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## REVISION ON IMPORTANT LINEAR ALGEBRA

### 1 Determinants

Let  $A \in \mathbb{R}^{n \times n}$  and  $x \in \mathbb{R}^n$ . Which of the following statements are true?

Prove or provide a counterexample:

- (a) There exists  $x^* \neq 0$  such that  $Ax^* = 0$  if  $\det(A) = 0$ ;
- (b) There exists  $x^* \neq 0$  such that  $Ax^* = 0$  only if  $\det(A) = 0$ ;
- (c) There exists  $x^* \neq 0$  such that  $Ax^* = 0$  if and only if  $\det(A) \neq 0$ .

*Solution*

**(a) True.**

Given that the determinant of matrix  $A$  is zero, we can conclude that at least one column can be expressed as a linear combination of the others. Consequently, through elementary column operations, we can obtain an equivalent matrix  $B$ , where one of its columns is reduced to zeros, i.e.,  $A \equiv B$ . It's important to note that these column operations do not alter the vector space generated by the matrix, so  $\text{Span}(A) = \text{Span}(B)$ . (The solution space of the linear system remains the same when we replace matrix  $A$  with matrix  $B$ .)

Now, we have the system  $Bx = 0$ , and since one of the columns of  $B$  is entirely zero, we have more variables than equations, indicating that the solution space for this linear system contains a free component that can take any nonzero real value. Therefore, there exists a non-zero vector  $x^* \neq 0$  that satisfies the linear system  $Ax = 0$ .

**(b) True.**

Let's employ a counter-positive proof. Suppose that  $\det(A) \neq 0$ , which implies that the matrix is invertible. Now, consider the equation  $Ax = 0$ . We can multiply both sides by  $A^{-1}$ , yielding  $A^{-1} \times Ax = A^{-1} \times 0$ . As a result, we find that  $x = 0$  is the only solution to this equation.

Therefore, if we assume  $\det(A) \neq 0$ , it implies that the only solution to  $Ax = 0$  is  $x = 0$ . In other words, there are no nonzero solutions ( $x^* \neq 0$ ) to this equation when  $\det(A) \neq 0$ .

**(c) False.**

In reference to item (b), when  $\det(A) \neq 0$ , it implies that the unique solution to the equation is  $x = \mathbf{0}^n$ , where  $\mathbf{0}^n$  represents the zero vector in  $\mathbb{R}^n$ .

### 2 Rank

Let  $A \in \mathbb{R}^{m \times n}$ , where  $m \geq n$  and  $\text{rank}(A) = n$ . Prove that  $A^T A$  is non-singular.

*Solution*

We start by considering matrix  $A$  with dimensions  $m \times n$ , which implies that its transpose,  $A^T$ , is  $n \times m$ . Therefore, the product  $A^T A$  results in a square matrix of size  $m \times m$ , as required for nonsingularity.

To complete the proof, we need to demonstrate that if  $A^T A$  is nonsingular, then the null space of the matrix contains only the zero-vector.

We begin with the equation  $A^T A x = 0$ , where  $x \in \mathbb{R}^m$ . By multiplying both sides by  $x^T$ , we get:

$$x^T A^T A x = x^T \cdot 0.$$

Simplifying further:

$$(Ax)^T (Ax) = 0.$$

Now, applying the Euclidean norm ( $L_2$  norm), we have:

$$\|Ax\|_2^2 = 0.$$

The Euclidean norm of a vector is only equal to zero if and only if the vector itself is the zero-vector, i.e.,  $\|y\|_2 = 0 \iff y = 0$ . Thus:

$$\|Ax\|_2 = 0 \iff x = 0.$$

This result indicates that  $Ax$  can only be the zero vector when  $x$  is the zero vector.

Now, let's interpret this outcome.  $Ax$  represents the result of a linear combination of the columns of matrix  $A$ . Given that the rank of  $A$  is  $n$ , we can conclude that the columns of  $A$  are linearly independent. Consequently, the only solution for  $x$  that yields  $Ax = 0$  is the zero-vector.

Returning to our original system:

$$A^T A x = 0$$

Given that the only solution for  $x$  is the zero vector, we can confidently assert that  $A^T A$  is indeed nonsingular.

