[Adapted from [1, p. 47]]

DESCRIPTION

Consider the quantities a_k s, with measured values \hat{a}_k s and measured uncertainty Δa_k s, and the quantities b_l s, with sample mean values \bar{b}_l s and sample standard deviations σ_{b_l} s; *i.e.*, the \hat{a}_k s arise from single measurements and the \bar{b}_l s from multiple measurements. Consider now a function f that depends on the a_k s and on the a_l s. Then, the most likely value of f is given by

$$\hat{y} = f[\hat{a}_k, \bar{b}_l] ,$$

whereas its maximum uncertainty by

$$\Delta y = \sum_k \operatorname{abs} \partial_{a_k} y \Delta a_k + \sum_l \operatorname{abs} \partial_{b_l} y \sigma_{b_l} \,,$$

where abs x represents the absolute value of x.

EXAMPLE

Determine the local free fall acceleration by the period of a mathematical pendulum of length $l/{\rm m}=1.00\pm0.01$ and period $t/{\rm s}=2.0062\pm0.0057$. The length was measured once and the period thousand times (Monte Carlo simulation).

The period of a math pendulum of length l is given by

$$t = 2\pi \sqrt{\frac{l}{g}},$$

where g represents the local free fall acceleration.

From the pendulum equation, isolate g to have

$$g = 4\pi^2 \frac{l}{t} \,.$$

Then, the max uncertainty of g is

$$\Delta g = \mathrm{abs}\, \partial_l g \Delta l + \mathrm{abs}\, \partial_t g \sigma_t = 4\pi^2 \frac{1}{t^2} \Delta l + 8\pi^2 \frac{l}{t^3} \sigma_t \,.$$

Divide the last equation by the equation for g to have the relative uncertainty (fractional change) of g

$$\frac{\Delta g}{q} = \frac{\Delta l}{l} + 2\frac{\sigma_t}{t} \,.$$

Replace the given values in the g equation and in the equation for its relative uncertainty to find

$$\begin{split} g &= 4\pi^2 \frac{l}{t} = 4\pi^2 \frac{1.00}{2.0062^2} = 9.808696222936447 \,, \\ \Delta g &= g \left(\frac{\Delta l}{l} + 2 \frac{\sigma_t}{t} \right) \\ &= 9.808696222936447 \left(\frac{0.01}{1.00} + 2 \frac{0.0057}{2.0062} \right) \\ &= 0.153823746668 \,. \end{split}$$

Finally, the value for the free fall acceleration is $g/{\rm m\,s^{-2}}=9.809\pm0.154.$

REFERENCES

[1] Carl von Ossietzky Universität Oldenburg. Error theory and regression analysis. Institute of Physics, 2014.