Set jednostavnih akcija nad slikom

Projekat iz računarske elektronike

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1 Postavka projekta

Napisati program koji sa učitava sliku u PGMA formatu i nakon učitavanja slike, sa standardnog ulaza učitava se akcija koju je potrebno izvršiti nad slikom. Naziv slike koja se učitava unosi se sa standardnog ulaza. Akcija koja se izvršava nad slikom definiše se unošenjem nekog od sledećih karaktera:

- $\bullet\,$ rl Rotiranje slike za 90 $^\circ$
- $\bullet\,$ rr Roti
ranje slike za -90 $^\circ$
- $\bullet\,$ rf Roti
ranje slike za 180 $^\circ$
- mh Horizontalno ogledanje slike
- mf Vertikalno ogledanje slike

2 Koncept

U ovom delu izveštaja je obješnjen pristup rešavanju problema obrade slike. Sve zadate operacije predstavljaju proste transformacije nad slikom, tj. matricom..

2.1 Rotiranje

Budući da je traženo rotiranje 90° a ne za proizvoljan ugao, dovoljno je samo proći kroz celu matricu i zameniti odgovarajuće indexe. Pretpostavimo da je slika A dimenzija NxM, tj. da ima N redova i M kolona, shodno tome elementi nove matrice B, invertovanih dimenzija MxN, se formiraju na sledeći način:

$$B[i][j] = A[j][M - i - 1] \tag{1}$$

Ovim je objašnjeno rotiranje za 90°. Za rotiranja od 180° i -90° je ili potrebno više puta koristiti objašnjeno rotiranje ili koristiti odgvarajuću zavisnost indexa.

2.2 Vertikalno ogledanje

Slično kao i sa rotiranjem korišćena je zavisnost indeksa piskela izlazne matrice i odgovarajućeg piksela izlazne matrice. U slucaju vertikalnog ogledanja :

$$B[i][j] = A[n-i-1][j]; (2)$$

2.3 Horizontalno ogledanje

Suprotan problem vertikalnom ogledanju, tj. ovaj put je potrebno izvršiti ogledanje po horizontalnoj osi:

$$B[i][j] = A[i][M - j - 1]; (3)$$

3 Tok programa

Za procedure u kojima moze doći do greške postoji prost mehanizmam Exceptions. Exceptions je promneljiva koja sadrzi status uspeha procedure. Kod je podeljen u više logičkih celina. U procedurima je grupisan kod koji se potencijalno više puta koristi, od ostalih delova koda su napravljeni makroi radi bolje preglednosti koda. Kod je napisan u Irvine MASM asmebleru. Od ugradjenih funkcija iz irvione biblioteke su korićenje sledeće:

- ReadString
- CreateOutputFile
- mWrite
- WriteToFile
- CloseFile
- WriteDec
- Crlf

• ParseDecimal32

Procedure koje se nalaze u kodu su :

- WriteToImage Procedura za ispis buffera u file-a(ACII matricu)
- ReadFromImage Procedura za čitanje ASCII matrice(file-a) u buffer
- Variable Procedura za header-a slike
- rotateLeft Procedura za rotiranje "integer,, matrice za 90°
- rotate180 Procedura za rotiranje "integer,, matrice za 180°
- rotateRigth Procedura za rotiranje "integer,, matrice za -90°
- mirrorHor Procedura za horiznotalno ogledanje "integer,, matrice
- mirrorVer Procedura za vertikalno ogledanje "integer, matrice 90°

Pored napisanih procedura kod sadrži i nekoliko makro-a. U nastavku je objašn-jen sam tok programa.

