

1 Analysis

1.1 Hilbert Spaces

Theorem 1.1 (Hilbert Projection). H is Hilbert space & $C \subseteq H$ closed+convex $\implies \forall x \in H \exists$ unique $y \in C$ s.t. $\|x - y\| = \inf_{z \in C} \|x - z\|$ (i.e., y closest to x). C is subspace $\implies \langle y - x, z \rangle = 0 \forall z \in C$.

Theorem 1.2 (Orthogonality Principle). H is Hilbert space & $U \subseteq H$ closed subspace $\implies \forall x \in H, \exists$ unique $u \in U$ closest to x . $u \in U$ closest to x iff $\langle u - x, z \rangle = 0 \forall z \in U$.

1.2 Harmonic Analysis

Definition 1.3 (DTFT). $x \in \ell^2(\mathbb{Z}) \implies \hat{x}(\omega) = \sum_{n \in \mathbb{Z}} x(n) e^{-i\omega n}, \omega \in [-\pi, \pi]$.

Theorem 1.4 (Parseval Identity). $x, y \in \ell^2(\mathbb{Z}) \implies \langle x, y \rangle_{\ell^2(\mathbb{Z})} = \langle \hat{x}, \hat{y} \rangle_{L^2(\mathbb{S}^1)}$.

Definition 1.5 (IDTFT). $\hat{x} \in L^2(\mathbb{S}^1) \implies x(n) = \frac{1}{2\pi} \int_{-\pi}^{\pi} \hat{x}(\omega) e^{i\omega n} d\omega, n \in \mathbb{Z}$

Theorem 1.6 (Convolution Theorem). $x, y \in \ell^2(\mathbb{Z})$ & $\hat{y} \in L^\infty(\mathbb{S}^1) \implies z = x * y \in \ell^2(\mathbb{Z})$ & $\hat{z}(\omega) = \hat{x}(\omega) \hat{y}(\omega) \forall \omega \in \mathbb{S}^1$.

2 Probability Theory

2.1 Basics

Proposition 2.1. $\mathcal{B}_{\mathbb{R}}$ is generated by the class of half-open intervals.

Theorem 2.2. \mathbf{P} is PM \implies (i) $A \subseteq B \implies \mathbf{P}(A) \leq \mathbf{P}(B)$; (ii) $A = \bigcup_n A_n \implies \mathbf{P}(A) \leq \sum_n \mathbf{P}(A_n)$ (union bound); (iii) (A_n) ascending & $A = \bigcup_n A_n \implies \mathbf{P}(A_n) \uparrow \mathbf{P}(A)$; (iv) (A_n) descending & $A = \bigcap_n A_n \implies \mathbf{P}(A_n) \downarrow \mathbf{P}(A)$.

Theorem 2.3 (Borel-Cantelli). $\sum_n \mathbf{P}(A_n) < \infty \implies \mathbf{P}(A_n \text{ i.o.}) = 0$.

Theorem 2.4 (Borel-Cantelli Converse). (A_n) independent & $\sum_n \mathbf{P}(A_n) = \infty \implies \mathbf{P}(A_n \text{ i.o.}) = 1$.

Theorem 2.5 (Carathéodory Extension). If $\mathcal{G} \subseteq 2^\Omega$ has (i) $\emptyset, \Omega \in \mathcal{G}$, (ii) $A, B \in \mathcal{G} \implies A \cap B \in \mathcal{G}$, (iii) $A, B \in \mathcal{G} \implies \exists C_1, \dots, C_n \in \mathcal{G}: A \setminus B = \bigcup_{i=1}^n C_i$ and $\exists p: \mathcal{G} \rightarrow [0, 1]$ s.t. (i) $p(A) \geq 0 \forall A \in \mathcal{G}$, (ii) $p(\Omega) = 1$, (iii) (A_n) disjoint and $B = \bigcup_n A_n \implies p(B) = \sum_n p(A_n)$, then \exists unique PM on $\sigma(\mathcal{G})$ agreeing with p .

Theorem 2.6. $F: \mathbb{R} \rightarrow [0, 1]$ is dist. func. of RV iff F non-decreasing and right-continuous. RV is real-valued iff $\lim_{x \rightarrow -\infty} F(x) = 0$ and $\lim_{x \rightarrow +\infty} F(x) = 1$.

Theorem 2.7 (Fatou). (X_n) non-negative & $X = \liminf_{n \rightarrow \infty} X_n \implies \liminf_{n \rightarrow \infty} \mathbf{E}(X_n) \geq \mathbf{E}(X)$.

