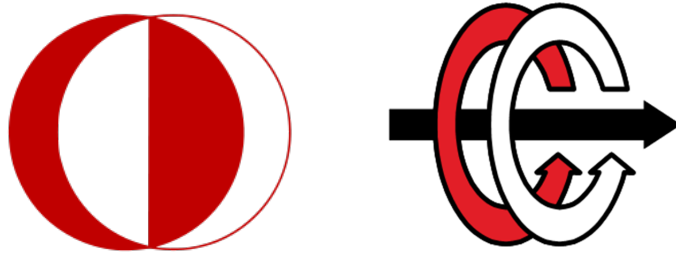


EE462 Spring 2016

Project 0

DC Motor Drive and Analysis

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Middle East Technical University

Electrical and Electronics Engineering Department

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1 Brief Explanation

These report will try to explain and give information about DC Motor drive and analysis . The wanted specific details are,

- A short info about the motor (voltage, current, power ratings etc.)
- Short info about the power source and control system
- Graphs showing acceleration curve from stationary to rated speed
- Start-up current graphs
- Produced torque during startup

2 Results

In that project,I used Chopper-Fed DC Motor Drive Example.

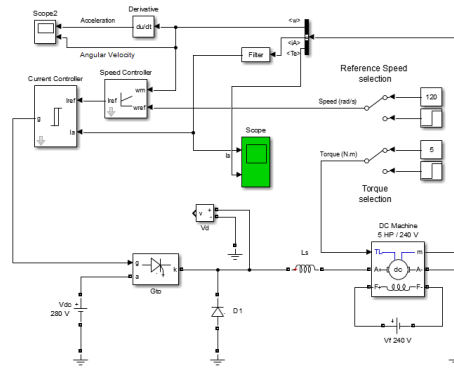


Figure 1: Simulink Diagram of Chopper-Fed DC Motor Drive

DC Motor Properties

I looked motor properties from Simulink DC Motor block,and properties are,

- 240V
- Nominal 5A(Maximum 30A)
- $\approx 240 * 5 = 1.2kW$
- 300V field voltage
- 5 HP

-While looking and testing different motor selection, I realised that when I decreased the voltage of the field, field current was weakening .So,

- Induced Voltage(E_a) $\downarrow \rightarrow$ RotorCurrent(I_a) $\uparrow \rightarrow$ MotorTorque(T_m) \uparrow

Finally,when motor torque increased our acceleration will increase,so our speed will increase . Then our induced voltage will increase and hopefully our system will be again in steady-state .[2]

-!!! about HP calculation , because

$$HP = \text{Volt} * \text{Ampere} * \text{eff} / 746$$

and if we choose our $HP = 1, \text{Volt} = 240V, I = 5A$ our $\text{Eff} \approx 3$

That efficiency value is too small.Tomorrow I will look DC motor model again .

Power Source and Control Explanation

TODO

-Power Source and Control Explanation

-Graphs [OK]

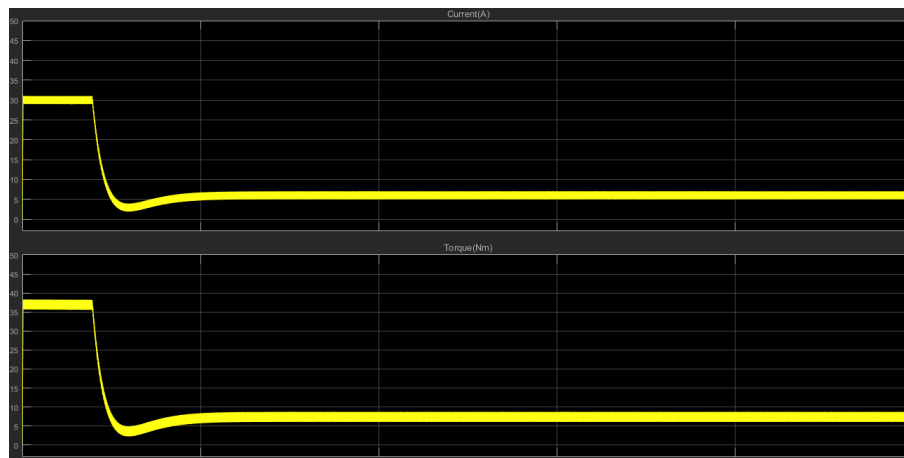


Figure 2: Torque and Current Graphs of DC Motor Drive



Figure 3: Acceleration and Velocity Graphs of DC Motor Drive

References

- [1] H. Le-Huy *Universite Laval, Quebec*. SimScape Power Systems Examples, MathWorks
- [2] <https://www.quora.com/Why-do-we-decrease-the-field-current-in-a-DC-shunt-motor-by-to-increase-the-speed-and-mechanical-output-power> *Quora*. (Loren Rademacher answer..)