### 3 Kernel & Image

Let  $A \in \mathbb{R}^{m \times n}$ , where  $m \leq n$  and  $\text{rank}(A) = k$ . We define the subspaces:

Kernel of  $A$ :  $N_u(A) = \{x \in \mathbb{R}^n | Ax = 0\}$ ;

Image of  $A$ :  $Im(A) = \{y \in \mathbb{R}^m | \exists x \in \mathbb{R}^n | y = Ax\}$ ;

Prove that:

(a)  $N_u(A) \perp Im(A^T)$ ;

(b)  $\dim(N_u(A)) = n - k$ ;

(c)  $\mathbb{R}^n = N_u(A) \oplus Im(A^T)$ .

*Solution*

**(a)** To demonstrate the orthogonality of  $N_u(A)$  and  $Im(A^T)$ , consider the following:

Let  $u \in N_u(A)$  and  $y \in Im(A^T)$ . This means that there exists an  $x$  such that  $y = Ax$ . Now, we can proceed as follows:

$$\begin{aligned} u^T \cdot y &= u^T \cdot Ax \\ &= (A \cdot u) \cdot x \\ &= 0 \cdot x \\ &= 0 \end{aligned}$$

Therefore, we conclude that  $N_u(A)$  is orthogonal to  $Im(A^T)$ , denoted as  $N_u(A) \perp Im(A^T)$ .

**(b)** To demonstrate that the dimension of the kernel of matrix  $A$  is equal to the number of columns, denoted as  $n$ , where  $m > n$ , subtracted by the rank of  $A$ ,  $\text{Rank}(A) = k$ , consider the following argument:

We can perform elementary column operations on matrix  $A$  to transform it into a new column-echelon matrix  $R$ . This transformation ensures that the span of the columns of  $A$  remains the same, as column operations do not alter the vector space generated. Since  $\text{Rank}(A) = k$ , it follows that  $\text{Rank}(R) = k$  because they share the same vector space.

Considering that the rank of a matrix represents the number of non-zero columns, we deduce that this new matrix  $R$  possesses  $k$  non-zero columns. Furthermore, the kernel of the column space of a matrix corresponds to

the number of zero columns. Since matrix  $R$  is in echelon form, we have that there are  $n - k$  zero columns, which precisely corresponds to the dimension of the null space of  $A$ .

**(c)** We aim to prove that the direct sum of the Null-space of matrix  $A$  and the Image Space of  $A$  forms the entire vector space of the columns of  $A$ .

To establish this, we can approach the proof as follows:

Firstly, let's establish that the intersection of  $Nu(A)$  and  $Im(A)$  is trivial, containing only the zero vector. Suppose  $u \in Nu(A) \cap Im(A)$ . As shown in item (a), we have previously established that  $u^T u = 0$  to demonstrate the orthogonality of the kernel and the image space. Consequently, this intersection has a dimension of zero.

The rank of a matrix represents the dimension of its image space:  $dim(Im(A)) = rank(A) = k$ .

From item (b), we know that the dimension of the null-space is  $dim(Nu(A)) = n - k$ .

Therefore, the dimension of  $Nu(A) + Im(A)$  is:

$$dim(Nu(A) + Im(A)) = dim(Nu(A)) + dim(Im(A)) - dim(Nu(A) \cap Im(A)) = (n - k) + k - 0 = n = dim(\mathbb{R}^n).$$

Since  $Nu(A)$  and  $Im(A)$  are both subsets of  $\mathbb{R}^n$ , we can conclude that  $Nu(A) \oplus Im(A) \subset \mathbb{R}^n$ .

The equality of dimensions and the fact that  $Nu(A) \oplus Im(A) \subset \mathbb{R}^n$  are enough to establish that:

$$\mathbb{R}^n = Nu(A) \oplus Im(A).$$

This demonstrates that the direct sum of the Null-space of  $A$  and the Image Space of  $A$  indeed forms the entire vector space of the columns of  $A$ .

## 4 Intersection of Hyperplanes / Linear Systems / Equation of the Line

Consider the equations

$$\sum_{j=1}^n a_{ij}x_j = b_i, \quad i = 1, \dots, n-1,$$

or equivalently,  $Ax = b$  with  $A \in \mathbb{R}^{(n-1) \times n}$ ,  $b \in \mathbb{R}^{n-1}$ , and  $x \in \mathbb{R}^n$ , corresponding to  $n - 1$  "linearly independent" hyperplanes. The intersection of these hyperplanes determines a line in  $\mathbb{R}^n$ . We can represent this line in the form

$$y = x + \lambda d$$

with  $\lambda \in \mathbb{R}$  and  $x, d \in \mathbb{R}^n$ . Discuss how to choose  $x$  and  $d$ .