U main proceduri se prvo poziva **ReadFromImage** procedura koja u promenljivu **InputBuffer** upiše ceo ulazni fajl. Nakon toga se poziva **Variables** iz koje se dobijaju dimenzije slike i maksimalna vrednost piksela. Pošto ASCII matrica nije pogodna za dalju obradu ona se makroom kopira u "integer, matricu. Integer matrica je matrica u kojoj svaki piksel ima jedan bajt za razliku od učitane matrice gde je svaka cifra piksela ASCII karakter pa samim tim jedan piksel sadrži od 1 do 3 bajtova. Nakon toga se poziva funkcija koju je korisnik uneo sa standardnog ulaza (rotate90, rotate180, rotate270, mirrorHor, mirrorVer). Izlaz procedure se smešta u pomoćni buffer. Nakon toga potrebno je prvo dodati header iz originalne slike (Ukoliko je pozvana rotateRight ili rotateLeft potrebno je invertovati dimenzije slike. Za kraj je potrebno pozvati makro za prebacivanje ovakve matrice u ASCII matricu sa dodatim headerom i proceduru **WriteToImage**.

3.1 Korisnički interfejs

Korisnički interfejs se sastoji od 3 dela. Pitanje za ime ulaznog fajla, željene operacije na učitanom slikom i ime izlaznog fajla.

4 Test primeri

Program je testiran na slikama koje su date sa postavom projekta. U nastavku je pokazan rad programa na slici balloons.pgm.



Nakon poziva procedure ${\bf RotateLeft}$



Nakon poziva procedure $\mathbf{RotateRight}$



Nakon poziva procedure ${f Rotate 180}$



Nakon poziva procedure ${\bf mirrorHor}$



Nakon poziva procedure $\mathbf{mirrorVer}$



Appendix A Code

```
;Project number 5 :
;Implements basic operations for image : rotate left, rotate right, mirror left,
    rotate 180 degrees , mirror right and mirror left
;GitHub repository : https://github.com/vule12345/RE.git

INCLUDE Irvine32.inc
INCLUDE macros.inc

BUFFER_SIZE = 256*256*5
POM_SIZE = 50 * 50 * 4

.data
InputBuffer BYTE BUFFER_SIZE DUP(? )
TempBuffer BYTE BUFFER_SIZE DUP(? )
OutputBuffer BYTE BUFFER_SIZE DUP(? )
ImageBuffer BYTE BUFFER_SIZE DUP(? )
ProcedureHelper BYTE BUFFER_SIZE DUP(? )
```

```
ProcedureHelper1 BYTE BUFFER_SIZE DUP(? )
pomBuff BYTE POM_SIZE DUP(? )
addrese_First_M DWORD ?
size_M WORD 0
size_N WORD 0
counter_A DWORD 2
max_Value WORD ?
InputFilename BYTE 80 DUP(0)
Outfilename BYTE 80 DUP(0)
fileHandle HANDLE ?
stringLength DWORD ?
i DWORD ?
j DWORD ?
N DWORD ?
M DWORD ?
NumOfPixels DWORD ?
Exception BYTE ?
stringIn DWORD ?
DigitHelper BYTE 3 DUP(? )
FinalImageSize DWORD ?
. code
 intToStrmacro macro