Theorem 2.8 (MCT). (X_n) non-negative monotone & $X = \lim_{n \rightarrow \infty} X_n \implies \lim_{n \rightarrow \infty} \mathbf{E}(X_n) = \mathbf{E}(X)$.

Theorem 2.9. $X, Y \in L^1$ or $X, Y \geq 0 \implies$ (i) $X = Y \implies \mathbf{E}(X) = \mathbf{E}(Y)$; (ii) $X \leq Y \implies \mathbf{E}(X) \leq \mathbf{E}(Y)$; (iii) $a, b \in \mathbb{R} \implies \mathbf{E}(aX + bY) = a\mathbf{E}(X) + b\mathbf{E}(Y)$; (iv) $|\mathbf{E}(XY)|^2 \leq \mathbf{E}(|X|^2) \mathbf{E}(|Y|^2)$ (Cauchy-Schwarz); (v) $\phi: \mathbb{R} \rightarrow \mathbb{R}$ convex & $\phi(X) \in L^1 \implies \phi(\mathbf{E}(X)) \leq \mathbf{E}(\phi(X))$ (Jensen).

Theorem 2.10 (DCT). (X_n) RVs, $Y \in L^1$ & $|X_n| \leq Y \forall n$ & $X = \lim_{n \rightarrow \infty} X_n \implies \lim_{n \rightarrow \infty} \mathbf{E}(X_n) = \mathbf{E}(X)$.

Theorem 2.11 (Bayes Rule). (A_n) partition Ω & $\mathbf{P}(A_n) > 0$ & $\mathbf{P}(B) > 0 \implies \mathbf{P}(A_n | B) = \frac{\mathbf{P}(A_n) \mathbf{P}(B | A_n)}{\sum_i \mathbf{P}(A_i) \mathbf{P}(B | A_i)}$.

Notation 2.12. $\mathcal{B}(Y) = \text{Cl}_{L^2}(L^\infty \text{ func. of } Y)$; $\mathcal{L}(Y) = \text{Cl}_{L^2}(\text{affine func. of } Y)$.

Theorem 2.13. $X \in L^1, Y$ is RV $\implies \mathbf{E}(X | Y) = \text{proj}_{\mathcal{L}(Y)}(X; \mathcal{B}(Y))$.

Theorem 2.14 (Radon-Nikodym). $\mu \ll \lambda$ (i.e., $\lambda = 0 \implies \mu = 0$) $\implies \exists \frac{d\mu}{d\lambda} \geq 0$.

Theorem 2.15 (Iterated Expectation). $X \in L^1, Y, Z$ RVs $\implies \mathbf{E}(\mathbf{E}(X | Y, Z) | Y) = \mathbf{E}(X | Y)$.

Proposition 2.16. CE, e.g., operator $\mathbf{E}(\cdot | Z)$ obeys properties of $\mathbf{E}(\cdot)$.

2.2 Limit Theorems

Theorem 2.17 (WLLN). $(X_n) \in L^1$ i.i.d. $\implies \lim_{n \rightarrow \infty} \frac{S_n}{n} = \mathbf{E}(X_1)$.

Theorem 2.18 (SLLN). $(X_n) \in L^1$ i.i.d. $\implies \lim_{n \rightarrow \infty} \frac{S_n}{n} = \mathbf{E}(X_1)$.

Theorem 2.19 (CLT). $(X_n) \in L^2$ i.i.d. $\implies \lim_{n \rightarrow \infty} \frac{S_n - n\mathbf{E}(X_1)}{\sqrt{n \text{Var}(X_1)}} = \mathcal{N}(0, 1)$.

Theorem 2.20. $\lim_{n \rightarrow \infty} X_n = X \implies \lim_{n \rightarrow \infty}^p X_n = X \implies \lim_{n \rightarrow \infty}^d X_n = X$.

Theorem 2.21 (Skorohod). $(F_n), F$ dist. func., $\lim_{n \rightarrow \infty} F_n(x) = F(x) \forall x \in C_F \implies \exists (X_n), X: X_n \sim F_n, X \sim F, \lim_{n \rightarrow \infty} X_n = X$.

Theorem 2.22 (Helly). (X_n) RVs $\implies \exists (X_{n_k}), X: \lim_{k \rightarrow \infty}^d X_{n_k} = X$.

Theorem 2.23. $\lim_{n \rightarrow \infty}^d X_n = X \iff \lim_{n \rightarrow \infty} \mathbf{E}(g(X_n)) = \mathbf{E}(g(X)) \forall g \in L^\infty \cap C^0$.