*Solution*

Considering that the system has  $n$  variables and  $n - 1$  equations, we have a free variable that may assume any real value.

Then, by defining an arbitrary value for this free variable and solving the  $(n - 1) \times (n - 1)$  system, we get a single solution  $x_0$  one they are linearly independent. Then, fixing a new value for the free variable, and solving again the linear system, we will get another value  $x_1$ . Then, with these two values we are capable of defining a equation for the line formed by the intersection of the hyperplanes

$$y = x_1 + (x_1 - x_0) \cdot \lambda$$

## 5 Eigenvalues and Eigenvectors

Find the eigenvalues and eigenvectors of the matrix  $A = uu^T$ , where  $u \in \mathbb{R}^n$ .

*Solution*

We have define that the matrix  $A$  is equal the outer product  $uu^T$ . Then, every line of  $A$  is a linear combination of  $u^T$ , so the rank of  $A$  is equal to 1.

$$uu^T = \begin{bmatrix} u_1 \\ u_2 \\ \vdots \\ u_n \end{bmatrix} \begin{bmatrix} u_1 & u_2 & \cdots & u_n \end{bmatrix}$$

$$\begin{aligned} A &= uu^T \\ A \cdot u &= uu^T \cdot u = u \cdot \langle u^T, u \rangle \\ A \cdot u &= \langle u^T, u \rangle \cdot u \end{aligned}$$

Then,  $\lambda = \langle u^T, u \rangle$  is one eigenvalue associated with the eigenvector  $u$ .

*NOTE: There are some other eigenvalues, and apparently we are supposed to prove that they are all zero eigenvalues, I can't do it right now, I'll try to prove it afterwards*

## 6 Eigenvalues and Eigenvectors and Orthogonality

Prove that the eigenvectors of a matrix associated with distinct eigenvalues are linearly independent, and if the matrix is symmetric, they are orthogonal.

## 7 Positive Definite Matrix and Eigenvalues

Prove that the eigenvalues of a symmetric matrix are positive if and only if the matrix is positive definite.

*Solution*

We are going to proceed with the technique for biconditional proof.

$\Rightarrow$  Let  $A$  be a symmetric matrix with all its eigenvalues positive. Then, we can decompose this matrix in the following manner:

$$A = Q\Lambda Q^T$$

where:

$Q$  is a orthogonal matrix (i.e  $QQ^T = I$ )

$\lambda$  is a diagonal matrix with its eigenvalues.

Let  $x \neq 0$ , then

$$x^T Ax = x^T Q\Lambda Q^T X$$

Furthermore, we can have  $\Lambda = \sqrt{\Lambda}\sqrt{\Lambda}$ , then

$$\begin{aligned} x^T Ax &= x^T Q\sqrt{\Lambda}\sqrt{\Lambda}Q^T X \\ &= ||\sqrt{\Lambda}Q^T x||_2^2 \end{aligned}$$

Then, since  $\sqrt{\Lambda}Q^T$  is non-singular,  $x$  is different from 0 and a norm is positive, we conclude that  $A$  have to be positive definite.

$\Leftarrow$  Let  $B$  be a positive definite matrix. Then,

$$\begin{aligned} Av &= \lambda v \\ v^T Av &= v^T \lambda v \end{aligned}$$

Considering  $A$  as positive definite, the left-hand side of the equation is positive, then  $\lambda$  must be positive. This concludes the proof that the eigenvalues must be positive.

## 8 Eigenvalues of Invertible Matrices

Prove that if  $\lambda$  is an eigenvalue of a non-singular matrix  $A$ , then  $\frac{1}{\lambda}$  is an eigenvalue of  $A^{-1}$ .

*Solution*

$$\begin{aligned} Av &= \lambda v \\ A^{-1}Av &= \lambda A^{-1}v \\ Iv &= \lambda A^{-1}v \\ \frac{1}{\lambda}v &= A^{-1}v \end{aligned}$$

Therefore,  $\frac{1}{\lambda}$  is an eigenvalue of  $A^{-1}$ .

## 9 Eigenvalues

Prove that  $A \in \mathbb{R}^{n \times n}$  is singular if and only if 0 is an eigenvalue.

*Solution*

$\Rightarrow$  Let  $A$  be a singular matrix, then  $\det(A) = 0$ . For the characteristic equation:

$$\det(A - I\lambda) = 0$$

, where  $\lambda$  are the eigenvalues.

Hence,  $\lambda = 0$  is an eigenvalue of the singular matrix  $A$ .

