Monte Carlo Methods

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- accuracy of estimate $\widehat{E(heta)}_T$ improves as $T o \infty$.
- all this generalizes to (a) vectors $\mathbf{\theta} = (\theta_1, \dots, \theta_D)'$; (b) estimates of functionals of $\mathbf{\theta}$, $h(\mathbf{\theta})$.

Brief history of Monte Carlo methods

- Buffon's needle, estimating π ; see simple in my pscl package for R
- Lord Kelvin
- Enrico Fermi
- Metropolis and Ulam; Manhattan Project, Los Alamos

Brief history of Monte Carlo methods

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THE MONTE CARLO METHOD

NICHOLAS METROPOLIS AND S. ULAM

Los Alamos Laboratory

We shall present here the motivation and a general description of a method dealing with a class of problems in mathematical physics. The method is, essentially, a statistical approach to the study of differential equations, or more generally, of integro-differential equations that occur in various branches of the natural sciences.

Simulation Consistency

Theorem (Simulation Consistency, Independent Draws, Part 1)

Suppose $\{\mathbf{\theta}^{(t)}\}$ is a sequence of independent draws from the density $f(\mathbf{\theta})$, with $\mathbf{\theta} \in \mathbb{R}^k$ and $h : \mathbb{R}^k \to \mathbb{R}$. Then

$$\bar{h}^{(T)} = T^{-1} \sum_{t=1}^{T} h(\mathbf{\Theta}^{(t)}) \stackrel{a.s.}{\rightarrow} E[h(\mathbf{\Theta})]$$

Proof.

The claim is a restatement of the strong law of large numbers (e.g., Proposition B.10; BASS).



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Simulation Consistency

Theorem (Simulation Consistency, Independent Draws, Part 2)

Further, suppose that for $p \in (0, 1)$, there is a unique q_p such that $Pr[h(\mathbf{\theta}) \leq q_p] \geq p$ and $Pr[h(\mathbf{\theta}) \geq q_p] \geq 1$ - p are both true. Consider $q_p^{(T)} \in \mathbb{R}$ such that

$$T^{-1}\sum_{t=1}^{T}\mathcal{I}(-\infty < h(\mathbf{\theta}^{(t)}) < q_p^{(T)}) \geq p$$

where $p \in (0, 1)$ and $\mathcal{I}(\cdot)$ is a binary indicator function, equal to 1 if its argument is true, and zero otherwise. Then $q_p^{(T)} \stackrel{a.s.}{\to} q_p$.

Proof.

Geweke (2005, Theorem 4.1.1); Rao (1973, 423); van der Vaart (1998, 305).

Learning about a uniform random variable

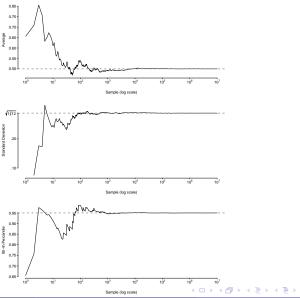
- Suppose $\theta \sim \text{Unif}(0, 1)$
- But we have forgotten that $E(\theta) = .5$, $sd(\theta) = \sqrt{1/12}$, $Pr(\theta \le q) = q$, $q \in (0, 1)$ etc.
- Monte Carlo methods? Use rnorm in R.
- the average of the sampled values, $\bar{\theta}^{(T)} = T^{-1} \sum_{t=1}^{T} \theta_t$, will be very close to $E(\theta) = .5$. Importantly, $\bar{\theta}^{(T)}$ gets arbitrarily close to .5 as $T \to \infty$.
- 2 likewise, the standard deviation of the sampled values

$$\mathsf{sd}(heta)^{(T)} = \left[(T - 1)^{-1} \sum_{t=1}^T (heta_t - ar{ heta}^{(T)})^2 \right]^{1/2}$$

will get arbitrarily close to $\sqrt{1/12}$ as $T \to \infty$.

1 the p-th quantile of the sampled values, $q_p^{(T)}$, $p \in (0, 1)$; $q_p^{(T)} \stackrel{a.s.}{\to} p$.

