

tesseract\_environment  
::Command



```
graph BT; A[tesseract_environment::ChangeLinkVisibilityCommand] --> B[tesseract_environment::Command];
```

The diagram illustrates an inheritance relationship. A light gray box at the bottom represents the base class, `tesseract_environment::ChangeLinkVisibilityCommand`. A dark blue arrow points vertically upwards from this box to a white box at the top, which represents the derived class, `tesseract_environment::Command`. Both boxes have a black border.

tesseract\_environment  
::ChangeLinkVisibilityCommand