Theorem 2.24 (Lévy's Continuity). $\lim_{n \rightarrow \infty}^d X_n = X \iff \lim_{n \rightarrow \infty} \phi_{X_n}(t) = \phi_X(t) \forall t$.

Theorem 2.25. $X \perp\!\!\!\perp Y \iff \phi_{(X,Y)}(s, t) = \phi_X(s) \phi_Y(t)$.

2.3 Gaussians

Theorem 2.26. Distribution of jointly Gaussian random variables is defined by the mean/covariance. E.g., if X, Y are JG then $\text{Cov}(X, Y) = 0 \iff X \perp\!\!\!\perp Y$.

Theorem 2.27. X, Y JG & $\Sigma_Y > 0 \implies X = \mu_X + \Sigma_{XY}\Sigma_Y^{-1}(Y - \mu_Y) + V$, $V \sim \mathcal{N}(0, \Sigma_X - \Sigma_{XY}\Sigma_Y^{-1}\Sigma_{YX})$ & $V \perp\!\!\!\perp Y$.

Definition 2.28. (X_t) is Gaussian process (GP) iff all FDDs are jointly Gaussian.

Definition 2.29. (X_t) is Brownian motion (BM) if: (i) it has independent stationary increments; (ii) it is zero-mean GP with $X_0 = 0$; (iii) a.s. continuous sample paths. Standard BM has $\text{Var}(X_1) = 1$.

Proposition 2.30. BM is zero-mean GP with a.s. continuous sample paths and $\text{Cov}(X_s, X_t) = \text{Var}(X_1) \cdot (s \wedge t)$.

2.4 Linear Estimation

Theorem 2.31. $Y = (Y_i) \in L^2 \implies \forall X \in L^2 \exists \mathbf{L}(X | Y) \in \mathcal{L}(Y): \mathbf{L}(X | Y) = \text{proj}_{L^2}(X; \mathcal{L}(Y))$.

Theorem 2.32 (Vector BLE). $X \in L^2, Y = (Y_1, \dots, Y_n) \in L^2$ & $\Sigma_Y > 0 \implies \mathbf{L}(X | Y) = \mathbf{E}(X) + \Sigma_{XY}\Sigma_Y^{-1}(Y - \mathbf{E}(Y))$ & $\|X - \mathbf{L}(X | Y)\|_{L^2}^2 = \Sigma_X - \Sigma_{XY}\Sigma_Y^{-1}\Sigma_{YX}$.

Theorem 2.33 (Kalman Filter). State space model $X_{n+1} = a_n X_n + U_n; Y_n = X_n + V_n$ with $\text{Var}(X_0) = P_0$ & $\text{Var}(U_n) = Q_n$ & $\text{Var}(V_n) = N_n$ and $U_i \perp\!\!\!\perp V_j \perp\!\!\!\perp X_0$, initialize $\hat{X}_{0|-1} = 0$, $\sigma_{0|-1}^2 = P_0$, iterate $\hat{X}_{n+1|n} = a_n \hat{X}_{n|n-1} + k_n(Y_n - \hat{X}_{n|n-1})$ where $k_n = a_n \sigma_{n|n-1}^2 (\sigma_{n|n-1}^2 + N_n)^{-1}$ is Kalman gain, and $\sigma_{n+1|n}^2 = \text{Var}(X_{n+1} - \hat{X}_{n+1|n}) = a_n(a_n - k_n)\sigma_{n|n-1}^2 + Q_n$.

2.5 WSS Estimation

Definition 2.34. WSS process X has regular covariance (RC) iff (i) $R_{XX} \in \ell^2(\mathbb{Z})$, and (ii) $\inf S_{XX} > 0$ & $\sup S_{XX} < \infty$.

Definition 2.35. $I \subseteq \mathbb{Z}, Y$ is zero-mean WSS RC, $Z \in L^2 \implies \exists h \in \ell^2(\mathbb{Z}): \mathbf{L}(X | Y_I) = \sum_{i \in I} h_i Y_i$, h unique on I .

Theorem 2.36 (Wiener-Hopf). For $I \subseteq \mathbb{Z}, Y$ is zero-mean WSS RC, $h \in \ell^2(\mathbb{Z})$ s.t. $\mathbf{L}(X | Y_I) = \sum_{i \in I} h_i Y_i$ satisfies $\langle X, Y_n \rangle_{L^2} = (R_{YY} * h)(n)$ for $n \in I$ and $h(n) = 0$ for $n \notin I$.

