`, at the point  $x = 0$ ;
  - `log()`, at the point  $x = 1$ .
- 7.22** Write the following function that returns the product of the  $n$  values  $f(1), f(2), \dots$ , and  $f(n)$ . (See Example 7.18 on page 171.)
- ```
int product(int (*pf)(int k), int n)
```
- 7.23** Implement the *Bisection Method* for solving equations. Use the following function:
- ```
double root(double (*pf)(double x), double a, double b, int n)
```
- Here, `pf` points to a function `f` that defines the equation  $f(x) = 0$  that is to be solved, `a` and `b` bracket the unknown root  $x$  (i.e.,  $a \leq x \leq b$ ), and `n` is the number of iterations to use. For example, if  $f(x) = x^2 - 2$ , then `root(f, 1, 2, 100)` would return 1.414213562373095 ( $= \sqrt{2}$ ), thereby solving the equation  $x^2 = 2$ . The Bisection Method works by repeatedly bisecting the interval and replacing it with the half that contains the root. It checks the sign of the product  $f(a)f(b)$  to determine whether the root is in the interval  $[a, b]$ .
- 7.24** Implement the *Trapezoidal Rule* for integrating a function. Use the following function:
- ```
double trap(double (*pf)(double x), double a, double b, int n)
```
- Here, `pf` points to the function `f` that is to be integrated, `a` and `b` bracket the interval  $[a, b]$  over which  $f$  is to be integrated, and `n` is the number of subintervals to use. For example, the