Learning about a uniform random variable (Figure 3.1)



Monte carlo integration/marginalization (method of composition)

- $oldsymbol{ heta}=(heta_1, heta_2)$, with $heta_j\in heta_j\subseteq\mathbb{R}, j=1,2$.
- Posterior density: $p(\theta|y)$.
- But interest centers on the marginal posterior density of θ_1 ,

$$p(\theta_1|\mathbf{y}) = \int_{\Theta_2} p(\theta_1, \theta_2|\mathbf{y}) d\theta_2 = \int_{\Theta_2} p(\theta_1|\theta_2, \mathbf{y}) p(\theta_2|\mathbf{y}) d\theta_2.$$

Method of composition:

- 1: **for** t = 1 to T **do**
 - 2: sample $\theta_2^{(t)}$ from $p(\theta_2|\mathbf{y})$
 - 3: sample $heta_1^{(t)}$ from $p(heta_1| heta_2^{(t)}, \mathbf{y})$.
 - 4: end for
- $\theta_1^{(t)} \sim p(\theta_1|\mathbf{y})$, as desired.



Method of Composition to sample from a t density

$$p(\boldsymbol{\beta}|\mathbf{y},\mathbf{X}) = \int_0^{\infty} p(\boldsymbol{\beta}|\sigma^2,\mathbf{y},\mathbf{X}) p(\sigma^2|\mathbf{y},\mathbf{X}) d\sigma^2$$

$$p(\sigma^2|\mathbf{y},\mathbf{X}) \equiv \text{inverse-Gamma}(v/2,vs^2/2)$$

$$p(\boldsymbol{\beta}|\sigma^2,\mathbf{y},\mathbf{X}) \equiv N(\mathbf{b},\sigma^2\mathbf{B})$$

```
1: for t=1 to T do
2: sample \sigma^{2(t)} from p(\sigma^2) \equiv \text{inverse-Gamma}(v/2, vs^2/2)
3: sample \boldsymbol{\beta}^{(t)} from p(\boldsymbol{\beta}|\sigma^{2(t)}) \equiv N(\boldsymbol{b}, \sigma^{2(t)}\boldsymbol{B})
4: end for
i.e., \boldsymbol{\beta}^{(t)} \sim p(\boldsymbol{\beta}|\mathbf{v}, \mathbf{X}) \equiv \text{student} - t.
```

Monte carlo inference, functions of parameters

• 2-by-2 table:

x_i			
Уi	0	1	
0	$n_0 - r_0$	n ₁ - r ₁	
1	r_0	r_1	
	n_0	n_1	n

- Two success probabilities: $0 \le \theta_0$, $\theta_1 \le 1$; $\Pr(y_i = 1 | x_i = j) = \theta_j$, $j \in \{0, 1\}$.
- MLEs: $\hat{\theta}_j = r_j/n_j$, $j \in \{0, 1\}$.
- Bayesian analysis: independent, conjugate Beta priors over each θ_j , $\theta_j \sim \text{Beta}(\alpha_j, \beta_j)$. posterior densities are independent Beta densities $\theta_j | r_j, n_j \sim \text{Beta}(\alpha_j + r_j, \beta_j + n_j r_j)$.

Inference for Difference of Two Binomial Proportions

- $q = \theta_1$ θ_0 ; difference of two binomial proportions
- $p(\theta_i|r_i,n_i) \equiv \text{Beta.}$
- But what is $p(q|r_0, r_1, n_0, n_1)$?
- Until recently (Pham-Gia and Turkkan 1993), the density of the difference of two Betas was unknown (unavailable in closed form)
- Characterize this density by Monte Carlo methods.

Algorithm:

- **1** sample $\theta_0^{(t)}$ from Beta $(\alpha_0 + r_0, \beta_0 + n_0 r_0)$
- 2 sample $\theta_1^{(t)}$ from Beta $(\alpha_1 + r_1, \beta_1 + n_1 r_1)$
- $oldsymbol{0}$ compute $q^{(t)}= heta_1^{(t)}$ $heta_0^{(t)}$

Repeat many times, t = 1, ..., T; sampled $q^{(t)}$ are a sample from the posterior density of q; summarize numerically, make histogram, etc.

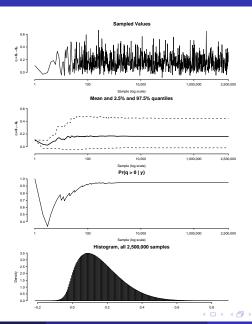
Sekhon (2005); Geddes (1990); Skocpol (1979):

	Revolution	No Revolution
Defeated & Invaded/Lost Territory	1	7
Not Defeated within 20 years	2	74

- Each observation spans 20 years for each Latin American country
- The sole observation in the top left of the cross-tabulation is Bolivia: it suffered a military defeat in 1935, and a social revolution in 1952.
- The two observations in the lower left of the table are Mexico (revolution in 1910) and Nicaragua (revolution in 1979).
- The MLEs are $\hat{\theta}_0 = 2/(2+74) = .026$ and $\hat{\theta}_1 = 1/(7+1) = .125$, suggesting that revolutions are much more likely conditional on military defeat than conditional on not having experienced a military defeat.
- Uniform priors $\theta_j \sim \text{Beta}(1, 1), j = 0, 1$; posterior densities $\theta_0 | r_0, n_0 \sim \text{Beta}(3, 75)$ and $\theta_1 | r_1, n_1 \sim \text{Beta}(2, 8)$.