Corollary 2.37. Y zero-mean WSS RC $\implies h \in \ell^2(\mathbb{Z})$ s.t. $\mathbf{L}(X | Y) = \sum_{i \in \mathbb{Z}} h_i Y_i$ has frequency response $H(\omega) = \frac{S_{YX}(\omega)}{S_{YY}(\omega)} \forall \omega \in \mathbb{S}^1$ & $\|X - \mathbf{L}(X | Y)\|_{L^2}^2 = \text{Var}(X) - \frac{1}{2\pi} \int_{\mathbb{S}^1} \frac{|S_{YX}(\omega)|}{S_{YY}(\omega)} d\omega$.

Theorem 2.38 (Noncausal Wiener Filter). X, Y zero-mean JWSS, Y RC, $\mathbf{L}(X_n | Y) = \sum_{i \in \mathbb{Z}} h_i Y_{n-i} \implies h$ has frequency response $H(\omega) = \frac{S_{YX}^*(\omega)}{S_{YY}(\omega)} \forall \omega \in \mathbb{S}^1$ & $\|X_n - \mathbf{L}(X_n | Y)\|_{L^2}^2 = \frac{1}{2\pi} \int_{\mathbb{S}^1} \left(S_{XX}(\omega) - \frac{|S_{YX}(\omega)|^2}{S_{YY}(\omega)} \right) d\omega$.

3 Random Processes

3.1 DTMC

Proposition 3.1. $A \subseteq \mathbb{N}$, $\text{gcd}(A) = d$, A closed under addition $\implies \exists N: kd \in A \forall k \geq N$.

Notation 3.2. $T_j := \inf \{n \in \mathbb{N}: X_n = j\}$. $\mu_{jj} := \mathbf{E}(T_j | X_0 = j)$. $N_j(n) := |\{k \in [n]: X_k = j\}|$.

Definition 3.3 (Markov Property). $X_s - X_t - X_u \forall s < t < u$.

Definition 3.4 (Strong Markov Property). $X_s - X_\tau - X_u \forall s < \tau < u$, for all finite stopping times τ .

Theorem 3.5 (Chapman-Kolmogorov). $m, n \geq 0$ & $i, j \in \mathcal{S} \implies P_{ij}^{m+n} = \sum_{k \in \mathcal{S}} P_{ik}^m P_{kj}^n$.

Proposition 3.6. Periodicity, transience, positive recurrence, and null recurrence are class properties.

Lemma 3.7. State i is recurrent iff $\sum_{n \in \mathbb{N}} P_{ii}^n = +\infty$.

Corollary 3.8. If $i \leftrightarrow j$ and j is recurrent, then $\mathbf{P}(T_j < \infty | X_0 = i) = 1$.

Theorem 3.9 (DTMC SLLN). (X_n) DTMC, $X_0 = i$, $i \leftrightarrow j \implies \lim_{n \rightarrow \infty} \frac{N_j(n)}{n} = \frac{1}{\mu_{jj}}$.

Corollary 3.10. (X_n) irreducible DTMC $\implies \lim_{n \rightarrow \infty} \frac{1}{n} \sum_{k=1}^n P_{ij}^k = \frac{1}{\mu_{jj}}$.

Theorem 3.11 (Balance Equations). π is SD iff $\pi_j = \sum_i \pi_i p_{ij} \forall j \in \mathcal{S}$.

Definition 3.12. State i is positive recurrent iff $\mu_{ii} < \infty$, null recurrent iff recurrent and $\mu_{ii} = \infty$, and transient otherwise.

Theorem 3.13. Irreducible DTMC satisfies exactly one: (i) all states are transient or null recurrent, then, no SD exists and $\lim_{n \rightarrow \infty} \frac{1}{n} \sum_{k=1}^n P_{ij}^k = 0 \forall i, j$; (ii) all states are positive recurrent, then \exists unique SD and $\pi_j = 1/\mu_{jj} = \lim_{n \rightarrow \infty} \frac{1}{n} \sum_{k=1}^n P_{ij}^k \forall i, j$.

Theorem 3.14. (X_n) irreducible aperiodic positive recurrent DTMC $\implies \lim_{n \rightarrow \infty} \sum_j |P_{ij}^n - \pi_j| = 0$, i.e., $P_{ij}^n \rightarrow \pi_j \forall i, j$. If periodic, $\lim_{n \rightarrow \infty} P_{jj}^{nd} = d\pi_j \forall j$. If transient/null recurrent (not necessarily aperiodic), $P_{ij}^n \rightarrow 0 \forall i, j$.

