

B.TECH. SECOND YEAR

(III SEM. CSE/IT/CCE)

ACADEMIC YEAR: 2020-2021



COURSE NAME: ENGINEERING MATHEMATICS III

COURSE CODE : MA 2101

LECTURE SERIES NO: UNIT-III (LECTURE NO. 14-22)

CREDITS : 3

MODE OF DELIVERY: ONLINE (POWER POINT PRESENTATION)

FACULTY : DR. REEMA JAIN

EMAIL-ID : reema.jain@laipur.manipal.edu

PROPOSED DATE OF DELIVERY: August 17, 2020



VISION

Global Leadership in Higher Education and Human Development

MISSION

- Be the most preferred University for innovative and interdisciplinary learning
- Foster academic, research and professional excellence in all domains
- Transform young minds into competent professionals with good human values

VALUES

Integrity, Transparency, Quality,
Team Work, Execution with Passion, Humane Touch



SESSION OUTCOME

"TO UNDERSTAND THE CONCEPT OF TREES AND APPLY THE TREE ALGORITHMS TO ANALYZE THE SHORTEST PATH PROBLEMS"



ASSIGNMENT

QUIZ

MID TERM EXAMINATION -I & II END TERM EXAMINATION

ASSESSMENT CRITERIA



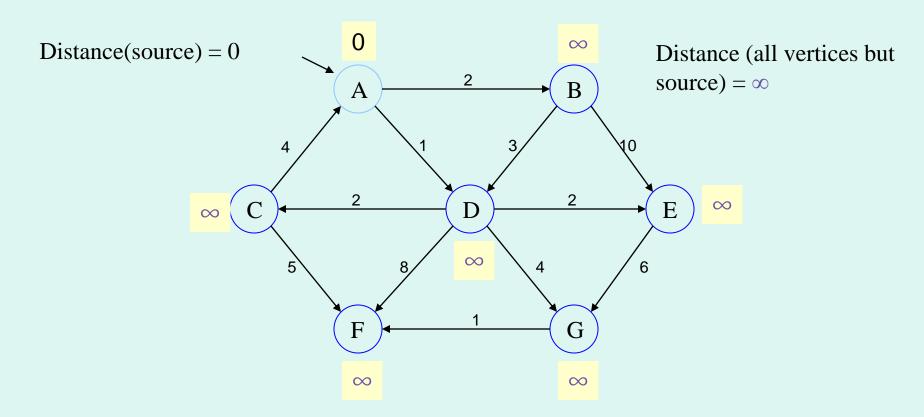
Approach of Dijkstra's Algorithm

- The algorithm computes for each vertex u the distance to u from the start vertex v, that is, the weight of a shortest path between v and u.
- The algorithm keeps track of the set of vertices for which the distance has been computed, called the cloud C.
- Every vertex has a label D associated with it. For any vertex u, D[u] stores an approximation of the distance between v and u. The algorithm will update a D[u] value when it finds a shorter path from v to u.
- When a vertex u is added to the cloud, its label D[u] is equal to the actual (final) distance between the starting vertex v and vertex u.

Dijkstra's Algorithm Pseudocode

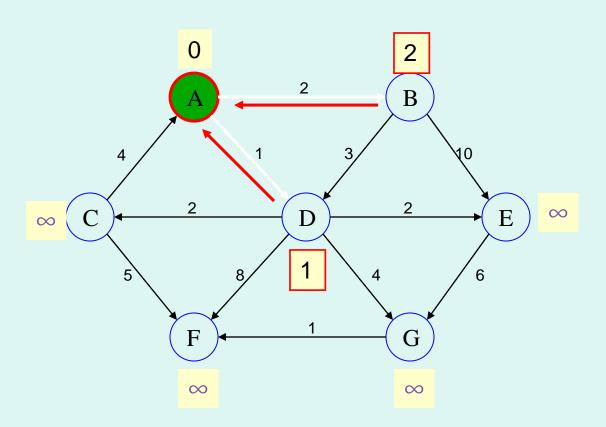
```
Dijkstra(v1, v2):
  for each vertex v:
                                      // Initialization
     v's distance := infinity.
     v's previous := none.
  v1's distance := 0.
  List := {all vertices}.
  while List is not empty:
     v := remove List vertex with minimum distance.
          mark v as known.
     for each unknown neighbor n of v:
        dist := v's distance + edge (v, n)'s weight.
        if dist is smaller than n's distance:
          n's distance := dist.
          n's previous := v.
  reconstruct path from v2 back to v1,
  following previous pointers.
```