We seek the posterior density of $q = \theta_1 - \theta_0$; we use Monte Carlo methods:

- 1: **for** t = 1 to T **do**
- 2: sample $\theta_1^{(t)}$ from $p(\theta_1|\mathbf{y}) \equiv \text{Beta}(2,8)$
- 3: sample $\theta_0^{(t)}$ from $p(\theta_0|\mathbf{y}) \equiv \text{Beta}(3,75)$
- 4: $q^{(t)} \leftarrow \theta_1^{(t)} \theta_0^{(t)}$
- 5: end for



R code is trivial:

```
nsims <- 1e6
theta1 <- rbeta(nsims,2,8)
theta0 <- rbeta(nsims,3,75)
q <- theta1 - theta0
summary(q)
mean(q>0)
```

In JAGS

```
model{
         ## model for the data
         for(i in 1:2){
            r[i] ~ dbin(theta[i],n[i])
         }
         ## priors
         for(i in 1:2){
            theta[i] ~ dbeta(1,1)
         ## quantity of interest
         q <- theta[2] - theta[1]
```

Sampling algorithms

Suppose $\theta \sim p$? How to sample from p?

- inverse-CDF method
- importance sampling
- rejection sampling
- slice sampler

Inverse-CDF method

- $m{\Theta} \sim m{p}, m{\theta} \in m{\Theta} \subseteq \mathbb{R}$.
- $F(q) = \Pr(\theta \le q) = \int_{-\infty}^{q} p(\theta) d\theta$; n.b., $F: \Theta \mapsto (0, 1)$.
- Suppose F^{-1} exists, is computable; $F^{-1}:(0,1)\mapsto\Theta$
- Inverse-CDF algorithm:
 - 1: **for** t = 1 to T **do**
 - 2: sample $p^{(t)} \sim \text{Unif}(0, 1)$
 - 3: $\theta^{(t)} \leftarrow F^{-1}(p^{(t)})$
 - 4: end for
- Reasonably rare that an inverse-CDF exists. E.g., not available in closed form for the normal, but good approximations exist; e.g., Wichura (1988), used in the pnorm function in R).

Importance Sampling

- we can evaluate the target density at any given point in its support; i.e., we can compute $p(\theta) \forall \theta \in \Theta$.
- no algorithm for direct sampling from $p(\theta)$.
- we *can* sample from a density $s(\theta)$, where $s(\theta)$ has the property that $p(\theta) > 0 \Rightarrow s(\theta) > 0$, $\forall \theta \in \Theta$.
- Exploit the following identity: consider some $h(\theta)$, then

$$E[h(\theta)] = \int_{\Theta} h(\theta)p(\theta)d\theta = \int_{\Theta} h(\theta)p(\theta)/s(\theta)s(\theta)d\theta.$$

- Importance sampling algorithm:
 - 1: **for** t = 1 to T **do**
 - 2: sample $\theta^{(t)} \sim s(\theta)$.
 - 3: $\mathbf{w}^{(t)} \leftarrow p(\theta^{(t)})/s(\theta^{(t)})$
 - 4: end for
 - 5: $\bar{h}^{(T)} \leftarrow T^{-1} \sum_{t=1}^{T} h(\theta^{(t)}) w^{(t)}$



Accept-Reject Sampling (von Neumann 1951)

- $\theta \sim p(\theta)$, but can't sample from this density
- can sample from a *majorizing function* $g(\theta)$, that is, where $g(\theta) > p(\theta), \forall \theta$.
- can trivially find a majorizing function by rescaling a *proposal* density: $g(\theta) = cm(\theta)$:

```
1: for t = 1 to T do
    sample z \sim m(\theta)
 2:
 3: sample u \sim \text{Unif}(0, 1)
 4: r \leftarrow p(z)/cm(z)
 5: if u < r then
           \theta^{(t)} \leftarrow z \{\text{``accept''}\}\
 6:
        else
 7:
           go to 2 {"reject"}
 8:
        end if
 9:
10: end for
```

Accept-Reject Sampling

- The target density p need only be known up to a factor of proportionality. All that matters is that we can sample from a function that majorizes the target density, and we can control that through the scaling constant, c.
- Useful in Bayesian analysis, where it is often the case that posterior densities are only known up to an (unknown) proportionality constant.
- An accept-reject algorithm produces potentially many draws that are rejected, and hence the algorithm can be computationally inefficient.
- More efficient if the majorizing function g closely approximates the target density, p; e.g., $r=p/g\approx 1$.