Definition 3.15 (DTMC Reversibility). $\pi_i p_{ij} = \pi_j p_{ji} \forall i, j$.

Theorem 3.16 (DBEs). If $\exists \pi$ s.t. $\pi_i p_{ij} = \pi_j p_{ji} \forall i, j$ then DTMC reversible with SD π .

Definition 3.17 (Total Variation Distance). $\|\mu - \nu\|_{\text{TV}} := \sup_{A \in \mathcal{F}} |\mu(A) - \nu(A)|$.

Definition 3.18 (Spectral Gap). (X_n) reversible DTMC, spectral gap is $\gamma := 1 - \lambda_2$, where $\lambda_2 \geq 0$ is the smallest number for which $\text{Var}_\pi(Pf) \leq \lambda_2 \text{Var}_\pi(f)$; here $(Pf)(i) = \sum_j p_{ij}f(j)$ and $\text{Var}_\pi(f) = \text{Var}_{X \sim \pi}(f(X))$.

Theorem 3.19. (X_n) reversible DTMC, spectral gap $\gamma \implies \|P_i^n - \pi\|_{\text{TV}}^2 \leq \frac{(1-\gamma)^n}{\pi_i} \forall n \in \mathbb{N}, i \in \mathcal{S}$. DTMC is irreducible, aperiodic, finite state space $\implies \gamma > 0$.

3.2 Martingales

Definition 3.20 (Martingale). (X_n) RVs, (M_n) is (sub/super) martingale w.r.t. (X_n) if (M_n) adapted to (X_n) , each $M_n \in L^1$, and $\mathbf{E}(M_{n+1} | X^n) = M_n$ (\geq/\leq).

Proposition 3.21. (M_n) submartingale, $m > n \implies \mathbf{E}(M_m | X^n) \geq M_n$.

Proposition 3.22. (M_n) submartingale, T stopping time $\implies (M_{T \wedge n})$ submartingale.

Proposition 3.23. (M_n) submartingale, T stopping time $\implies \mathbf{E}(M_0) \leq \mathbf{E}(M_{T \wedge n}) \leq \mathbf{E}(M_n)$.

Theorem 3.24 (Optional Stopping Theorem). (M_n) submartingale, T stopping time; if $\exists k < \infty$ s.t. $T \leq k$ or $|M_n| \leq k \forall n$ & $T < \infty$ or $\mathbf{E}(T) \in L^\infty$ & $|M_n - M_{n-1}| \leq k \forall n$, then $\mathbf{E}(M_0) \leq \mathbf{E}(M_T)$.

Theorem 3.25 (Wald's Identity). (Y_n) adapted to (X_n) , $Y_{n+1} \perp\!\!\!\perp X^n \forall n$, $\sup_n \mathbf{E}(|Y_n|) < \infty$, $\mathbf{E}(Y_n) = \mu \forall n$, $T \in L^1$ is stopping time w.r.t. $(X_n) \implies \mathbf{E}\left(\sum_{i=1}^T Y_i\right) = \mu \mathbf{E}(T)$.

Theorem 3.26 (Doob). (M_n) submartingale, $\alpha > 0, n \in \mathbb{N} \implies \mathbf{P}(\max_{0 \leq k \leq n} M_k \geq \alpha) \leq \frac{\mathbf{E}(M_n^+)}{\alpha}$.

Theorem 3.27 (Azuma-Hoeffding). (M_n) submartingale w.r.t. (X_n) , $\forall k \exists L_k, U_k$ predictable s.t. $L_k \leq M_{k+1} - M_k \leq U_k$ and $U_k - L_k \leq c_k$ for some $c_k \geq 0 \implies \forall n \in \mathbb{N}, t > 0: \mathbf{P}(M_n \leq M_0 - t) \leq \exp\left(-\frac{2t^2}{\sum_{k=1}^n c_k^2}\right)$.

Lemma 3.28 (Hoeffding). Y RV s.t. $\mathbf{E}(Y) \leq 0, Y \in [a, b], \alpha > 0 \implies \mathbf{E}(e^{\alpha Y}) \leq \exp\left(\frac{\alpha^2(b-a)^2}{8}\right)$.