           Local petlja1, petlja2
 petlja1:
   mov ebx, 10
    xor edx, edx
    div ebx
   mov DigitHelper[esi], dl
    inc esi
    cmp eax, 0
   mov ebx,esi
    jz petlja2
    jmp petlja1
  petlja2:
    sub ebx,1
    mov dl, DigitHelper[ebx]
    add edx,30h
    mov byte ptr ImageBuffer[edi], dl
    inc edi
    cmp ebx,0
    jnz petlja2
 endm
main PROC
  ;Load ASCII image to InputBuffer
  call ReadFromImage
  ;Proc ReadfromImage raises Exception if there were any errors
  mov eax, 1
  cmp al, Exception
 jz quit
  mov esi,OFFSET InputBuffer
  mov ecx, SIZEOF InputBuffer
  mov edi,OFFSET pomBuff
  push\ max\_Value
  push addrese_First_M
    push size_M
```

```
push size_N
push esi
push ecx
push edi
call Variables
add esp,12
pop size_N
pop size_M
pop addrese_First_M
pop max_Value
mov eax,0
;Move image width end heigth to N and M adn
;calculate ImageSize
xor eax, eax
mov ax, size_N
imul ax, size_{-}M
sub eax, 1
mov [NumOfPixels] , eax
xor eax,eax
mov ax, size_N
mov N, eax
xor eax,eax
mov ax, size_M
mov M, eax
;Copy Input to BYTE matrix
cld
mov ecx,0
mov esi, 0
mov edx, addrese_First_M
mov edi, OFFSET TempBuffer
{\tt copy\_image:}
  cmp esi, NumOfPixels
  jz nastavak
  xor eax,eax
 mov al, byte ptr [edx+ecx]
  call IsDigit
  jnz maybeNewLine
  inc ecx
  jmp copy_image
{\tt maybe New Line:}
  push eax
  xor eax,eax
  mov al, byte ptr [edx+ecx+1]
  call IsDigit
  jz writeToOutput
  inc ecx
  {\rm jmp\ copy\_image}
writeToOutput:
  call ParseDecimal32
  ;call WriteDec
  mov [edi+esi], eax
  ;mWrite "
  inc esi
  inc ecx
  add edx, ecx
  mov ecx, \theta
  pop eax
```

```
{\sf jmp\ copy\_image}
nastavak:
;Rest of proccessing
; push M
; push N
 ;push offset OutputBuffer
  ;push offset TempBuffer
  ;call mirrorVer
  ;add esp, 16
 ;User interface
 mWrite "Enter desired operation: "
 mov edx,OFFSET stringIn
   mov ecx,3
   call ReadString
mov eax, stringIn
mov eax, 6C72h
cmp eax, stringIn
jnz nextOp
 ;Rotate left
 push NumOfPixels
 push M
 push N
 push offset OutputBuffer
  push offset TempBuffer
  call rotate90
 add esp, 20
 mov eax, N
 mov ebx, M
 mov N, ebx
 mov M, eax
  jmp PrintingToOutput
nextOp:
  ;rotate right
  mov eax, 7272h
 cmp eax, stringIN
  jnz next0p1
 push NumOfPixels
  push M
  push N
 push offset OutputBuffer
  push offset TempBuffer
  call rotate270
 add esp, 20
 mov eax, N
 mov ebx, M
 mov N, ebx
 mov M, eax
 jmp PrintingToOutput
nextOp1:
;rotate 180
 mov eax, 6672h
  cmp eax, stringIN
```

