

tesseract_kinematics
/include/tesseract_kinematics
/kdl/kdl_fwd_kin_chain_factory.h

```
graph BT; A["tesseract_environment  
/src/core/manipulator  
_manager.cpp"] --> C["tesseract_kinematics  
/include/tesseract_kinematics  
/kdl/kdl_fwd_kin_chain_factory.h"]; B["tesseract_kinematics  
/test/kdl_kinematics  
_unit.cpp"] --> C;
```

The diagram illustrates a dependency structure where two source files include a common header file. At the top is a grey box representing the header file: `tesseract_kinematics/include/tesseract_kinematics/kdl/kdl_fwd_kin_chain_factory.h`. Below it are two white boxes representing source files. The left box is `tesseract_environment/src/core/manipulator_manager.cpp` and the right box is `tesseract_kinematics/test/kdl_kinematics_unit.cpp`. Blue arrows point from each source file box up to the header file box, indicating that both source files include this header.

tesseract_environment
/src/core/manipulator
_manager.cpp

tesseract_kinematics
/test/kdl_kinematics
_unit.cpp