Adaptive Rejection Sampling

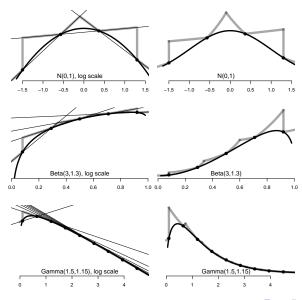
- hard to find a good proposal density
- but if target density $p(\theta)$ is log-concave and continuously differentiable, then use adaptive rejection sampling
- build a proposal density as a set of piecewise exponential densities bracketing the target density
- A density $p(\mathbf{\theta})$, $\mathbf{\theta} \in \mathbb{R}^k$, is log-concave if the determinant of

$$\mathbf{H} = \begin{pmatrix} \frac{\partial^2 \log p}{\partial \theta_1 \partial \theta_1} & \frac{\partial^2 \log p}{\partial \theta_1 \partial \theta_2} & \cdots & \frac{\partial^2 \log p}{\partial \theta_1 \partial \theta_k} \\ \frac{\partial^2 \log p}{\partial \theta_2 \partial \theta_1} & \frac{\partial^2 \log p}{\partial \theta_2 \partial \theta_2} & \cdots & \frac{\partial^2 \log p}{\partial \theta_2 \partial \theta_k} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial^2 \log p}{\partial \theta_k \partial \theta_1} & \frac{\partial^2 \log p}{\partial \theta_k \partial \theta_2} & \cdots & \frac{\partial^2 \log p}{\partial \theta_k \partial \theta_k} \end{pmatrix}$$

is non-positive.



Adaptive Rejection Sampling



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Adaptive Rejection Sampling

- algorithm is adaptive: successfully sampled points are added to the set of evaluation points.
- initialization/adaptation phase consists of getting a good set of evaluation points
- ARS was a critical step in developing a general purpose computer program for simulation-based Bayesian statistical analysis; e.g., Gilks and Wild (1992).
- Extension to non-log-concave densities (e.g., Gilks, Best and Tan 1995)

Slice Sampling §5.2.7

- $\theta \sim p(\theta), \theta \in \Theta \subseteq \mathbb{R}$, restricting ourselves to the one-dimensional case for the time being.
- This is equivalent to sampling the pair (θ, U) uniformly from the set $\mathcal{J} = \{(\theta, u) : 0 < u < p(\theta)\}.$
- i.e., let $\widetilde{\Theta} = \Theta \times [0, m]$, where $p(\theta) \leq m \, \forall \, \theta \in \Theta$.
- Now pick a random point $(\theta^*, U^*) \in \widetilde{\Theta}$.
- if If $0 < U^* < p(\theta^*)$, then accept the draw.
- sampling over the u dimension is equivalent to marginalizing u out of $f(\theta, u)$, i.e.,

$$p(\theta) = \int_0^{p(\theta)} f(u) du = \int_0^{p(\theta)} du, \ 0 < u < p(\theta),$$

since f(u) here is a constant.

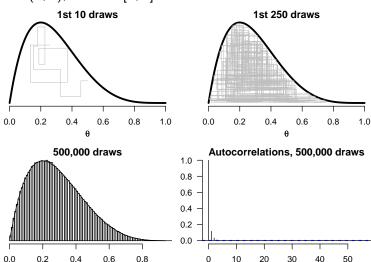


Slice Sampling §5.2.7

- sequentially sample from $g(U|\theta)$ and $g(\theta|U)$
- Given $(\theta^{(t-1)}, U^{(t-1)})$:
 - 1: sample $U^{(t)} \sim \mathsf{Unif}(0, p(\theta^{(t-1)}))$
 - 2: sample $\theta^{(t)} \sim \mathsf{Unif}(\mathcal{A}^{(t)})$ where $\mathcal{A}^{(t)} = \{\theta : p(\theta) \geq U^{(t)}\}$.
- special case of the Gibbs sampler

Slice sampling from a Beta density, Example 5.12

$$p(\theta) \equiv \text{Beta}(2,5), \theta \in \Theta \equiv [0,1]$$



Lag

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