

tesseract_kinematics
/include/tesseract_kinematics
/kdl/kdl_inv_kin_chain_lma
_factory.h

```
graph BT; A["tesseract_environment  
/src/core/manipulator  
_manager.cpp"] --> C["tesseract_kinematics  
/include/tesseract_kinematics  
/kdl/kdl_inv_kin_chain_lma  
_factory.h"]; B["tesseract_kinematics  
/test/kdl_kinematics  
_unit.cpp"] --> C;
```

A diagram showing two source files at the bottom and a header file at the top. Two blue arrows point from the source files to the header file, indicating inclusion relationships.

tesseract_environment
/src/core/manipulator
_manager.cpp

tesseract_kinematics
/test/kdl_kinematics
_unit.cpp