• Initialization

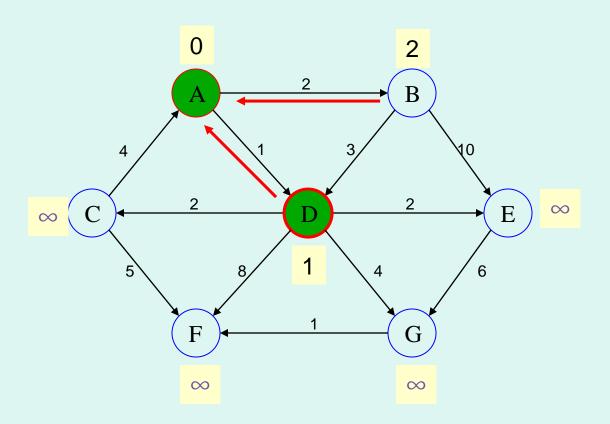


Pick vertex in List with minimum distance

• Update neighbours' distance

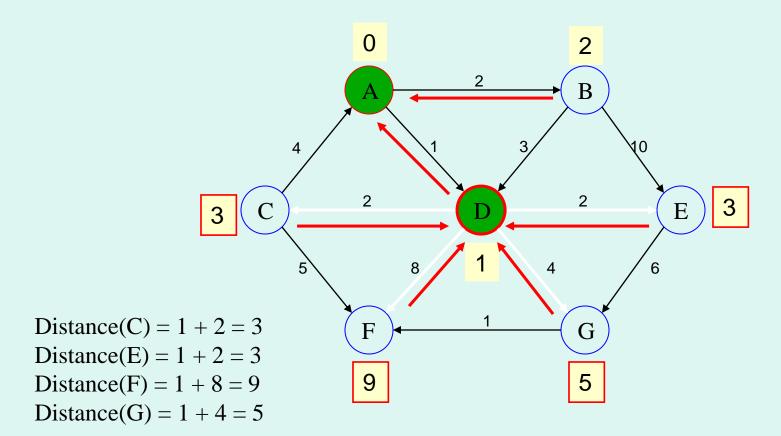


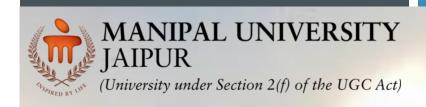
• Remove vertex with minimum distance



Pick vertex in List with minimum distance i.e. D

• Update neighbors





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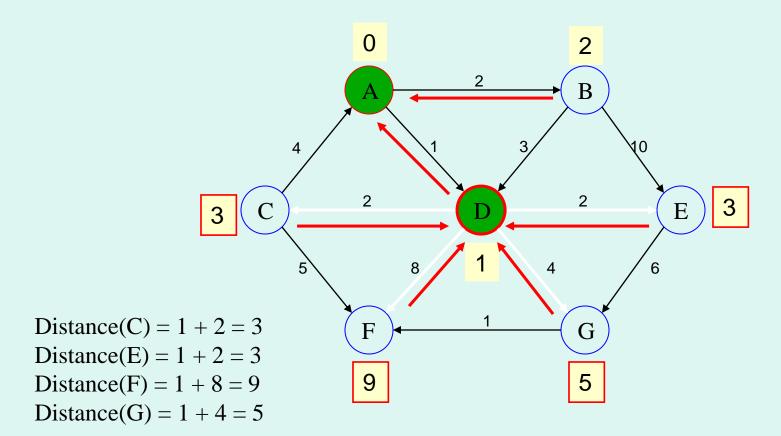
QUIZ