Theorem 3.29 (McDiarmid). X_1, \dots, X_n independent, $\exists c_k$ s.t. f varies by at most c_k by only changing k^{th} argument $\implies \forall t > 0: \mathbf{P}(f(X_1, \dots, X_n) \geq \mathbf{E}(f(X_1, \dots, X_n)) + t) \leq \exp\left(-\frac{2t^2}{\sum_{k=1}^n c_k^2}\right)$.

Theorem 3.30 (Convergence). (M_n) (sub/super) martingale, $\sup_n \mathbf{E}(|M_n|) < \infty \implies M := \lim_{n \rightarrow \infty} M_n$ exists, L^1 .

Corollary 3.31. (M_n) (sub/super) martingale, $\exists Y \in L^1: |M_n| \leq Y \forall n \implies M$ exists, $\mathbf{E}(M) = \lim_{n \rightarrow \infty} \mathbf{E}(M_n)$.

3.3 Poisson Processes

Theorem 3.32 (Memoryless). Exponential distribution is memoryless: $\mathbf{P}(T > t + s | T > t) = \mathbf{P}(T > s)$.

Theorem 3.33. $X_i \stackrel{\text{i.i.d.}}{\sim} \text{Exp}(\lambda_i) \implies \min_{1 \leq i \leq n} X_i \sim \text{Exp}(\sum_{i=1}^n \lambda_i)$.

Definition 3.34 (Counting Process). (N_t) is CP iff $N_t \in \mathbb{N}_0 \forall t$, sample paths non-decreasing & right-continuous.

Proposition 3.35. (N_t) is PP(λ) $\implies \forall t: N_t \sim \text{Pois}(\lambda t)$.

Theorem 3.36. CP (N_t) is PP(λ) iff $N_0 = 0, N_t \sim \text{Pois}(\lambda t) \forall t$, and has independent/stationary increments.

Theorem 3.37. (N_t) is PP with arrival times $(T_i) \implies (T_1, \dots, T_n) | \{N_t = n\} \sim (tU_{(1)}, \dots, tU_{(n)})$.

Theorem 3.38 (Thinning). (N_t) is PP(λ), arrival labeled i with prob. p_i ind. \implies arrivals of class i are ind. PP(λp_i).

Theorem 3.39 (Merging). (N_t^i) are ind. PP(λ_i) $\implies (\sum_i N_t^i)$ is PP($\sum_i \lambda_i$).

Definition 3.40 (Inhomogeneous). CP (N_t) is IPP(λ) if $N_0 = 0$, independent increments, $N_t - N_s \sim \text{Pois}\left(\int_s^t \lambda(r) dr\right)$.

Theorem 3.41. (N_t) is PP(λ), $p: \mathbb{R}_{\geq 0} \rightarrow [0, 1]$, counting arrivals at time t with prob. $p(t)$ ind. gives IPP(λp).

3.4 CTMC

Definition 3.42. (X_t) is CTMC if sample paths are right-continuous and obeys Markov property.

Theorem 3.43 (Chapman-Kolmogorov). $P_{ij}^{t+s} = \sum_k P_{ik}^t P_{kj}^s$.

Theorem 3.44. (X_t) CTMC, $X_0 = i, T := \inf\{t \geq 0: X_t \neq i\} \implies T \sim \text{Exp}(\lambda_i)$ for $P_{ii}^h = 1 - h\lambda_i + o(h)$; also $X_T \perp\!\!\!\perp T$ and has distribution $p_{ij} := \mathbf{P}(X_T = j | X_0 = i) = \lim_{h \downarrow 0} \frac{P_{ij}^h}{1 - P_{ii}^h}$.

Definition 3.45. (X_t) is CTMC has infinitesimal generator $Q: q_{ij} := \lambda_i p_{ij}$ for $j \neq i, q_{ij} := -\lambda_i$ for $j = i$.

Corollary 3.46. (X_t) CTMC w. IG Q has $P_{ii}^h = 1 - h\lambda_i + o(h)$ and $P_{ij}^h = hq_{ij} + o(h) \forall j \neq i$.

Theorem 3.47 (KDE). If CTMC is minimal, P^t satisfies $\frac{d}{dt} P^t = Q P^t$ (KBE) and $\frac{d}{dt} P^t = P^t Q$ (KFE) with $P_0 = I$.

Corollary 3.48. If $\sup_i \lambda_i < \infty$, then $P^t = e^{tQ} := \sum_{k \in \mathbb{N}_0} t^k \frac{Q^k}{k!}$.

Definition 3.49. p is SD for CTMC if $p_j = \sum_i p_i P_{ij}^t \forall t \geq 0$.

