Pros and cons of propositional logic

- Propositional logic is **declarative**: pieces of syntax correspond to facts
- Propositional logic allows partial/disjunctive/negated information
  (unlike most data structures and databases)
- Propositional logic is **compositional**:
  meaning of $B_{1,1} \wedge P_{1,2}$ is derived from meaning of $B_{1,1}$ and of $P_{1,2}$
- Meaning in propositional logic is **context-independent**
  (unlike natural language, where meaning depends on context)
- Propositional logic has very limited expressive power
  (unlike natural language)
  E.g., cannot say "pits cause breezes in adjacent squares"
  except by writing one sentence for each square

First-order logic

Whereas propositional logic assumes world contains **facts**,
first-order logic (like natural language) assumes the world contains

- Objects: people, houses, numbers, theories, Ronald McDonald, colors, baseball games, wars, centuries . . .
- Relations: red, round, bogus, prime, multistoried . . .,
  brother of, bigger than, inside, part of, has color, occurred after, owns, comes between, . . .
- Functions: father of, best friend, third inning of, one more than, end of . . .

Interacting with FOL KBs

Suppose a wumpus-world agent is using an FOL KB
and perceives a smell and a breeze (but no glitter) at $t = 5$:

$Tell(KB, Percept([Smell, Breeze, None], 5))$
$Ask(KB, \exists a \;\; Action(a, 5))$

I.e., does KB entail any particular actions at $t = 5$?

Answer: $Yes, \; \{a/Shoot\}$ $\quad\leftarrow$ substitution (binding list)

Given a sentence S and a substitution σ,
$S\sigma$ denotes the result of plugging σ into S; e.g.,
$S = Smarter(x, y)$
$\sigma = \{x/Hillary, y/Bill\}$
$S\sigma = Smarter(Hillary, Bill)$

$Ask(KB, S)$ returns some/all σ such that $KB \models S\sigma$

Knowledge base for the wumpus world

"Perception"

$\forall\, b, g, t \;\; Percept([Smell, b, g], t) \;\Rightarrow\; Smelt(t)$

$\forall\, s, b, t \;\; Percept([s, b, Glitter], t) \;\Rightarrow\; AtGold(t)$

Reflex: $\forall\, t \;\; AtGold(t) \;\Rightarrow\; Action(Grab, t)$

Reflex with internal state: do we have the gold already?

$\forall\, t \;\; AtGold(t) \land \neg Holding(Gold, t) \;\Rightarrow\; Action(Grab, t)$

$Holding(Gold, t)$ cannot be observed

$\Rightarrow$ keeping track of change is essential

Deducing hidden properties

Properties of locations:
$\forall\, x,t\;\; At(Agent,x,t) \land Smelt(t) \;\Rightarrow\; Smelly(x)$
$\forall\, x,t\;\; At(Agent,x,t) \land Breeze(t) \;\Rightarrow\; Breezy(x)$

Squares are breezy near a pit:

Diagnostic rule—infer cause from effect

$$\forall\, y\;\; Breezy(y) \;\Rightarrow\; \exists\, x\;\; Pit(x) \land Adjacent(x,y)$$

Causal rule—infer effect from cause

$$\forall\, x,y\;\; Pit(x) \land Adjacent(x,y) \;\Rightarrow\; Breezy(y)$$

Neither of these is complete—e.g., the causal rule doesn't say whether squares far away from pits can be breezy

Definition for the $Breezy$ predicate:

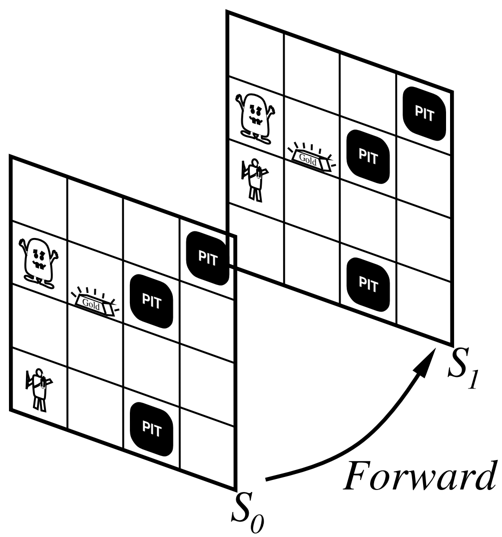
$$\forall\, y\;\; Breezy(y) \;\Leftrightarrow\; [\exists\, x\;\; Pit(x) \land Adjacent(x,y)]$$

Keeping track of change

Facts hold in situations, rather than eternally
E.g., $Holding(Gold, Now)$ rather than just $Holding(Gold)$

Situation calculus is one way to represent change in FOL:
Adds a situation argument to each non-eternal predicate
E.g., Now in $Holding(Gold, Now)$ denotes a situation

Situations are connected by the $Result$ function
$Result(a, s)$ is the situation that results from doing a in s



Describing actions I

"Effect" axiom—describe changes due to action

$\forall s \;\; AtGold(s) \;\Rightarrow\; Holding(Gold, Result(Grab, s))$

"Frame" axiom—describe **non-changes** due to action

$\forall s \;\; HaveArrow(s) \;\Rightarrow\; HaveArrow(Result(Grab, s))$

Frame problem: find an elegant way to handle non-change

(a) representation—avoid frame axioms

(b) inference—avoid repeated "copy-overs" to keep track of state

Qualification problem: true descriptions of real actions require endless caveats—what if gold is slippery or nailed down or . . .

Ramification problem: real actions have many secondary consequences—what about the dust on the gold, wear and tear on gloves, . . .

Describing actions II

Successor-state axioms solve the representational frame problem

Each axiom is "about" a **predicate** (not an action per se):

$$\begin{array}{lcl} \text{P true afterwards} & \Leftrightarrow & [\text{an action made P true} \\ & \vee & \text{P true already and no action made P false}] \end{array}$$

For holding the gold:

$$\forall\, a, s \;\; Holding(Gold, Result(a,s)) \;\Leftrightarrow$$
$$[(a = Grab \wedge AtGold(s))$$
$$\vee\, (Holding(Gold, s) \wedge a \neq Release)]$$

Making plans

Initial condition in KB:

$At(Agent, [1,1], S_0)$
$At(Gold, [1,2], S_0)$

Query: $Ask(KB, \exists\, s \;\; Holding(Gold, s))$
i.e., in what situation will I be holding the gold?

Answer: $\{s/Result(Grab, Result(Forward, S_0))\}$
i.e., go forward and then grab the gold

This assumes that the agent is interested in plans starting at S_0 and that S_0 is the only situation described in the KB

Making plans: A better way

Represent plans as action sequences $[a_1, a_2, \ldots, a_n]$

$PlanResult(p, s)$ is the result of executing p in s

Then the query $Ask(KB, \exists\, p \;\; Holding(Gold, PlanResult(p, S_0)))$
has the solution $\{p/[Forward, Grab]\}$

Definition of $PlanResult$ in terms of $Result$:

$$\forall\, s \;\; PlanResult([\,], s) = s$$

$$\forall\, a, p, s \;\; PlanResult([a|p], s) = PlanResult(p, Result(a, s))$$

Planning systems are special-purpose reasoners designed to do this type of inference more efficiently than a general-purpose reasoner