jnz next0p2

```
push NumOfPixels
  push M
  push N
  push offset OutputBuffer
  push offset TempBuffer
  call rotate180
  add esp, 20
  jmp PrintingToOutput
next0p2:
;mirror horizontally
  mov eax, 686Dh
  cmp eax, stringIN
  jnz next0p3
  push M
  push N
  push offset OutputBuffer
  push offset TempBuffer
  call mirrorHor
  add esp, 16
  jmp PrintingToOutput
next0p3:
;mirror vertically
 mov eax, 766Dh
  cmp eax, stringIN
  jnz notAllowed
  push M
  push N
  push offset OutputBuffer
  push offset TempBuffer
  call mirrorVer
  add esp, 16
PrintingToOutput:
; Print header to output file
mov ecx, 0
mov edi, 0
;P2
mov byte ptr ImageBuffer[edi], 50h
mov byte ptr ImageBuffer[edi], 32h
inc edi
mov byte ptr ImageBuffer[edi], 20h
inc edi
;Width
mov esi,0
mov eax, M
intToStrmacro
mov byte ptr ImageBuffer[edi], 20h
inc edi
;Height
mov esi,0
mov eax, N
\verb"intToStrmacro"
mov byte ptr ImageBuffer[edi], 20h
```

```
inc edi
  ;Maximum pixel value
 mov esi.0
 xor eax, eax
 mov ax, max_Value
 intToStrmacro
  ;Creating outputImage from matrix of ,,integeres,,
  ;Just allocating 1 byte for every digit and adding space after each number
 while1:
   mov byte ptr ImageBuffer[edi], 20h
   inc edi
   mov esi,0
   cmp ecx, NumOfPixels
   jz writings
   xor eax, eax
   mov al, byte ptr OutputBuffer[ecx]
   inc ecx
   \verb"intToStrmacro"
   jmp while1
 writings:
 mov FinalImageSize, edi
 ;Call to WriteImage procedure
  ;Just writing final matrix to file
 call WriteToimage
 cmp al, Exception
 jz quit
 quit:
 exit
 notAllowed:
 mWrite "Operation not allowed"
main ENDP
WriteToImage PROC
;Procedure for copying data from OutPutBuffer to output file
  ;Reading output file name for std
 mWrite "Enter name of output file: "
 mov edx, OFFSET Outfilename
 mov ecx, SIZEOF Outfilename
 call ReadString
 mov Exception, 0
 ;Creating new file with entered name
 mov edx, OFFSET Outfilename
 call CreateOutputFile
 mov fileHandle, eax
  ;Checking for errors
 cmp eax, INVALID_HANDLE_VALUE ;Comparing if error is found
 jne out_file_ok
                    ; Jump to label out_file_ok which copies data
 mWrite <"Error occcurd while trying to open output file", 0dh, 0ah> ;Print error msg
     to std
 mov Exception,1
  jmp quit
                      ;Jump to end if error occurd
```

```
;Coping OutputBuffer to outut file
  out_file_ok:
 mov eax, fileHandle
 mov edx, OFFSET ImageBuffer
 mov ecx, FinalImageSize
  call WriteToFile
                           ;Writing to file
 mov eax, fileHandle
 call CloseFile
                           ;Closing file
  quit:
 ret
WriteToImage ENDP
ReadFromImage PROC
  ; Reading input file name from std input into input_file_name variable
 mWrite "Enter name of input file ?:
 mov edx, OFFSET InputFilename
 mov ecx, SIZEOF InputFilename
 call ReadString
  mov Exception, 0
  ;Opening input file for reading data
 mov edx, OFFSET InputFilename
 call OpenInputFile
 mov fileHandle. eax
  ;Checking if there are eny mistakes
  cmp eax, INVALID_HANDLE_VALUE ; Checking if there are mistakes
  jne input_file_ok
                     ;Jump to label ,,file_is_ok" if no exception were raised
 mWrite <"Can not open wanted file", 0dh, 0ah> ;Writing to std the error which occurd
 mov Exception, 1
  jmp quit
                     ;Jump to label ,,quit" , which is above exit
  ;Reading contets of file to buffer varriable
  input_file_ok:
    mov edx,OFFSET InputBuffer
                                ;Required parametars for ReadFromFile function
    mov ecx,BUFFER_SIZE
                         ;Required parametars for ReadFromFile function
   call ReadFromFile
