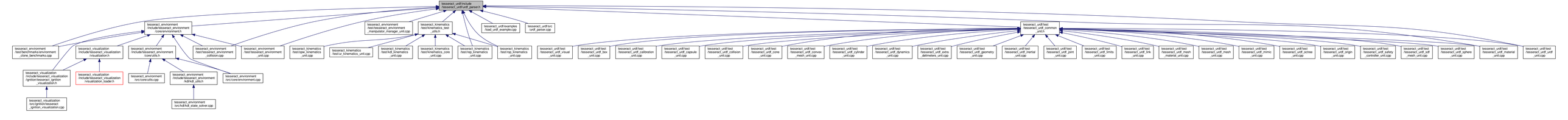
tesseract_urdf/include /tesseract_urdf/urdf_parser.h
tesseract_environment /include/tesseract_environment /core/environment.h
tesseract_environment /test/tesseract_environment /manipulator_manager_unit.cpp
tesseract_kinematics /test/kinematics_test _utils.h
tesseract_urdf/examples /load_urdf_example.cpp
tesseract_urdf/src /urdf_parser.cpp
tesseract_urdf/test /tesseract_urdf_common _unit.h
tesseract_environment /test/benchmark/environment _clone_benchmark.cpp
tesseract_visualization /include/tesseract_visualization /visualization.h
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tesseract_urdf/test /tesseract_urdf_calibration _unit.cpp
tesseract_urdf/test /tesseract_urdf_capsule _unit.cpp
tesseract_urdf/test /tesseract_urdf_collision _unit.cpp
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tesseract_urdf/test /tesseract_urdf_octree _unit.cpp
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tesseract_environment /src/kdl/kdl_state_solver.cpp