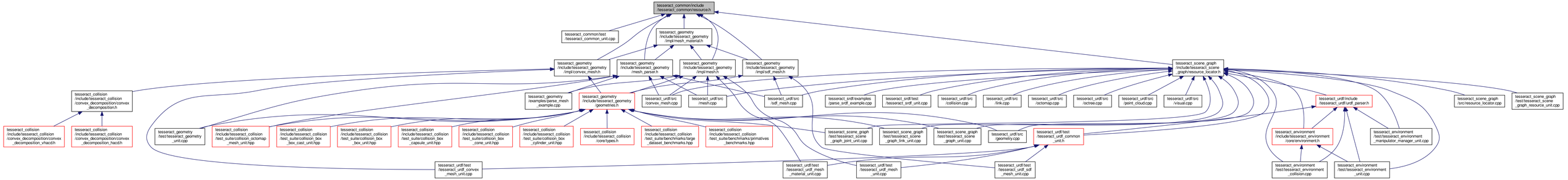
tesseract_common/include/tesseract_common/resource.h
tesseract_common/test/tesseract_common_unit.cpp
tesseract_geometry/include/tesseract_geometry/impl/mesh_material.h
tesseract_geometry/include/tesseract_geometry/impl/convex_mesh.h
tesseract_geometry/include/tesseract_geometry/mesh_parser.h
tesseract_geometry/include/tesseract_geometry/impl/mesh.h
tesseract_geometry/include/tesseract_geometry/impl/sdf_mesh.h
tesseract_scene_graph/include/tesseract_scene_graph/resource_locator.h
tesseract_collision/include/tesseract_collision/convex_decomposition/convex_decomposition.h
tesseract_geometry/examples/parse_mesh_example.cpp
tesseract_geometry/include/tesseract_geometry/geometries.h
tesseract_urdf/src/convex_mesh.cpp
tesseract_urdf/src/mesh.cpp
tesseract_urdf/src/sdf_mesh.cpp
tesseract_srdf/examples/parse_srdf_example.cpp
tesseract_srdf/test/tesseract_srdf_unit.cpp
tesseract_urdf/src/collision.cpp
tesseract_urdf/src/link.cpp
tesseract_urdf/src/octomap.cpp
tesseract_urdf/src/octree.cpp
tesseract_urdf/src/point_cloud.cpp
tesseract_urdf/src/visual.cpp
tesseract_urdf/include/tesseract_urdf/urdf_parser.h
tesseract_scene_graph/src/resource_locator.cpp
tesseract_scene_graph/test/tesseract_scene_graph_resource_unit.cpp
tesseract_collision/include/tesseract_collision/convex_decomposition/convex_decomposition_vhacd.h
tesseract_collision/include/tesseract_collision/convex_decomposition/convex_decomposition_hacd.h
tesseract_geometry/test/tesseract_geometry_unit.cpp
tesseract_collision/include/tesseract_collision/test_suite/collision_octomap_mesh_unit.hpp
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tesseract_collision/include/tesseract_collision/test_suite/collision_box_box_unit.hpp
tesseract_collision/include/tesseract_collision/test_suite/collision_box_capsule_unit.hpp
tesseract_collision/include/tesseract_collision/test_suite/collision_box_cone_unit.hpp
tesseract_collision/include/tesseract_collision/test_suite/collision_box_cylinder_unit.hpp
tesseract_collision/include/tesseract_collision/core/types.h
tesseract_collision/include/tesseract_collision/test_suite/benchmarks/large_dataset_benchmarks.hpp
tesseract_collision/include/tesseract_collision/test_suite/benchmarks/primitives_benchmarks.hpp
tesseract_scene_graph/test/tesseract_scene_graph_joint_unit.cpp
tesseract_scene_graph/test/tesseract_scene_graph_link_unit.cpp
tesseract_scene_graph/test/tesseract_scene_graph_unit.cpp
tesseract_urdf/src/geometry.cpp
tesseract_urdf/test/tesseract_urdf_common_unit.h
tesseract_environment/include/tesseract_environment/core/environment.h
tesseract_environment/test/tesseract_environment_manipulator_manager_unit.cpp
tesseract_environment/test/tesseract_environment_collision.cpp
tesseract_environment/test/tesseract_environment_unit.cpp
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tesseract_urdf/test/tesseract_urdf_mesh_unit.cpp
tesseract_urdf/test/tesseract_urdf_sdf_mesh_unit.cpp