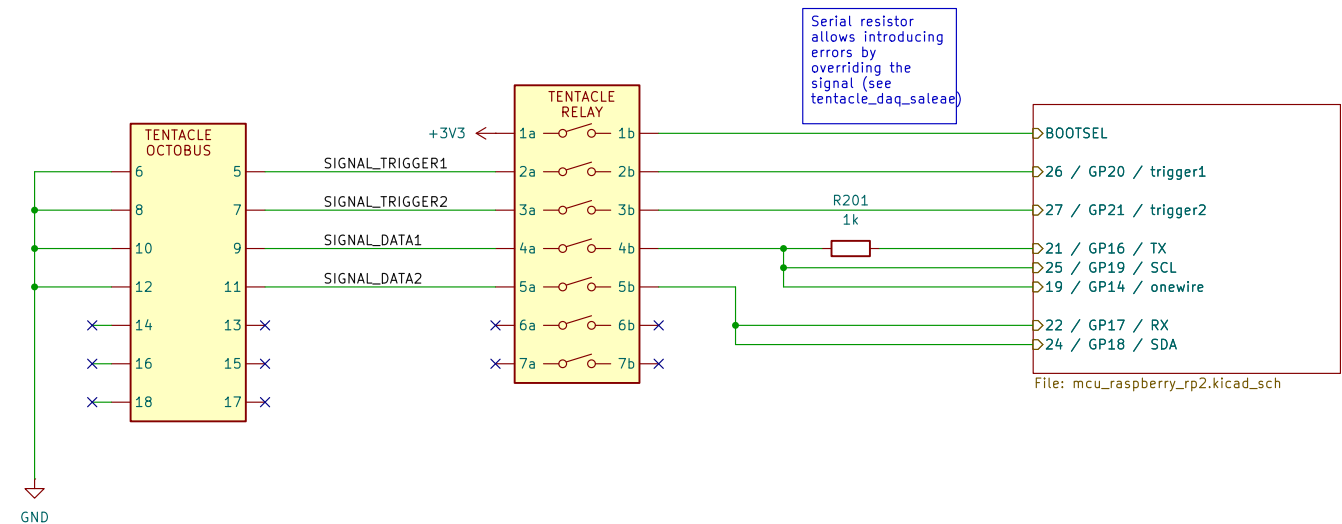
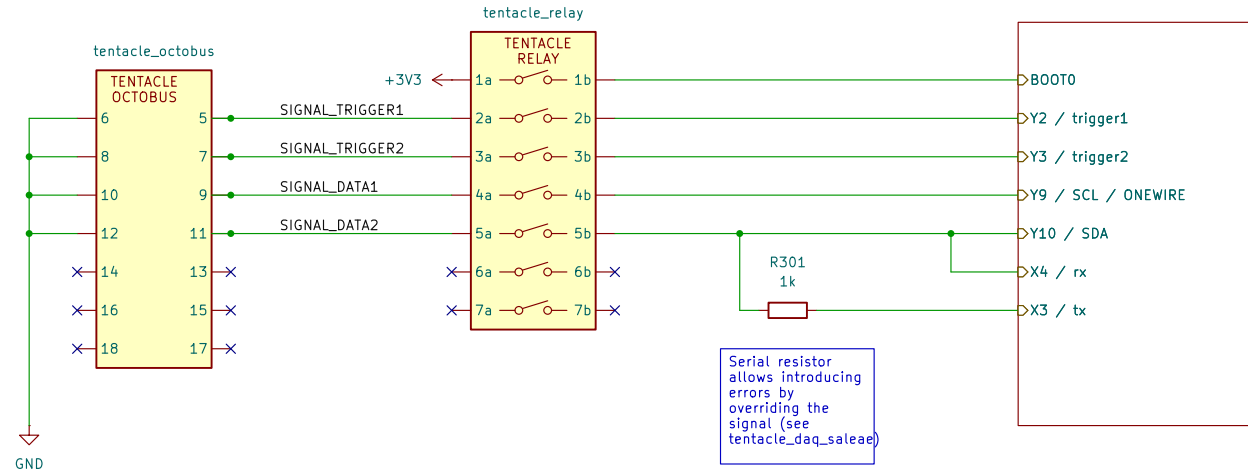
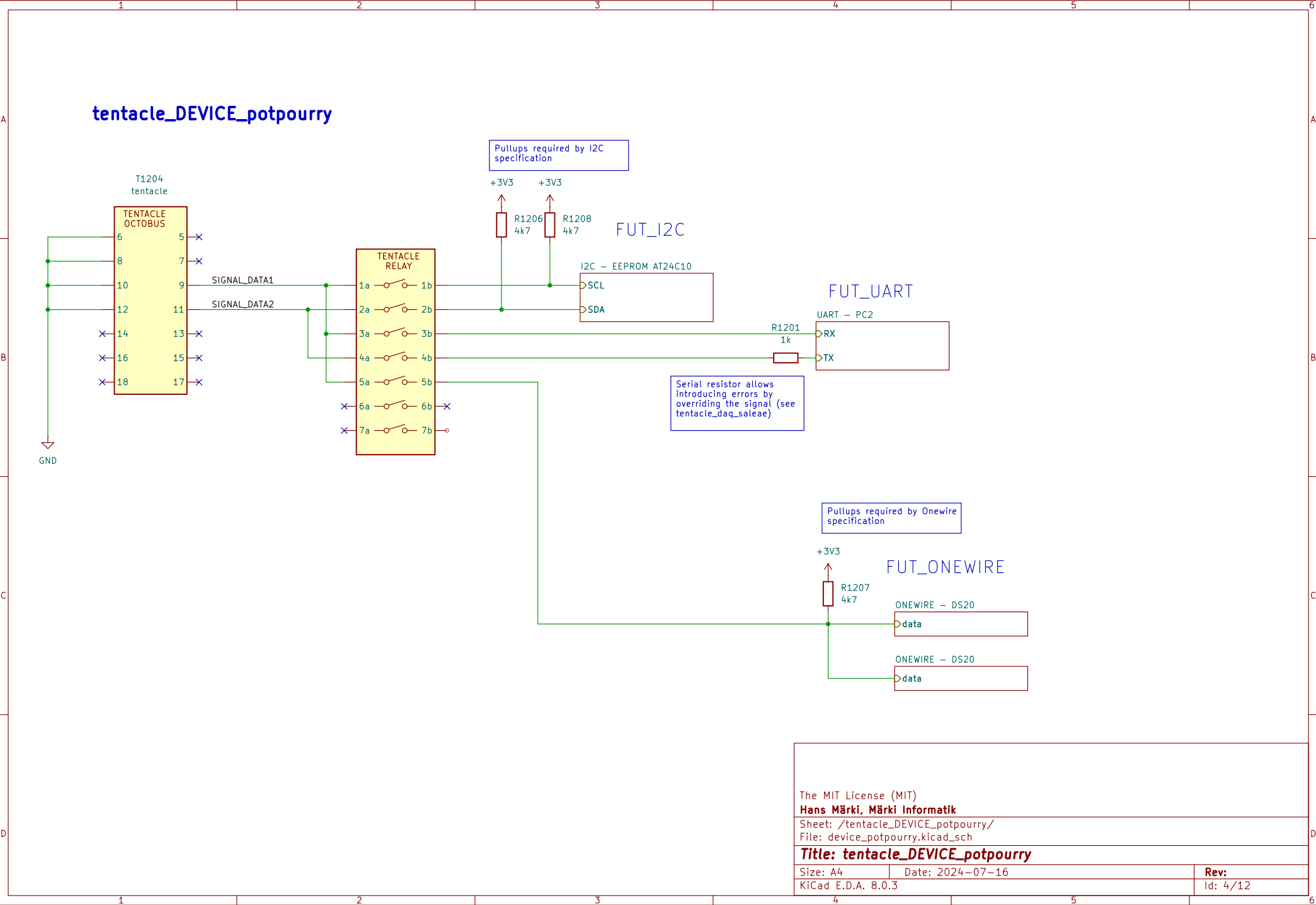


tentacle\_MCU\_raspberry\_pico



tentacle\_MCU\_grobotics\_pyboard





tentacle\_Daq\_saleae

The diagram illustrates the wiring for the tentacle\_Daq\_saleae circuit. It features three main components: a TENTACLE OCTOBUS, a TENTACLE RELAY, and a TENTACLE GPIO. The TENTACLE OCTOBUS is connected to GND and has four signal lines (6, 8, 10, 12) connected to the TENTACLE RELAY. The TENTACLE RELAY has four signal lines (1a, 2a, 3a, 4a) connected to the TENTACLE GPIO. The TENTACLE GPIO has four signal lines (GPIO9, GPIO10, GPIO11, GPIO12) connected to the TENTACLE RELAY. The TENTACLE RELAY also has four signal lines (1b, 2b, 3b, 4b) connected to the TENTACLE GPIO. The TENTACLE GPIO has four signal lines (GPIO13, GPIO14, GPIO15) connected to GND. The TENTACLE RELAY has four signal lines (1b, 2b, 3b, 4b) connected to the TENTACLE GPIO. The TENTACLE RELAY has four signal lines (1b, 2b, 3b, 4b) connected to the TENTACLE GPIO.

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