    jnc check_buffer_size
                             ;Jump to label for checking if buffer size is enough
    mWrite "Error occurd while trying to read from input file." ;Write reading
        error in windows box
    call WriteWindowsMsg
   mov Exception, 1
                             ;Jump to label for closing opened input file
    jmp close_input_file
  ;Checking if buffer is big enough
  check_buffer_size:
    cmp eax, BUFFER_SIZE
                             ;Buffer bigger than BUFFER_SIZE ?
    ib buf_size_ok
                           ;Jump to label for further proccesing
    mWrite <"Error occurd : buffer is too small ", Odh, Oah> ;Write error to std output
   mov Exception, 1
    jmp quit
  ;If buffer is ok
  buf_size_ok:
    mov InputBuffer[eax], 0
                               ;Inserting null terminator
                              ;Displaying file size
    mWrite "File size :"
   mov stringLength, eax
    call WriteDec
    call Crlf
  ;Closing input file
```

```
close_input_file:
    mov eax, fileHandle
    call CloseFile
 quit:
    ret
{\tt ReadFromImage\ ENDP}
rotate90 PROC c InputOffset:DWORD, OutputOffset:DWORD, N_size:DWORD, M_size:DWORD,
    img_size:DWORD
;Procedure for rotating image by 90 degrees
;param: InputOffset : Adress of input matrix
;param: OutputOffset : Adress of output matrix
;param row_size : number of rows in image
;param img\_size : complete number of bits
mov ecx , \theta
 loopus:
    push ecx
   mov eax, ecx
   mov ebx, N_{-}size
   xor edx, edx
   div ebx
   mov i, eax
                  ;eax =i/N
                  ;edx = j%N
   mov j, edx
   mul N_size; eax= i*N
   mov ebx, eax; ebx =i*N
   mov ecx, j; ecx = j
   mov eax, j
   mul M_size ; eax = j*M
   mov edi, eax; edi =j*M
   mov edx, M_{\rm size}
    sub edx, i
   sub edx, 1; edx = M-i-1
   mov esi, InputOffset
    add esi, edi
   add esi, edx
   mov al, byte ptr [esi]
   mov esi, OutputOffset
   add esi,ebx
   add esi, ecx
   mov [esi], al
   pop ecx
    \quad \text{inc ecx} \quad
    cmp ecx, img_size
    jnz loopus
    ret
rotate90 ENDP
rotate180 PROC c InputOffset:DWORD, OutputOffset:DWORD, row_size:DWORD,
    column_size:DWORD,img_size:DWORD
;Procedure for rotating image by 180 degrees
;param: InputOffset : Adress of input matrix
;param: OutputOffset : Adress of output matrix
```

```
;param row\_size : number of rows in image
;param column_size :number of columns in image
;param img_size : complete number of bits
   push img_size
   push column_size
   push\ row\_size
   push offset ProcedureHelper
   push InputOffset
   call rotate90
   add esp, 16
   push \ img\_size
   push row_size
   push\ column\_size
   push OutputOffset
   push offset ProcedureHelper
   call rotate90
   add esp, 16
    ret
rotate180 ENDP
rotate270 PROC c InputOffset:DWORD, OutputOffset:DWORD, row_size:DWORD,
    column_size:DWORD,img_size:DWORD
;Procedure for rotating image by 270 degrees
;param: InputOffset : Adress of input matrix
;param: OutputOffset : Adress of output matrix
;param row_size : number of rows in image
;param column\_size:number\ of\ columns\ in\ image
;param img\_size : complete number of bits
   push\ img\_size
   push column_size
   push\ row\_size
   push offset ProcedureHelper
   push InputOffset
   call rotate90
   add esp, 16
   push\ img\_size
   push row_size
   push column_size
   push offset ProcedureHelper1
   push offset ProcedureHelper
   call rotate90
   add esp, 16
   push\ img\_size
   push column_size
   push row_size
   push OutputOffset
   push offset ProcedureHelper1
   call rotate90
   add esp, 16
    ret
```