MID TERM EXAMINATION -I & II END TERM EXAMINATION

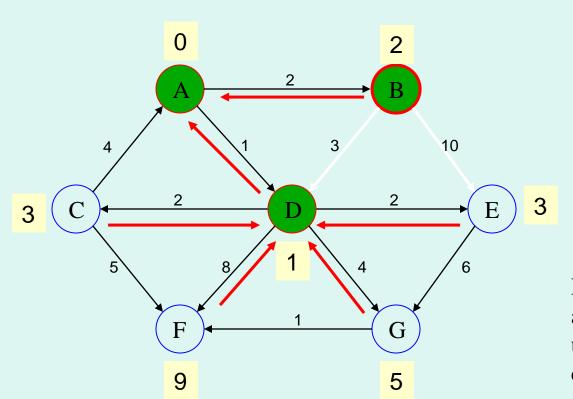
ASSESSMENT CRITERIA



• Update neighbors

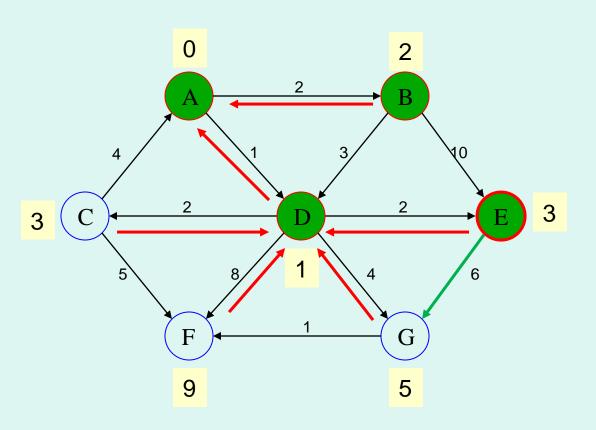


• Pick vertex in List with minimum distance (B) and update neighbors

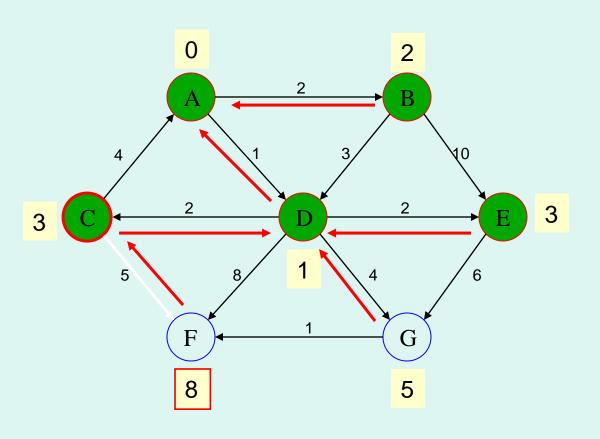


Note: distance(D) not updated since D is already known and distance(E) not updated since it is larger than previously computed

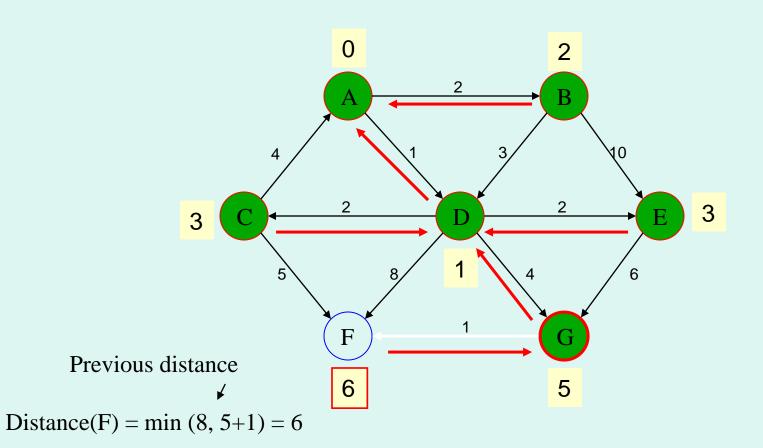
Pick vertex List with minimum distance (E) and update neighbors



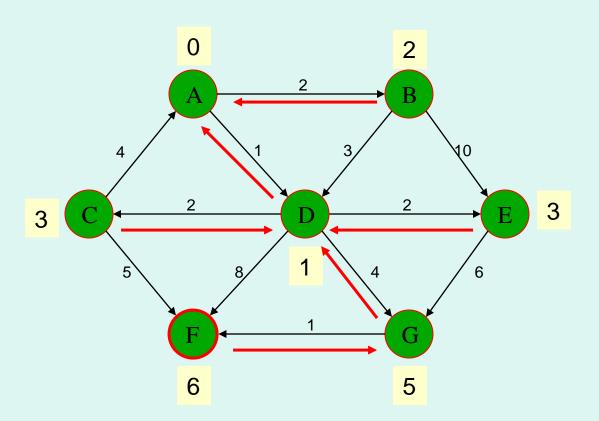
Pick vertex List with minimum distance (C) and update neighbors



Pick vertex List with minimum distance (G) and update neighbors



• Example (end)



Pick vertex not in S with lowest cost (F) and update neighbors

THANK YOU