

IRSensor::detectObstacle



```
graph LR; A[IRSensor::detectObstacle] --> B[IRSensor::readADC]
```

The diagram consists of two rectangular boxes connected by a blue arrow. The left box is gray and contains the text 'IRSensor::detectObstacle'. The right box is white and contains the text 'IRSensor::readADC'. A blue arrow points from the right side of the gray box to the left side of the white box.

IRSensor::readADC