Theorem 3.50. p s.t. $\sum_i p_i \lambda_i < \infty$ is SD iff $\sum_i p_i Q_{ij} = 0 \forall j$. CTMC irreducible $\implies p$ unique.

Corollary 3.51. Irreducible CTMC has TFAE: (i) CTMC has SD p with $\sum_i p_i \lambda_i < \infty$; (ii) embedded DTMC has SD π with $\sum_i \frac{\pi_i}{\lambda_i} < \infty$. If both are true then $\pi_i \propto \lambda_i p_i$.

Proposition 3.52. \exists SD p with $\sum_i p_i \lambda_i = \infty \implies$ explosion. \exists embedded SD π with $\sum_i \frac{\pi_i}{\lambda_i} = \infty \implies$ infinite lag.

Notation 3.53. $T_{jj} = \inf \{t \geq 0: X_t = j, \exists s \in (0, t): X_s \neq j\}$; $m_{jj} = \mathbf{E}(T_{jj})$.

Theorem 3.54. (X_t) irreducible CTMC, $f_j(t) = \frac{1}{t} \int_0^t 1_{\{X_s=j\}} ds$, $X_0 = i \implies \lim_{t \rightarrow \infty} f_j(t) = \frac{1}{\lambda_j m_{jj}}$.

Corollary 3.55. (X_t) irreducible CTMC, $X_0 = i \implies \lim_{t \rightarrow \infty} \frac{1}{t} \int_0^t P_{ij}^s ds = \frac{1}{m_{jj} \lambda_j}$.

Theorem 3.56. Irreducible CTMC has exactly one: (i) transient/null recurrent, then $\lim_{t \rightarrow \infty} \frac{1}{t} \int_0^t P_{ij}^s ds = 0 \forall i, j$ & no SD exists; (ii) positive recurrent, then \exists unique SD $p_j = \frac{1}{m_{jj} \lambda_j} = \lim_{t \rightarrow \infty} \frac{1}{t} \int_0^t P_{ij}^s ds$.

Theorem 3.57 (Ergodic Theorem). Irreducible positive-recurrent CTMC, SD p , $r: \mathcal{S} \rightarrow \mathbb{R}$ bounded $\implies \forall i: X_0 = i, \lim_{t \rightarrow \infty} \frac{1}{t} \int_0^t r(X_s) ds = \mathbf{E}_{X \sim p}(r(X))$. Holds for DTMCs too: $\forall i: X_0 = i, \lim_{n \rightarrow \infty} \frac{1}{n} \sum_{k=0}^n r(X_k) = \mathbf{E}_{X \sim \pi}(r(X))$.

Theorem 3.58. Irreducible positive recurrent CTMC, SD $p \implies \lim_{t \rightarrow \infty} \|P_{ij}^t - p\|_{TV} = 0 \forall i, j$.

Definition 3.59. CTMC reversible if $\exists p: \sum_i p_i \lambda_i < \infty$ and $p_i q_{ij} = p_j q_{ji} \forall i, j$. Then p is SD.

Definition 3.60 (Spectral Gap). λ = largest s.t. $\text{Var}_p(f) \leq \frac{1}{\lambda} \mathcal{E}(f, f) = \frac{1}{\lambda} \cdot \frac{1}{2} \sum_{i,j} |f(i) - f(j)|^2 q_{ij} p_i \forall f \in L^2(p)$.

Theorem 3.61. If reversible CTMC admits spectral gap λ , then $\|P_{ij}^t - p\|_{TV}^2 \leq e^{-2\lambda t} / p_i \forall t \geq 0$.

3.5 Renewal Processes

Theorem 3.62 (SLLN). For RP (X_t) with holding times (τ_n) , $\lim_{t \rightarrow \infty} \frac{X_t}{t} = \frac{1}{\mathbf{E}(\tau_1)}$.

Theorem 3.63 (Elementary Renewal Theorem). Renewal function $m(t) = \mathbf{E}(X_t)$ satisfies $\lim_{t \rightarrow \infty} \frac{m(t)}{t} = \frac{1}{\mathbf{E}(\tau_1)}$.

Theorem 3.64. (W_n) i.i.d. L^1 are rewards. Renewal-reward process for (X_t) is (R_t) where $R_t = \sum_{i=1}^{X_t} W_i$. Reward function $r(t) = \mathbf{E}(R_t)$. Then $\lim_{t \rightarrow \infty} \frac{R_t}{t} = \frac{\mathbf{E}(W_1)}{\mathbf{E}(\tau_1)}$ and $\lim_{t \rightarrow \infty} \frac{r(t)}{t} = \frac{\mathbf{E}(W_1)}{\mathbf{E}(\tau_1)}$.

