

Netzwerkalgorithmen

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1 Topologisches Sortieren

1.1 BFS

```
bool TOPSORT (const graph& G, node_array<int>& topnum){
    int count = 0
    list<node> zero
    node_array<int> indeg(G)
    node v
    forall_nodes(v,G){
        indeg[v] = G.indeg(v)
        if (indeg[v] == 0) zero.append(v)
    }
    while (!zero.empty()){
        node v = zero.pop()
        topnum[v] = ++count
        edge e
        forall_out_edges(e,v){
            node w = G.target(e)
            if(--indeg[w] == 0) zero.append(w)
        }
    }
    return count == G.number_of_nodes()
}
```

1.2 DFS

```
bool DFS_TOPSORT (const graph& G, node_array<int>& dfsnum, node_array<int>& compnum){
    int count1 = 0
    int count2 = 0
    node_array<bool> visited(G, false)
    node v
    forall_nodes(v,G){
        if (!visited[v]) dfs(G,v,count1,count2,dfsnum,compnum)
    }
}

void dfs(const graph& G, node v, int& count1, int& count2, node_array<int>& dfsnum, node_a
dfsnum[v] = ++count1
visited[v] = true
edge e
forall_out_edges(e,v){
    edge w = G.target(e)
    if (!visited[w]) dfs(G,w,count1,count2,dfsnum,compnum)
}
compnum[v] = ++count2
```

```
}
```

1.3 Starke Zusammenhangskomponenten

2 Kürzeste Wege

2.1 $\mathcal{O}(n + m)$

```
forall v in V do
    DIST[v] = unendlich
od
DIST[s] = 0
U = {s}
while U nicht leer
    wähle das u aus U mit minimaler topologischen Nummer
    forall v in V mit (u,v) in E do
        c = DIST[u] + cost(u,v)
        if c < DIST[v] then
            DIST[v] = c
            U = U + {v}
        fi
    od
od
```

2.2 Dijkstra

1x Konstruktor, n*(insert+delmin+empty), mx*decrease

Binärer Heap/Balancierter Baum: $\mathcal{O}((n + m) * \log(n))$

Fib-Heap: $\mathcal{O}(n * \log(n) + m)$

```
void DIJKSTRA(const graph& G, node s, const edge_array<int>& cost,
    _ const node_array<int>& dist, node_array<edge>& pred){
    node_pq<int> PQ(G);
    node v
    forall_nodes(v,G){
        dist[v] = unendl
        pred[v] = null
    }
    dist[s] = 0
    PQ.insert(s,0)
    while(!PQ.empty()){
        node u = PQ.delmin()
        edge e
        forall_out_edges(e,u){
            node v = G.target(e)
            int c = DIST[u] + cost(e)
            if(c < dist[v]){
                if(dist[v] == MAXINT){
                    PQ.insert(v,c)
                }else{
                    PQ.decrease(v,c)
                }
                dist[v] = c
                pred[v] = u
            }
        }
    }
}
```

2.3 Bellman-Ford

```

bool BELLMAN(const graph& G, node s, const edge_array<int>& cost, node_array<int>& DIST){
    queue<node> Q;
    node_array<bool> inQ(G, false)
    node_array<int> count
    DIST[s] = 0
    Q.append(s)
    inQ[s] = true
    while (!Q.empty()){
        node u = Q.pop()
        inQ[u] = false
        if (++count[u] > G.number_of_nodes()){
            return false
        }
        edge e
        forall_out_edges(e,u){
            node v = G.target(e)
            int c = DIST[u] + cost[e]
            if (c<DIST[v]) {
                DIST[v] = c
                //Setze PRED verweis hier falls nötig
                if (!inQ[v]){
                    Q.append(v)
                    inQ[v] = true
                }
            }
        }
    }
    return true
}

```

3 Maximaler Fluss

3.1 MF-Labeling

Labeling: $\mathcal{O}(n+m)$, Gesamt: $\mathcal{O}(n^2U + nmU)$, da max $n-1$ Kanten über den Schnitt laufen und damit $F_{max} \leq n * U$ mit U der Kapazität der mächtigsten Kante.

Bei zusammenhängendem Graphen: $\mathcal{O}(nmU)$

```

void MF_Labeling (const graph& G, node s, node t, const edge_array<int>& cap,
_ edge_array<int>& flow){
    list<node> L
    node_array<bool> labeled(G, false)
    node_array<edge> pred(G, null)
    while(true){
        labeled[s] = true
        L.append(s)
        while (!L.empty()) {
            node v = L.pop()
            edge e
            forall_out_edges(e,v){
                if ( flow[e]==cap[e]) continue
                node w = G.target(e)
                if (labeled[w]) true
                labeled[w]=true
                pred[w]=e
            }
        }
    }
}

```

```

        L.append(w)
    }
    forall_in_edges(e,v){
        if (flow[e]==0) continue
        node w = G.source(e)
        if (labeled[w]) continue
        labeled[w] = true
        pred[w] = e
        L.append(w)
    }
    if (labeled[t]) L.clear()
}
if (labeled[t]) AUGMENT(G,s,t,pred,cap,flow)
else break
}
}

void AUGMENT (const graph& G, node s, node t, cost node_array<edge>& pred, edge_array<int>
    int delta = MAXINT
    node v = t
    while (v != s){
        int r
        edge e = pred[v]
        if(v==G.source(e)){
            r = flow[e]
            v = G.target[w]
        }else{
            r = cap[e]-flow[e]
            v = G.source(e)
        }
        if (r<delta) delta =r
    }
    v = t
    while (v!=s){
        edge e = pred[v]
        if(v==G.source(e)){
            flow[e] -= delta
            v = G.target(e)
        }else{
            flow[e] += delta
            v = G.source(e)
        }
    }
}
}

```

3.2 Capacity-Scaling

Anzahl der Phasen $\leq \log U$

Jede Phase führt max 2m Erhöhungen aus + labeling: $\mathcal{O}(2mm)$

$\mathcal{O}(m^2 * \log(U))$

In Labeling:

```

    if (cap[e]-flow[e] < delta) continue
    statt: if (flow[e] == cap[e]) continue

    if (flow[e] < delta) continue

```

```

      statt: if (flow[e]==0) continue

CAPACITY_SCALING (G,s,t,cap,flow,U){
  flow = 0 // alle Flüsse = 0
  delta = 2^(log(U))
  while delta > 0 do
    MF-LABELING(G,s,t,cap,flow,delta)
    delta = delta / 2
  od
}

```