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rotate270 ENDP

```
mirrorHor PROC c InputOffset:DWORD, OutputOffset:DWORD, row_size:DWORD,
    column_size:DWORD
;Procedure for horizontal mirror of image
;param: InputOffset : Adress of input matrix
;param: OutputOffset : Adress of output matrix
;param row\_size : number of rows in image
;param column_size :number of columns in image
xor ebx, ebx
xor ecx, ecx
    row_loop:
    mov ecx, 0
    column_loop:
    mov eax, ebx
    mul column_size ; eax=i*M
    mov edi, eax; edi=i*M
    mov edx,eax ; edx=i*M
    add edx, column\_size
    sub edx, ecx
    sub edx, 1; edx=i*M+M-j-1
    {\sf mov} esi, {\sf InputOffset}
    add esi,edx
    mov al, [esi]
    {\tt add} \ {\tt edi}, \ {\tt ecx}
    mov esi, OutputOffset
    add esi,edi
    mov [esi], al
    inc ecx
    cmp ecx, column_size
    jnz column_loop
    inc ebx
    cmp ebx, row\_size
    jnz row_loop
    ret
mirrorHor ENDP
mirrorVer PROC c InputOffset:DWORD, OutputOffset:DWORD, N_size:DWORD, M_size:DWORD
;Procedure for vertical mirror of image
;param: InputOffset : Adress of input matrix
;param: OutputOffset : Adress of output matrix
;param row_size : number of rows in image
;param column_size :number of columns in image
xor ebx, ebx;i=0
xor ecx, ecx;j=0
    row_loop:
    mov ecx, 0
    \verb|column_loop|:
    mov eax, ebx
    mul M_size ;eax=i*M
    add eax, ecx
```

```
mov edi, eax ;edi =i*M+j
    add edi, OutputOffset
    mov eax, N_{\rm size}
    sub eax,ebx
    sub eax,1 ;eax=N-i-1
    mul M_size ;
    add eax, ecx ;eax=(N-i-1)*M+j]
    mov esi, eax
    add esi, InputOffset
   mov al, [esi]
    mov [edi], al
    inc ecx
    cmp ecx, M_size
    jnz column_loop
    inc ebx
    cmp ebx, N_{\rm size}
    jnz row_loop
    ret
mirrorVer ENDP
Variables PROC uses esi edi edx eax ebx
               LOCAL counter_m1:BYTE, degree1:WORD, size_M1:WORD, size_N1:WORD,
                    size_max:WORD
       mov size_M1,0
        mov size_N1,0
    mov counter_m1,0
   mov degree1,1
    mov size_max,0
    push ebp
    mov edi, [ebp+8]
       mov ecx, [ebp+12]
      mov esi, [ebp+16]
  to_Out_Buffer:
    lodsb
    stosb
    dec ecx
    cmp eax,'#'
    je next
    inc counter_m1
  next:
     lodsb
    stosb
    cmp eax,0ah
    je m_On
    loop next
    m_0n:
    cmp counter_m1,2
    je picture_Size
    cmp counter_m1,3
    je remember
    loop to_Out_Buffer
    remember:
```

```
mov degree1,1
 push eax
 push esi
 push ebx
 mov esi, 2
 mov ebx, 10
loop2:
   mov edx,edi
 sub edx,esi
 mov eax,0
 mov al,[edx]
 cmp al,0ah
 jz max_value_end
 sub ax,30h
 mul degree1
 add size_{-}max, ax
 mov ax,degree1
 mul bx
 mov degree1,ax
 inc esi
 jmp loop2
 {\tt max\_value\_end:}
   pop ebx
 pop esi
 pop eax
   mov ax,size_N1
 mov [ebp+20],ax
 mov ax,size_M1
 mov [ebp+22],ax
 mov eax,esi
 mov [ebp+24],eax
 mov ax,size_max
 mov [ebp+28],ax
 jmp kraj
 ;;;;
 picture_Size:
 push eax
 push esi
 push ebx
 mov esi, 2
 mov ebx, 10
loop1:
   mov edx,edi
 sub edx,esi
 mov eax,0
 mov al,[edx]
 cmp al,20h
 jz jump1
 sub ax,30h
 mul degree1
 add size_N1,ax
```

mov ax,degree1

```
mul bx
   mov degree1,ax
   inc esi
   jmp loop1
   jump1:
   mov degree1,1
jmp picture_Size1
 picture_Size1:
     inc esi
     mov edx,edi
    sub edx,esi
   mov eax,0
   mov al,[edx]
   cmp eax,0ah
   jz jump
   sub ax,30h
   mul degree1
   add size_M1,ax
   mov ax,degree1
   mul bx
   mov degree1,ax
   jmp picture_Size1
 jump:
   pop ebx
pop esi
   pop eax
   jmp to_Out_Buffer
     pop ebp
    ret
Variables ENDP
intToStrmacro macro
mov eax,0
endm
END main
```

References

- $[1]\,$ Assembly Language for X86 Processors, Kip Irvine
- [2] Prezentacije sa vežbi