Theorem 3.65 (Little's Law). G/G/1 queue. CP for arrivals (A_t) is RP with holding times (τ_n) . CP for departures (D_t) . Define $N_t = A_t - D_t$. W_n = time spent by n^{th} customer. If service time $\mu < \mathbf{E}(\tau_1) < \infty$ then $\bar{N} := \lim_{t \rightarrow \infty} \int_0^t N_s ds$ and $\bar{W} := \lim_{n \rightarrow \infty} \frac{1}{n} \sum_{i=1}^n W_i$ exist and $\bar{N} = \frac{\bar{W}}{\mathbf{E}(\tau_1)}$.

3.6 Hypothesis Testing

Definition 3.66 (Errors). Type I error: $\mathbf{P}_0(\hat{H} = H_1)$; Type II error: $\mathbf{P}_1(\hat{H} = H_0)$.

Definition 3.67 (Threshold Test). $\Lambda = \frac{d\mathbf{P}_1}{d\mathbf{P}_0} = \frac{d\mathbf{P}_1/d\lambda}{d\mathbf{P}_0/d\lambda}$. $\hat{H}_\eta = H_{1\{\Lambda \geq \eta\}}$.

Definition 3.68 (Error Curve). $u(\theta) := \sup_{\eta \geq 0} \left\{ \mathbf{P}_1(\hat{H}_\eta = H_0) + \eta \left(\mathbf{P}_0(\hat{H}_\eta = H_1) - \theta \right) \right\}$.

Theorem 3.69 (Neyman-Pearson Lemma). If $\mathbf{P}_1 \ll \mathbf{P}_0$ every \hat{H}_η lies on error curve, and all tests lie above it.

Definition 3.70 (Sufficient Statistic). T is sufficient iff $\exists \nu: \Lambda = \nu \circ T$.

4 Distributions

- Discrete:

- $X \sim \text{Bernoulli}(p)$: $p_X(x) = p^x(1-p)^{1-x}$; $\mathbf{E}(X) = p$; $\text{Var}(X) = p(1-p)$; $\phi_X(t) = 1 - p + pe^{it}$.
- $X \sim \text{B}(n, p)$: $p_X(x) = \binom{n}{x} p^x(1-p)^{n-x}$; $\mathbf{E}(X) = np$; $\text{Var}(X) = np(1-p)$; $\phi_X(t) = (1 - p + pe^{it})^n$.
- $X \sim \text{Geo}(p)$: $p_X(x) = (1-p)^{x-1}p$; $F_X(x) = 1 - (1-p)^x$; $\mathbf{E}(X) = \frac{1}{p}$; $\text{Var}(X) = \frac{1-p}{p^2}$; $\phi_X(t) = \frac{pe^{it}}{1-(1-p)e^{it}}$.
- $X \sim \text{Pois}(\lambda)$: $p_X(x) = \frac{\lambda^x e^{-\lambda}}{x!}$; $\mathbf{E}(X) = \lambda$; $\text{Var}(X) = \lambda$; $\phi_X(t) = \exp(\lambda(e^{it} - 1))$.

- Continuous:

- $X \sim \mathcal{N}(\mu, \Sigma)$: $p_X(x) = \frac{1}{(2\pi)^{n/2} \det(\Sigma)^{1/2}} e^{-\frac{1}{2}(x-\mu)^* \Sigma^{-1}(x-\mu)}$; $\mathbf{E}(X) = \mu$; $\text{Var}(X) = \Sigma$; $\phi_X(t) = \exp(i\mu^* t - \frac{1}{2} t^* \Sigma t)$.
- $X \sim \text{Exp}(\lambda)$: $p_X(x) = \lambda e^{-\lambda x}$; $F_X(x) = 1 - e^{-\lambda x}$; $\mathbf{E}(X) = \frac{1}{\lambda}$; $\text{Var}(X) = \frac{1}{\lambda^2}$; $\phi_X(t) = \frac{\lambda}{\lambda - it}$.
- $X \sim \text{Erlang}(\lambda, k)$: $p_X(x) = \frac{\lambda^k x^{k-1} e^{-\lambda x}}{(k-1)!}$; $\mathbf{E}(X) = \frac{k}{\lambda}$; $\text{Var}(X) = \frac{k}{\lambda^2}$; $\phi_X(t) = (1 - \frac{it}{\lambda})^{-k}$.