



**MIDDLE EAST TECHNICAL UNIVERSITY**

**Department of Electrical and Electronics Engineering**

**EE 462 – Utilization of Electrical Energy**

**Project 0 Report**

**Umut Kilci-1937267**

## TABLE OF CONTENTS

A. Motor (voltage, current, power ratings etc) .....	2
B. Power Source and Control System .....	2
C. Related Graphs .....	3
D. REFERENCES .....	3

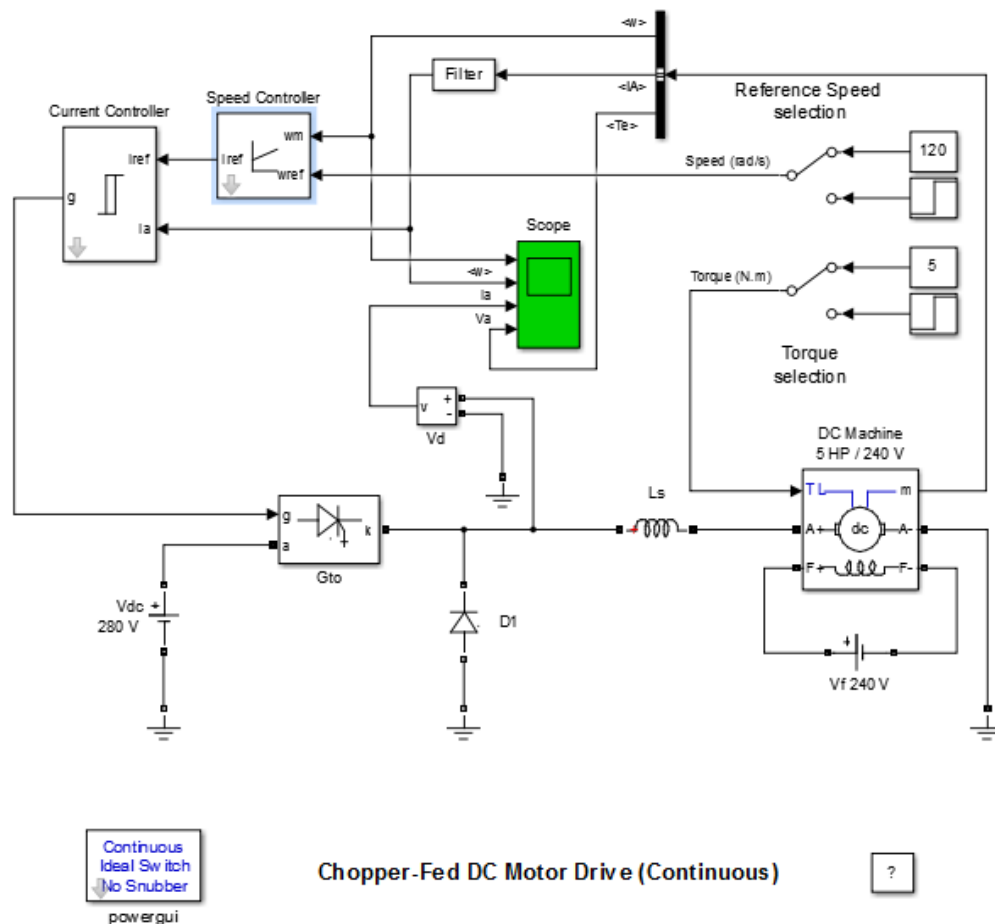


Figure 1. Chopper-Fed DC Motor Drive [1]

## A. Motor (voltage, current, power ratings etc)

5 HP (approximately 3.73 kW), 240 V wound field DC motor is used.

## B. Power Source and Control System

Power source is a constant DC source. The motor is fed through a chopper that consists of a Gto thyristor and a free-wheeling diode.

A PI speed controller outputs a current reference signal to equalize the speed of the rotor to the reference speed. A current controller compares this signal and actual current measurement from the motor and adjusts the base signal of the Gto accordingly.