$\Leftarrow$  Let  $\lambda = 0$  be an eigenvalue of the square matrix  $A$  associated with the eigenvector  $v$ . Then,  $Av = 0$ . Eigenvectors are by definition non-zero, so the solution set for the system is not trivial so the matrix  $A$  is singular.

## 10 Limits of Sequences

Suppose  $\lim_{k \rightarrow \infty} x_k = \alpha$ . Prove that if  $\alpha > \beta$ , there exists  $M > 0$  such that for all  $k \geq M$ , we have  $x_k > \beta$ .

*Solution*

Considering the fact that  $\lim_{k \rightarrow \infty} x_k = \alpha$ , then for every  $\epsilon > 0$  there exists  $k > k_0$  such that:

$$\begin{aligned} |x^k - \alpha| &< \epsilon \\ -\epsilon &< x^k - \alpha < \epsilon \\ \alpha - \epsilon &< x^k < \alpha + \epsilon \\ \beta - \epsilon &< \alpha - \epsilon < x^k < \alpha + \epsilon \end{aligned}$$

Since there is  $k$  for every  $\epsilon > 0$ , we can take  $\epsilon = \alpha - \beta$ . Then,

$$\begin{aligned} \alpha - (\alpha - \beta) &< x^k \\ \beta &< x^k \end{aligned}$$

## 11 Limit of Sequence

Prove que if  $\lim_{k \rightarrow \infty} x_k = \alpha$  and for all  $k \geq 0$ ,  $x_k \geq \beta$ , then  $\alpha \geq \beta$ . If we change the  $\geq$  sign to  $>$ , does the statement still hold? Prove or provide a counterexample.

*Solution*

As the limit of  $x_k$  as  $k$  goes to the positive infinity, we have that for every  $\epsilon$  greater than 0 we find a  $k > k_0$  such that:

$$|x_k - \alpha| < \epsilon$$

Then,

$$\begin{aligned} |x_k - \alpha| &< \epsilon \\ -\epsilon &< x_k - \alpha < \epsilon \\ \alpha - \epsilon &< x_k < \alpha + \epsilon \\ \beta &\leq x_k < \alpha + \epsilon \end{aligned}$$

Then

$$\beta < \alpha + \epsilon$$

Taking:  $\epsilon = \alpha - \beta$

$$\beta < \alpha + \alpha - \beta$$

Hence  $\beta < \alpha$

## 12 Convergence of Sequences

If  $\{x_k\}$  is a convergent sequence, is this sequence bounded? Is the converse true?

## 13 Norms

Prove that the following functions are norms:

- (a)  $|\cdot|_\infty : \mathbb{R}^n \rightarrow \mathbb{R}$ ,  $|x|_\infty = \max_{1 \leq i \leq n} |x_i|$ ;
- (b)  $|\cdot|_1 : C([a, b]) \rightarrow \mathbb{R}$ ,  $|f|_1 = \int_a^b |f(x)| dx$  (where  $C([a, b])$  represents continuous functions on  $[a, b] \rightarrow \mathbb{R}$ ).

## 14 Jacobians

Consider the functions  $f : \mathbb{R}^m \rightarrow \mathbb{R}^p$  and  $g : \mathbb{R}^n \rightarrow \mathbb{R}^m$  with Jacobians  $J_f \in \mathbb{R}^{p \times m}$  and  $J_g \in \mathbb{R}^{m \times n}$ , respectively. Find the Jacobian of the composite function  $h : \mathbb{R}^n \rightarrow \mathbb{R}^p$  given by  $h(x) = f(g(x))$ .

## 15 Gradient and Hessian

Compute the gradient and Hessian of the functions  $f : \mathbb{R}^n \rightarrow \mathbb{R}$  below:

- (a)  $f(x) = a^T x$ ;
- (b)  $f(x) = 2x^T Ax + b^T x + c$ , where  $A \in \mathbb{R}^{n \times n}$ ,  $b \in \mathbb{R}^n$ ,  $c \in \mathbb{R}$ ;
- (c)  $f(x) = g^T(x)g(x) = |g(x)|_2^2$ , where  $g : \mathbb{R}^n \rightarrow \mathbb{R}^m$ .

## 16 Gradient and Hessian

Let  $A \in \mathbb{R}^{m \times n}$ ,  $b \in \mathbb{R}^m$ . For  $x \in \mathbb{R}^n$ , we define  $q(x) = f(Ax + b)$  with  $f : \mathbb{R}^m \rightarrow \mathbb{R}$ . Calculate the gradient and Hessian of the function  $q$ .