### C. Related Graphs

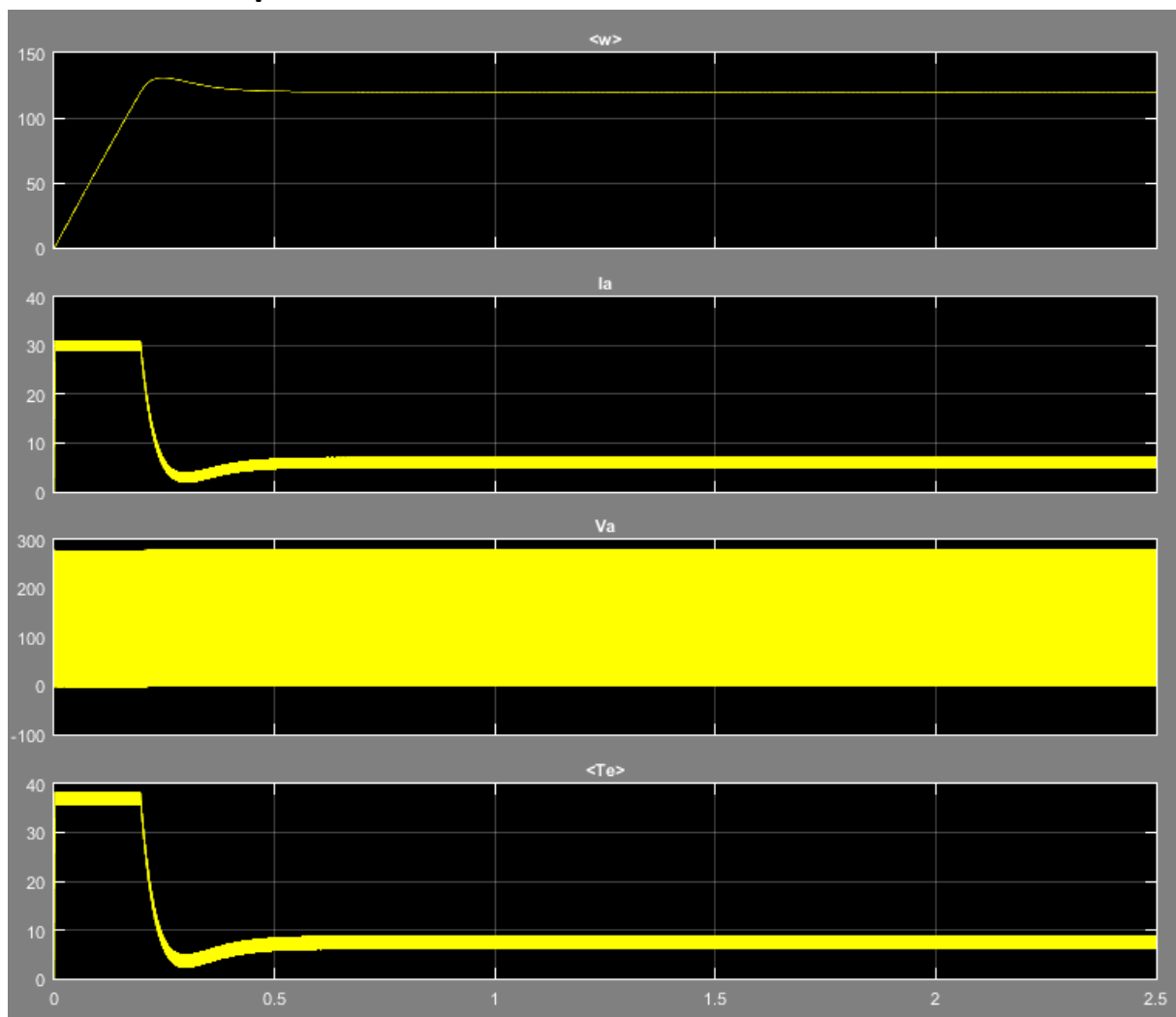


Figure 2. Speed, current, voltage and torque vs time graphs

### D. REFERENCES

- [1] <https://www.mathworks.com/help/physmod/sps/examples/chopper-fed-dc-motor-drive-continuous.html>